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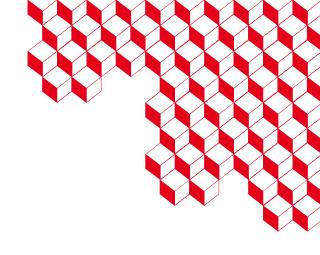


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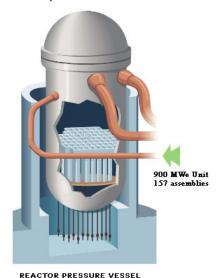


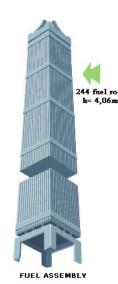
- Context

Context

 Reactor physics is a highly multiphysics field involving nuclear physics, neutronics, thermalhydraulics, structural mechanics, material science,

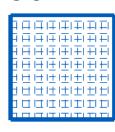
- Industries rely on highly verified and validated code systems to perform routine computations based on low-order approximations for optimal precision to computing time ratio.
 - Parametric computations to sweep a very large domain for design and operational studies
 - ex: two-scale (assembly and core) approach in neutronics,
 1D simplified thermalhydraulics



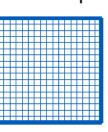


 High-fidelity simulations are required to provide sufficient validation on low-order model validity to safety authorities for usual Pressurised Water Reactor from the nuclear fleet or to design new reactors such as Small Modular Reactors, Advanced Modular Reactors, ...etc.

■ CFD for mixing grid studies or transport computation in neutronics

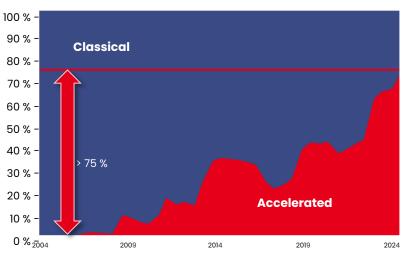




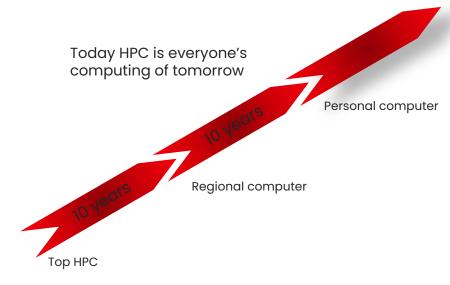


Context

- HPC is a tool in a wide range of domains, source of competitivity
 - At CEA, we host machines
 - To take part in the French & European HPC ecosystem
- We just entered the Exascale era, that means GPU
 - European pre-Exascale systems: Mix of AMD & Nvidia
 - First Exascale machines planned in Europe for 2024/2025
 - Jupiter machine at Jülich (Germany) => Nvidia & Rhea
 - Alice Recogue machine at CEA/TGCC (open call)
 - Need to adapt or re-develop applications with Performance portability
- GPU programming models: software catalysts
 - France and Europe had great research but no production tool
- A need for a long-term sustainable solution
 - Adapted to our hardware and software specificities
 - Trust in the roadmap

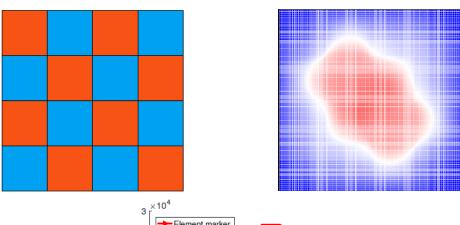


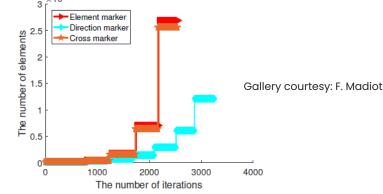
Computing power of the 500 top supercomputers from june 2004 to june 2024 (source Top500)



High-fidelity simulations

- Distinguish between particle-based vs. mesh-based approaches
 - e.g. Monte Carlo and deterministic methods for neutronics
- For instance, starting point for Monte Carlo is a CAD-like geometry model. This model is meshed for the meshclass family of methods
- Pre-processing: meshes
- Online stage:
 - Numerical schemes set up for nuclear reactor simulation
 - High-order methods
 - Adaptive methods (AMR)
 -
 - Numerical strategies for solving the problem
- Post-processing: Error estimates
- Computer science: algorithms and parallel programming models

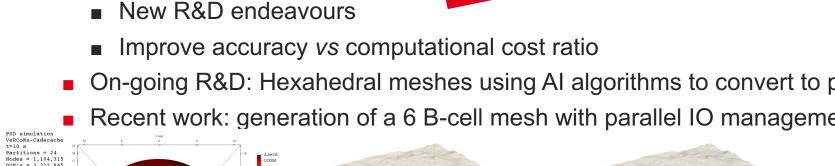


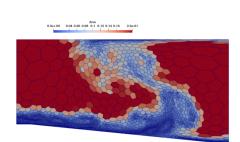


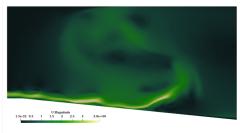
Overview of some codes

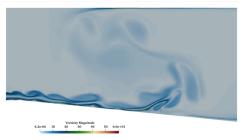
Meshes: towards more complex elements

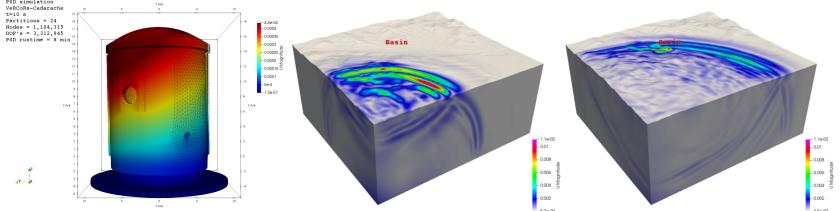
- Meshes: first part of the model (except particle-based methods, *cf.* previous slide)
- Mesh tool within the SALOME environment
 - Co-developed with EDF
 - SMESH: usual simplices
- Polygonal/polyhedral meshes
- On-going R&D: Hexahedral meshes using Al algorithms to convert to polycubes
- Recent work: generation of a 6 B-cell mesh with parallel IO management (SNA + MC 2024)

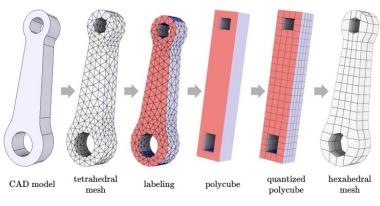










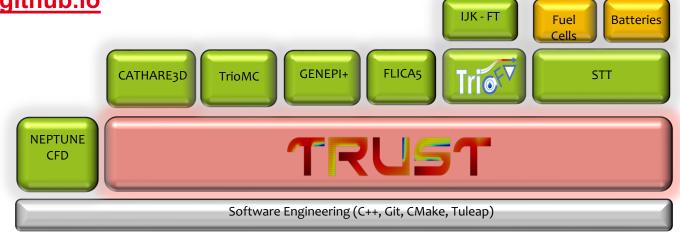




TRUST: a brief overview



- TRUST: HPC thermalhydraulic platform for multiphase problems
 - More than 20 years of development
 - Born out of the splitting of Trio_U into TRUST and TrioCFD
 - Opensource: https://cea-trust-platform.github.io
 - Initially, incompressible Navier-Stokes
 - Now multiphase and compressible
 - Laminar/Turbulent flow
 - Spatial discretisations: VDF, VEF, MAC, PolyMAC

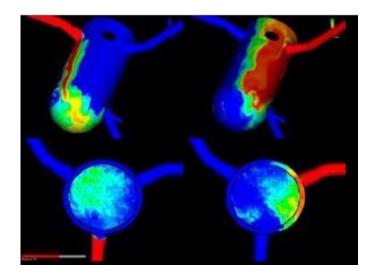


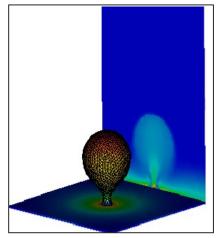
- Several applications are developed on the TRUST platform
 - Derived physics application using TRUST as a core building block

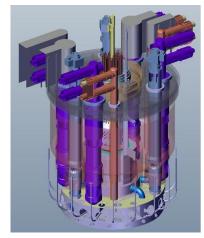


Numerical and physical models of TRUST

- Front-tracking model:
 - Eulerian mesh where incompressible Navier-Stokes equations are solved
 - Lagrangian moving mesh for the interface location
 - Coalescence or breakup models for bubbles and drops
- Multiphase flow simulation
 - Arbitrary number of phases
 - Source terms and operators for phase coupling
 - Dedicated numerical schemes for resolution
- Examples of performed simulations
 - Academic case studies
 - Plane channel with conduction coupling at the wall
 - Flow around an obstacle
 - Pipe flow
 - Isotropic turbulence...
 - Industrial case studies
 - Various studies about the core of a reactor
 - Thermal stress in a T-shaped mixing pipe
 - Natural convection in a storage room of waste
 - Atmospheric dispersion (pollution or radio-nuclides) ...









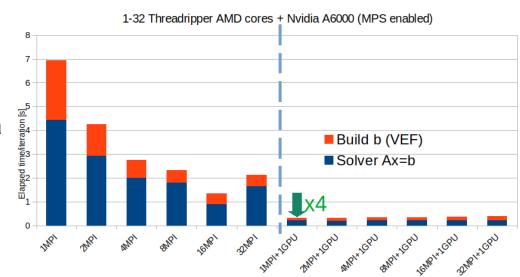
Porting TRUST to GPU



- Computational efforts for models are levelled by HPC cutting-edge technologies (hardware: ex Adastra) and techniques (algorithms, adapted numerical schemes)
 - On-going GPU-porting with OpenMP and Kokkos programming models
 - Promising performance gains from workstation to supercomputer
 - Running a first module (incompressible laminar flow) on a mesh with 1 billion cells, accelerated by 512 Nvidia V100 (JeanZay, IDRIS) or 1024 AMD MI100 (Adastra, CINES)







Poiseuille 3D simulation with TRUST 1.9.2 (Tetra mesh 2.6 MDOF)

Gallery courtesy: P. Ledac

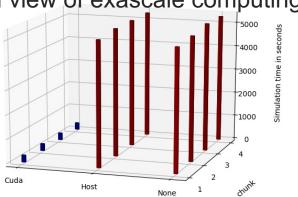
Advanced neutron transport (Monte Carlo)

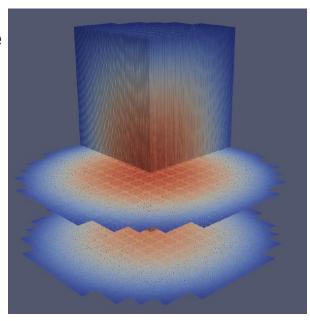
arlo)

- Monte Carlo: embarrasingly parallel
 - TRIPOLI-4 developed at CEA
- PATMOS
 - Prototype for testing new programming paradigms for Monte Carlo in particle
 - Developed at SERMA
 - Led to the seeding of the Tripoli-5 project supported by EDF and co-developed with IRSN
 - Very efficient scaling on the Hoogenboom-Martin (PWR) benchmark
 - On-the-fly Doppler broadening (to account for feedback with thermalhydraulics)

On-going GPU-porting of Monte Carlo algorithm in view of exascale computing

Testing of several programming models: Cuda, OpenACC, OpenMP offloading, Kokkos





Coupling of PATMOS and THEDI (1D thermalhydraulics): power distribution

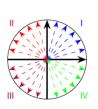
Gallery courtesy: TRIPOLI-5 team

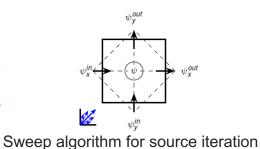
Advanced neutron transport (deterministic)



Power distribution Takeda 4 benchmark

Deterministic neutron transport: APOLLO3® code for industrial schemes







HPC

- Vectorisation of sweep kernel with Kokkos
- Porting to GPU: not just simple rewriting but re-conceiving the sweep algorithm
- Numerical schemes
 - High-order DGFEM* on structured meshes (improvement of *dofs* vs time)
 - Towards one-step: PhD works on dynamic homogenisation and coupled **IDT-TH** computation

Performance tests and results: AVX

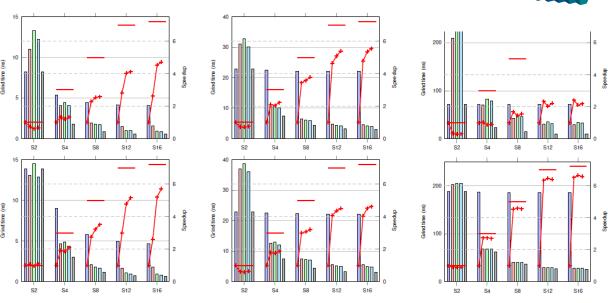


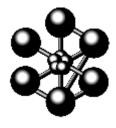
Figure 3 – GCC (up) and Clang (down) using AVX. Left to right: $\mathcal{DD}0$, $\mathcal{DD}1$, $\mathcal{DD}2$. Bars: grind-time (left to right: Scalar, A, B, C, Ideal). "+": measured speedup. "-": ideal speedup.

From Europlexus/CAST3M to MANTA





- Europlexus: Explicit dynamics for structures and compressible fluids
- Fluid / structure interactions
- Industrial applications
- Finite-elements, finite-volumes, sph, discrete element method
- ~40 years of development



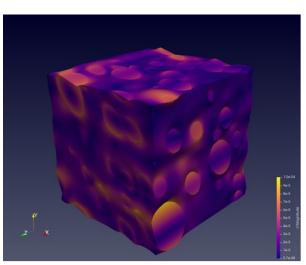
- CAST3M: Generic tool for "implicit problems"
- Mainly geared for (non-linear) mechanics
- ... but also applied to incompressible fluids, electromagnetism, metallurgy, ...
- Industrial applications
- Finite-elements
- ~40 years of development



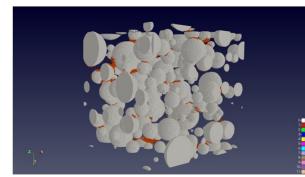
- Mechanical Analysis Numerical Toolbox for advanced
 Applications
- Next gen., HPC oriented
- Both implicit and explicit problems
- Structure / compressible fluids / ... , interactions
- Industrial applications
- Every mesh-based method (FE, FV, HDG, ...)
- C++
- "automatic parallelism"
- Easy to maintain and evolve on the long term
- Open-source

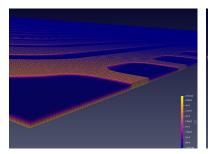
MANTA: current status

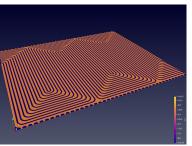
- On-going development at CEA with contribution from EDF
- Collaboration between software and mechanical research engineers
 - Support: I/O med, mesh partitioning, parallel solvers, ...
 - Management for checkpoint/restart
 - Performance portability: hybrid parallelisation techniques (MPI+X) CPU, then GPU

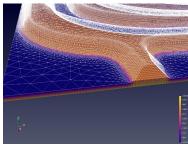


- REV simulation
- 2-phase: elastic inclusions and elasto-plastic matrix
- Contrast: 100
- Periodic boundary conditions
- 400x10e6 dofs
- 16384 MPI subdomains
- Implicit calculation









Shaping test for a fuel cell plate

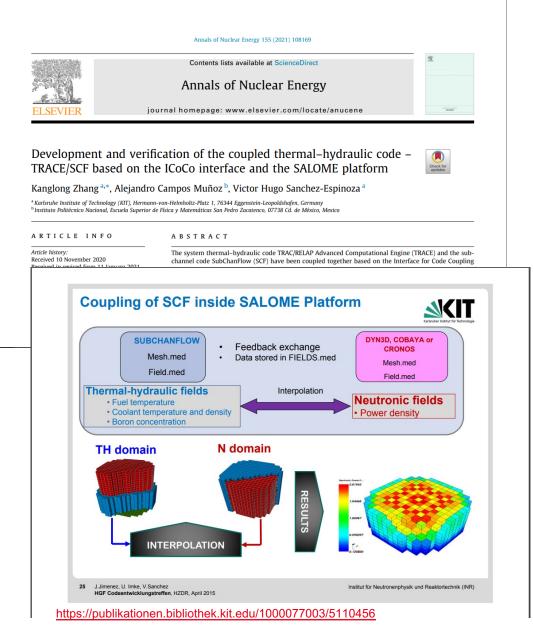
Gallery courtesy: O. Jamond

One to bind them all

 Physical systems require multiphysics modelling

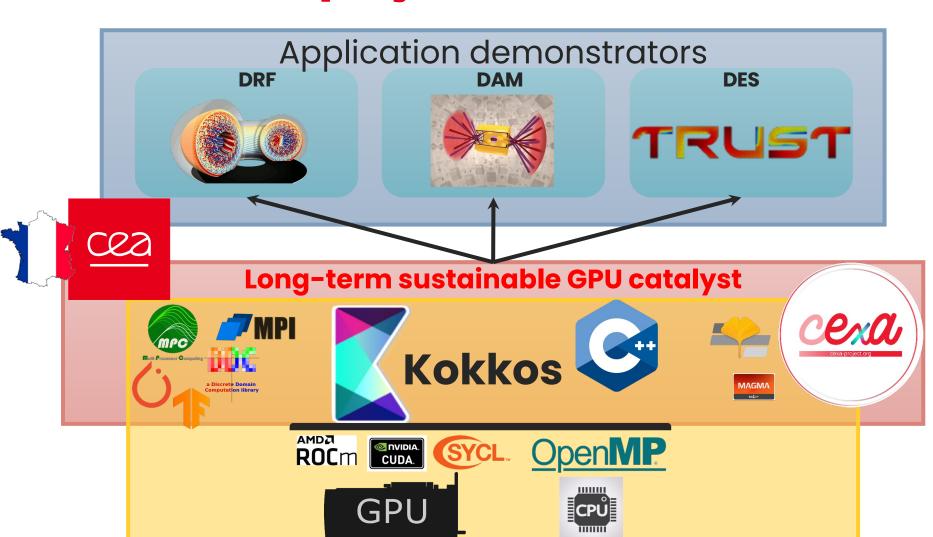


- Partitioned coupling approach
 - Few monolithic code with intricate coupling of all physics (e.g. SIMMER)
 - Simpler maintainance
- Code coupling: ICoCo + MEDCoupling (SALOME)
 - ICoCo = Interface for Code Coupling
 - MEDCoupling = Library with remapping options for quantities defined as fields (scalars/vectors on a mesh)
 - C3PO open-source python library (https://github.com/code-coupling/c3po)
 - Provides algorithms and accelerations for coupling
- NumPEx (ExaMA WP3) project on code coupling for exascale



Performance portability

The CExA project



HPC ecosystem



Adapt application demonstrators

Provide a longterm sustainable software catalyst for GPU computing

Available solutions



- Cuda
- HIP
- Kokkos
- OpenACC
- OpenMP (target)
- Raja
- SYCL
 - OneAPI/DPC++
 - AdaptiveC++/OpenSYCL/hipSYCL

- Production grade, with public support
- Vendor neutral
- Annotations
 - Works best with imperative languages: C,Fortran, ...
 - Compiler integration: potential for additional optimizations
 - Requires to re-design applications for GPU

Library

- Suited to language with deep encapsulation: C++, ...
- On top of vendor backends: easier to port to new hardware
- Requires to re-write applications for GPU

OpenMP & Kokkos: the simplest GPU loop



```
for (int j = 0 ; j < Nj ; ++j) {
    // [...]
}</pre>
```



Sequential



OpenMP Target

Kokkos

Execute in parallel, on a separate GPU thread each,

the same workload /.../

identified by a unique identifier j

Njtimes between 0 and Nj-1

OpenMP & Kokkos: memory transfer



```
double* x = malloc(Ni*sizeof(double));
double* y = malloc(Nj*sizeof(double));
double* A = omp_target_alloc(
    Ni*Nj*sizeof(double),
    omp_get_initial_device());
#pragma omp target data \
    map(to: x[0:Ni]) \setminus
    map(from: y[0:Nj])
#pragma omp teams distribute parallel for
for (int j = 0 ; j < Nj ; ++j) {
         for (int i = 0; i < Ni; ++i) {
                  y[j] += x[i] * A[j*Ni+i];
```

```
View<double*, Kokkos::HostSpace> x(Ni);
View<double*, Kokkos::HostSpace> y(Nj);
View<double*> A(Nj, Ni);
auto dx = create_mirror_view_and_copy(dev, x);
auto dy = create_mirror_view(dev, y);
parallel_for(Nj, KOKKOS_LAMBDA(int j) {
          for (int i = 0; i < Ni; ++i) {
          dy(\mathbf{j}) += dx(\mathbf{i}) * A(\mathbf{j},\mathbf{i});
});
deep_copy(y, dy);
```

OpenMP Target

Kokkos

Copy x to GPU from device before kernel and y from GPU to device after kernel Keep A on the device



What's in Kokkos



Multi-dimensional arrays

Layout auto change for performance

Other containers

Key-value maps, ...

Automatic ref-counted Host/Device memory allocation & management

Host/device memory transfers

Support of "dual" arrays with one version on each side

 Up-to-date tracking & automatic transfers when required

Scratch memory

Using "core-local" fast memory on the device

- Parallel patterns w. asynchronous support
 - o Independent interactions, Reductions, Scans
- Iteration strategies
 - Tiled, Hierarchical, ...
- Algorithms
 - Sorting
 - Random number generation
 - Most of STL parallel algorithms
 - 0 ...
- QoL features: portable printf, etc.
- Portable atomic operations
- SIMD
- Coarse & fine-grain tasks
- And much more...

Kokkos an anteroom for standard C++



C++ is (at last) standardizing base tools for HPC

- Parallel programming is slowly entering the ISO C++ language
 - Parallel algorithms, sender/receivers, etc.
- The Kokkos team leads the standardization of many required features
 - Multi-D arrays (std::mdspan)
 - Vectorization (std::simd)
 - Linear algebra (std::linalg)
 - And much more to come (mixed precision, etc.)

Kokkos offers a stable API today for the features of the C++ of tomorrow

- Standardization is slow (9 years for mdspan)
 - Consensus with all communities
- Kokkos offers the features today
 - And will keep maintaining the API on top of standardized ISO C++
 - With added interoperability layers (Cf. kokkos::view / std::mdspan)
 - And in a GPU-compatible implementation (Cf. kokkos::array)





HIGH PERFORMANCE SOFTWARE FOUNDATION

Members

Premier

HPSF Goals

- Provide neutral home for key HPC projects to enable collaboration between government, industry and academia
- Promote use of HPSF projects
- Ensure that HPC software is accessible and reliable by providing CI and turn-key builds
- Ensure that HPC software is secure and ready for cloud through collaborations with CNCF and OpenSSF
- Sponsor events and training to grow a diverse, skilled workforce for software in the HPSF ecosystem.









General

















Associate









NumPEx



 French project to co-design the exascale software stack and prepare applications to exascale era





- Funded by PEPR (Programme et Equipements Prioritaires de Recherche)
 - Exascale Computing Project (USA): co-design centres, software stack
- Partners: CEA, CNRS, INRIA, Universities,...

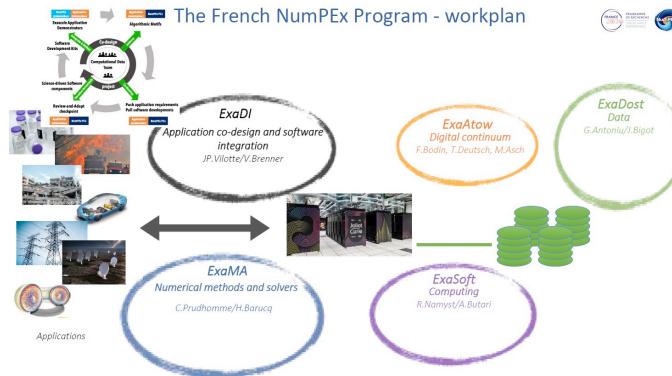
Some Exascale/post-Exascale challenges











4 Concluding remarks

Concluding remarks

- Code development/maintainance is a tedious and everlasting process
 - Essential as numerical and physical models are safeguarded within code systems (decades)
 - Accounting for all constraints to deliver industrial-grade material (results, software and methods)

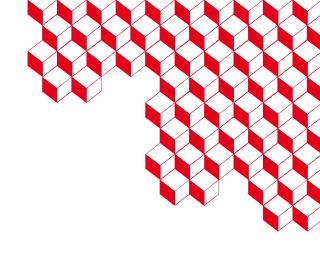
GPU porting: still a challenge but necessary for exascale computation, requires the design and

implementation of new algorithms

- Forthcoming short-term challenges
 - Floating-point arithmetics to explore intensive verification and numerical quality of codes and improve algorithms with mixed precision
 - More Al/ML to explore: promising to bridge the gaps on models
- How to adapt the codes to forthcoming hardware? Is it possible to win the rat race?
 - Quantum Computing: 2nd quantum revolution on the march, assess the relevance for our problems (linear algebra, iterative solvers), theoretical transition from the usual algorithms







Thanks for listening

Figures/Plots/Graphs – courtesy of DM2S and CExA team

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Compilation



OpenMP Target

- Use an OpenMP compiler
 - Compatible with the target construct
 - Compatible with the hardware you target
- Each vendor provides its own OpenMP compiler
 - Usually based on LLVM infra
- Default Clang/LLVM & GCC also try to support this
 - For some hardware

Kokkos

- A C++ template library
 - No direct code generation, rely on vendors C++-like languages
- Multiple "backends", selection at compile time
 - OpenMP, Cuda, OneAPI, HIP, ...
- Maximum 3 backends enabled at once
 - Serial backend
 - 1 Host parallel backend (openmp)
 - 1 Device parallel backend (cuda, HIP, Sycl)

References



[1] "Numerical modeling of a moderate hydrogen leakage in a typical two-vented fuel cell configuration", E. Saikali, P. Ledac *et. al.*, International Conference on Hydrogen Safety, September 2021

[2] SALOME: https://www.salome-platform.org/?lang=en

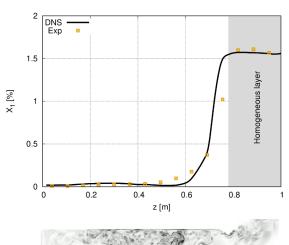
[3] TRUST: code https://github.com/cea-trust-platform; website https://cea-trust-platform.github.io/

[4] "PATMOS: A prototype Monte Carlo transport code to test high performance architectures", E. Brun, S. Chauveau, F. Malvagi, M&C 2017, April 2017

[5] "High-order Wachspress functions on convex polygons through computer algebra", D. Labeurthre, A. Calloo, R. Le Tellier, Journal of Computational Physics, 2022

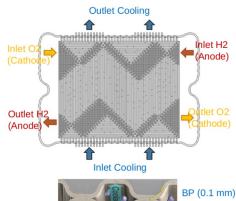
High-fidelity simulations for new systems

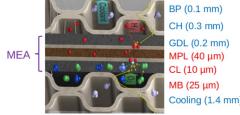
- GAMELAN (moderate hydrogen leakage) 2 billion mesh cells, 50 000 cores [1]
- PEMFC and batteries complex geometries

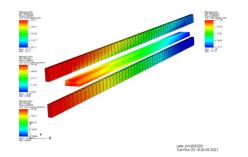




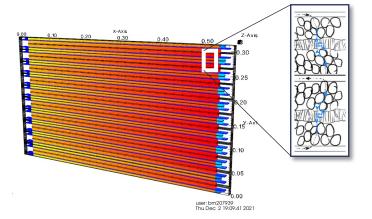
GAMELAN: reference results by CEA

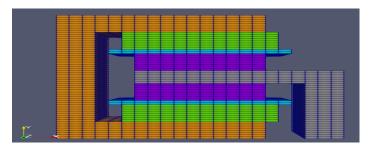






Battery simulation





MEDCoupling representation of PEMFC