

UF

15th July 2025

Higgs Hunting 2025.

SMEFT Geometry, Amplitudes &
a Shortcut to Riemann Normal Coordinates.

Mia West

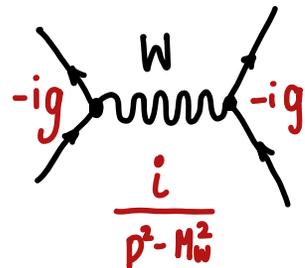
Soon to appear on
arXiv.

in collaboration with Cris Caballero & Rachel Houtz.

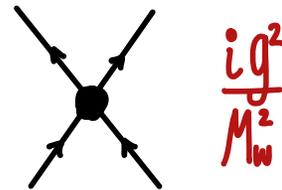
Effective field Theory

"Top Down"

Think 4-fermi theory:



$$M_W^2 \gg E_{cm}^2$$



"Bottom Up"

Build a tower of higher dimensional operators suppressed by the higher energy.

Standard Model EFT (SMEFT)

$$\mathcal{L}_{\text{SMEFT}} = \mathcal{L}_{\text{SM}} + \sum_{i=1}^{n_d} \frac{C_i^{(d)}}{\Lambda^d} Q_i^{(d)} \quad \text{for } d \geq 4.$$

Wilson Coefficients

Scale of new physics

Operators of SM fields obey $SU(3)_c \times SU(2)_L \times U(1)_Y$

In This Talk...

* Focussing on the Scalar Sector

↳ Custodial Symmetry Limit $SU(2)_L \times SU(2)_R \sim O(4)$

$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} \phi_1 + i\phi_2 \\ \phi_4 + i\phi_3 \end{pmatrix} \rightsquigarrow \vec{\phi} = \begin{pmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{pmatrix}$$

* Global Symmetry recover local symmetry following

[R. Alonso, E. Jenkins & A. Manohar: 1605.03602].

Scalar Lagrangian in (Cartesian / 'Warsaw') to two-derivatives:

$$\mathcal{L} = \partial_\mu \phi^a G_{ab}(\phi) \partial^\mu \phi^b + V(\phi) + (\text{higher derivatives})$$

where $G_{ab}(\phi) = A \left(\frac{\phi \cdot \phi}{\Lambda^2} \right) \delta_{ab} + B \left(\frac{\phi \cdot \phi}{\Lambda^2} \right) \frac{\phi_a \phi_b}{\Lambda^2}$

$$1 + a_1 \frac{\phi \cdot \phi}{\Lambda^2} + a_2 \left(\frac{\phi \cdot \phi}{\Lambda^2} \right)^2 + \dots$$

$$b_1 + b_2 \left(\frac{\phi \cdot \phi}{\Lambda^2} \right) + b_3 \left(\frac{\phi \cdot \phi}{\Lambda^2} \right)^2 + \dots$$

Field Redefinitions which leave Amplitudes Invariant:

$$\phi^a \rightarrow F^{ab}(\tilde{\phi}) \tilde{\phi}^b \quad \text{with} \quad F^{ab}(0) = \delta^{ab}$$

$\underbrace{\hspace{10em}}$
Real analytic function of $\tilde{\phi}$.

* In general, $F^{ab}(X)$ MAY include derivative couplings.

↳ But not in this talk.

[A. Manohar; hep-ph/1804.05863]

"Geometric SMEFT"

- $G_{ab}(\phi)$ is a **metric tensor**:

$$\tilde{G}_{ab}(\tilde{\phi}) = \frac{\partial \phi^c}{\partial \tilde{\phi}^a} G_{cd}(\phi(\tilde{\phi})) \frac{\partial \phi^d}{\partial \tilde{\phi}^b}$$

- $\partial_\mu \phi^a$ transforms as a **tangent vector field**:

$$\partial_\mu \tilde{\phi}^a = \frac{\partial \tilde{\phi}^a}{\partial \phi^b} \partial_\mu \phi^b$$

$$\left. \begin{array}{l} \mathcal{L}_{\text{kinetic}} = \frac{1}{2} \partial_\mu \phi^a G_{ab}(\phi) \partial^\mu \phi^b \\ = \frac{1}{2} \partial_\mu \tilde{\phi}^c \frac{\partial \phi^a}{\partial \tilde{\phi}^c} G_{ab}(\phi(\tilde{\phi})) \frac{\partial \phi^b}{\partial \tilde{\phi}^d} \partial^\mu \tilde{\phi}^d \\ = \frac{1}{2} \partial_\mu \tilde{\phi}^c \tilde{G}_{cd}(\tilde{\phi}) \partial^\mu \tilde{\phi}^d. \end{array} \right\}$$

ie we can treat the fields *geometrically* living on the surface of a *field-space manifold*.

[L. Alvarez-Gaume, D. Z. Freedman and S. Mukhi; Annals. Phys. 148 (1981) 85].

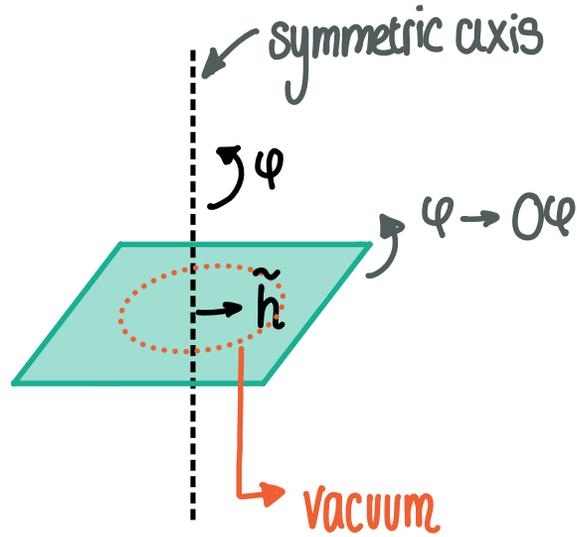
[R. Alonso, E. Jenkins and A. Manohar: 1605.03602] ← Geometry of scalars in HEFT

[A. Helset, A. Martin, M. Trott: 2001.01453] ← GeoSMEFT

...

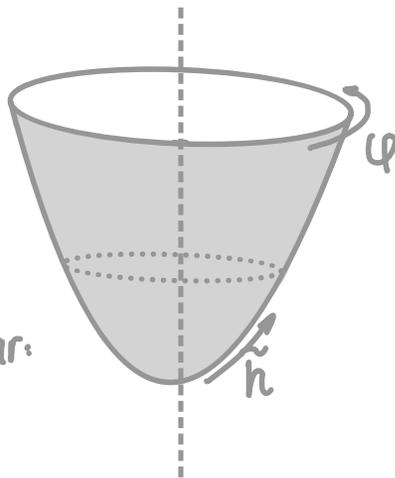
SMEFTs in pictures:

① SM

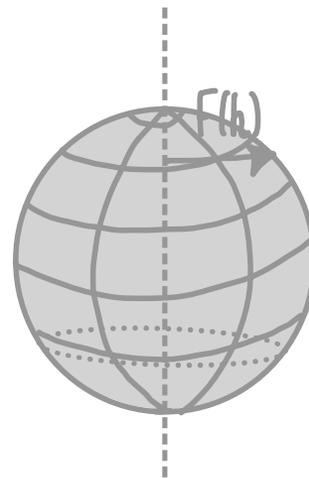


② SMEFTs

eg negative curvature models



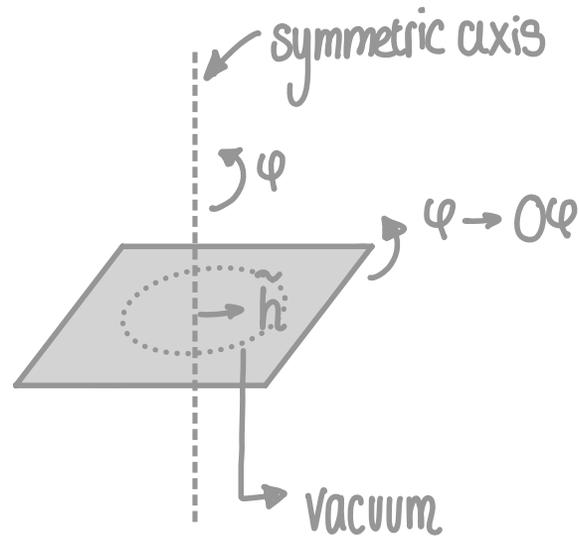
[R. Alonso, E. Jenkins, A. Manohar:
1602.00706]



eg Composite Higgs models

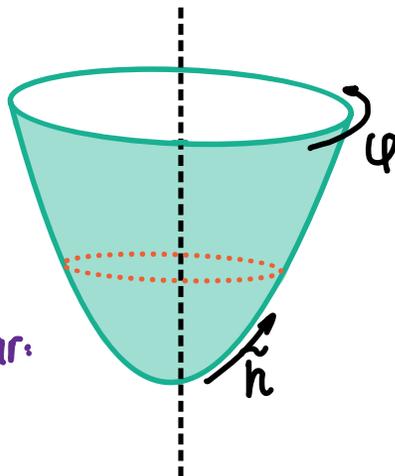
SMEFTs in pictures:

① SM

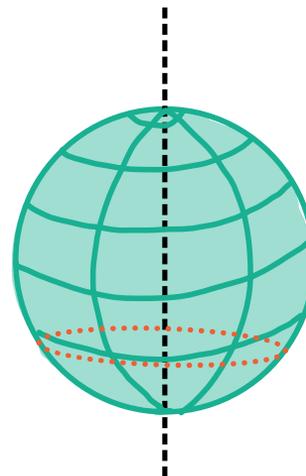


② SMEFTs

eg negative curvature models

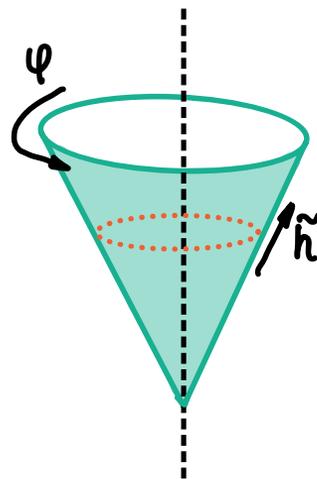
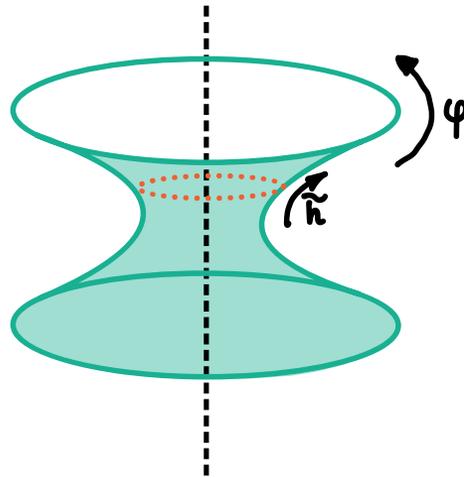


eg Composite Higgs models



[R. Alonso, E. Jenkins, A. Manohar:
1602.00706]

③ HFTs that aren't SFTs : Non-Linear Theories
(exclusive)



See eg:
[arXiv: 2109.13290;
R. Alonso & MW]
[arXiv: 2008.08597; T. Cohen,
N. Craig, X. Lu, D. Sutherland]
[A. Falkowski, R. Rattazzi;
1902.05936]

On-Shell Amplitudes in High Energy Limit ($E_{CM} \gg M_1, M_2, M_3$).

$$A_3 = 0$$

$$A_4 = s \overline{R}_{1(34)2} + t \overline{R}_{1(24)3} + u \overline{R}_{1(23)4} \quad \leftarrow \text{Evaluate at vacuum}$$

[C. Cheung, A. Helset and J. Parra-Martinez: 2111.03045].

$$\begin{aligned}
 A_4^{i_1 i_2 i_3 i_4} &= R^{i_1 i_3 i_2 i_4} s_{34} + R^{i_1 i_2 i_3 i_4} s_{24}, \\
 A_5^{i_1 i_2 i_3 i_4 i_5} &= \nabla^{i_3} R^{i_1 i_4 i_2 i_5} s_{45} + \nabla^{i_4} R^{i_1 i_3 i_2 i_5} s_{35} + \nabla^{i_4} R^{i_1 i_2 i_3 i_5} s_{25} \\
 &\quad + \nabla^{i_5} R^{i_1 i_3 i_2 i_4} s_{34} + \nabla^{i_5} R^{i_1 i_2 i_3 i_4} (s_{24} + s_{45}), \\
 A_6^{i_1 i_2 i_3 i_4 i_5 i_6} &= -\frac{1}{72} (R^{i_1 i_3 i_2 j} s_{12} + R^{i_1 i_2 i_3 j} s_{13}) \frac{1}{s_{123}} (R_j^{i_6 i_5 i_4} s_{46} + R_j^{i_5 i_6 i_4} s_{45}) \\
 &\quad + \frac{1}{108} (R^{i_1 i_3 i_2 j} (s_{12} - \frac{1}{6} s_{123}) + R^{i_1 i_2 i_3 j} (s_{13} - \frac{1}{6} s_{123})) (R_j^{i_6 i_5 i_4} + R_j^{i_5 i_6 i_4}) \\
 &\quad + \frac{1}{90} R^{i_1 i_6 i_5 j} R_j^{i_2 i_3 i_4} s_{13} + \frac{1}{80} \nabla^{i_6} \nabla^{i_5} R^{i_1 i_2 i_3 i_4} s_{13} + \text{perm.}
 \end{aligned}$$

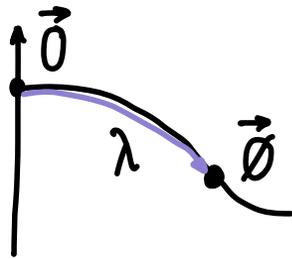
... 'best basis' for computing amplitudes: local inertial 'normal coordinate' frame.

[T. Cohen, N. Craig, X. Liu, D. Sutherland:

2108.03240]

Reach a generic point by following a **unique** geodesic from \vec{O}

$$\frac{d^2 \vartheta_{\text{geo}}^{\kappa}}{d\lambda^2} + \Gamma_{\beta\gamma}^{\kappa}(\vec{\vartheta}_{\text{geo}}(\lambda)) \frac{d\vartheta_{\text{geo}}^{\beta}}{d\lambda} \frac{d\vartheta_{\text{geo}}^{\gamma}}{d\lambda} = 0.$$



$$\vec{\vartheta}_{\text{geo}}(0) = 0$$

$$\vec{\vartheta}_{\text{geo}}(1) = \vec{\vartheta}.$$

Normal coordinate tangent to geodesic:

$$\eta^a \equiv \frac{d\vartheta_{\text{geo}}^a}{d\lambda}(0)$$

bar means evaluate at \vec{O}

$$\text{OR } \vartheta^a = \vartheta_{\text{geo}}^a(1) = \eta^a - \sum_{n=2}^{\infty} \frac{1}{n!} \bar{\Gamma}_{(b_1 \dots b_n)}^a \eta^{b_1} \dots \eta^{b_n}$$

Why Riemann Normal Coordinates?

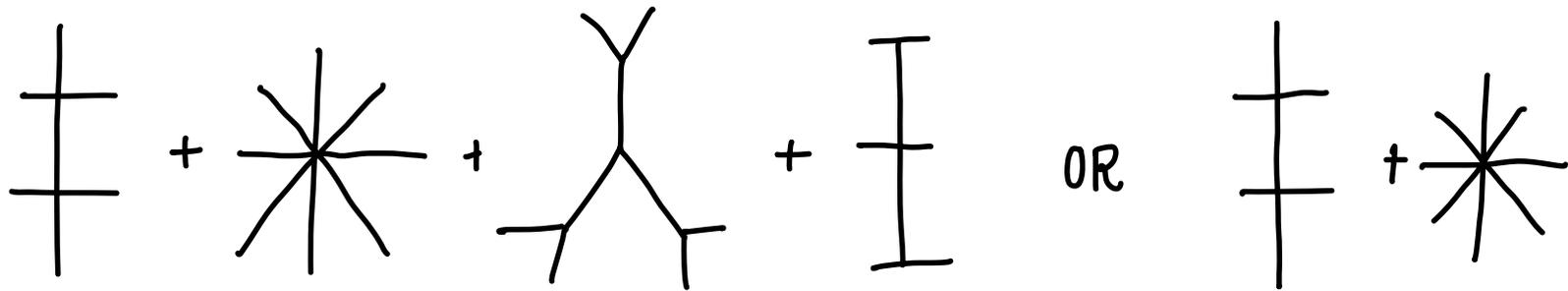
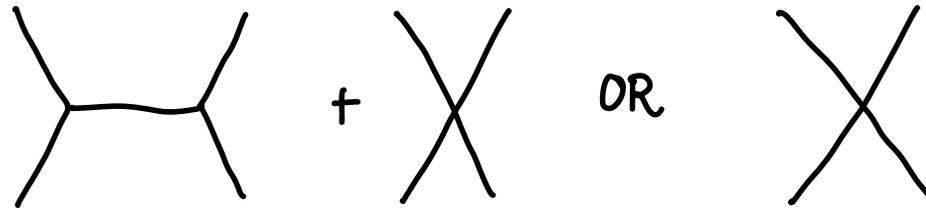
1 // Manifestly Field-Space Covariant:

$$G_{ab}(\eta) = \delta_{ab} + \frac{1}{3} \bar{R}_{aijb} \eta^i \eta^j + \frac{1}{6} \nabla_k \bar{R}_{aijb} \eta^i \eta^j \eta^k \\ + \frac{6}{5!} (\nabla_l \nabla_k \bar{R}_{aijb} + \frac{8}{9} \bar{R}_{aijc} \bar{R}^c_{kcb}) \eta^i \eta^j \eta^k \eta^l + \dots$$

[A. Hatzinikitas; hep-th/0001078].

$$\mathcal{L}_{\text{kinetic}} = \partial_\mu \eta^a G_{ab}(\eta) \partial^\mu \eta^b.$$

2 // No 3-point vertex



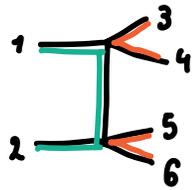
3// Each Feynman graph has *distinct kinematics* with poles relating to each propagator denominator on-shell:

→ Vertices invariant under p_i deformations of external legs *off shell* & leaving Mandelstams unchanged.

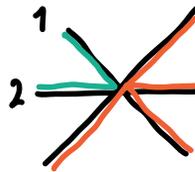
[T. Cohen, N. Craig, X. Lu and D. Sutherland: 2108.03240].

For example:

— type 1 particles
— type 2 particles



+



$$\frac{S_{34} S_{56}}{S_{134}}$$

$$S_{12}$$

NB//

$$S_{ij} = (p_i + p_j)^2$$

$$S_{ijk} = (p_i + p_j + p_k)^2$$

⇔ No 'cancellations' between diagrams.

Generic RNC construction method

$$\varnothing^a = \varnothing_{\text{geo}}^a(1) = \eta^a - \sum_{n=2}^{\infty} \frac{1}{n!} \bar{\Gamma}_{(b_1 \dots b_n)}^a \eta^{b_1} \dots \eta^{b_n}$$

where

RECURSIVE !!!

$$\Gamma_{b_1 \dots b_n c}^a = \partial_c \Gamma_{b_1 \dots b_n}^a - \sum_{j=1}^n \Gamma_{c b_j}^{\gamma} \Gamma_{b_1 \dots b_{j-1} \gamma b_{j+1} \dots b_n}^a$$

$$\Gamma_{bc}^a(\varnothing) = \frac{1}{2} G^{ai}(\varnothing) (\partial_c G_{ib}(\varnothing) + \partial_b G_{ic}(\varnothing) - \partial_i G_{bc}(\varnothing))$$

[arXiv: 2008.08597; T. Cohen,
N. Craig X. Lu, D. Sutherland]

Can we avoid this with Symmetry?

Metric transforms as a tensor around the symmetry point:

$$G_{ab}(\eta) = \delta_{ab} + \frac{1}{3} R_{aijb}(0) \eta^i \eta^j + \frac{1}{6} \nabla_k R_{aijb}(0) \eta^i \eta^j \eta^k + \dots$$

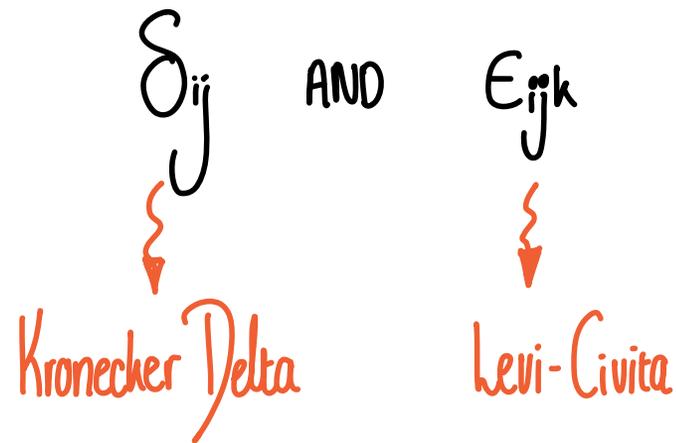
$$\rightarrow \delta_{cd} + \frac{1}{3} R_{aijb}(0) \sigma^i_k \sigma^j_l \tilde{\eta}^k \tilde{\eta}^l + \dots$$

$$= \sigma_a^c \delta_{cd} \sigma^{ad} + \frac{1}{3} R_{eijf}(0) (\sigma\sigma^T)_a^e (\sigma\sigma^T)_b^f \sigma^i_k \sigma^j_l \tilde{\eta}^k \tilde{\eta}^l$$

$$= \sigma_a^c \left[\delta_{cd} + \frac{1}{3} R_{eijf}(0) \sigma_c^e \sigma_d^f \sigma^i_k \sigma^j_l \tilde{\eta}^k \tilde{\eta}^l + \dots \right] \sigma^{ad}_b$$

Exactly an $O(4)$ isotropic tensor

Isotropic Tensor MUST be constructed from:



[P.G. Appleby, B.R. Duffy, R.W. Ogden: Glasgow Mathematical Journal 29(2) 185-196 (1987)]

Riemann Tensor at Fixed Point

$$\bar{R}_{a(ij)b} = \alpha \delta_{ai} \delta_{bj} + \beta \delta_{aj} \delta_{ib} + \gamma \delta_{ab} \delta_{ij} \quad ij \text{ symmetrised}$$

1// Skew Symmetry $R_{(ai)jb} = R_{ai(jb)} = 0 \Rightarrow \alpha = 0.$

2// Interchange Symmetry $R_{aijb} = R_{jbai} \Rightarrow \beta = -\gamma.$

$$\bar{R}_{a(ij)b} = \beta (\delta_{aj} \delta_{ib} - \delta_{ab} \delta_{ij}) \quad ij \text{ symmetrised}$$

Riemann Tensor at Fixed Point

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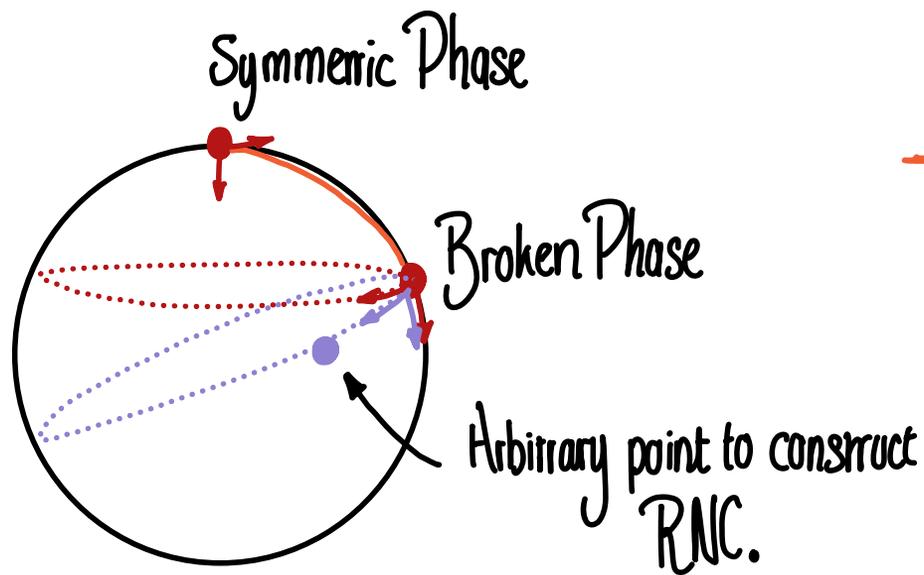
Symmetric Point Summary

$$G_{ab}(\eta) = \delta_{ab} + \frac{1}{3} \bar{R}_{aijb} \eta^i \eta^j + \frac{1}{6} \nabla_k \bar{R}_{aijb} \eta^i \eta^j \eta^k$$

$$+ \frac{6}{5!} (\nabla_i \nabla_k \bar{R}_{aijb} + \frac{8}{9} \bar{R}_{aijc} \bar{R}^c_{kib}) \eta^i \eta^j \eta^k \eta^l + \dots$$

$$= \delta_{ab} + \sum_{n=2}^{\infty} \frac{c_{(n-1)/2}}{\Lambda^{(n-2)}} \tilde{R}_{ai_1 i_2 b} \delta_{i_3 i_4} \dots \delta_{i_{(n-1)} i_n} \eta^{i_1} \dots \eta^{i_n}.$$

Breaking the Symmetry (in Progress...)



— Parallel Transport the RNC to the vacuum
→ The vector looks exactly the same

— Re-establish the normal coordinate
→ More Christoffels

RNC in the literature:

- Covariant effective actions [R. Alonso and MW: 2207.02050].

Renormalising field-space geometry [P. Aigner, L. Bellafronte, E. Gendy,
D. Haslehner and A. Weiler: 2503.09785]

[B. Assi, A. Helset, A. Manohar, J. Pagés
C-H. Shen: 2303.03187]

- Unitarity Bounds in HEFT [T. Cohen, N. Craig, X. Lu and D. Sutherland: 2108.03240].
- Geometric soft theorems [C. Cheung, A. Helset and J. Parra-Martinez: 2111.03045].

Summary & Future Prospects

- 1// Geometry is a neat way to encapsulate field-redefinition invariance **ON-SHELL**.
- 2// Riemann normal coordinates motivated as "good" choice of field-space basis.
- 3// Riemann normal coordinates easier with symmetry! Avoiding the Christoffels...

In the future this maths could be used elsewhere:

a// Gauge symmetries?

b// Other groups may have similar trick?

Summary & Future Prospects

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Derivative Field Redefinitions

Jet Bundle Geometry [M. Alminawi, I. Brivio and J. Davighi; 2308.00017]

Geometry-Kinematics Duality [C. Cheung, A. Helset and J. Parra-Martinez;
2202.06972]

Functional Geometry [T. Cohen, X. Lu and Z. Zhang; 2410.21378]

- Non-local field redefinitions

[T. Cohen, M. Forstlund, A. Helset; 2412.12247]

Equations of Motion:

The classical equation of motion $E[\phi] \equiv \frac{\delta S}{\delta \phi}$

$$\text{eg } \mathcal{L} = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 - \frac{1}{4!} \lambda \phi^4 \quad \Rightarrow \quad E[\phi] = -\partial^2 \phi(x) - m^2 \phi(x) - \frac{1}{3!} \lambda \phi^3(x)$$

consider a field redefinition with $\phi = \phi' + \epsilon f[\phi']$

$$\mathcal{L}[\phi] = \mathcal{L}[\phi'] + \epsilon f[\phi'] \frac{\delta S[\phi']}{\delta \phi} + \mathcal{O}(\epsilon^2)$$

$$= \mathcal{L}[\phi'] + \epsilon \Theta[\phi'] + \mathcal{O}(\epsilon^2)$$

$$\text{where } \Theta[\phi] = F[\phi] [E[\phi]] = F[\phi] \frac{\delta S}{\delta \phi}$$

ie a special case of a field redefinition [A. Manohar; hep-ph/1804.05863]

RNC in the broken phase...

$$\Gamma_{ij}^h = -v^2 F(h) F'(h) g_{ij}(\varphi)$$

$$\Gamma_{hj}^i = \frac{F'(h)}{F(h)} \delta_{ij}$$

$$\Gamma_{jk}^i = n_i g_{jk}(\varphi)$$

eg $\Gamma_{ijhk}^h = \partial_k \Gamma_{ijh}^h - \Gamma_{ki}^a \Gamma_{ajh}^h - \Gamma_{kj}^a \Gamma_{iah}^h - \Gamma_{kh}^a \Gamma_{ija}^h$

$$= \partial_k \left[\partial_h \Gamma_{ij}^h - \Gamma_{hi}^b \Gamma_{bj}^h - \Gamma_{hj}^b \Gamma_{ib}^h \right] \\ - \Gamma_{ki}^a \left[\partial_h \Gamma_{aj}^h - \Gamma_{ha}^b \Gamma_{bj}^h - \Gamma_{hj}^b \Gamma_{ab}^h \right] \\ - \Gamma_{kj}^a \left[\partial_h \Gamma_{ia}^h - \Gamma_{hi}^b \Gamma_{ba}^h - \Gamma_{ha}^b \Gamma_{ib}^h \right] \\ - \Gamma_{kh}^a \left[\partial_a \Gamma_{ij}^h - \Gamma_{ai}^b \Gamma_{bj}^h - \Gamma_{aj}^b \Gamma_{ib}^h \right]$$

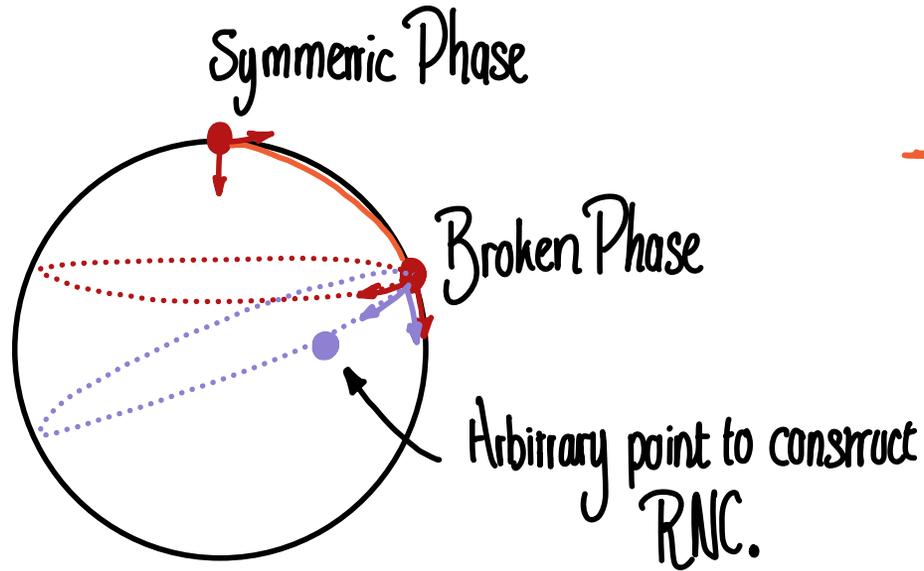
[arXiv: 2008.08597; T. Cohen, N Craig X Lu, D. Sutherland]

$$= -v^2 (F'(h)^2 + F''(h)F(h)) \partial_k g_{ij}(\varphi) + F'(h)^2 (\delta_i^z g_{zj}(\varphi) + \delta_j^z g_{iz}(\varphi))$$

$$- \varphi_k g_{ki}(\varphi) \left[-v^2 (F'(h)^2 + F''(h)F(h)) g_{zk}(\varphi) - F'(h)^2 (\delta_i^m g_{mj}(\varphi) + \delta_j^m g_{mi}(\varphi)) \right] \\ + \dots$$

Breaking the Symmetry

Breaking the Symmetry (in Progress...)



— Parallel Transport the RNC to the vacuum
→ The vector looks exactly the same

— Re-establish the normal coordinate
→ More Christoffels

The 'Wrong' way to do this: \rightarrow loose all orders result!

① CANONICALISE:

$$\begin{aligned} \partial_\mu \eta^A G_{AB}(\eta) \partial^\mu \eta^B &\xrightarrow{\text{Break the symmetry}} \partial_\mu \eta^A G_{AB}(\tilde{\eta}+V) \partial^\mu \eta^B \\ &= \partial_\mu \tilde{\eta}^a e_a^A(V) G_{AB}(\tilde{\eta}+V) e_b^B(V) \partial^\mu \tilde{\eta}^b \end{aligned}$$

\rightarrow vielbeins

where $\delta_{ab} = e_a^A(V) G_{AB}(V) e_b^B(V)$ does the canonicalisation.

[C. Cheung, A. Helset and J. Parra-Martinez: 2111.03045].

② Re-Establish THE RNC

$$v^i = \begin{pmatrix} 0 \\ 0 \\ 0 \\ v \end{pmatrix} \text{ for example!}$$

$$\tilde{\eta}^a = \sigma^a + \sum_{i=2}^{\infty} \Gamma_{b_1 \dots b_n}^a \Big|_{\text{vacuum}} \sigma^{b_1} \dots \sigma^{b_n}$$

and

$$\Gamma_{b_1 \dots b_n}^a \Big|_{\text{vacuum}} = \Gamma_{b_1 \dots b_n}^a \Big|_{\text{restored}}$$

$$+ \Gamma_{b_1 \dots b_n, b_{n+1}}^a \Big|_{\text{restored}} v^{b_{n+1}}$$

$$+ \Gamma_{b_1 \dots b_n, b_{n+1} b_{n+2}}^a \Big|_{\text{restored}} v^{b_{n+1}} v^{b_{n+2}} \times \frac{1}{2}$$

+...

$$G_{ab}(\eta) = \delta_{ab} + \frac{1}{3} c_i \tilde{R}_{aijb} \eta^i \eta^j + \dots$$

$$\rightarrow \left(\frac{\partial \tilde{\eta}^c}{\partial \sigma^a} \right) e_c^c(v) G_{cd}(\tilde{\eta} + v) e_d^d(w) \left(\frac{\partial \tilde{\eta}^d}{\partial \sigma^b} \right)$$

$$= \left[\delta_a^c - \left(\tilde{\Gamma}_{(j,i)2}^c \sigma^{i_1} \delta_a^{i_2} + \frac{1}{2} \tilde{\Gamma}_{(i_1 i_2), v}^c \sigma^{i_1} \delta_a^{i_2} + \frac{1}{6} \tilde{\Gamma}_{(i_1 i_2), v v}^c \sigma^{i_1} \delta_a^{i_2} + \dots \right) \right. \\ \left. - \frac{1}{2} \left(\tilde{\Gamma}_{(i_1 i_2 i_3)}^c \sigma^{i_1} \sigma^{i_2} \delta_a^{i_3} + \frac{1}{2} \tilde{\Gamma}_{(i_1 i_2 i_3), v}^c \sigma^{i_1} \sigma^{i_2} \delta_a^{i_3} + \dots \right) + \dots \right]$$

$$\times e_c^c(v) \left[\delta_{cd} + \frac{1}{3} c_i \tilde{R}_{cijo} \left(v^i \sigma^i - \frac{1}{2} \tilde{\Gamma}_{i_1 i_2, v}^i \sigma^{i_1} \sigma^{i_2} - \dots \right) \left(v^j + \sigma^j - \frac{1}{2} \tilde{\Gamma}_{j_1 j_2, v}^j \sigma^{j_1} \sigma^{j_2} + \dots \right) + \dots \right] e_d^d(w)$$

$$\times \left[\delta_b^d - \left(\tilde{\Gamma}_{(j,i)2}^d \sigma^{i_1} \delta_b^{i_2} + \frac{1}{2} \tilde{\Gamma}_{(i_1 i_2), v}^d \sigma^{i_1} \delta_b^{i_2} + \frac{1}{6} \tilde{\Gamma}_{(i_1 i_2), v v}^d \sigma^{i_1} \delta_b^{i_2} + \dots \right) \right. \\ \left. - \frac{1}{2} \left(\tilde{\Gamma}_{(i_1 i_2 i_3)}^d \sigma^{i_1} \sigma^{i_2} \delta_b^{i_3} + \frac{1}{2} \tilde{\Gamma}_{(i_1 i_2 i_3), v}^d \sigma^{i_1} \sigma^{i_2} \delta_b^{i_3} + \dots \right) + \dots \right]$$

Which is Awful...

Below is a working idea to avoid this.

Fortunately we already know the answer:

$$G_{Tab} = \delta_{ab} + \frac{1}{3} \bar{R}_{aijb} \sigma^i \sigma^j + \frac{1}{6} \nabla_k \bar{R}_{aijb} \sigma^k \sigma^i \sigma^j + \dots$$

new RNC at broken phase

So we can construct the new metric via a Taylor series:

$$\left. \frac{\partial^n G_{Tab}}{\partial \sigma^{i_1} \dots \partial \sigma^{i_n}} \right|_{\text{Broken}} = e^{i_1}_{I_1}(\eta) \dots e^{i_n}_{I_n}(\eta) e^A_a(\eta) e^B_b(\eta) \left. \frac{\partial^n G_{AB}(\eta)}{\partial \eta^{I_1} \dots \partial \eta^{I_n}} \right|_{\text{Broken}}$$

We don't know this @ broken so

take a Taylor expansion.

$$= e^{i_1}_{I_1}(\eta) \dots e^{i_n}_{I_n}(\eta) e^A_a(\eta) e^B_b(\eta) \left[\frac{\partial^n G_{AB}(0)}{\partial \eta^{I_1} \dots \partial \eta^{I_n}} + \frac{\partial^{n+1} G_{AB}(0)}{\partial \eta^{I_1} \dots \partial \eta^{I_{n+1}}} \eta^{I_{n+1}} + \dots \right]_{\text{Broken}}$$

$$\begin{aligned}
&= e_{I_1}^{i_1}(\eta) \dots e_{I_n}^{i_n}(\eta) e_a^A(\eta) e_b^B(\eta) \left[\frac{\partial^n G_{AB}(0)}{\partial \eta^{I_1} \dots \partial \eta^{I_n}} + \frac{\partial^{n+1} G_{AB}(0)}{\partial \eta^{I_1} \dots \partial \eta^{I_{n+1}}} \delta^{I_{n+1}} \right] \text{Broken} \\
&= e_{I_1}^{i_1}(\eta) \dots e_{I_n}^{i_n}(\eta) e_a^A(\eta) e_b^B(\eta) \left[\delta_{L I_1} \dots \delta_{L I_{n-1} I_n} \tilde{R}_{A I_{n-1} I_n B} + \dots \right] \text{Broken}
\end{aligned}$$

$$e_{i_1}^{I_1}(\eta) \delta_{I_1 I_2} e_{i_2}^{I_2}(\eta) \Big|_{\text{Broken}} \quad \eta \rightarrow v \text{ and } \tilde{\eta} \rightarrow 0$$

$$= e_{i_1}^{I_1}(\eta) G_{I_1 I_2}(\tilde{\eta}) e_{i_2}^{I_2}(\eta) \Big|_{\text{Broken}}$$

$$= e_{i_1}^{\tilde{I}_1}(\tilde{\eta}) \frac{\partial \eta^{I_1}}{\partial \tilde{\eta}^{\tilde{I}_1}} G_{I_1 I_2}(\tilde{\eta}) \frac{\partial \eta^{I_2}}{\partial \tilde{\eta}^{\tilde{I}_2}} e_{i_2}^{\tilde{I}_2}(\tilde{\eta}) \Big|_{\text{Broken}}$$

$$= e_{i_1}^{\tilde{I}_1}(\tilde{\eta}) G_{\tilde{I}_1 \tilde{I}_2}(\tilde{\eta}) e_{i_2}^{\tilde{I}_2}(\tilde{\eta}) \Big|_{\text{Broken}} = \delta_{i_1}^{I_1} G_{I_1 I_2}(v) \delta_{i_2}^{I_2}.$$

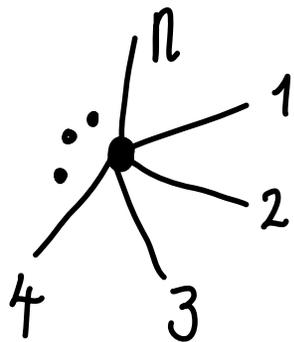
So n-point Feynman rule is:

$$\frac{\delta^n G_{ab}}{\delta \sigma^i \dots \delta \sigma^{in}} \Big|_{\text{Broken}} =$$

$$\begin{aligned} & \frac{C_{(n-2)/2}}{\Lambda^{n-2}} G_{i_1 i_2}(V) G_{i_3 i_4} \dots G_{i_{n-3} i_{n-2}} (G_{a i_{n-1}}(V) G_{i_n b}(V) - G_{ab}(V) G_{i_{n-1} i_n}(V)) \\ & + \frac{C_{n/2}}{\Lambda^n} G_{i_1 i_2}(V) G_{i_3 i_4} \dots G_{i_{n-1} i_n} (G_{a i_{n+1}}(V) G_{i_{n+2} b}(V) - G_{ab}(V) G_{i_{n+1} i_{n+2}}(V)) \\ & \quad \times v^{i_{n+1}} v^{i_{n+2}} \\ & + \dots \end{aligned}$$

where $v^i = \begin{pmatrix} 0 \\ \vdots \\ v \end{pmatrix}$

Relation to 'Warsaw' / Generic Basis.



$$\begin{aligned}
 V_{n\text{-point}}^{\text{RNC}} = & \frac{-i}{(n-2)!} \sum_{[1, \dots, n]} \delta_{\alpha_1, \alpha_2} \delta_{\alpha_3, \alpha_4} \dots \delta_{\alpha_{n-1}, \alpha_n} \frac{C_{(n-1)/2}}{\Lambda^{(n-2)}} \\
 & \partial[a_1, \dots, a_n] \times \left[2(p_{a_1} \cdot p_{a_2} + p_{a_3} \cdot p_{a_4} + \dots + p_{a_{n-1}} \cdot p_{a_n}) \right. \\
 & \quad \left. + (p_1^2 + p_2^2 + \dots + p_n^2) \right]
 \end{aligned}$$

Via Matching Kinetics:

Matching to Generic Basis:

$$V_{n\text{-point}}^{\text{Generic}} = \frac{-i}{(n-2)!} \sum_{[1, \dots, n]} \delta_{\alpha_1, \alpha_2} \delta_{\alpha_3, \alpha_4} \dots \delta_{\alpha_{n-1}, \alpha_n} \left[\frac{1}{\Lambda^{(n-2)}} \right. \\ \left. \partial[a_1, \dots, a_n] \quad a^{(n-2)/2} - b^{(n-2)/2} \left[\begin{aligned} & 2(p_{a_1} \cdot p_{a_2} + p_{a_3} \cdot p_{a_4} + \dots + p_{a_{n-1}} \cdot p_{a_n}) \\ & + (p_1^2 + p_2^2 + \dots + p_n^2) \end{aligned} \right] \right. \\ \left. - a^{(n-2)/2} + b^{(n-2)/2} \left[(p_1^2 + \dots + p_n^2) \right] \right]$$

$$V_{n\text{-point}}^{\text{RNC}} = \frac{-i}{(n-2)!} \sum_{[1, \dots, n]} \delta_{\alpha_1, \alpha_2} \delta_{\alpha_3, \alpha_4} \dots \delta_{\alpha_{n-1}, \alpha_n} \frac{c^{(n-1)/2}}{\Lambda^{(n-2)}} \\ \partial[a_1, \dots, a_n] \quad \times \left[\begin{aligned} & 2(p_{a_1} \cdot p_{a_2} + p_{a_3} \cdot p_{a_4} + \dots + p_{a_{n-1}} \cdot p_{a_n}) \\ & + (p_1^2 + p_2^2 + \dots + p_n^2) \end{aligned} \right]$$

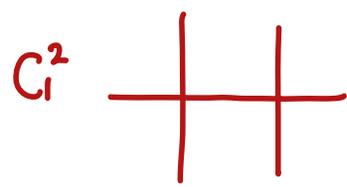
$$\text{---} = 2(p_{a_1} \cdot p_{a_2} + p_{a_3} \cdot p_{a_4} + \dots + p_{a_{n-1}} \cdot p_{a_n}) + (p_1^2 + p_2^2 + \dots + p_n^2)$$

$$\text{---} = p_1^2 + p_2^2 + \dots + p_n^2$$

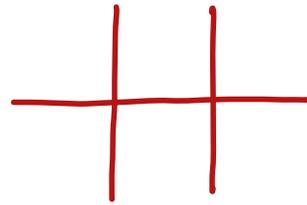
$$4\text{pt: } C_1 \text{ ---} = (a_1 - b_1) \text{ ---} + (a_1 + b_1) \text{ ---} = 0.$$

$$C_1 = (a_1 - b_1)$$

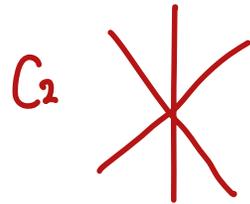
Opt:



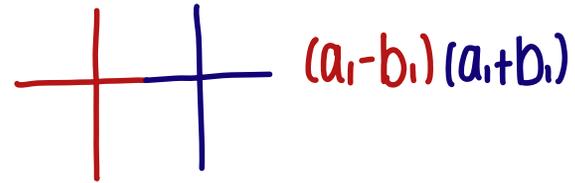
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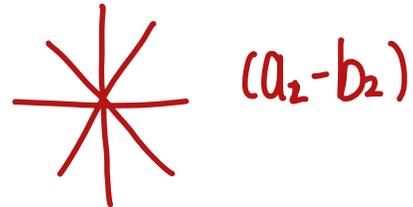
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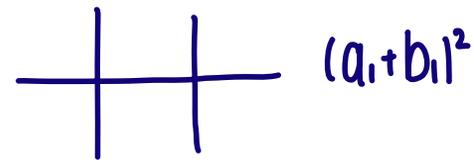
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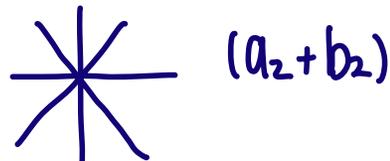
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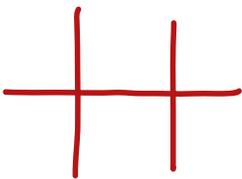
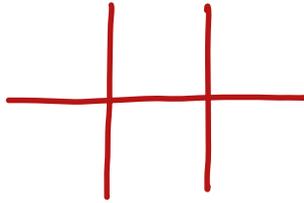
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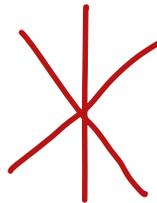
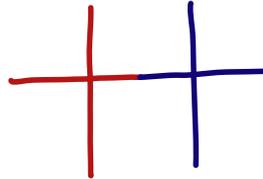
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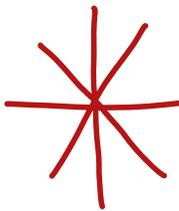


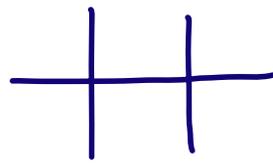
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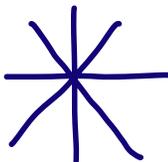
c_1^2  =  ← Previous Order

+

c_2  +  $(a_1 - b_1)(a_1 + b_1)$

+  $(a_2 - b_2)$ *

+  $(a_1 + b_1)^2$

+  $(a_2 + b_2)$ → 0

Symmetry point Riemann Tensor Rules

Odd Derivatives

eg $\nabla_{i_1} \bar{R} a_{i_2 i_3} \delta^{i_1} \delta^{i_2} \delta^{i_3}$

$\delta \dots$

even # of entries

Great but even \times odd = even

$\epsilon \dots$

odd # of entries

$\epsilon_{a b i_1} = 0$ AND $\epsilon_{a i_1 i_2} = 0$

Nothing we can write down.

Odd Derivatives

eg $\nabla_{i_1} \bar{R} a_{i_2 i_3 b} \delta^{i_1} \delta^{i_2} \delta^{i_3}$

$\delta \dots$

even # of entries

Great but even \times odd = even

$\epsilon \dots$

odd # of entries

$$\epsilon a_{b i_1} = 0 \text{ AND } \epsilon a_{i_1 i_2} = 0$$

Nothing we can write down.

$$\Rightarrow \text{All } \nabla_{i_1} \dots \nabla_{i_n} \bar{R} a_{i_{n+1} i_{n+2} b} = 0 \text{ for odd } n$$

$i_1 \dots i_{n+2}$ Symmetrised

Even Derivatives

$$\nabla_{i_1} \nabla_{i_2} \dots \nabla_{i_n} R_{a i_{n+1} i_{n+2}} \Big|_{\theta=0} = \delta_{i_1 i_2} \delta_{i_3 i_4} \dots \delta_{i_{n-1} i_n} \overset{i_1 \dots i_{n+2} \text{ Symmetrised}}{\tilde{R}_{a i_{n+1} i_{n+2} b}}$$

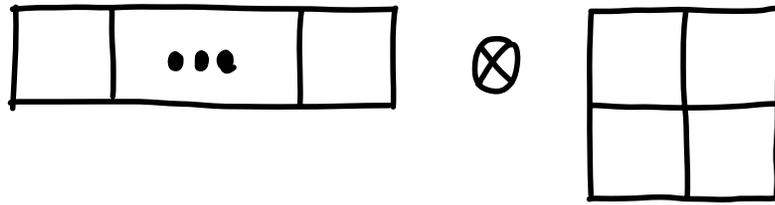
PROOF

We want to be able to write LHS as

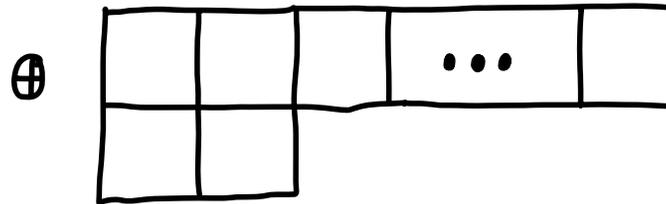
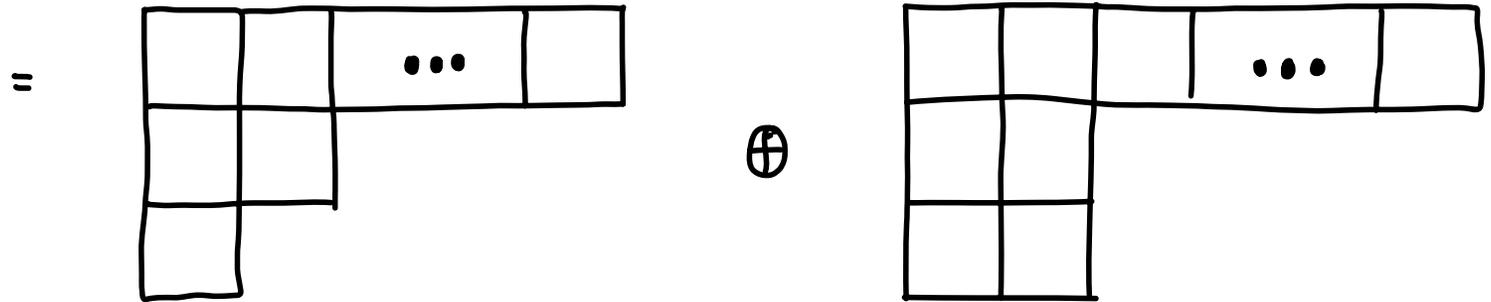
$$(S \otimes \tilde{R})_{i_1 \dots i_n a i_{n+1} i_{n+2} b} \equiv S_{i_1 \dots i_n} \tilde{R}_{a i_{n+1} i_{n+2} b}$$

totally symmetric tensor

which you can see by expressing it to the Young Tableau



[H. Georgi; *Front Phys* 54
(1999) 1-320]



Then $\left(\begin{array}{cccc} & & & \dots & \\ & & & & \\ & & & & \end{array} \right) \eta^i \dots \eta^{in} = 0$
etc.

$$\left(\begin{array}{|c|c|c|c|} \hline & & & \dots \\ \hline & & & \\ \hline \end{array} \right) \eta^{i_1} \dots \eta^{i_n} \neq 0 \text{ and so}$$

$$\nabla_{i_1} \nabla_{i_2} \dots \nabla_{i_n} R_{a_{i_{n+1}} i_{n+2}} \Big|_{\theta=0} \eta^{i_1} \dots \eta^{i_{n+2}} = (S \otimes \bar{R})_{i_1 \dots i_n a_{i_{n+1}} i_{n+2} b} \eta^{i_1} \dots \eta^{i_{n+2}}$$

$$= S_{i_1 \dots i_n} \bar{R}_{a_{i_{n+1}} i_{n+2} b} \eta^{i_1} \dots \eta^{i_{n+2}}$$

Isotropic

properties



$$= \delta_{i_1 i_2} \delta_{i_3 i_4} \dots \delta_{i_{n-1} i_n} \tilde{R}_{a_{i_{n+1}} i_{n+2} b} \eta^{i_1} \dots \eta^{i_{n+2}}$$

as we wanted!

"RR-reduction"

$$\begin{aligned}\tilde{R}_{ajc} \tilde{R}_{kcb} \eta^i \eta^j \eta^k \eta^l &= (\delta_{aj} \delta_{ic} - \delta_{ij} \delta_{ac}) (\delta^c{}_i \delta_{kb} - \delta^c{}_b \delta_{kc}) \eta^i \eta^j \eta^k \eta^l \\ &= \underbrace{[\delta_{aj} (\delta_{ic} \delta_{kb} - \delta_{ib} \delta_{kc}) - \delta_{ij} (\delta_{ac} \delta_{kb} - \delta_{ab} \delta_{kc})]}_{\rightarrow 0 \text{ from symmetrisation}} \eta^i \eta^j \eta^k \eta^l\end{aligned}$$

$\rightarrow 0$ from symmetrisation

$$= -\delta_{ij} [\delta_{ac} \delta_{kb} - \delta_{ab} \delta_{kc}] \eta^i \eta^j \eta^k \eta^l$$

$$= -\delta_{ij} \tilde{R}_{akcb} \eta^i \eta^j \eta^k \eta^l$$

Symmetric Point Metric

- $$\nabla_{i_1} \dots \nabla_{i_n} \bar{R}_{a_{i_{n+1}} i_{n+2} b} \eta^{i_1} \dots \eta^{i_{n+2}} = \begin{cases} 0 & \text{for odd } n \\ \delta_{i_1 i_2} \dots \delta_{i_{n-1} i_n} \tilde{R}_{a_{i_{n+1}} i_{n+2} b} \eta^{i_1} \dots \eta^{i_{n+2}} & \text{for even } n \end{cases}$$
- $$\nabla_{i_1} \dots \nabla_{i_n} \bar{R}_{a_{i_{n+1}} i_{n+2} b} \nabla_{i_{n+3}} \dots \nabla_{i_m} \bar{R}^b_{i_{m+1} i_{m+2} c} \eta^{i_1} \dots \eta^{i_{m+n+4}}$$

$$= \delta_{i_1 i_2} \dots \delta_{i_{m+n+1} i_{m+n+2}} \tilde{R}_{a_{i_{m+n+3}} i_{m+n+4} b} \eta^{i_1} \dots \eta^{i_{m+n+4}}$$