

Error mitigation and circuit division for early fault-tolerant quantum phase estimation

Alicja Dutkiewicz, Stefano Polla, Maximilian Scheurer,
Christian Gogolin, William J. Huggins, Thomas E. O'Brien

PRX Quantum **6**, 040318

AQAM, Montpellier

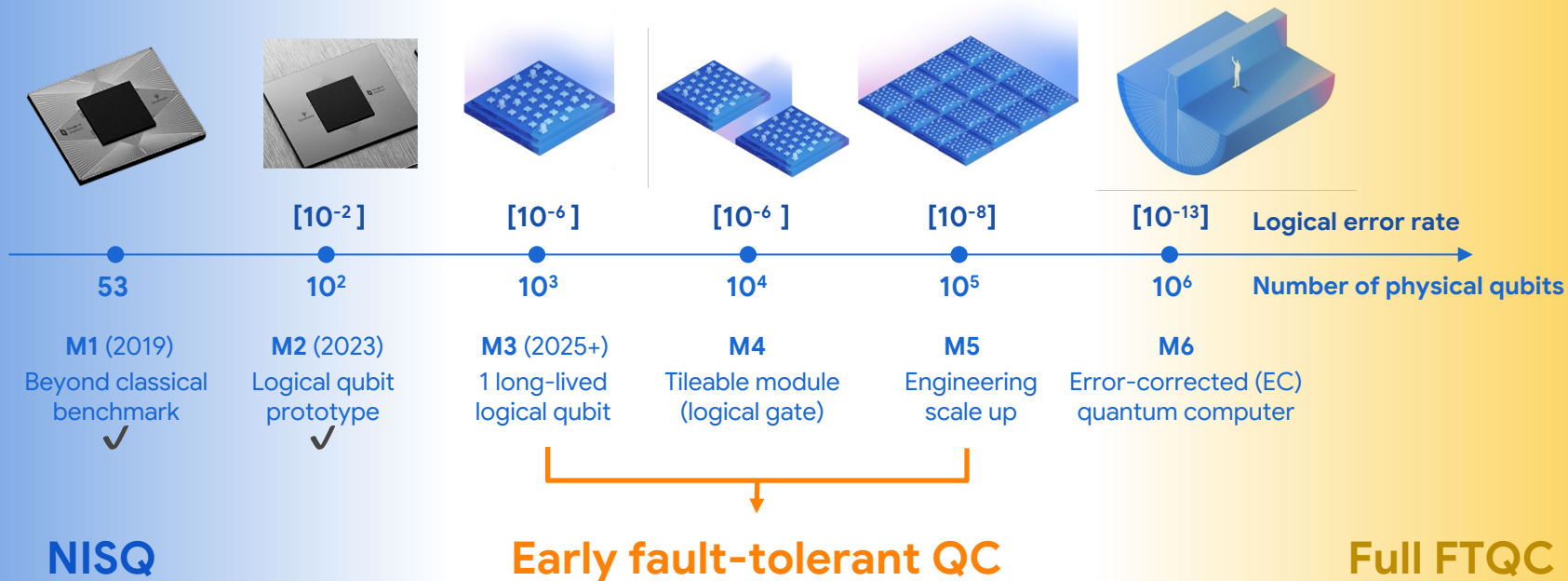


Universiteit
Leiden
The Netherlands



Google AI
Quantum



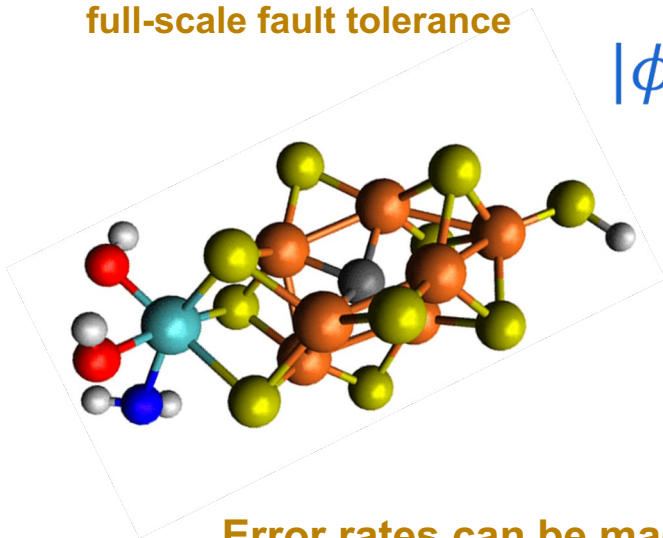


*The era when we can **correct all but $\Omega(1)$ errors**,
and must design algorithms to be robust to the remainder*

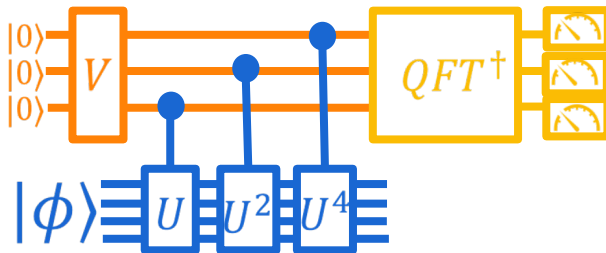
See also: Campbell '22, Wang et al '22,
Wan et al '22, Dong et al '22, Lin, Tong
'22, Katabarwa et al '23, Wang et al '23,
Ding, Lin '23, Kshirsagar et al '24,
Nelson, Baczewski '24, ...

QPE benchmarks

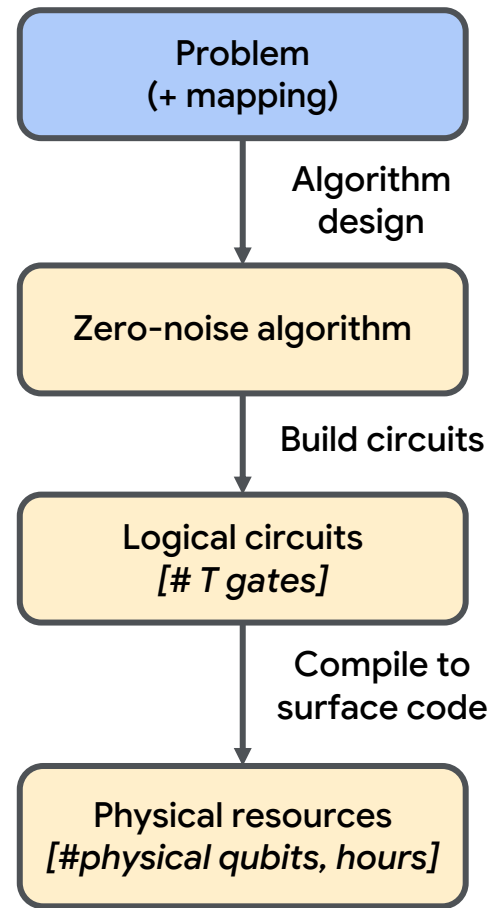
Most QPE benchmarks
assume
full-scale fault tolerance



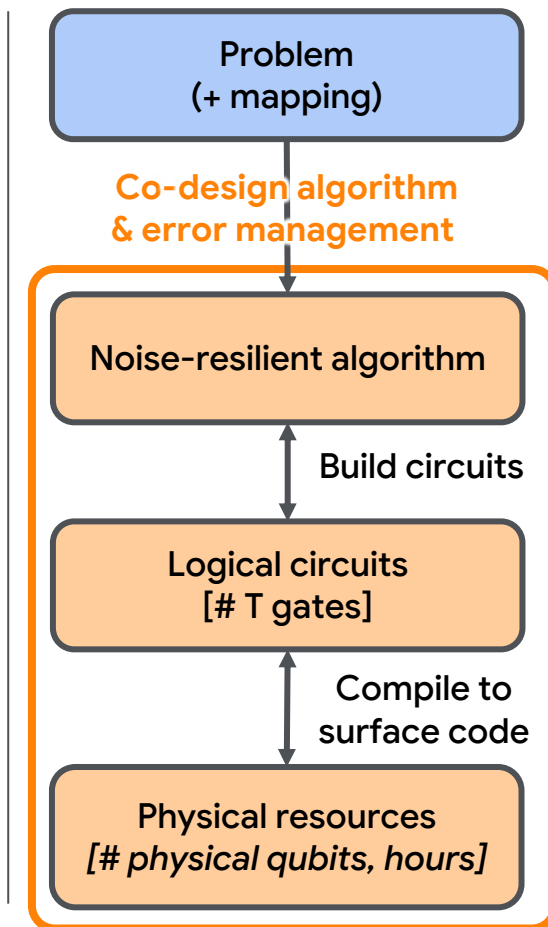
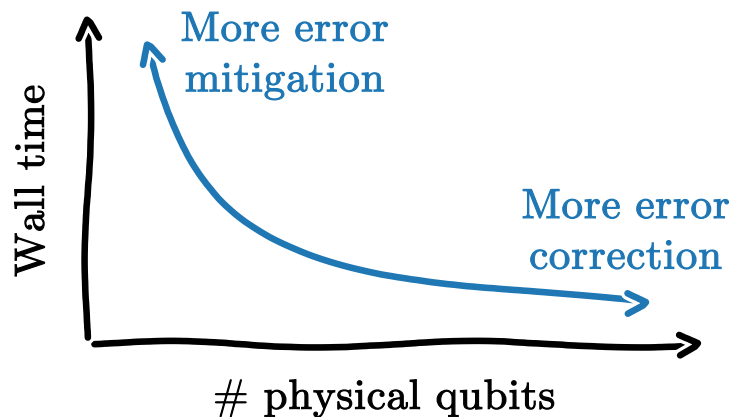
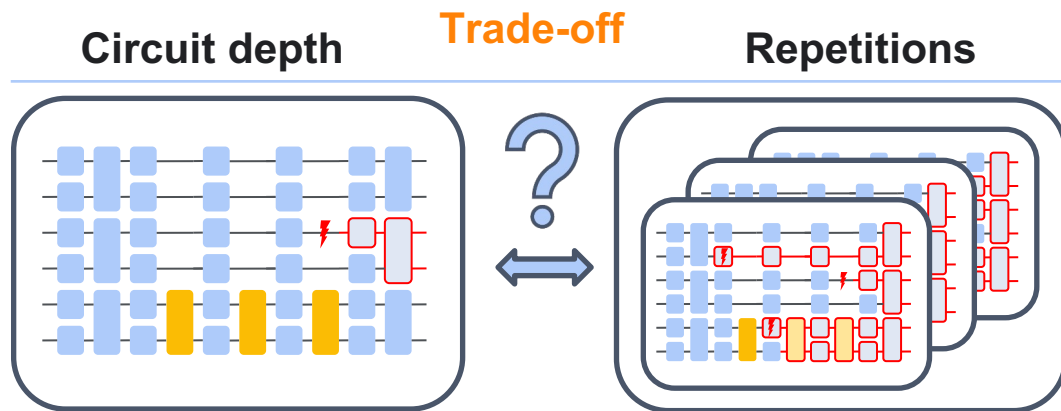
**Error rates can be made arbitrarily small
through error correction.**



Reiher *et al.* [PNAS 114, 2017]
Babbush *et al.* [PRX 8, 2018]
Von Burg *et al.* [PRR 3, 2021]
Lee *et al.* [PRQ 2, 2021]



Circuit division

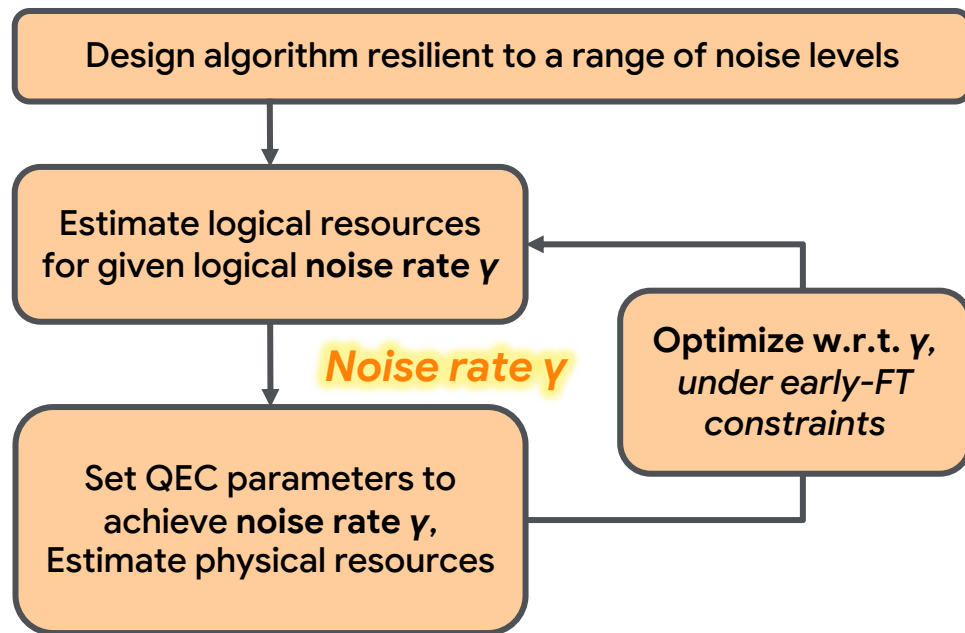
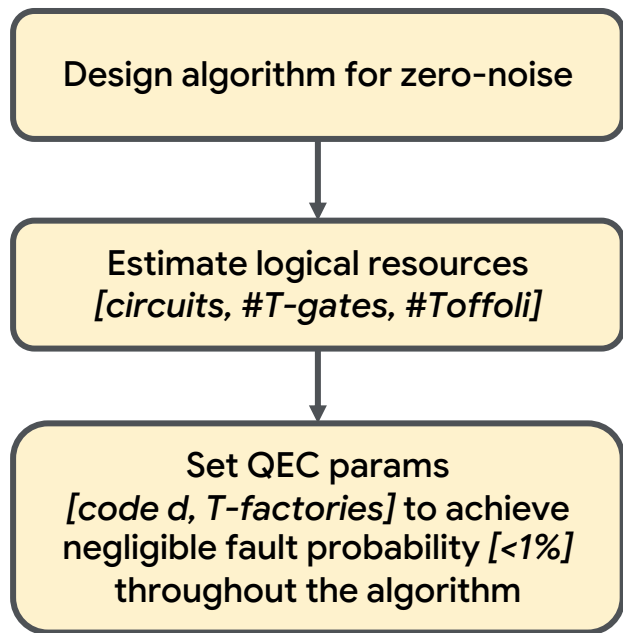


Algorithm design principles in FT

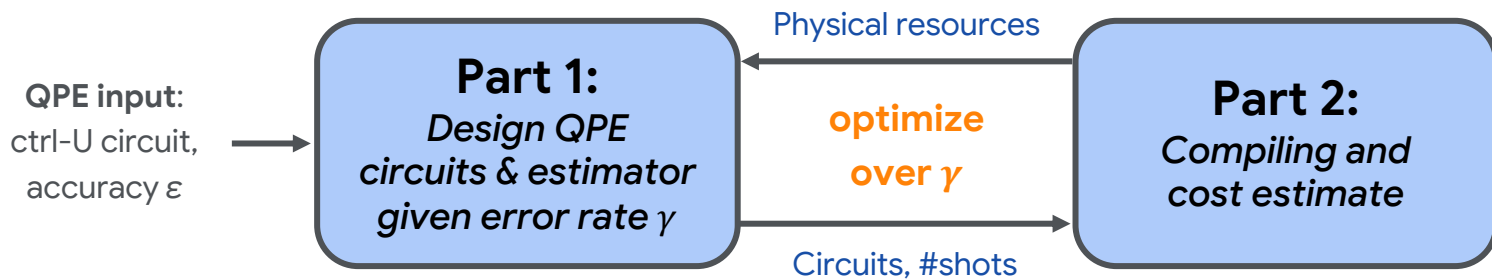
Full FTQC

vs

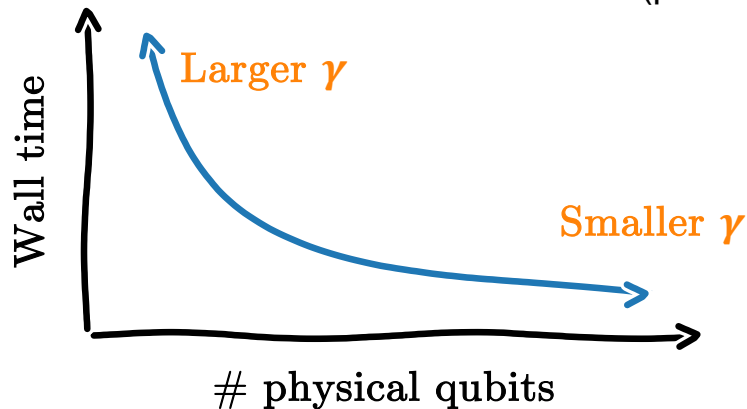
Early FTQC



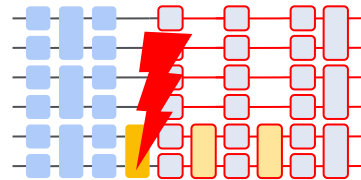
Structure of the talk



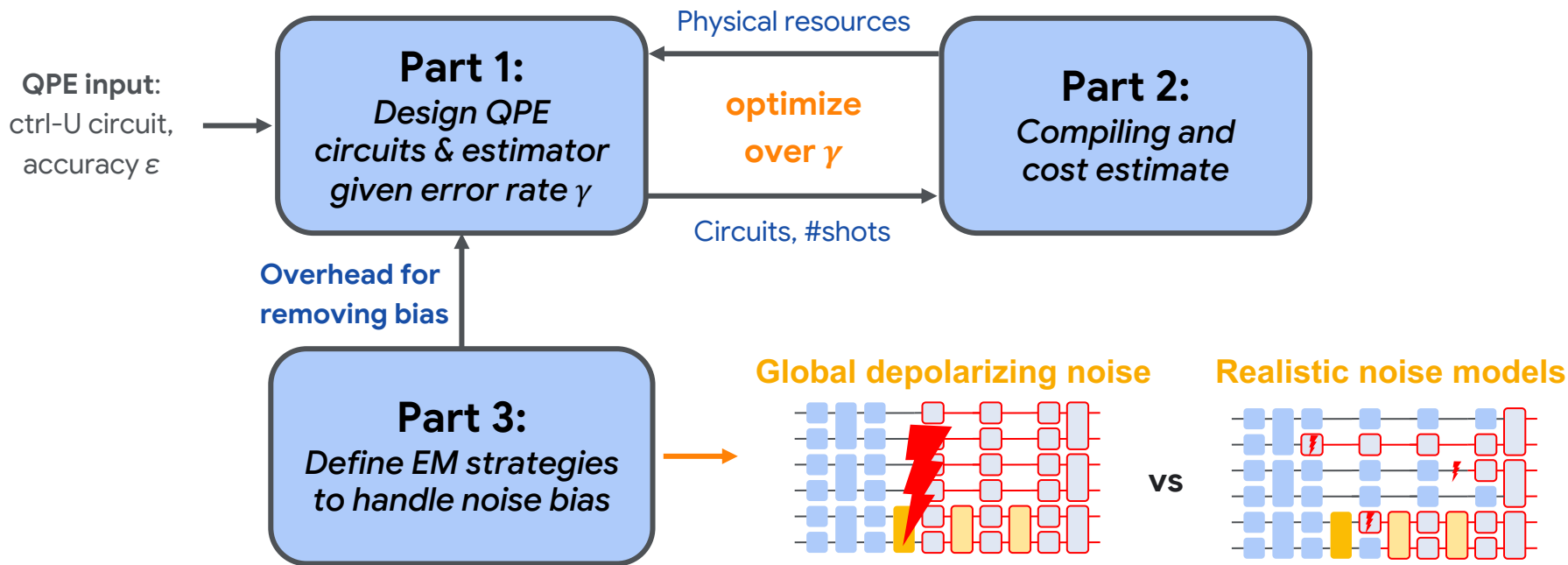
γ – Logical error rate
(per ctrl-U)



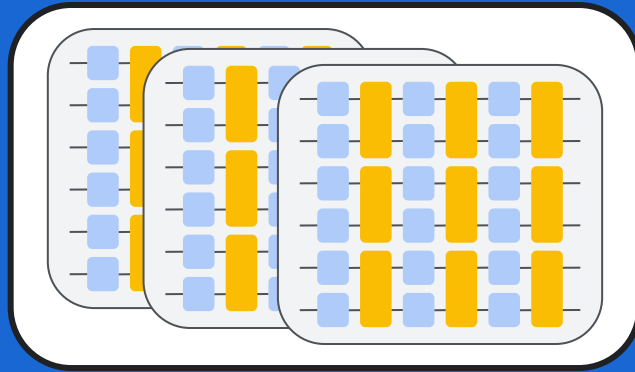
Global depolarizing noise



Structure of the talk

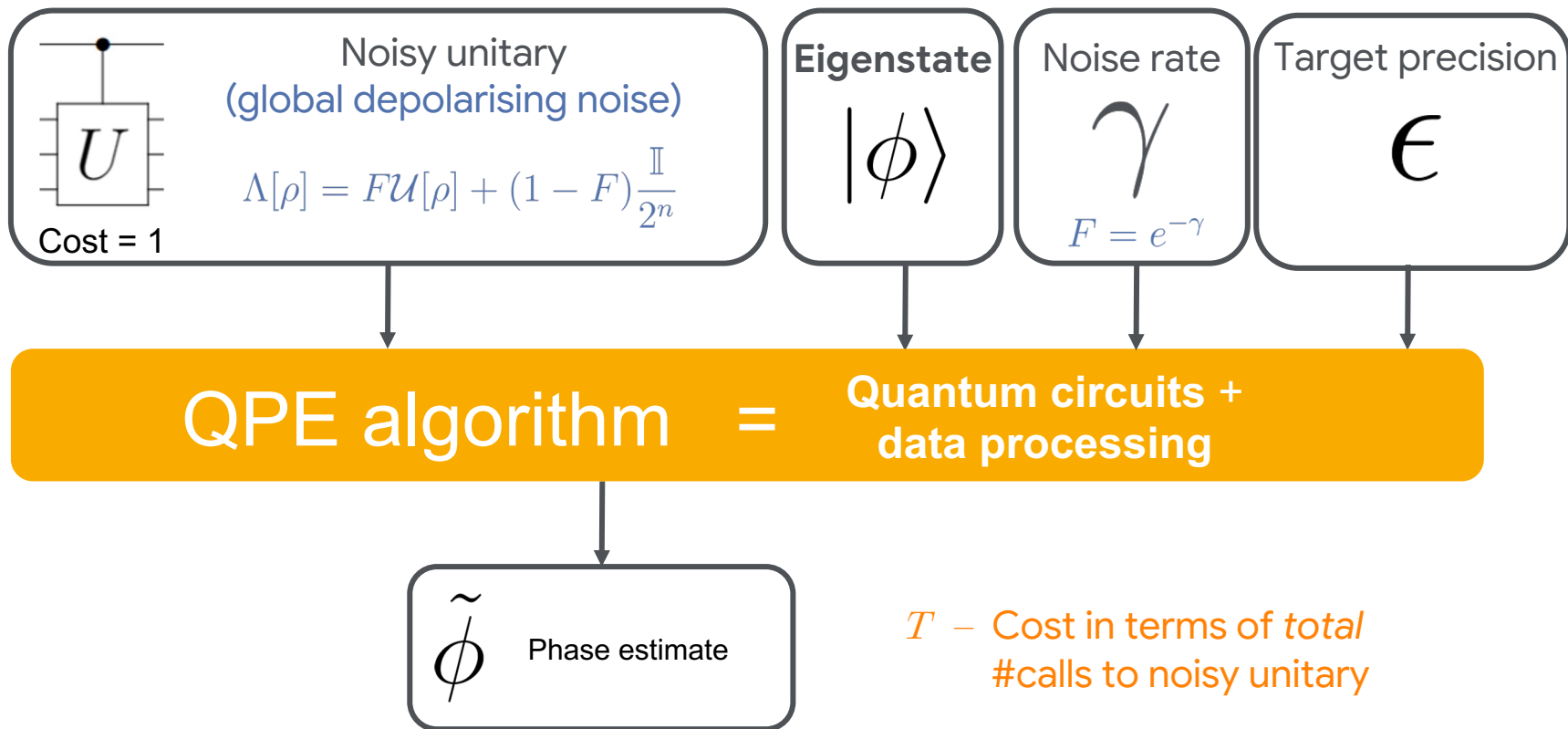


Quantum Phase Estimation with noise (global depolarizing noise)



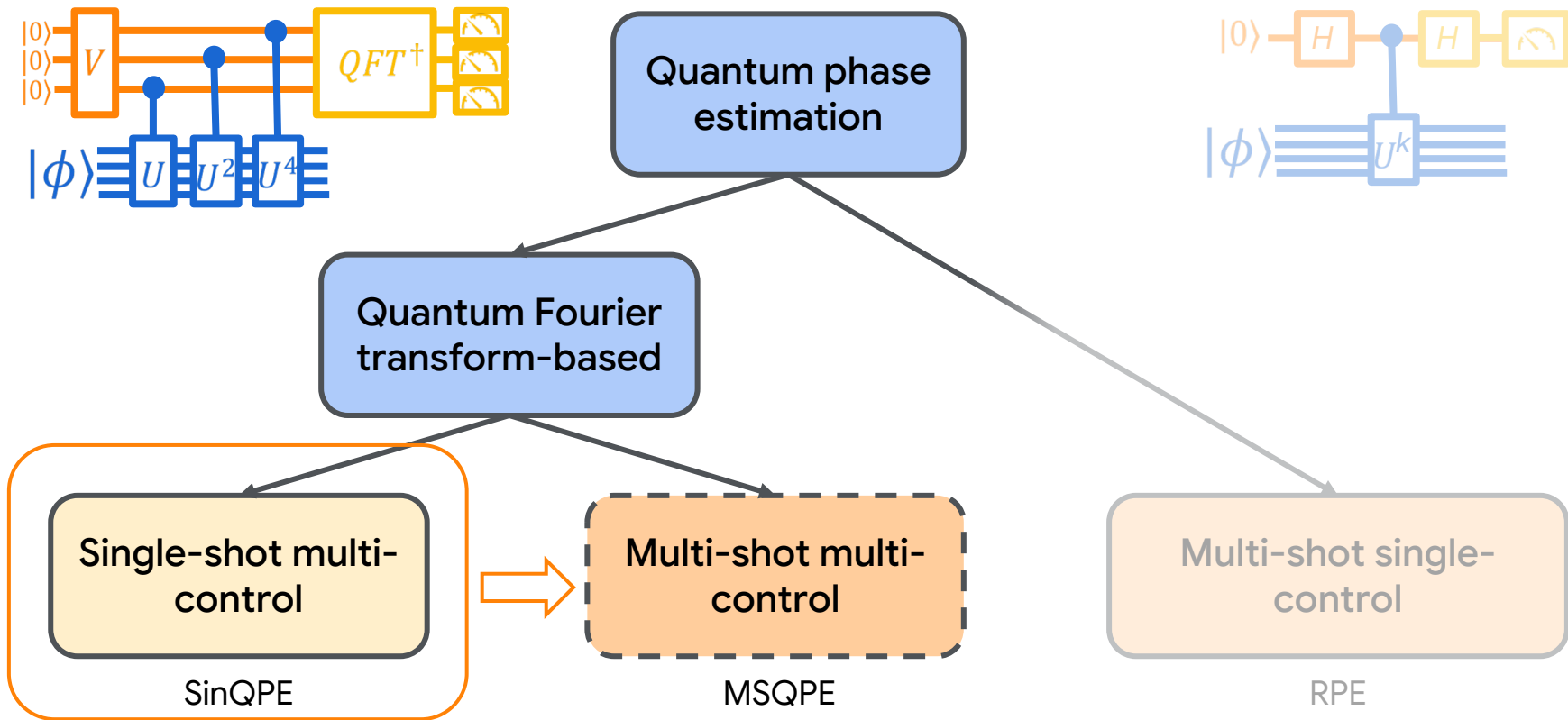
Quantum phase estimation

Part 1: QPE



Types of quantum phase estimation

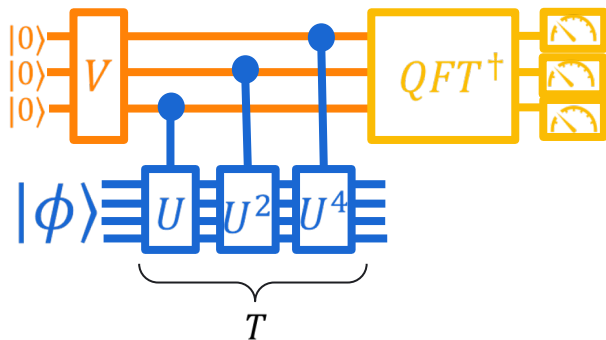
Part 1: QPE



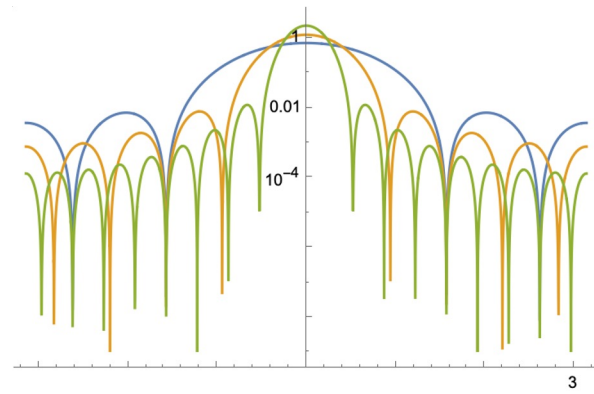
QFT-based quantum phase estimation

Optimal strategy in the absence of noise.

Achieves minimal mean error $\epsilon = \pi/T$ [Luis & Perina, 1996].



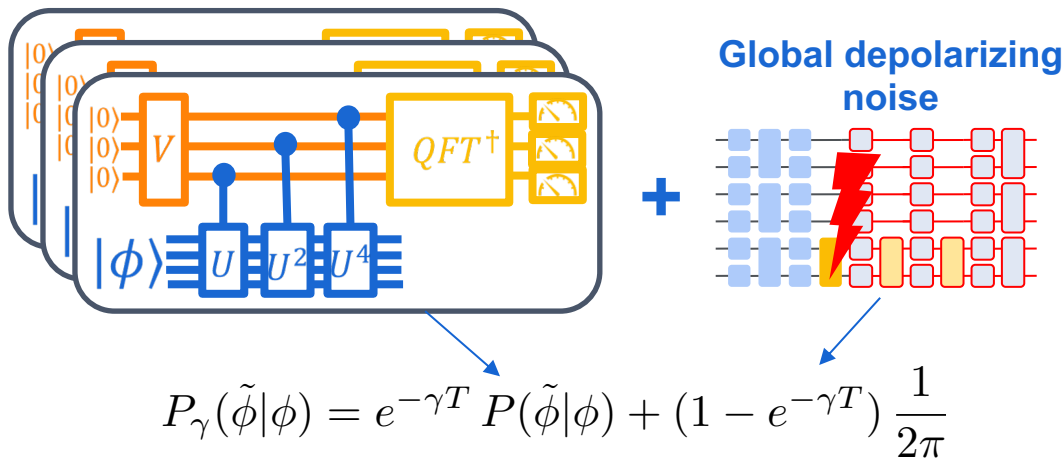
Known
analytical expression
for the
output distribution:



$$P(\tilde{\phi}|\phi) = \frac{\sin^2 \frac{\pi}{T+2}}{(T+1)(T+2)} \frac{1 + \cos((T+2)(\tilde{\phi} - \phi))}{\left(\cos(\tilde{\phi} - \phi) - \cos \frac{\pi}{T+2}\right)^2}$$

Max-likelihood quantum phase estimator

Part 1: QPE



Max-Likelihood estimation

$$\tilde{\phi} = \arg \max \log \mathcal{L}(\tilde{\phi}|\vec{x})$$

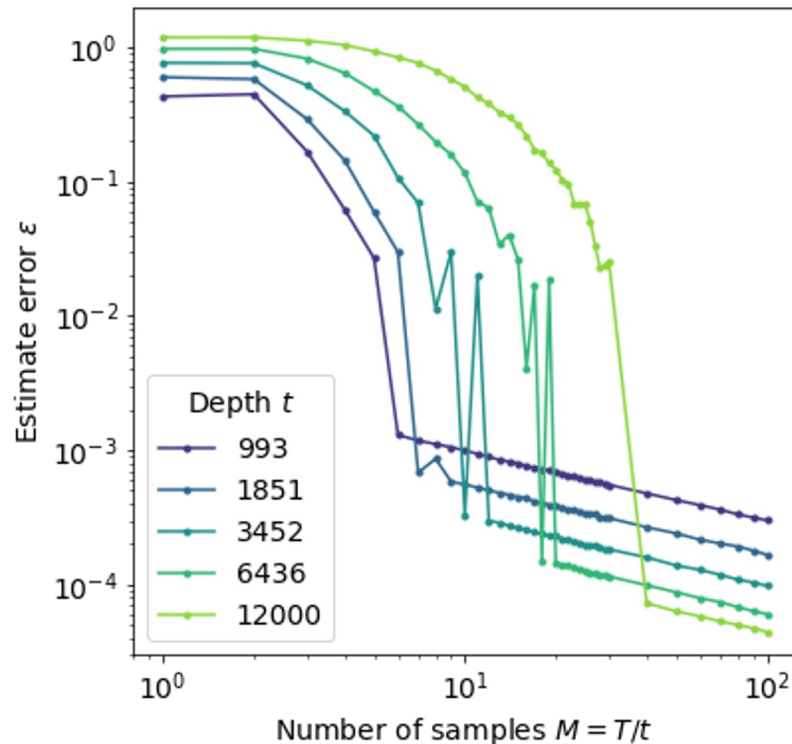
$$\log \mathcal{L}(\tilde{\phi}|\vec{x}) = \sum_{i=1}^M \log P(x_i|\tilde{\phi})$$

Max likelihood estimation

Asymptotically, the Cramer-Rao bound can be saturated using **max-likelihood estimation (MLE)**

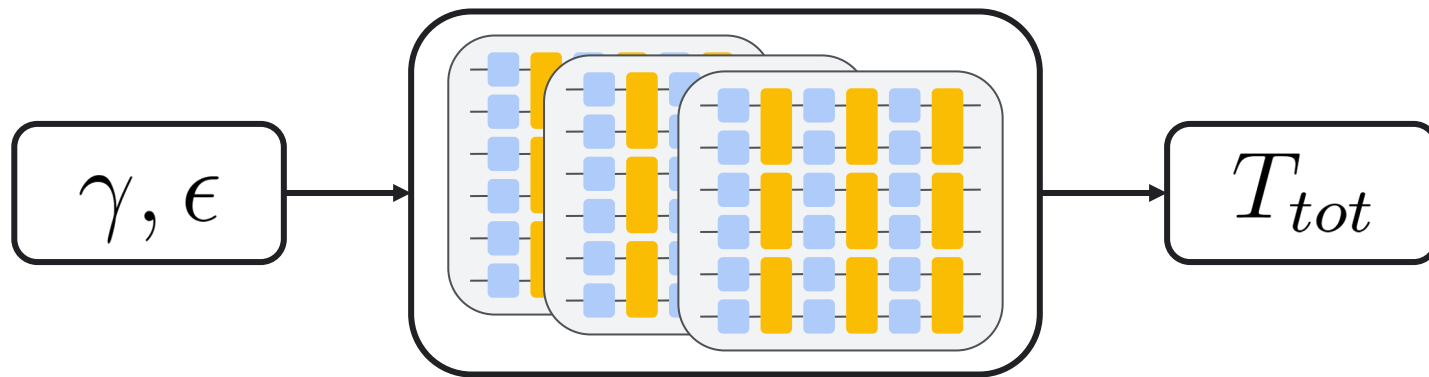
$$\tilde{\phi} = \arg \max \log \mathcal{L}(\tilde{\phi} | \vec{x})$$
$$\log \mathcal{L}(\tilde{\phi} | \vec{x}) = \sum_{i=1}^M \log P(x_i | \tilde{\phi})$$

However, with a **finite number of samples**, MLE is not guaranteed to converge.



Max-likelihood estimation (MLE)

Part 1: QPE



3 regimes:

Total cost:

Low noise	$\gamma \ll \epsilon$	Single circuit (like noiseless)	$\pi \epsilon^{-1}$
High precision	$\gamma \gg \epsilon$	Fixed depth (max Fisher Info)	$\approx 20 \gamma \epsilon^{-2}$
Intermediate	$\epsilon \sim \gamma$	Interpolate (empirical law, numerical validation)	

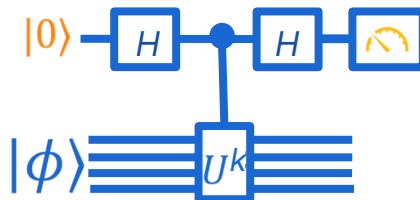
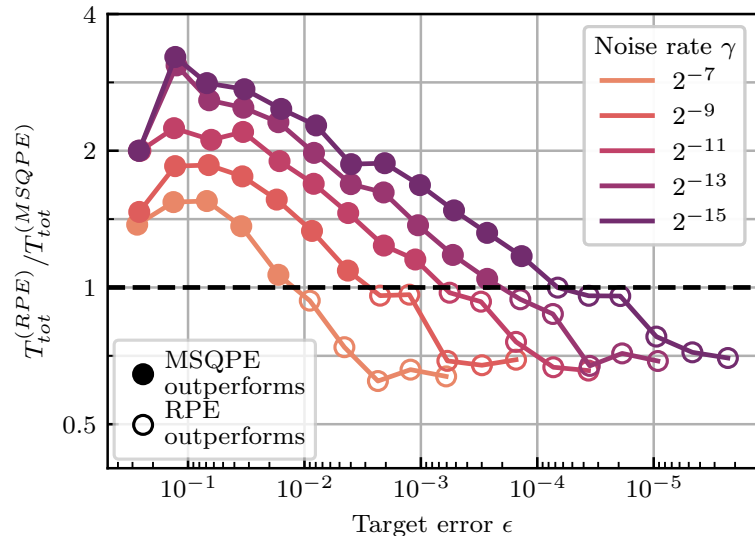
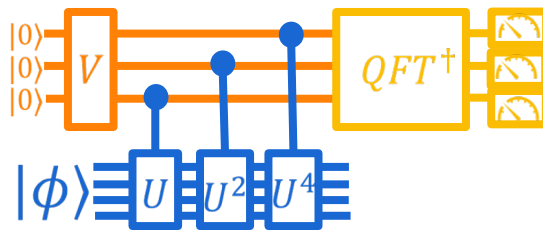
Summary MSQPE

Part 1: QPE

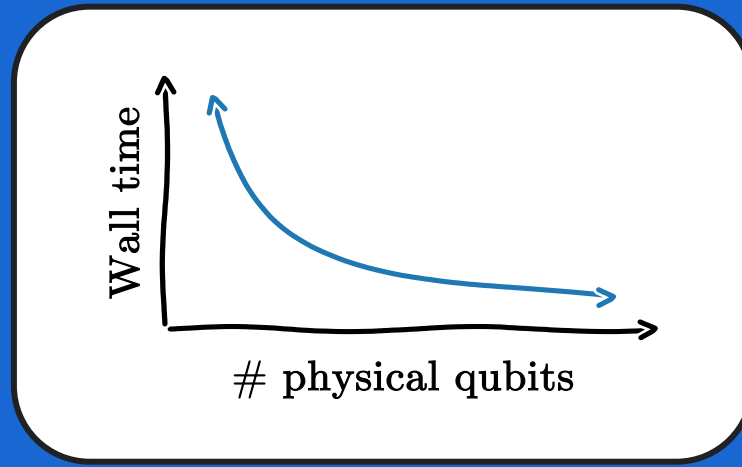
First complete multi-shot QFT-based QPE algorithm.

Optimised total runtime for global depolarising noise.

Advantage over Hadamard-test-based QPE for $\epsilon \sim \gamma$.



2. Compilation and cost estimate



Logical costing using Qualtran

github.com/quantumlib/Qualtran

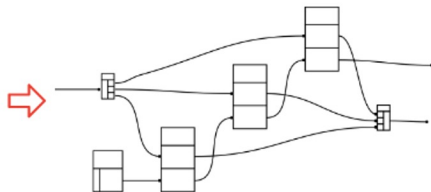
Release paper: arXiv:2409.04643

```
x = bb.add(IntState(val=1, bitsize=self.x_bitsize))
exponent = bb.split(exponent)

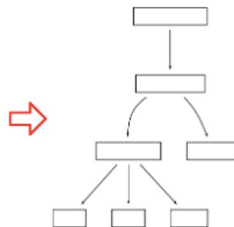
base = self.base
for j in range(self.exp_bitsize - 1, -1, -1):
    exponent[j], x = bb.add(
        CtrlModMul(k=base, ctrl=exponent[j], x=x)
    )
    base = base * base % self.mod

return {
    'exponent': bb.join(exponent),
    'x': x
}
```

Code defines
quantum subroutines



Use compute graph
representation



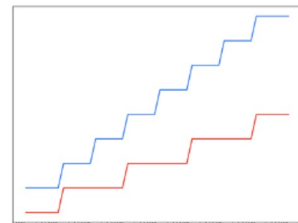
Call on a library of
existing primitives

Simulate and test

Qubit counts

Gate counts

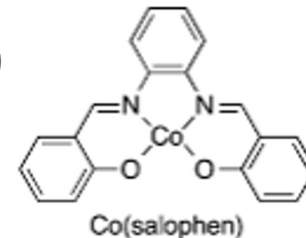
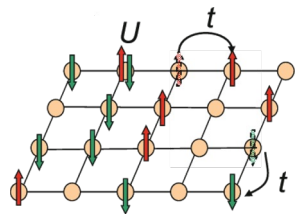
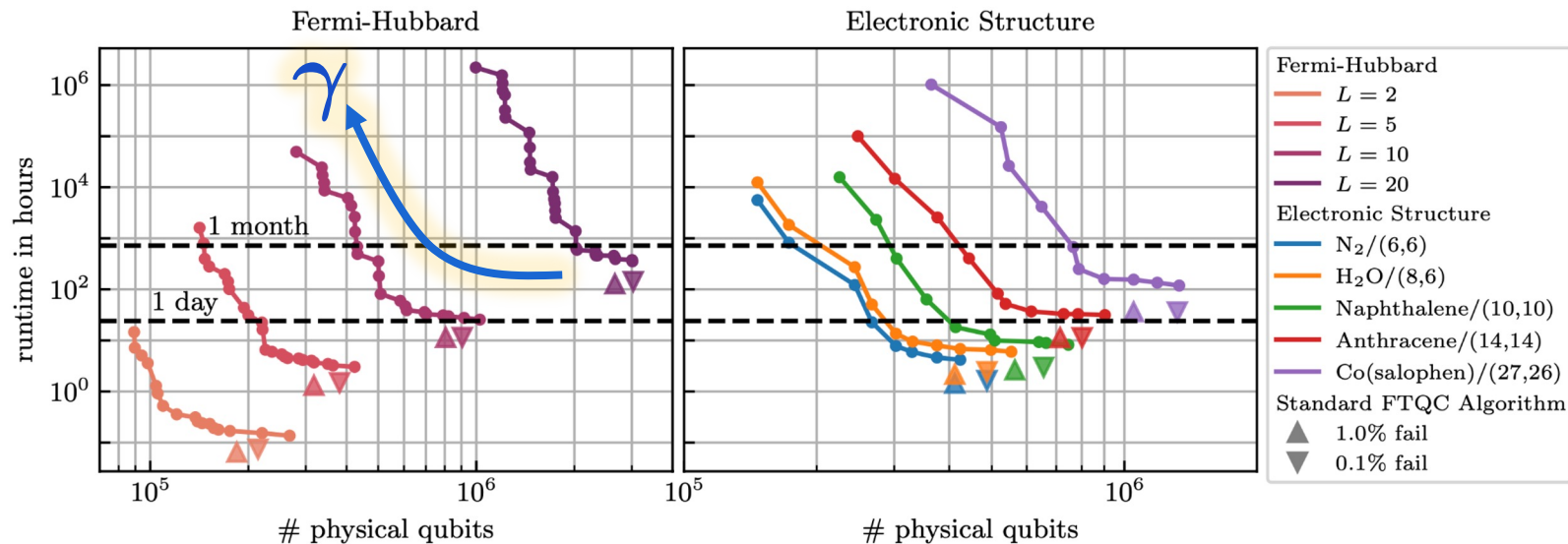
Analyze



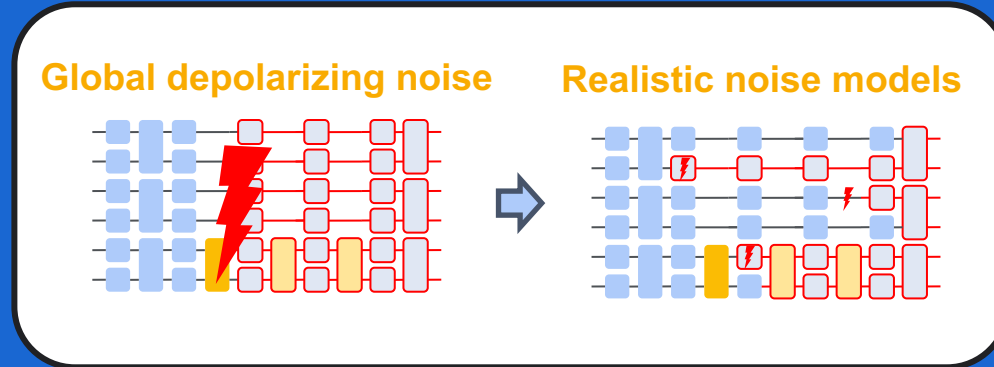
Model physical
costs

```
33 walk = get_walk_operator_for_hubbard_model(x_dim, y_dim, t, mu).controlled(1)
34 complexity = walk.t_complexity()
35
36 ccz_from_rotations = (
37     complexity.rotations * nbits_for_rotations
38 ) # CCZ cost for phase gradient rotations
39 ccz_from_logic = complexity.t / 4 # in this circuit all T gates come from CCZ gates
```

Trade off: physical qubits vs wall time

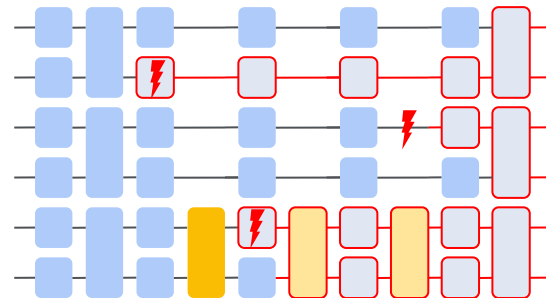


Error mitigation beyond expectation values



Logical noise (in surface code FTQC)

- Sources of logical noise
 - Data errors $\leftarrow$ code distance [+ decoder limit]
 - T-state imperfections $\leftarrow$ T-factory size
- Logical noise model
 - **Local** noise – random Pauli channel



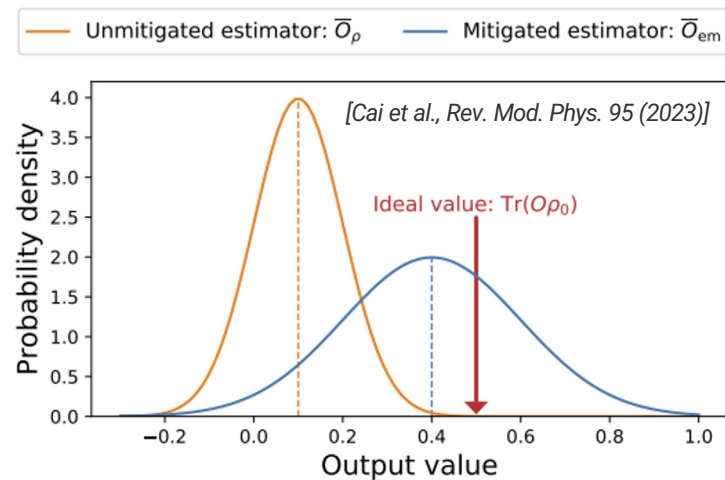
“Local noise biases phase kickback”

e.g. [T. E. O'Brien et al, New J. Phys. **21** (2019)]

Quantum error mitigation

Error mitigation is...

Trading bias for stochastic noise



Postselection	$C_{\text{em}} = \Lambda F^{-1}$	---	Symmetry verification, verified phase estimation*
Rescaling	$C_{\text{em}} = \Lambda F^{-2}$		Echo verification*, direct rescaling under GDN
Explicit unbiasing	$C_{\text{em}} = \Lambda F^{-4}$		Probabilistic error cancellation, virtual distillation

*depending if verification circuit is short

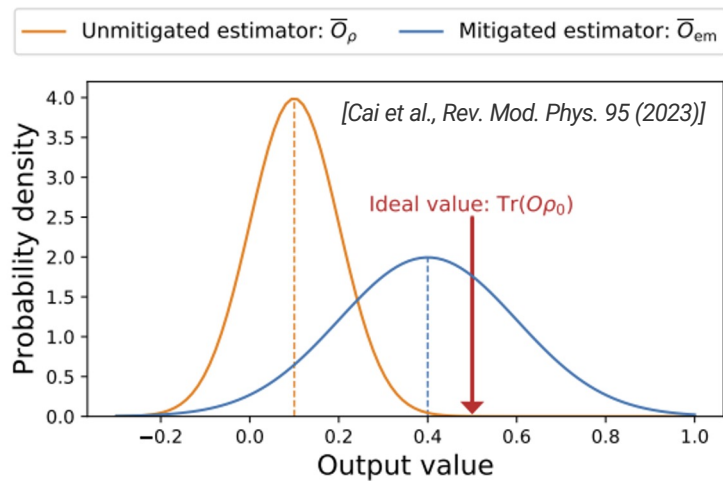
Quantum error mitigation

Error mitigation is...

Trading bias for stochastic noise

As we have control over circuit depth,

EM overhead can be reduced for QPE



Postselection	$C_{\text{em}} = \Lambda F^{-1}$	$C_{\text{em}}^{\text{QPE}}(\gamma, \epsilon) \leq \Lambda \kappa e / \pi \cdot \gamma / \epsilon$	Symmetry verification, verified phase estimation*
Rescaling	$C_{\text{em}} = \Lambda F^{-2}$	$C_{\text{em}}^{\text{QPE}}(\gamma, \epsilon) \leq \Lambda \kappa e / \pi \cdot 2\gamma / \epsilon$	Echo verification*, direct rescaling under GDN
Explicit unbiasing	$C_{\text{em}} = \Lambda F^{-4}$	$C_{\text{em}}^{\text{QPE}}(\gamma, \epsilon) \leq \Lambda \kappa e / \pi \cdot 4\gamma / \epsilon$	Probabilistic error cancellation, virtual distillation

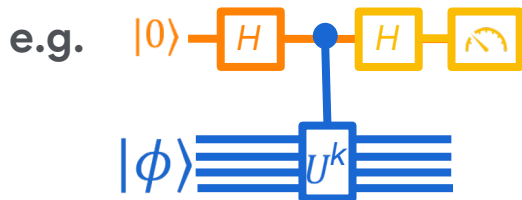
*depending if verification circuit is short

Quantum error mitigation

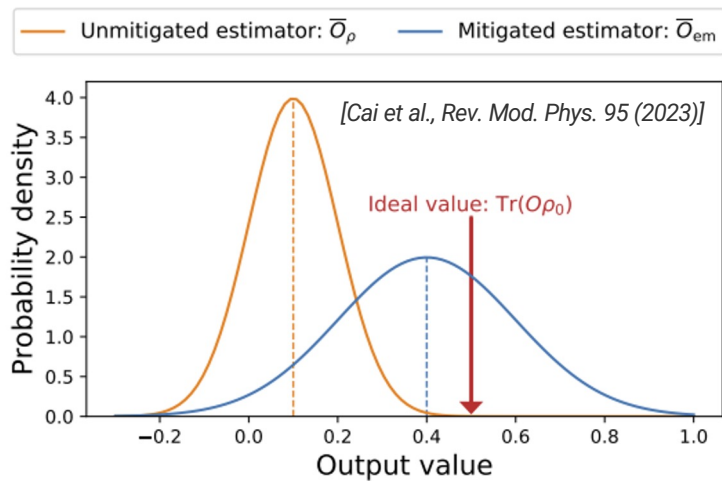
Error mitigation is...

Trading bias for stochastic noise

Current error mitigation schemes are designed
only for expectation values



$$\longrightarrow g(k) = \langle \phi | U^k | \phi \rangle$$

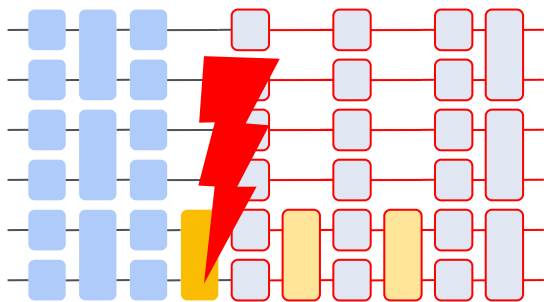


Global depolarising noise vs realistic noise

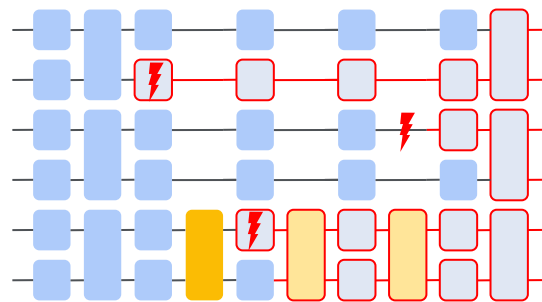
Max-Likelihood estimation

$$\tilde{\phi} = \arg \max \log \mathcal{L}(\tilde{\phi} | \vec{x})$$

$$\log \mathcal{L}(\tilde{\phi} | \vec{x}) = \sum_{i=1}^M \log P(x_i | \tilde{\phi})$$



$$P(\tilde{\phi} | \phi) = e^{-\gamma t} P_0(\tilde{\phi} | \phi) + (1 - e^{-\gamma t}) \frac{1}{2\pi}$$



$$P(\tilde{\phi} | \phi) = e^{-\gamma t} P_0(\tilde{\phi} | \phi) + ???$$

Probabilistic error cancellation

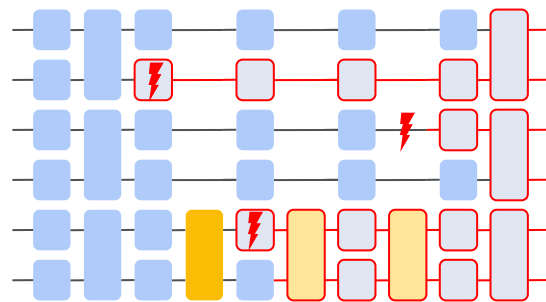
Max-Likelihood estimation

$$\tilde{\phi} = \arg \max \log \mathcal{L}(\tilde{\phi} | \vec{x})$$
$$\log \mathcal{L}(\tilde{\phi} | \vec{x}) = \sum_{i=1}^M \log P(x_i | \tilde{\phi})$$

PEC decomposition

$$P_0(x) = \sum_j \alpha_j Q_j(x)$$

↑
*Noisy circuits
we can actually
sample from*



$$P(\tilde{\phi} | \phi) = e^{-\gamma t} P_0(\tilde{\phi} | \phi) + ???$$

Probabilistic error cancellation

[Temme et al., 2017]

We decompose the ideal (noiseless) channel in implementable noisy circuits

$$\mathcal{U} = \sum_j \alpha_j \mathcal{B}_j$$

By linearity, the noiseless outcome distribution can be written as a nonconvex combination

$$P(x) = \sum_j \alpha_j Q_j(x)$$

$$Q_j(x) = \text{Tr} [|x\rangle\langle x| \mathcal{B}_j(|0\rangle\langle 0|)]$$

PEC is defined for expectation values

$$\mathbb{E}[x|x \sim P(x)] = \sum_j \alpha_j \mathbb{E}[x|x \sim Q_j(x)].$$

We can estimate the sample mean by importance-sampling j with probability

$$p_j = \frac{|\alpha_j|}{\sum_j |\alpha_j|}$$

Overhead:

$$C_{\text{em}} = \left(\sum_j |\alpha_j| \frac{\sqrt{\text{Var}[Q_j]}}{\sqrt{\text{Var}[P]}} \right)^2 \stackrel{*}{=} F^{-4}$$

Probabilistic error cancellation for MLE?

$$P(x) = \sum_j \alpha_j Q_j(x)$$

PEC decomposition

Standard MLE:

1. Get M samples x_i from $P(x|\phi)$.
2. Calculate the log likelihood:

$$C(\tilde{\phi}) = \log \mathcal{L}(\tilde{\phi}|\vec{x}) = \frac{1}{M} \sum_{i=1}^M \log P(x_i|\tilde{\phi})$$

3. Maximize $C(\tilde{\phi})$.

$$C(\tilde{\phi}) \xrightarrow{M \rightarrow \infty} \mathbb{E}[\log P(x|\tilde{\phi}) \mid x \sim P(x|\phi)]$$

Probabilistic error cancellation for MLE?

$$P(x) = \sum_j \alpha_j Q_j(x)$$

PEC decomposition

Standard MLE:

1. Get M samples x_i from $P(x|\phi)$.
2. Calculate the log likelihood:

$$C(\tilde{\phi}) = \log \mathcal{L}(\tilde{\phi}|\vec{x}) = \frac{1}{M} \sum_{i=1}^M \log P(x_i|\tilde{\phi})$$

Sample average

3. Maximize $C(\tilde{\phi})$.

$$C(\tilde{\phi}) \xrightarrow{M \rightarrow \infty} \mathbb{E}[\log P(x|\tilde{\phi}) | x \sim P(x|\phi)]$$

Expectation value

Explicitly-unbiased MLE

$$P(x) = \sum_j \alpha_j Q_j(x)$$

PEC decomposition

Standard MLE:

1. Get M samples x_i from $P(x|\phi)$.
2. Calculate the log likelihood:

$$C(\tilde{\phi}) = \log \mathcal{L}(\tilde{\phi}|\vec{x}) = \frac{1}{M} \sum_{i=1}^M \log P(x_i|\tilde{\phi})$$

3. Maximize $C(\tilde{\phi})$.

EUMLE:

1. Get M samples (j_i, x_i) from $\frac{|\alpha_j|}{\|\alpha\|} Q_j(x)$.
2. Calculate the log likelihood:

$$C(\tilde{\phi}) = \frac{\|\alpha\|}{M} \sum_{i=1}^M \text{sgn}(\alpha_{j_i}) \log P(x_i|\tilde{\phi})$$

3. Maximize $C(\tilde{\phi})$.

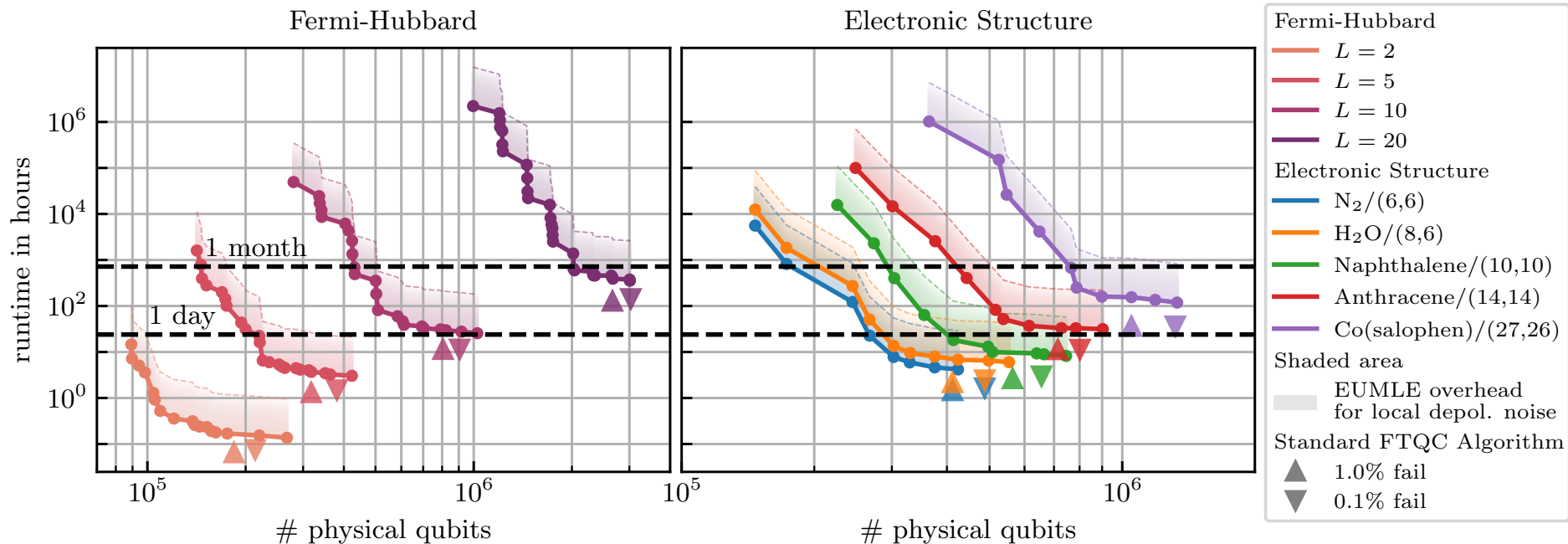
In both cases:

$$C(\tilde{\phi}) \xrightarrow{M \rightarrow \infty} \mathbb{E}[\log P(x|\tilde{\phi}) \mid x \sim P(x|\phi)]$$

Explicitly-unbiased max-likelihood estimator

- First error mitigation technique beyond expectation values
(note: MLE is very general)
- Proven convergence and **asymptotic normality**
- We further introduce **regularization** and **filtering**
- Under *local Pauli noise*, regularized EUMLE incurs in **$\approx 7\times$ overhead** compared to *global depolarizing noise* in max-likelihood QPE.
(Filtering could reduce this)

Resource estimates with EUMLE overhead



Take-home summary

- We can trade-off **qubits vs time** by combining error mitigation with error correction
- Designing algorithms to be noise-resilient is useful, even in fault-tolerant QC
- Error mitigation can be extended to general estimation tasks

Error mitigation and circuit division for early fault-tolerant quantum phase estimation



Alicja
Dutkiewicz



Stefano
Polla



Maximillian
Scheurer



Christian
Gogolin



William J.
Huggins



Thomas E.
O'Brien



https://github.com/StefanoPolla/EarlyFT_QPE