



# A SHORT STORY ON ARTIFICIAL INTELLIGENCE AND DEEP LEARNING

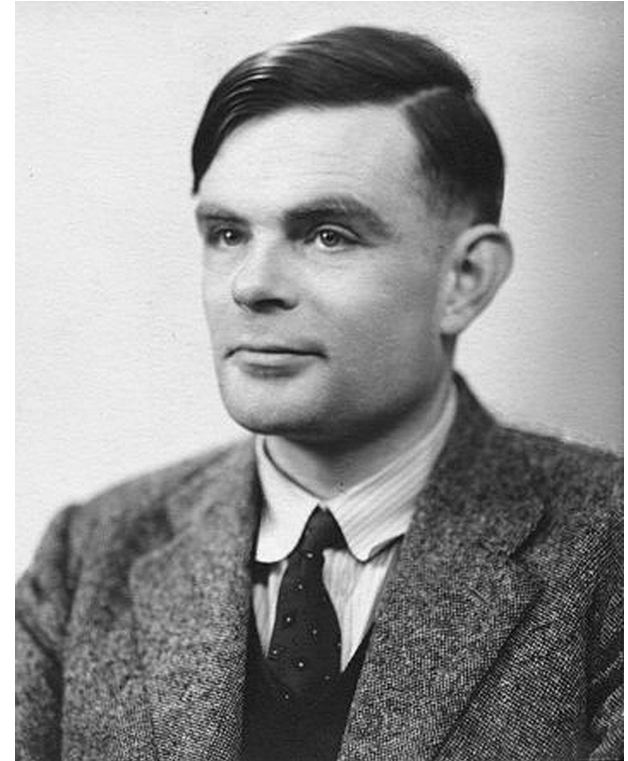
Part 1: From origins to perceptive AI

**Marc Duranton**  
Commissariat à l'énergie atomique et aux énergies alternatives

June 4<sup>th</sup>, 2025

# 1942: ALAN TURING

1942: Any form of mathematical reasoning can be made by a machine.

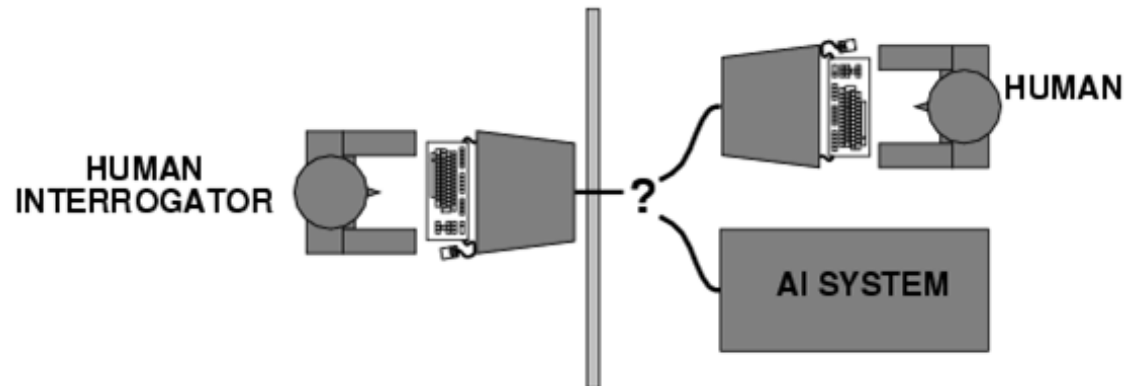
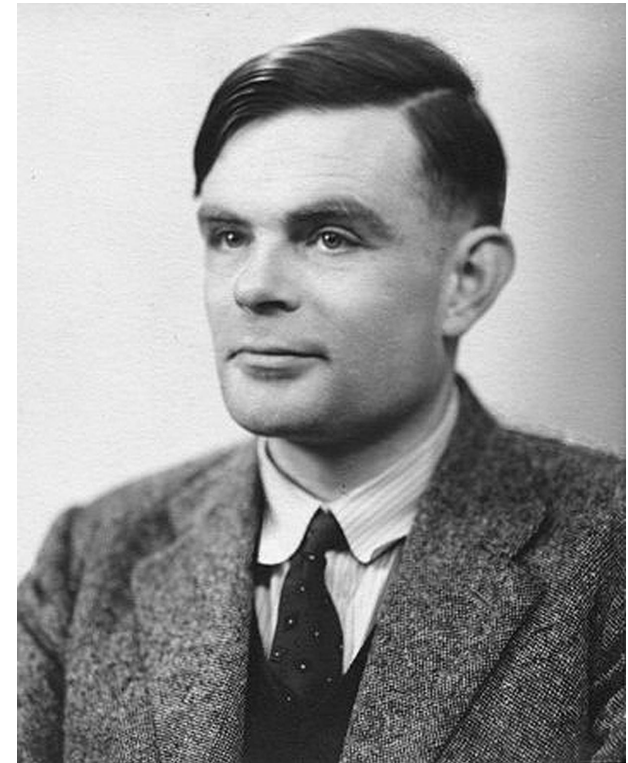




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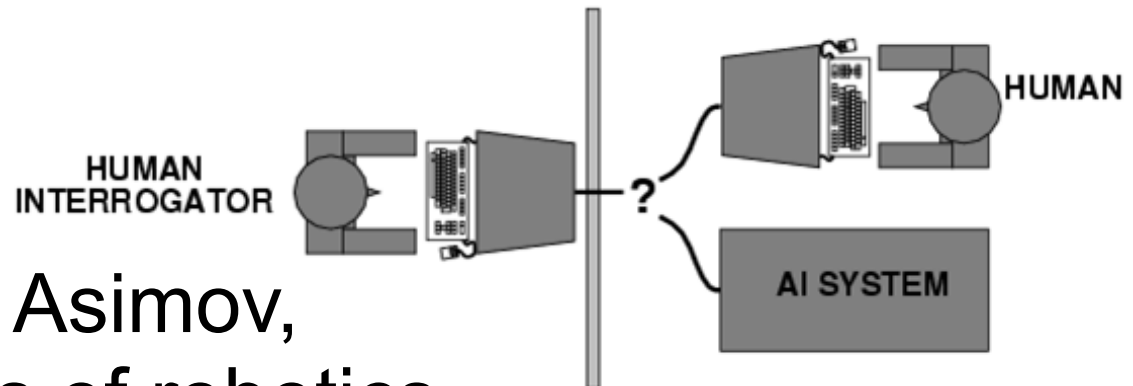
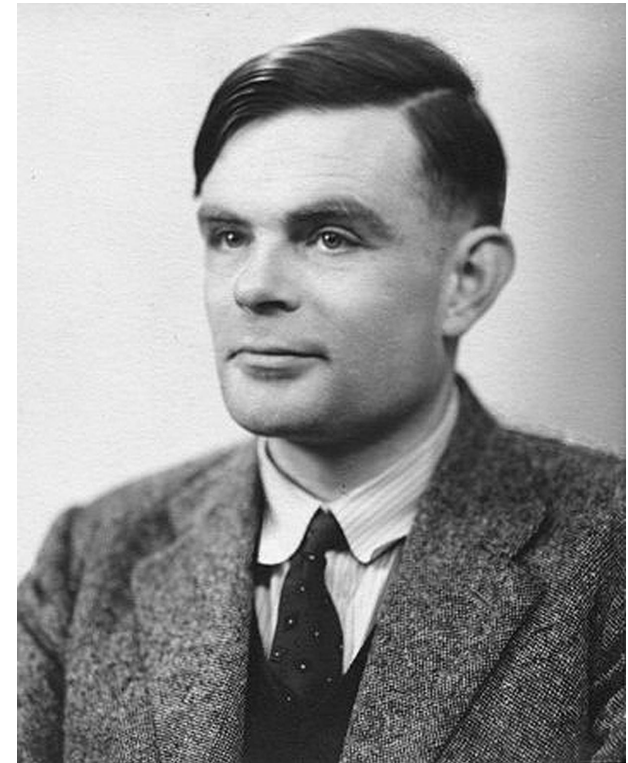
1950: He invented the “Turing test” to check if a system is “intelligent”, i.e. undisguisable from a human



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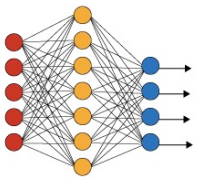
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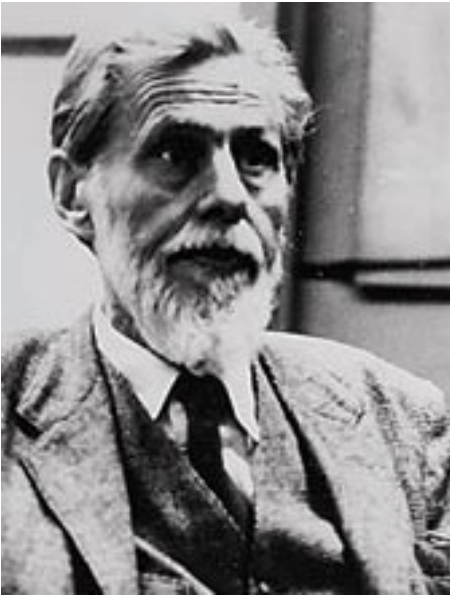


The same year, Isaac Asimov, invented the 3 (4) laws of robotics

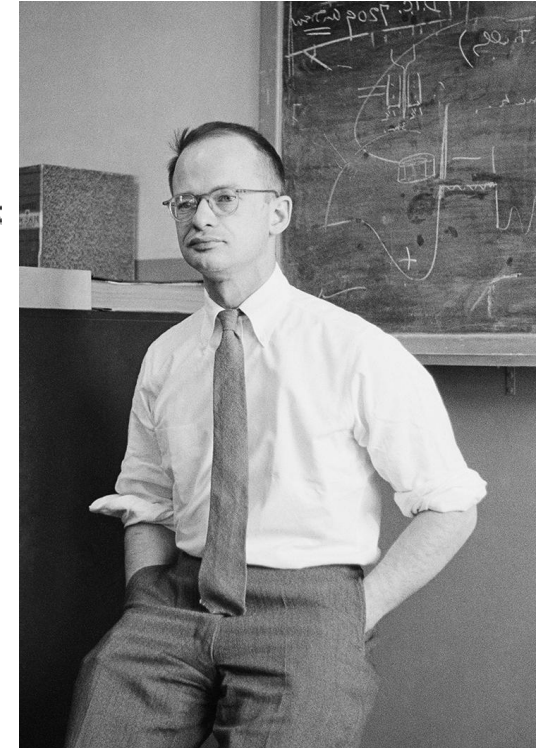
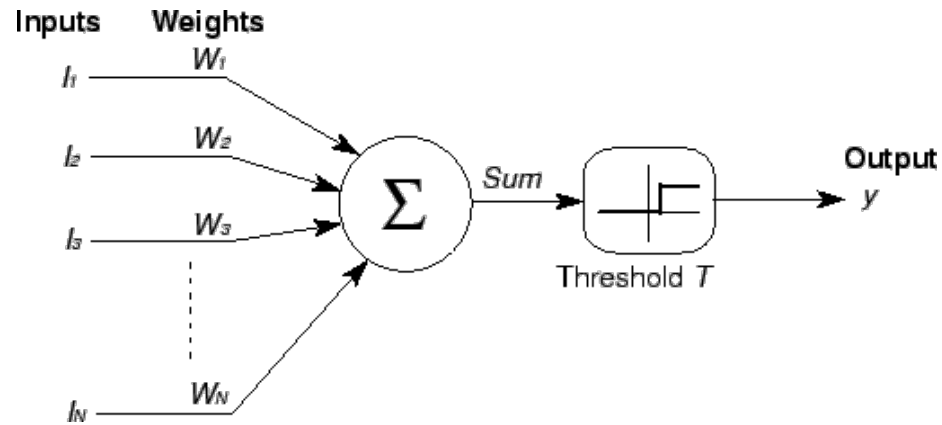




# 1943: MCCULLOCH AND PITTS

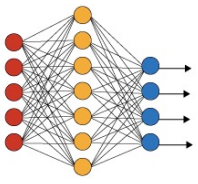


Neurophysiologist and cybernetician



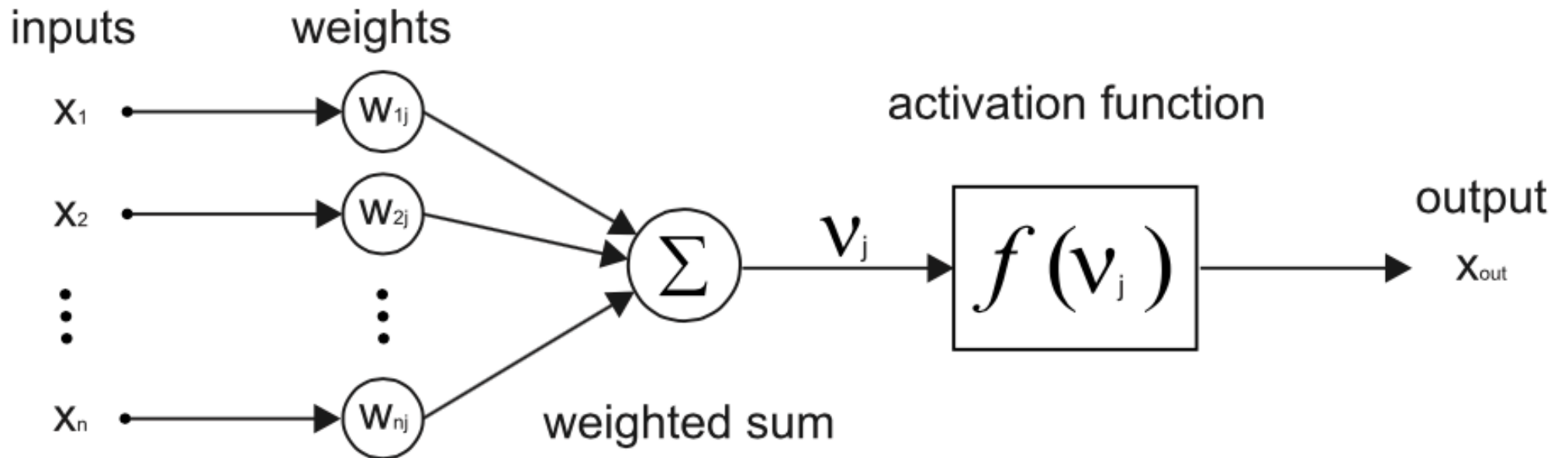
Logician working in the field of computational neuroscience

They laid the foundations of formal Neural Networks

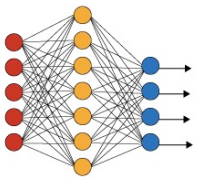


# WHAT IS A NEURAL NETWORK?

**A « formal » neuron:**

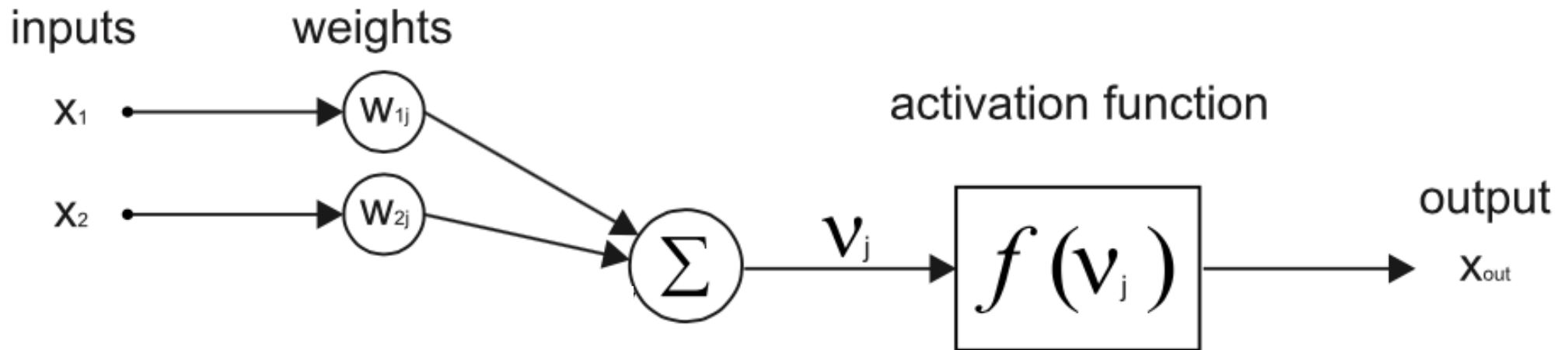






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The « formal » neuron:

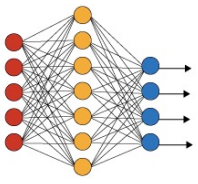


$$V_j = W_{1j} \cdot X_1 + W_{2j} \cdot X_2$$

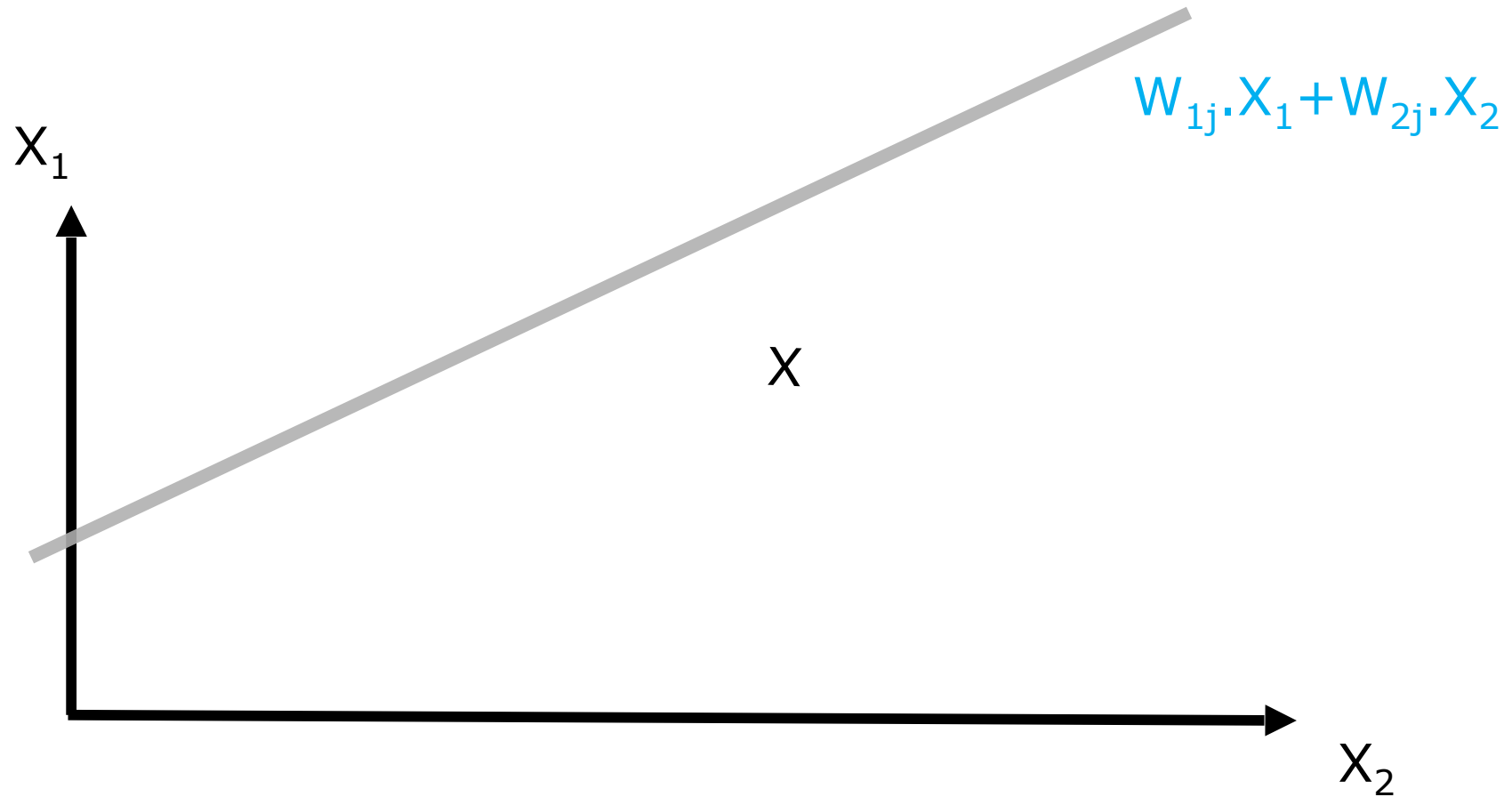
It is the definition of an hyperplane

$F(V_j)$  non linear  $\in \{-1, 1\}$  e.g. sign() function

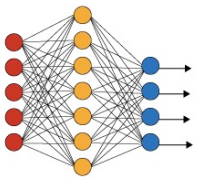
$X(X_1, X_2)$  is "above" or "below" the hyperplane



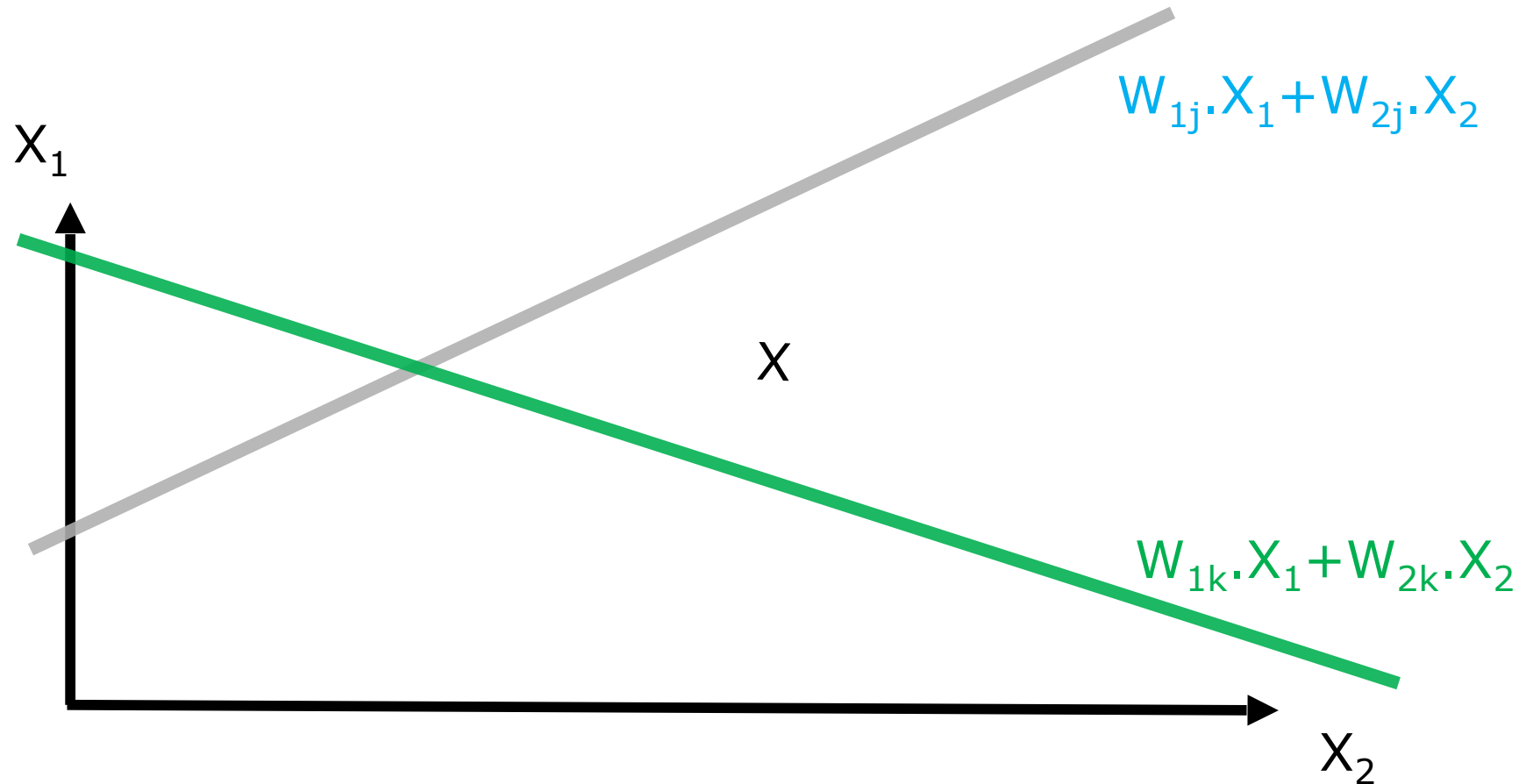
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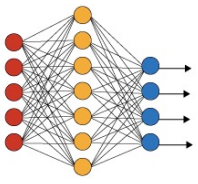




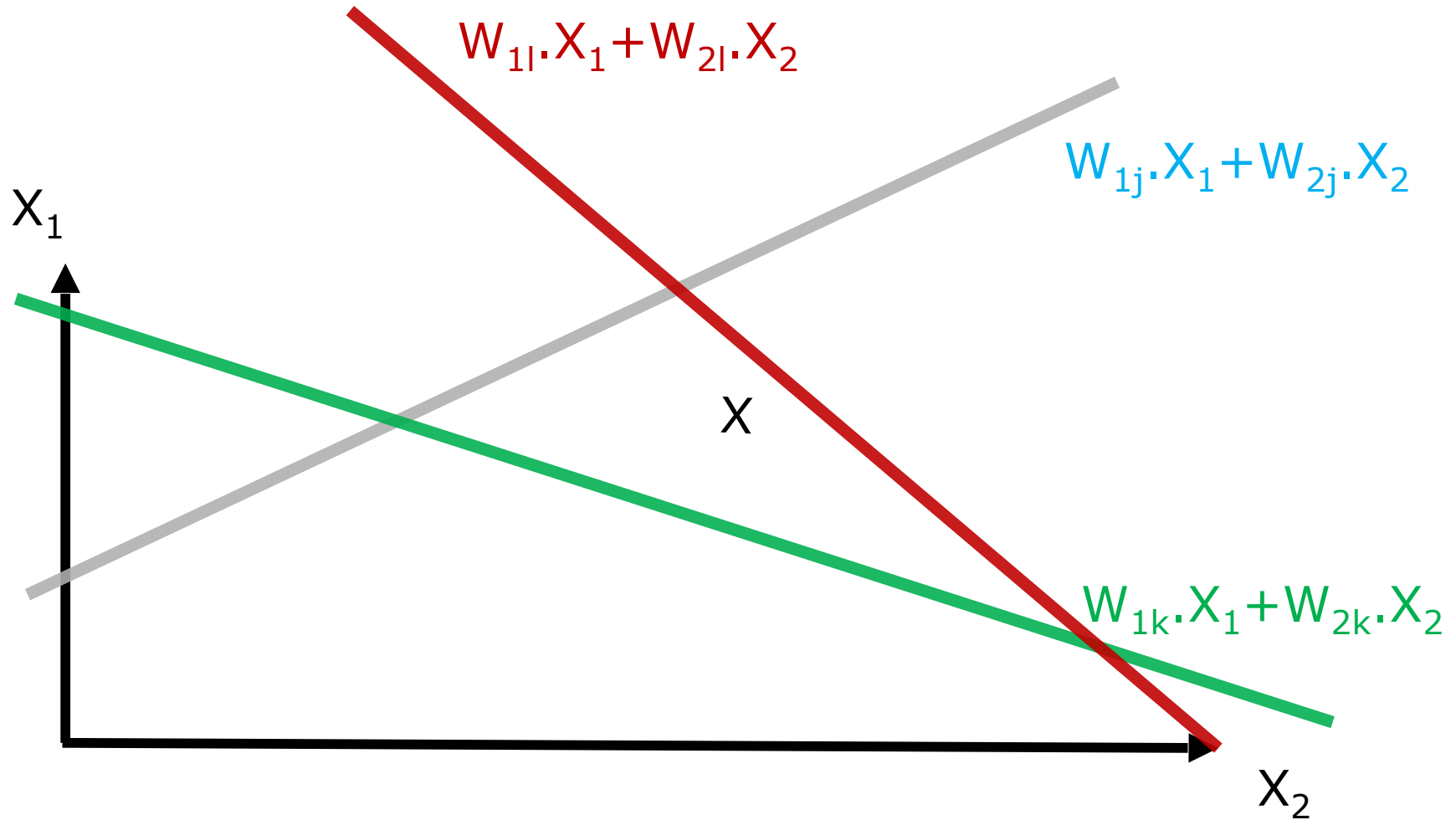


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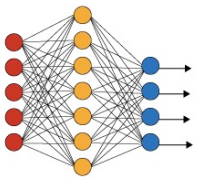




# WHAT IS A NEURAL NETWORK?







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Association of neurons to make logical functions.  
Example: AND gate

IN 1	IN 2	OUT
0	0	0
0	1	0
1	0	0
1	1	1

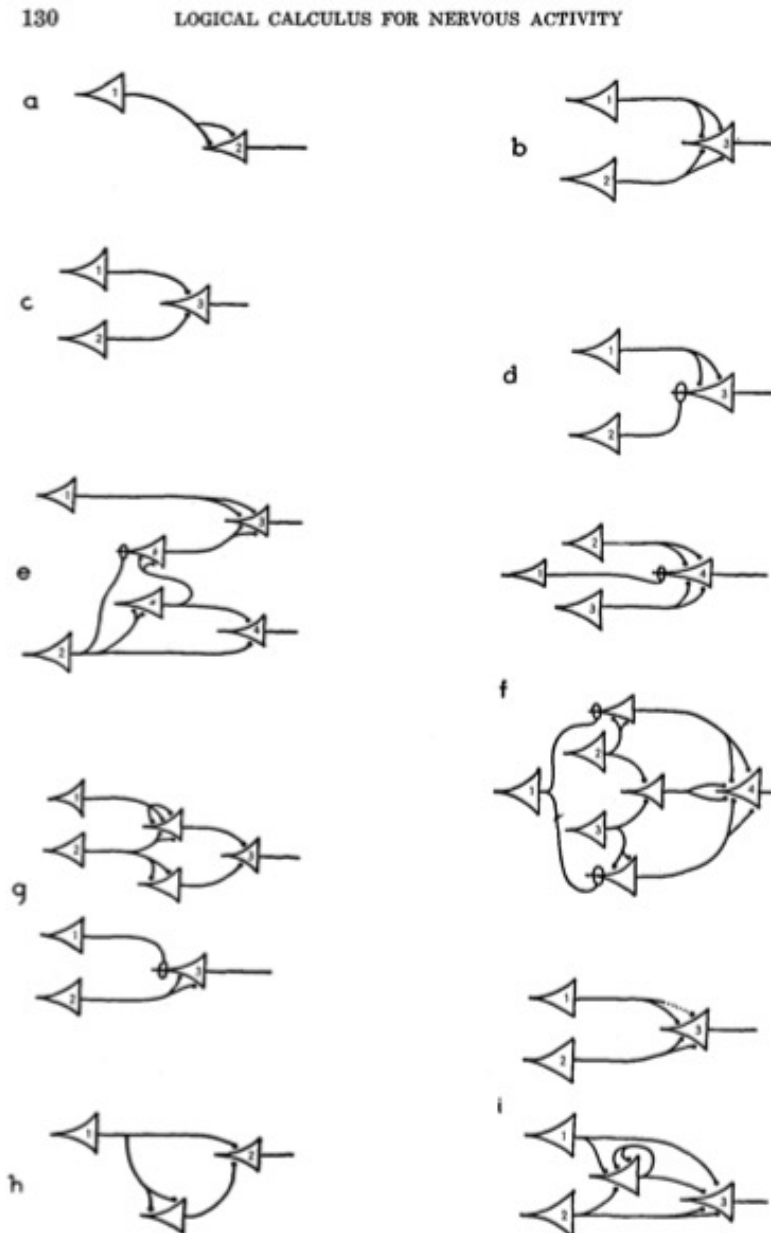
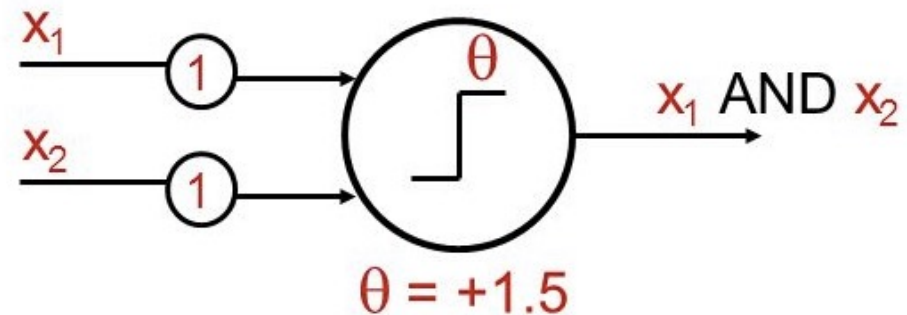
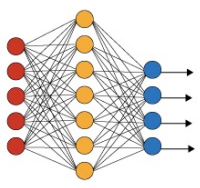
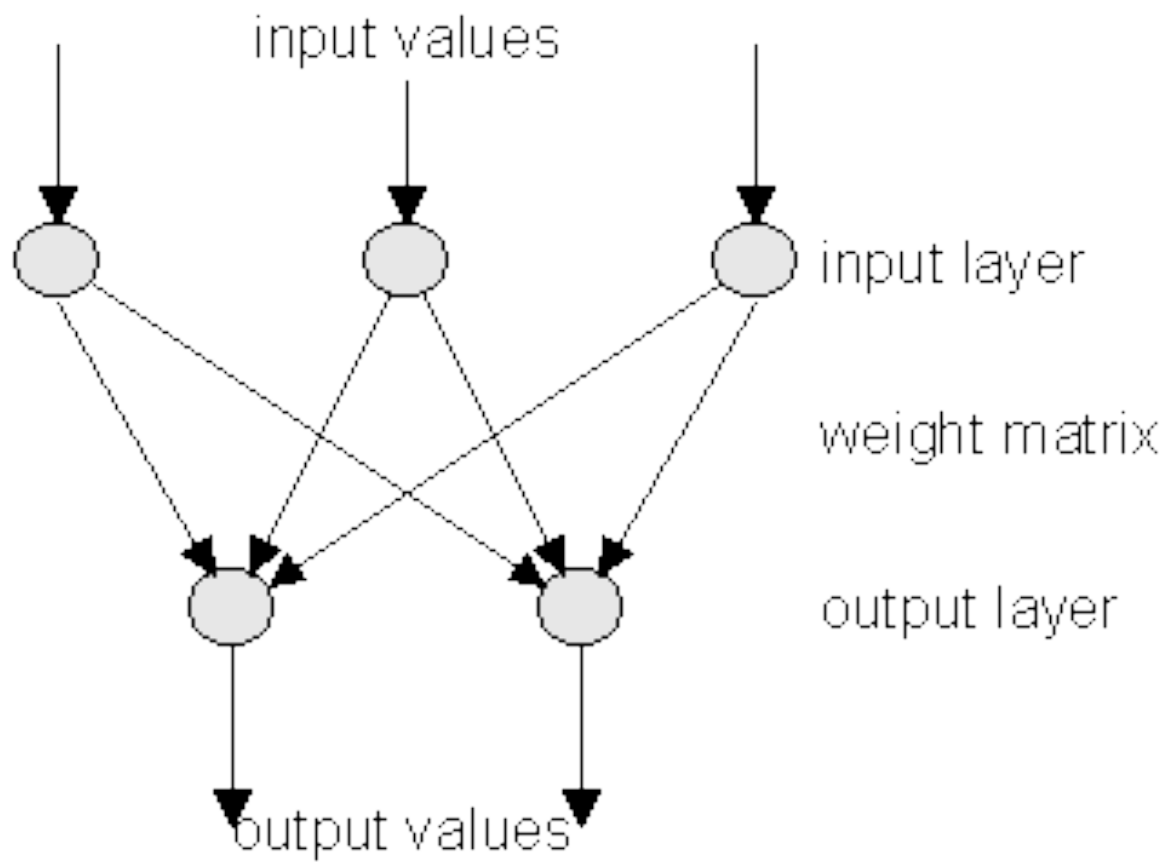
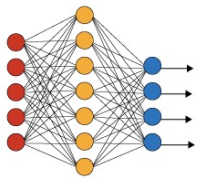


FIGURE 1

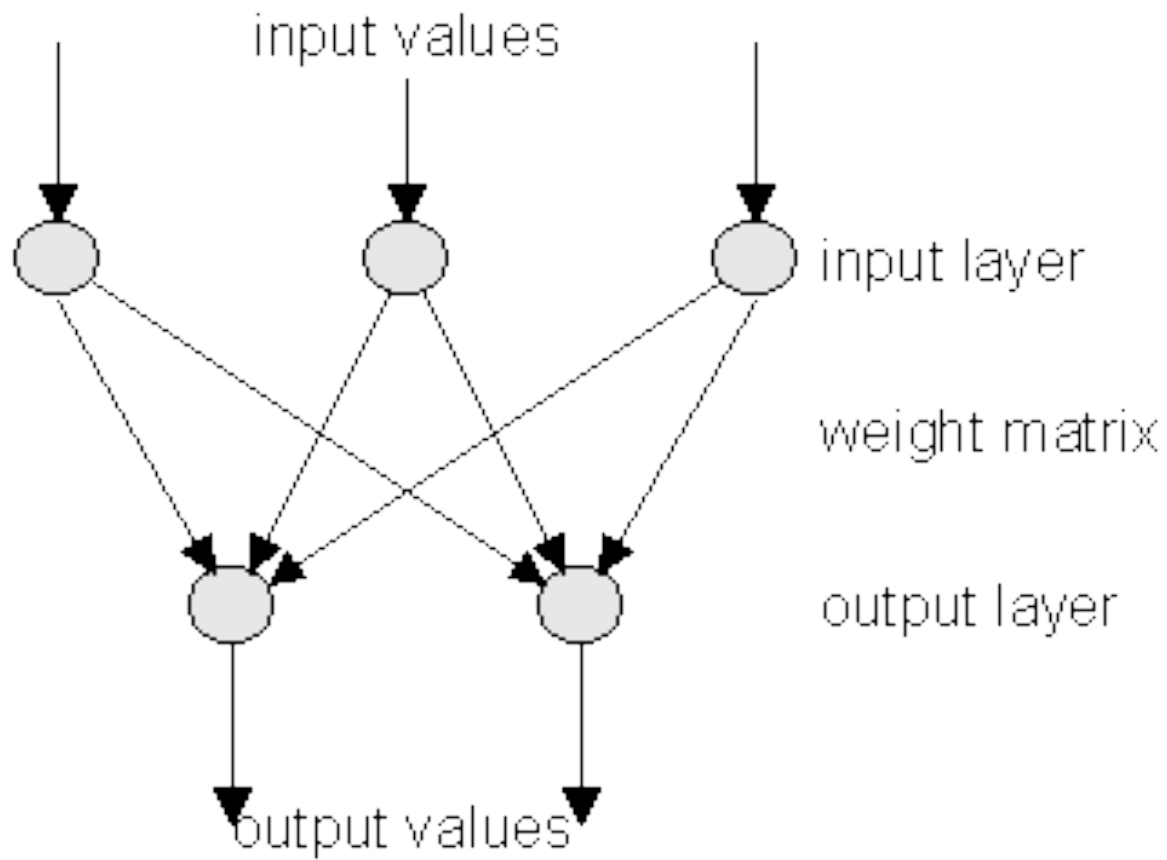


# MULTILAYER NETWORK

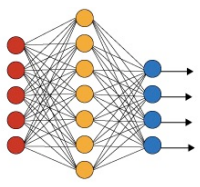




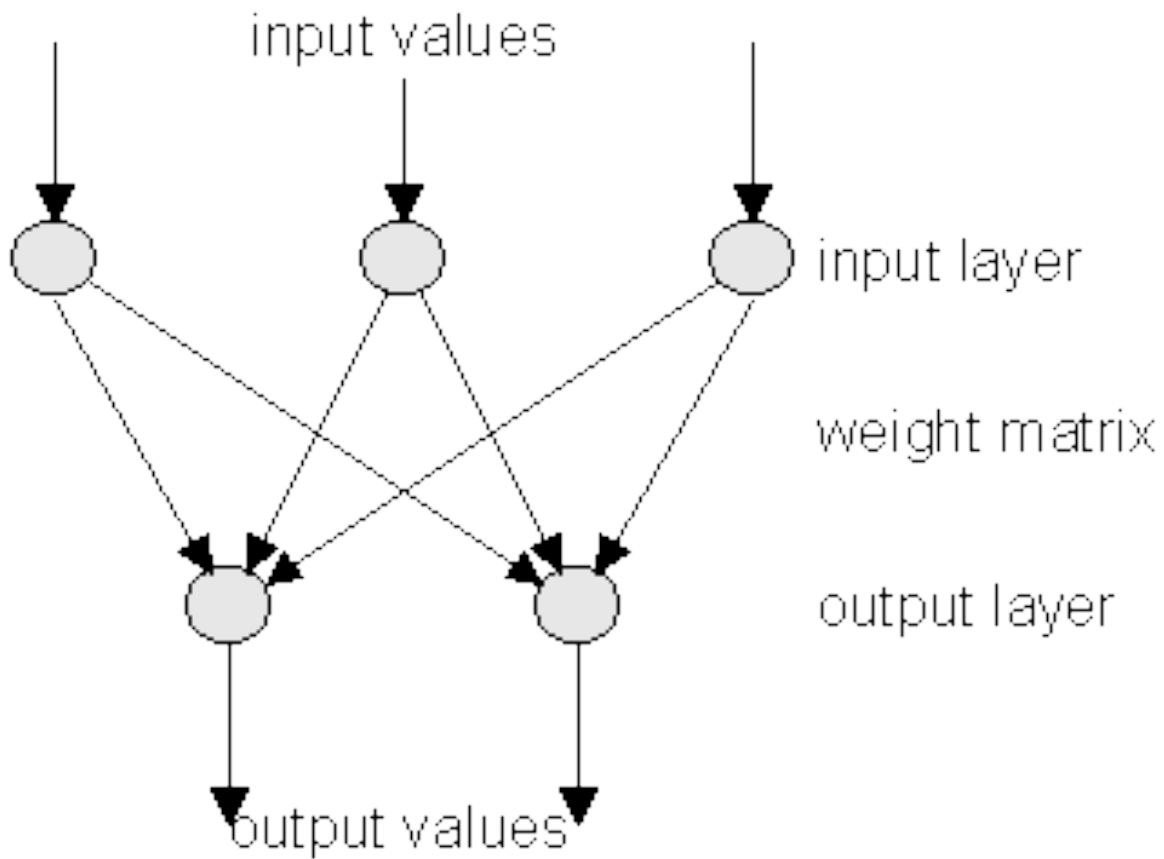
# MULTILAYER NETWORK



Hyperplane separation



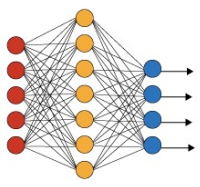
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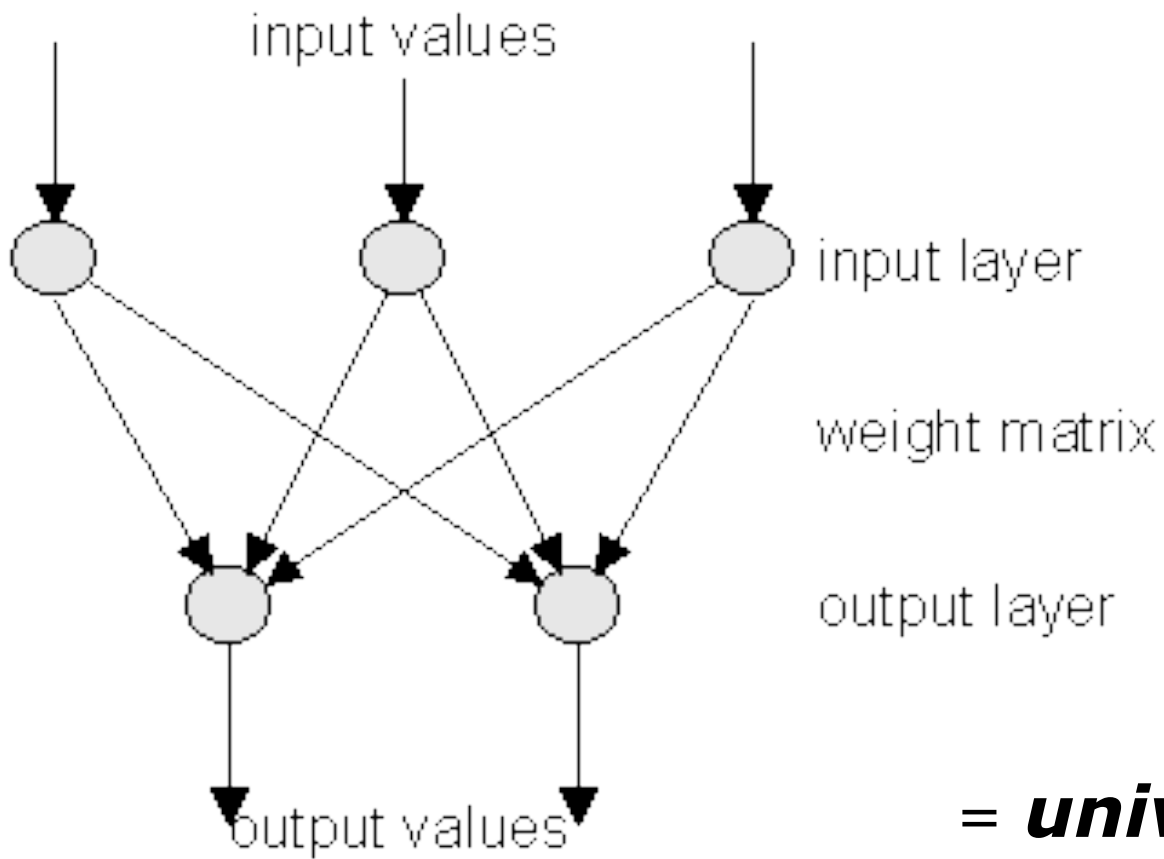
Hyperplane separation

“logic” composition  
Warren McCulloch and  
Walter Pitts, 1943





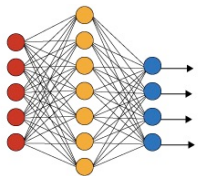
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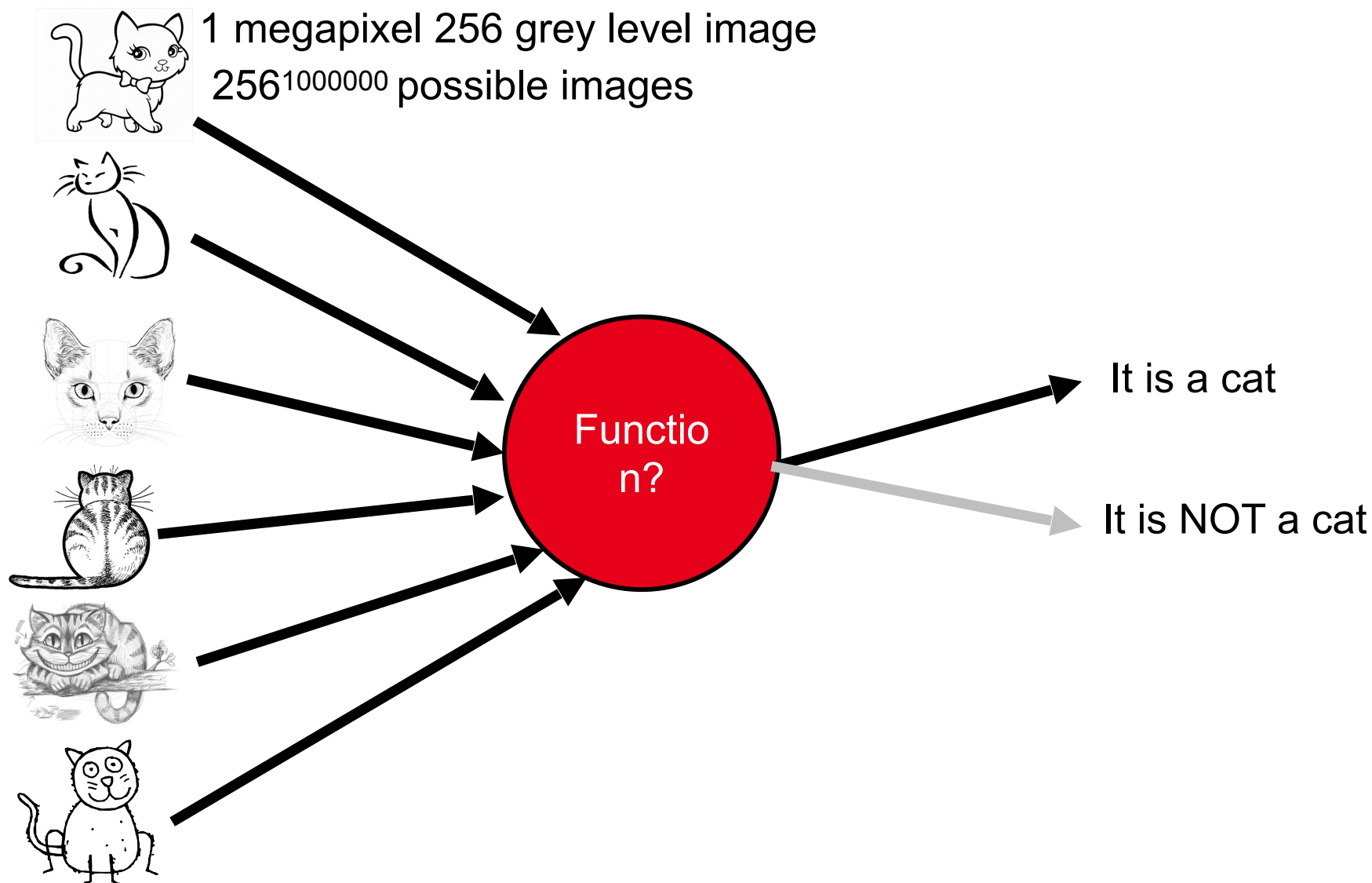
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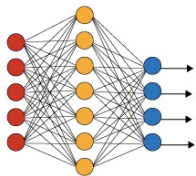
= ***universal approximator***



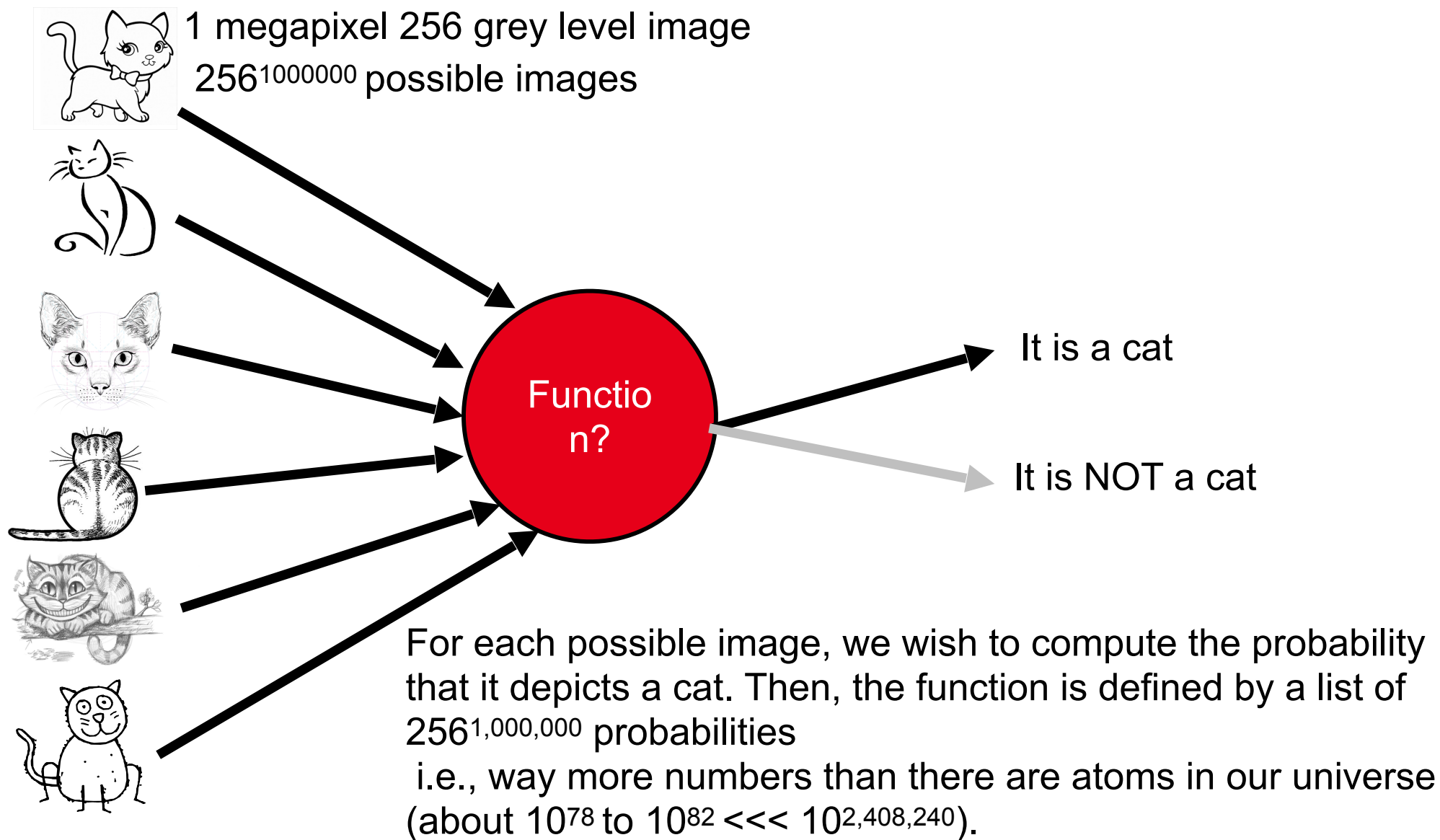
## WHY DOES DEEP LEARNING WORK SO WELL?\*



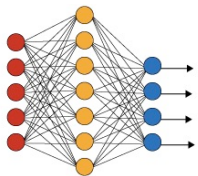
- Work of Henry W. Lin (Harvard) , Max Tegmark (MIT), and David Rolnick (MIT)  
<https://arxiv.org/abs/1608.08225>



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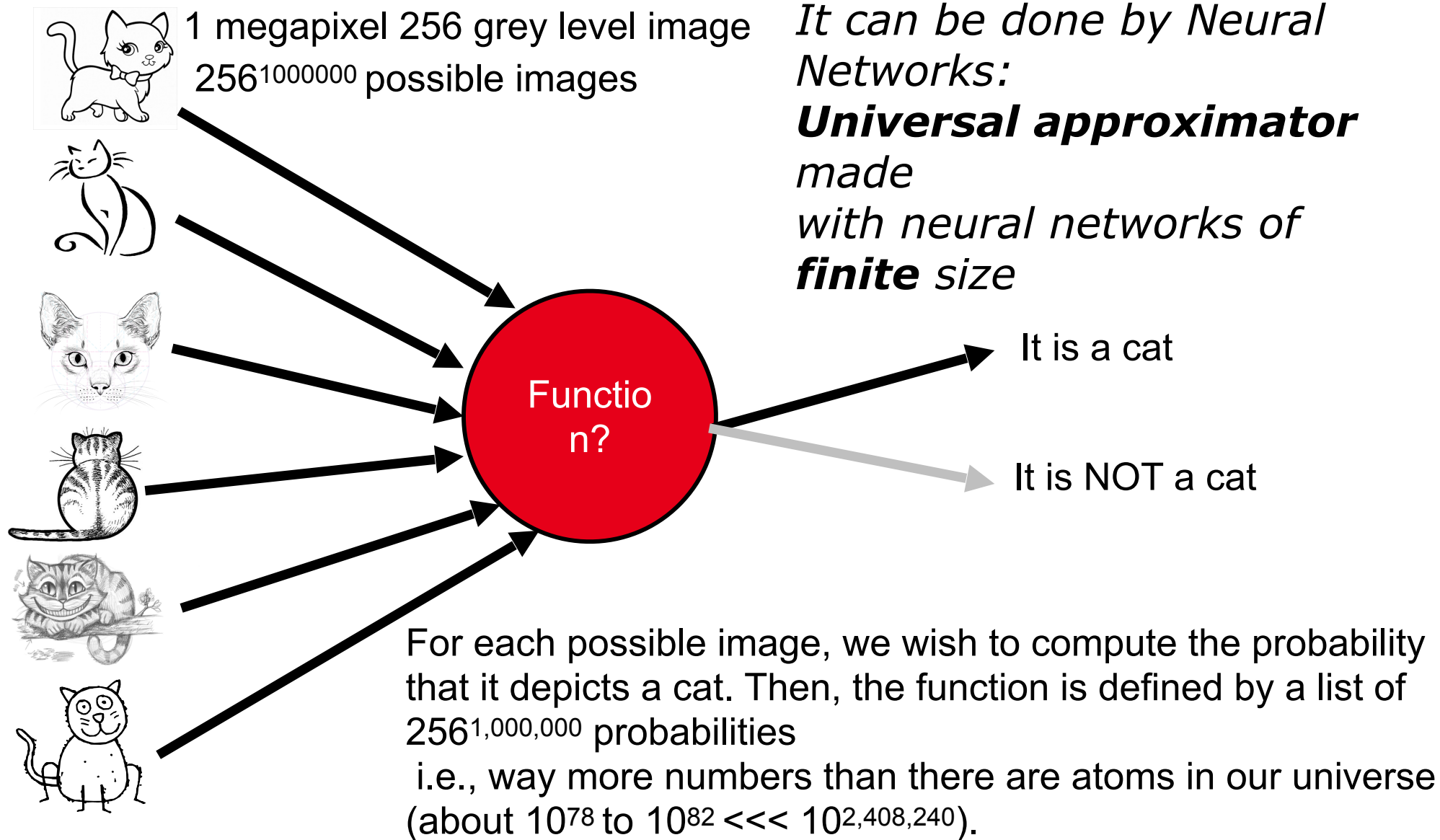


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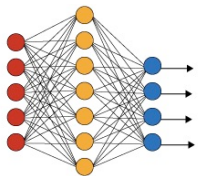


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*It can be done by Neural Networks:  
**Universal approximator**  
made  
with neural networks of  
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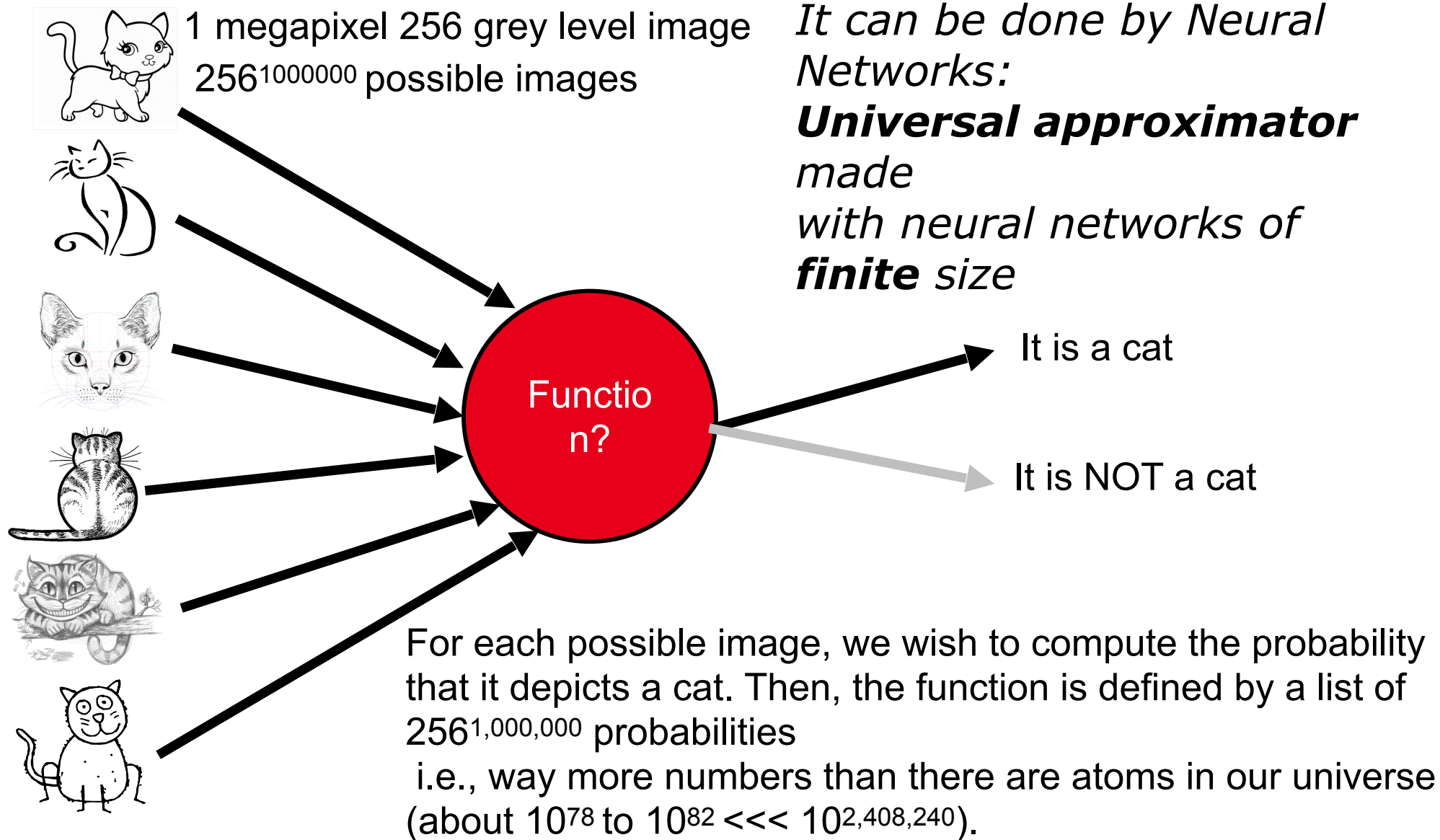


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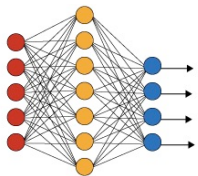
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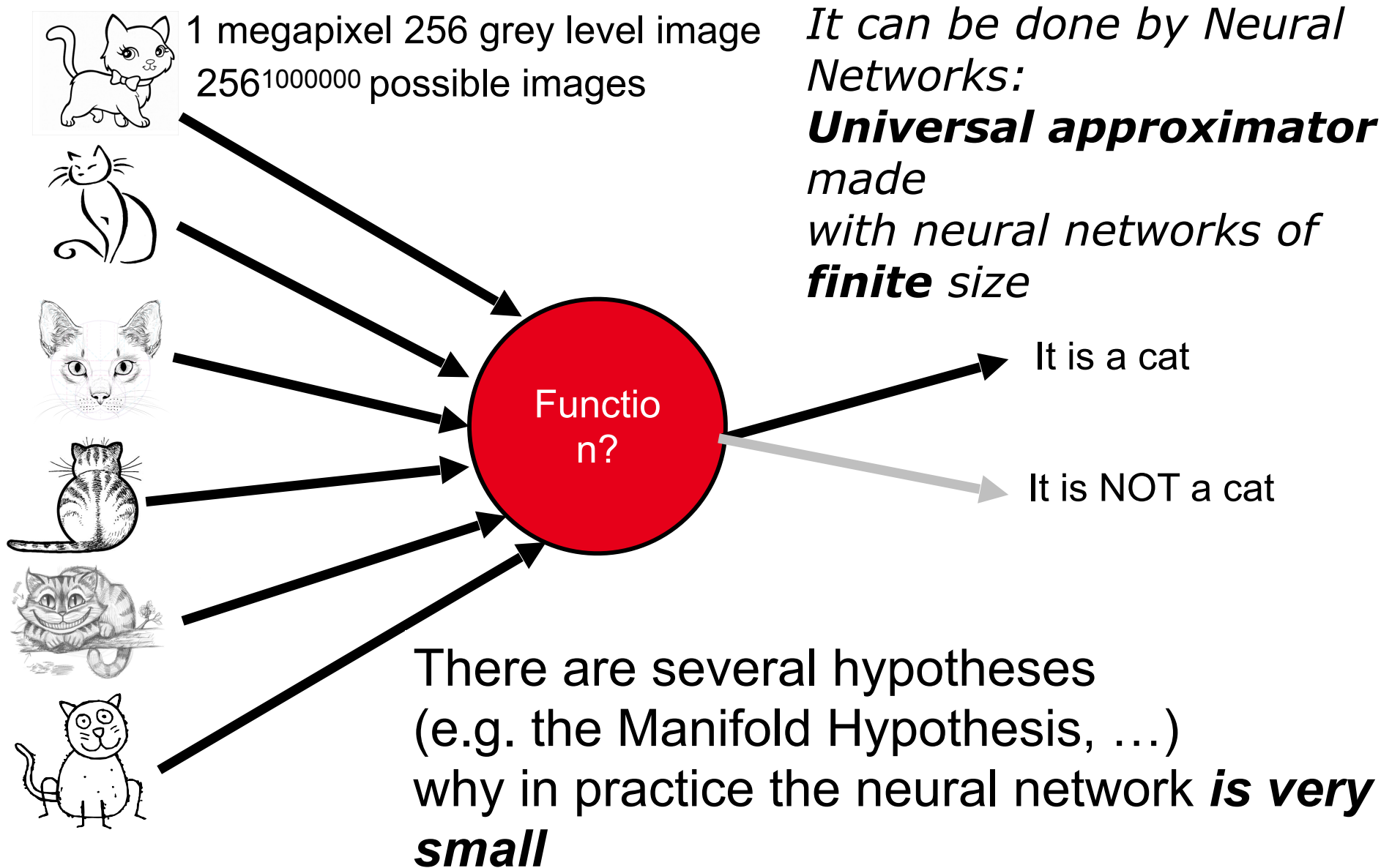


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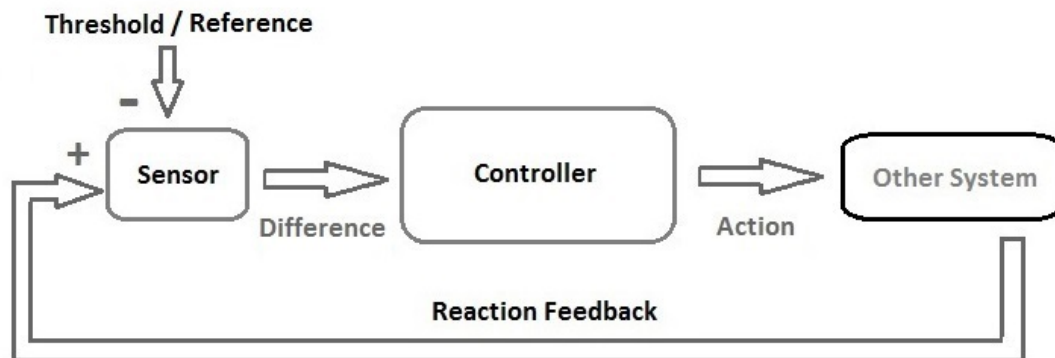
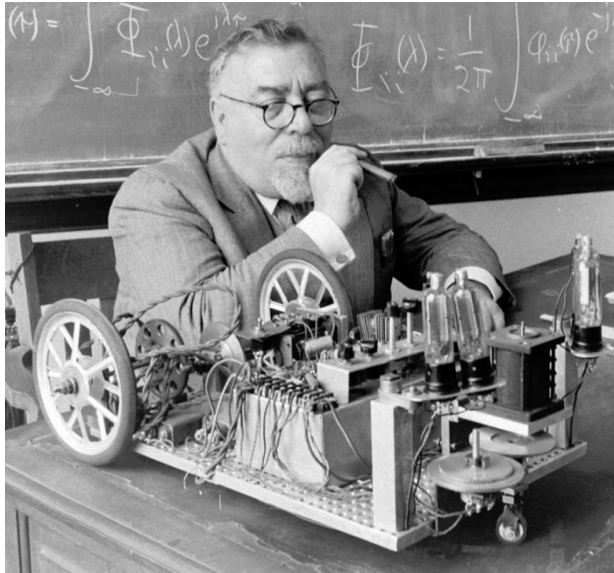


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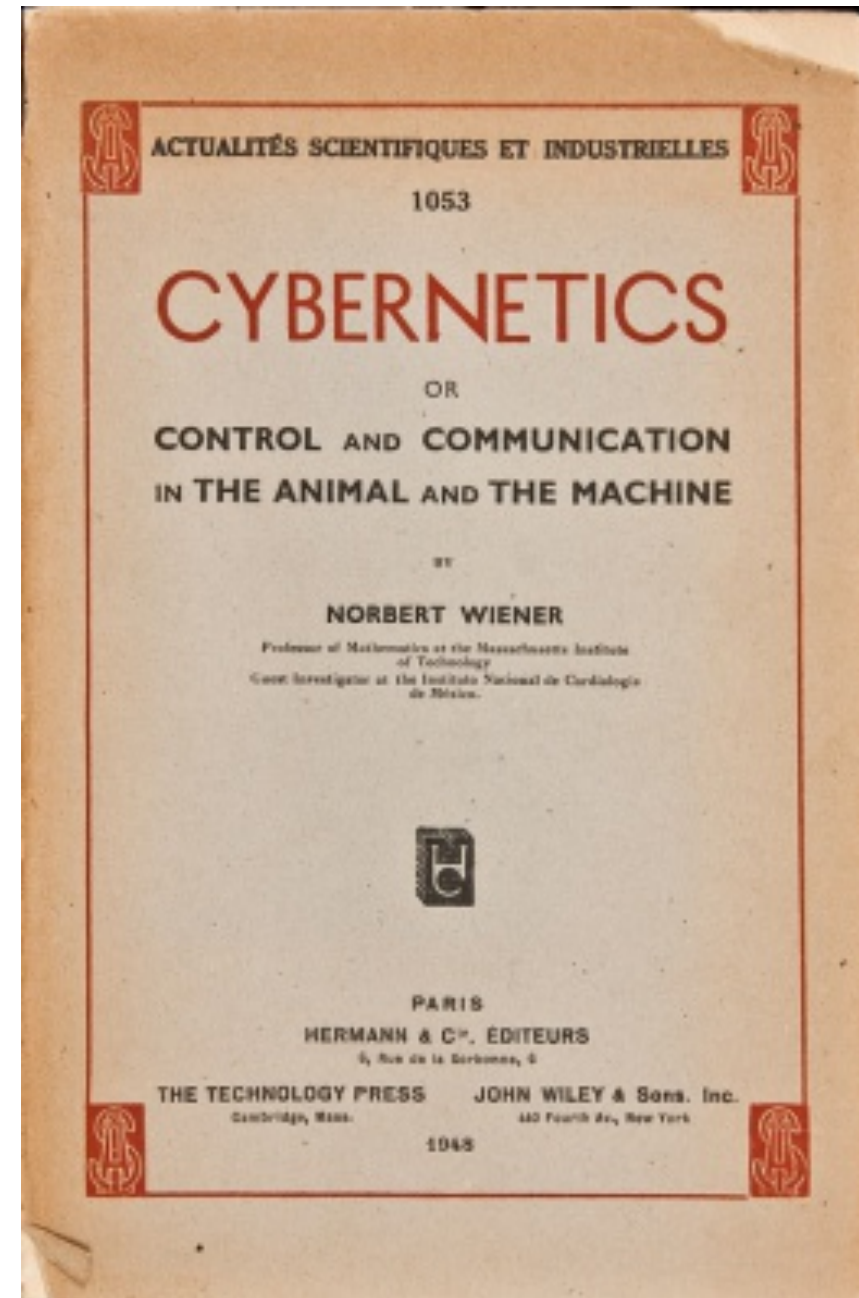


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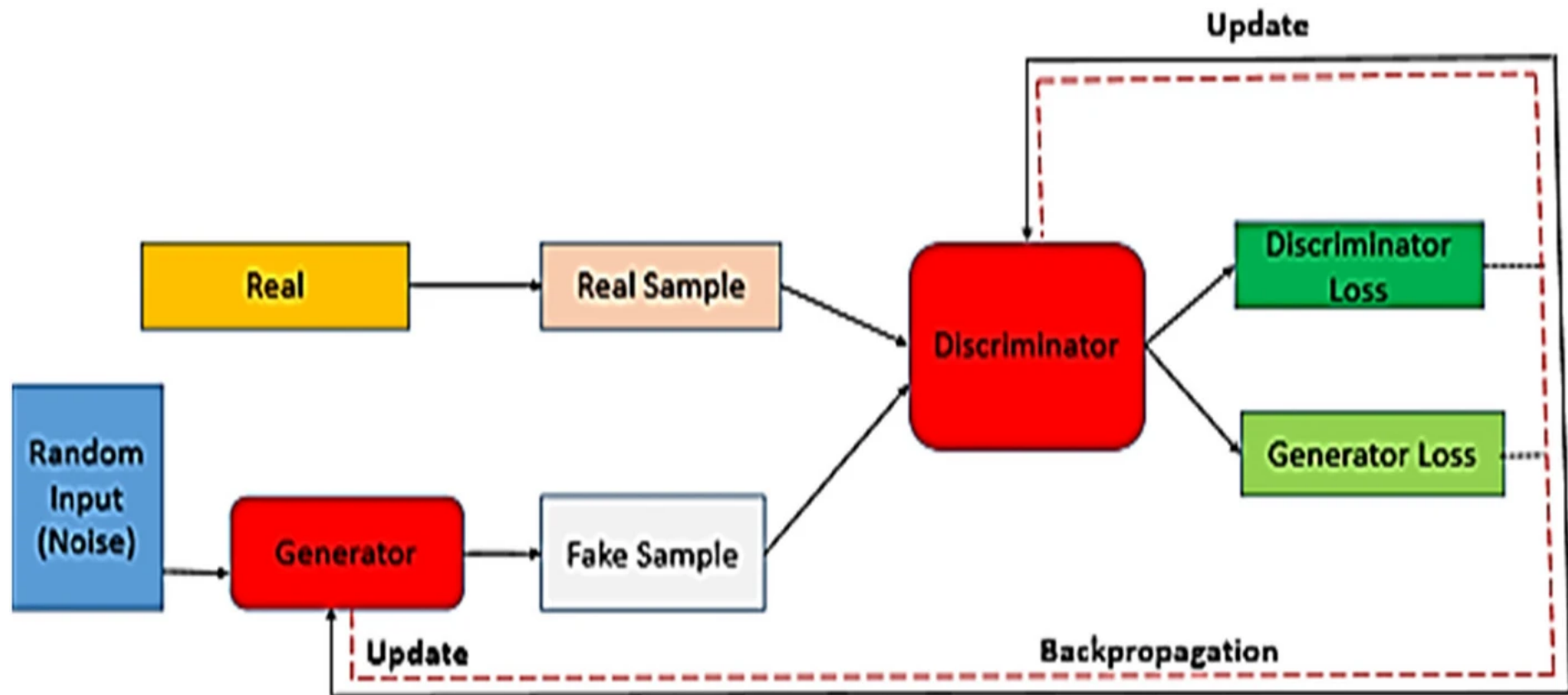
## 1948: NORBERT WIENER



**A Cybernetic Loop**

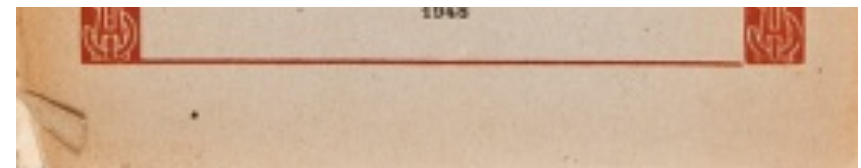


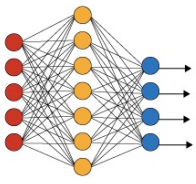
## 1948: NORBERT WIENER



Basic Generative adversarial networks (GAN)  
from <https://link.springer.com/article/10.1007/s11042-024-18767-y>

**A Cybernetic Loop**

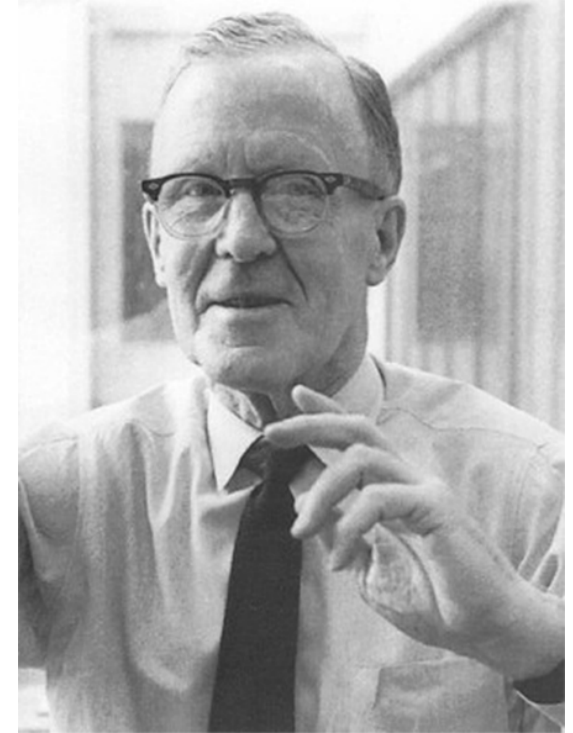




1949: DONALD HEBB

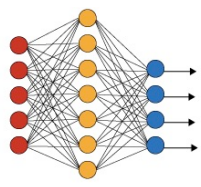
Hebb's rule or Hebbian theory: an explanation for the adaptation of neurons in the brain during the learning process

**Basic mechanism for synaptic plasticity:** an increase in synaptic efficacy arises from the presynaptic cell's repeated and persistent stimulation of the postsynaptic cell.

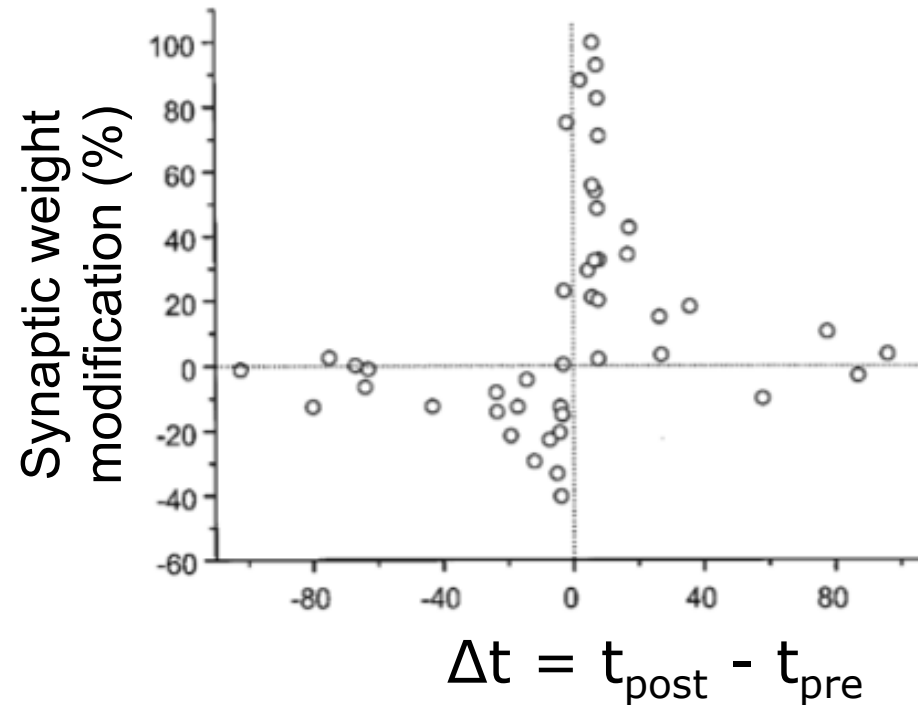
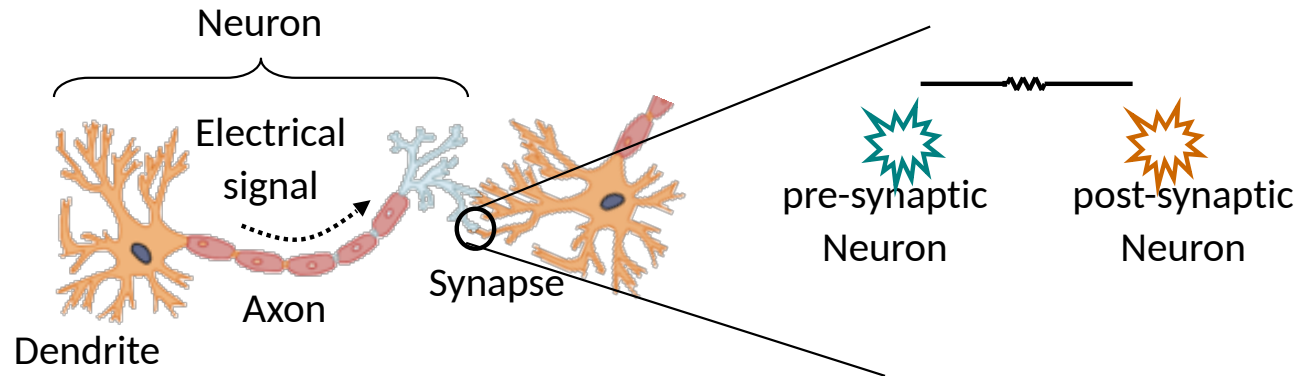


Psychologist, working in the area of neuropsychology

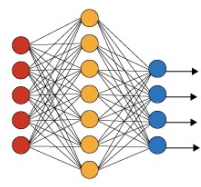
Introduced by Donald Hebb in his 1949 book « *The Organization of Behavior* »



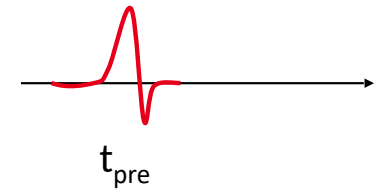
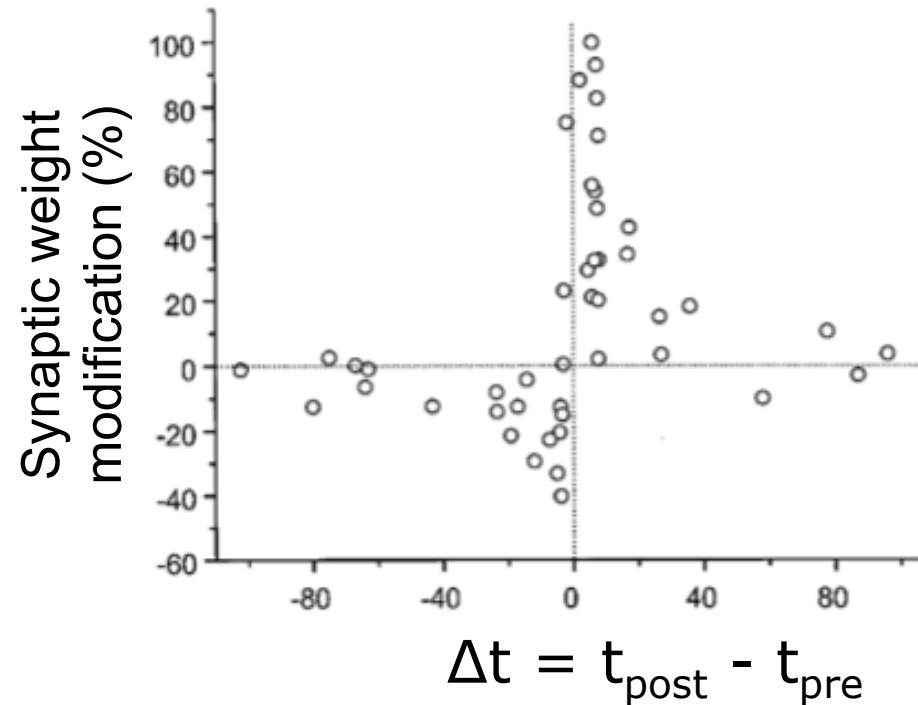
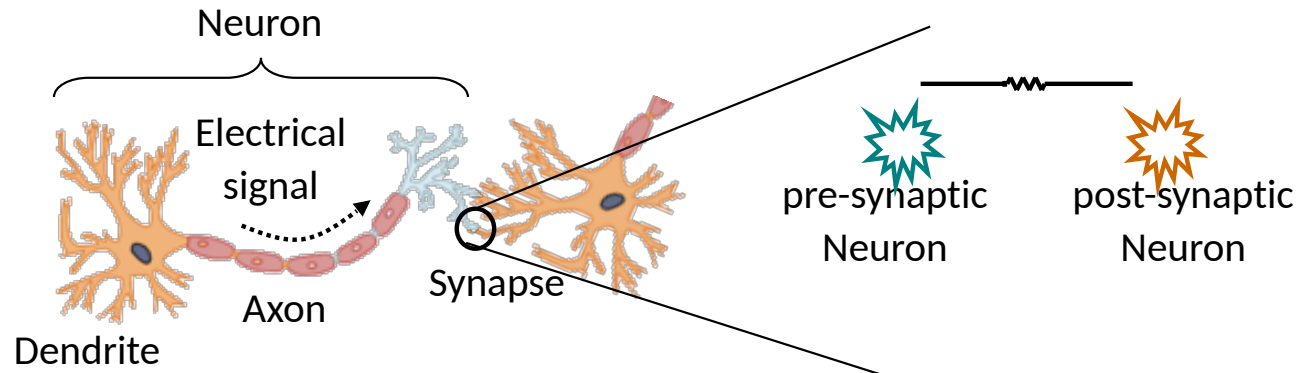
# DERIVED FROM HEBB'S RULE: STDP (SPIKE TIMING DEPENDENT PLASTICITY)

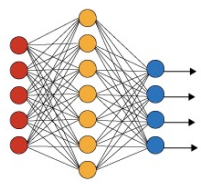




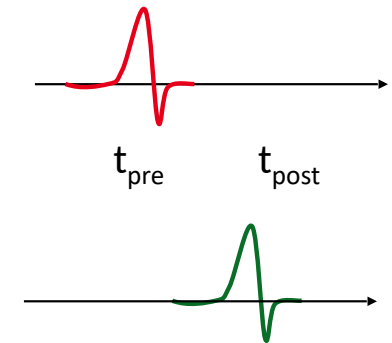
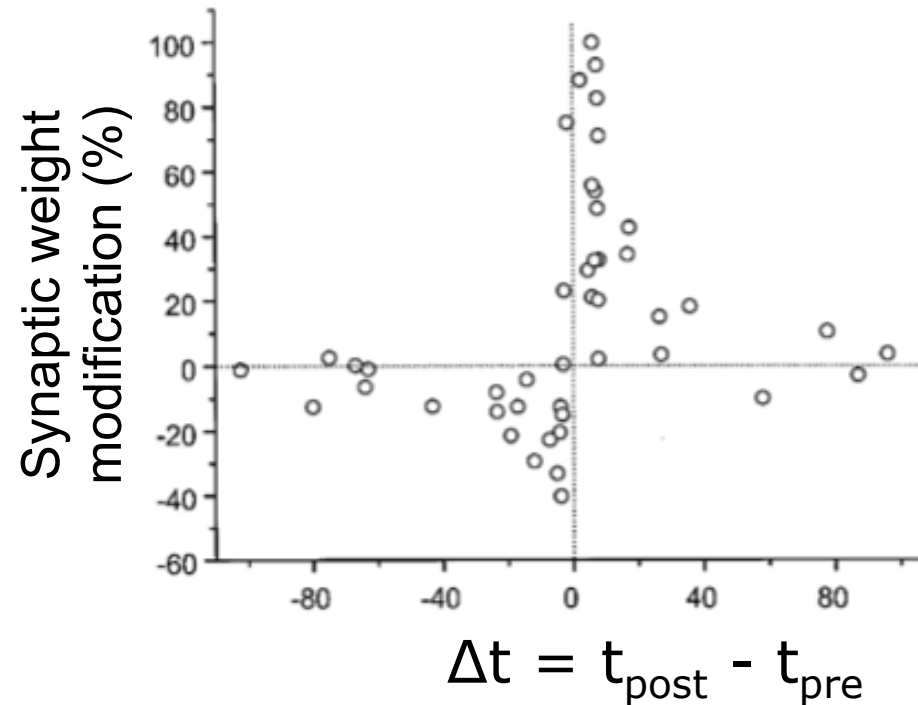
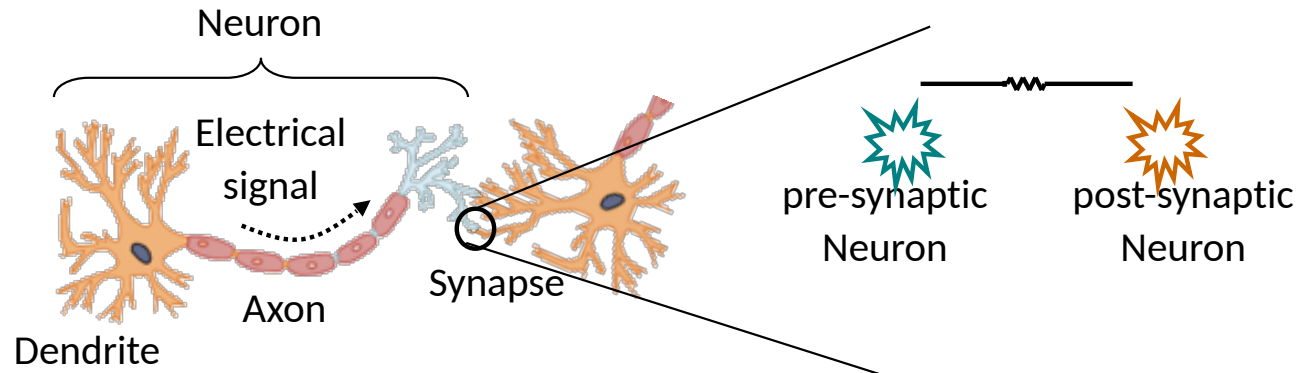


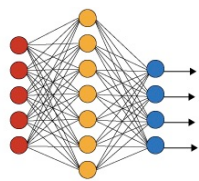
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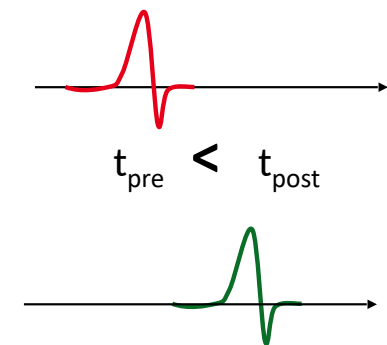
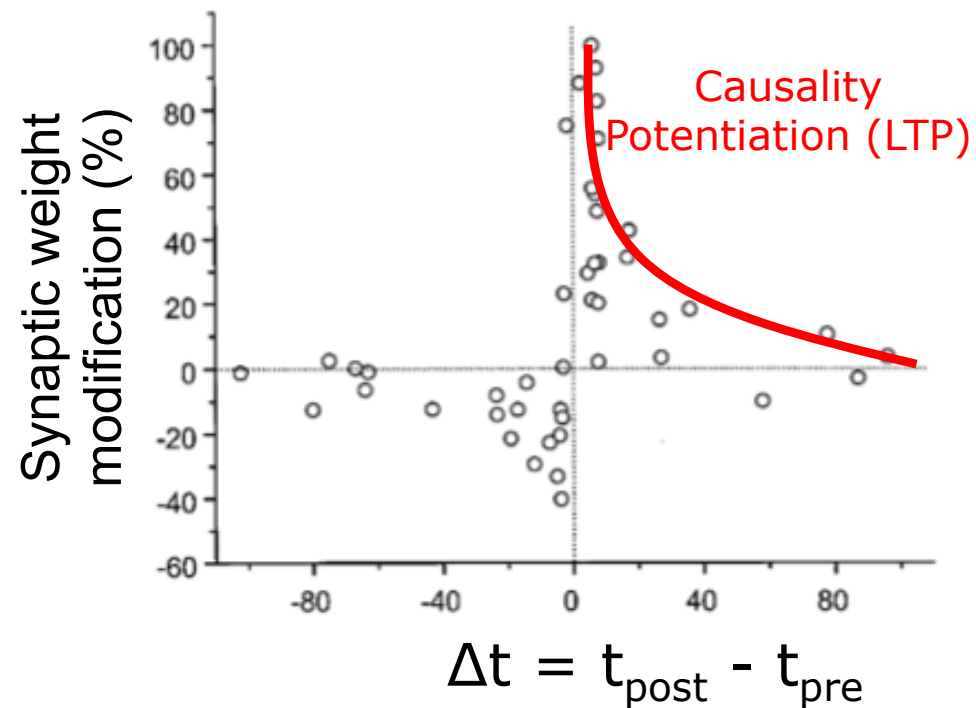
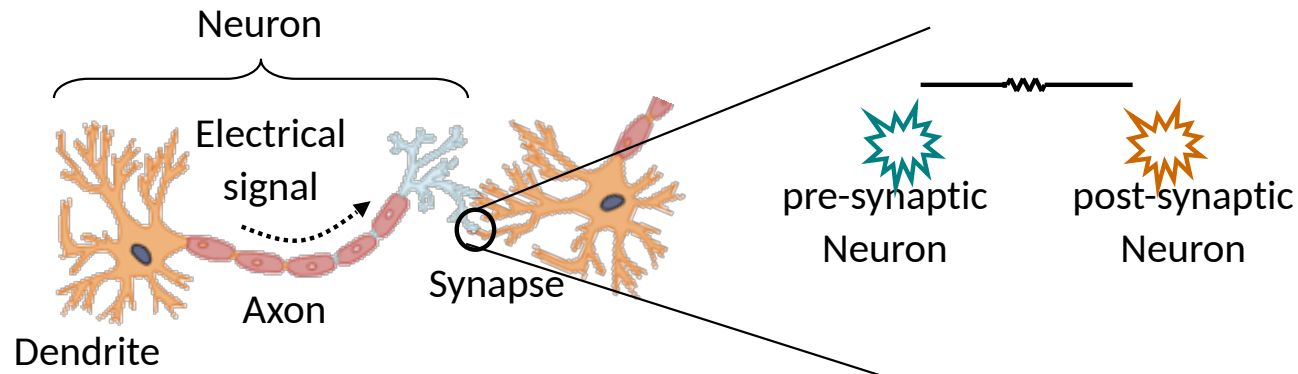


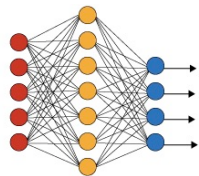
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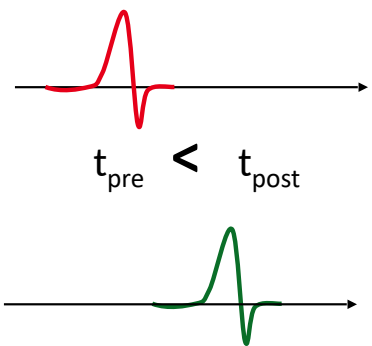
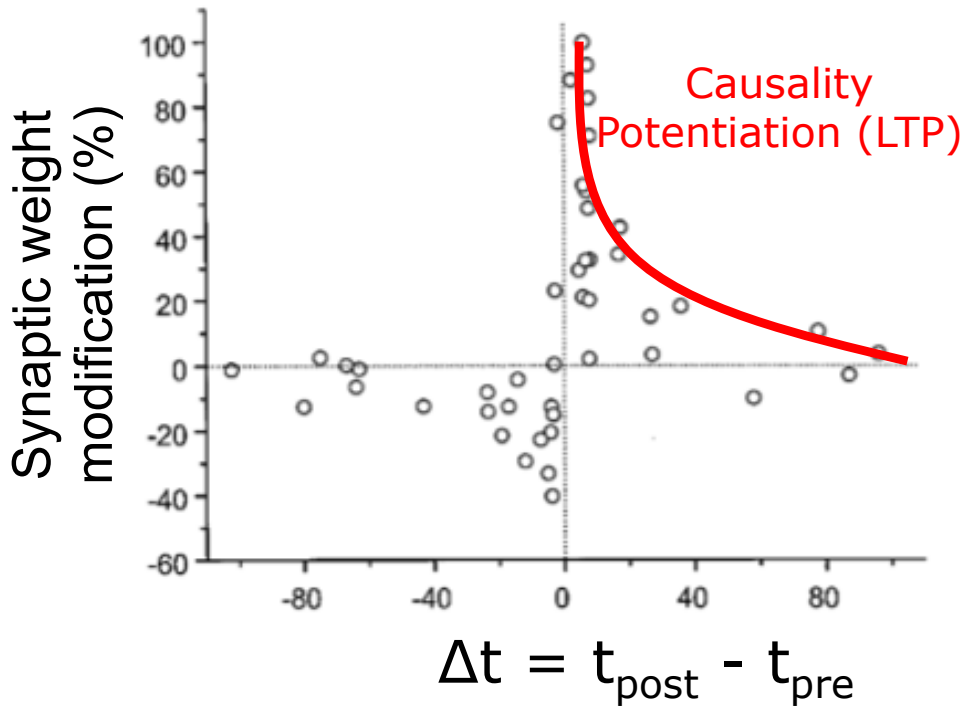
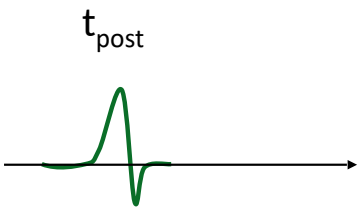
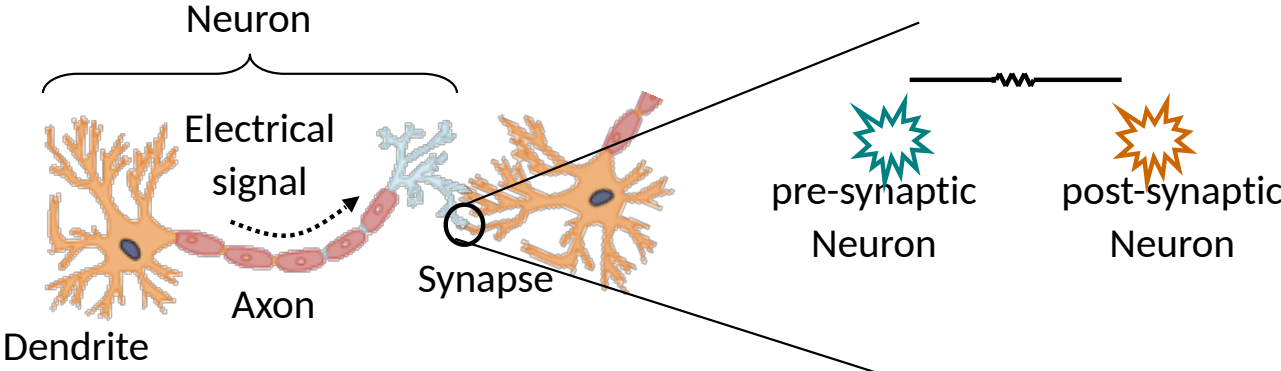


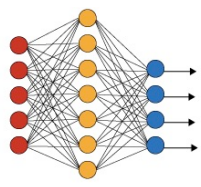
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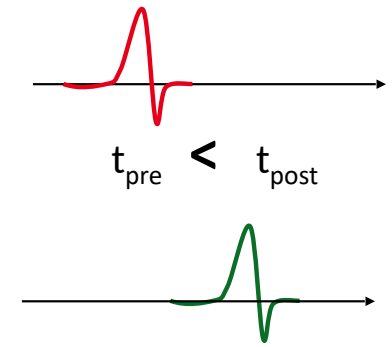
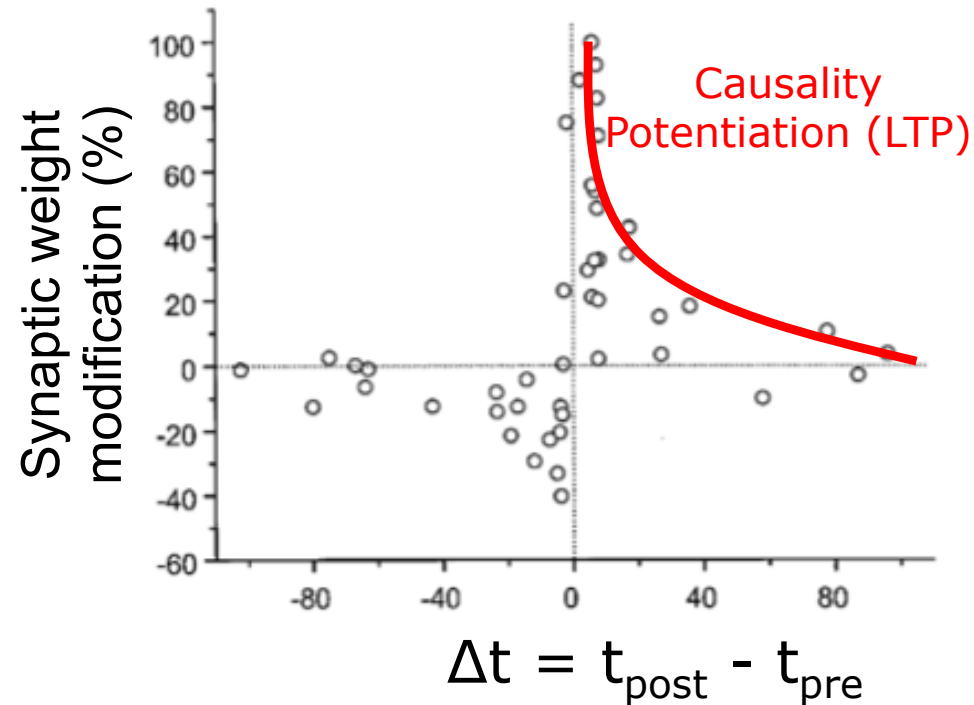
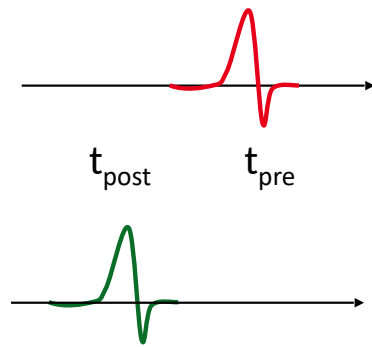
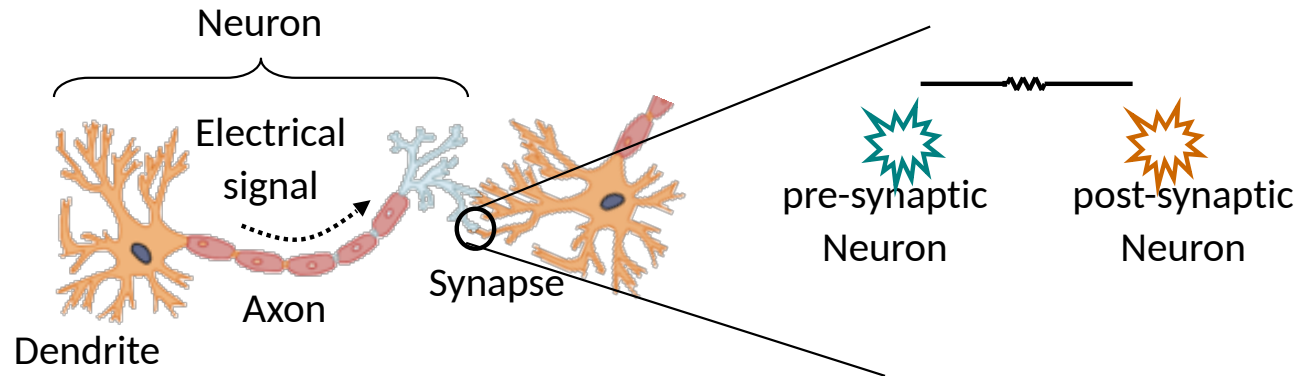


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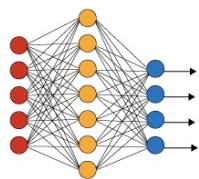




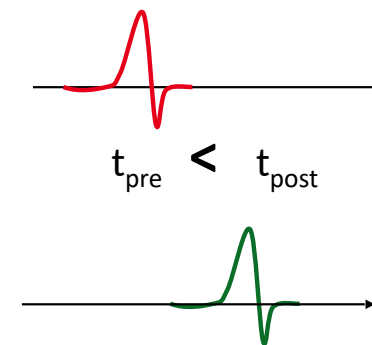
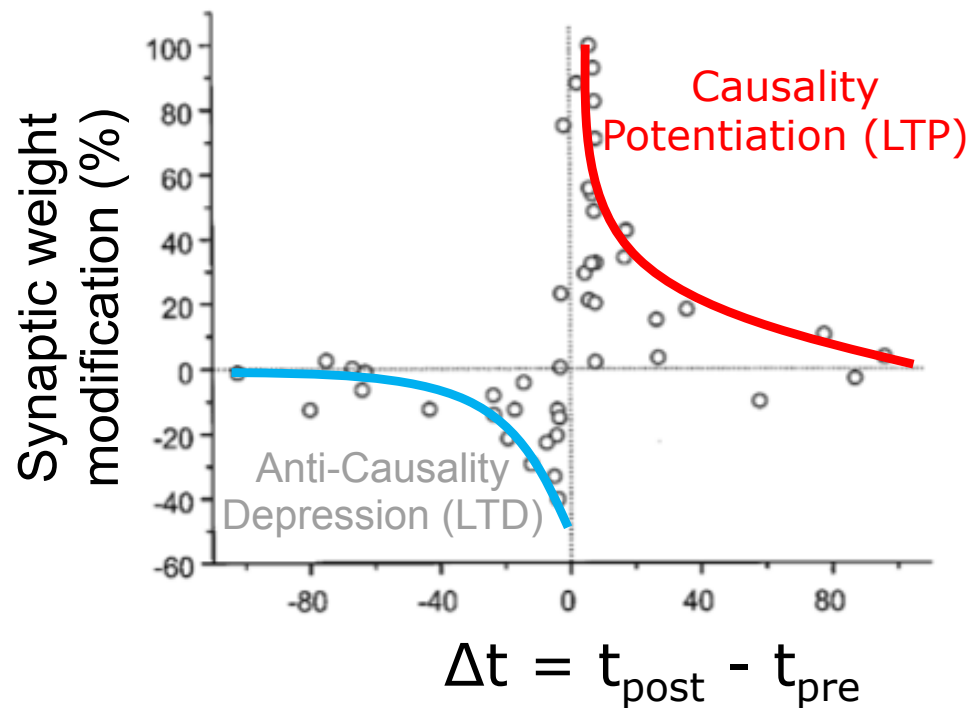
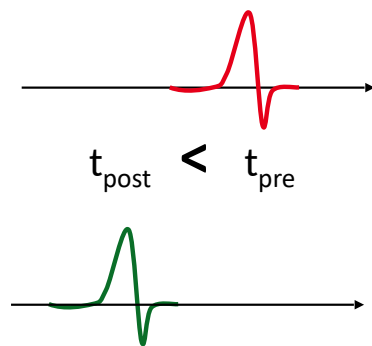
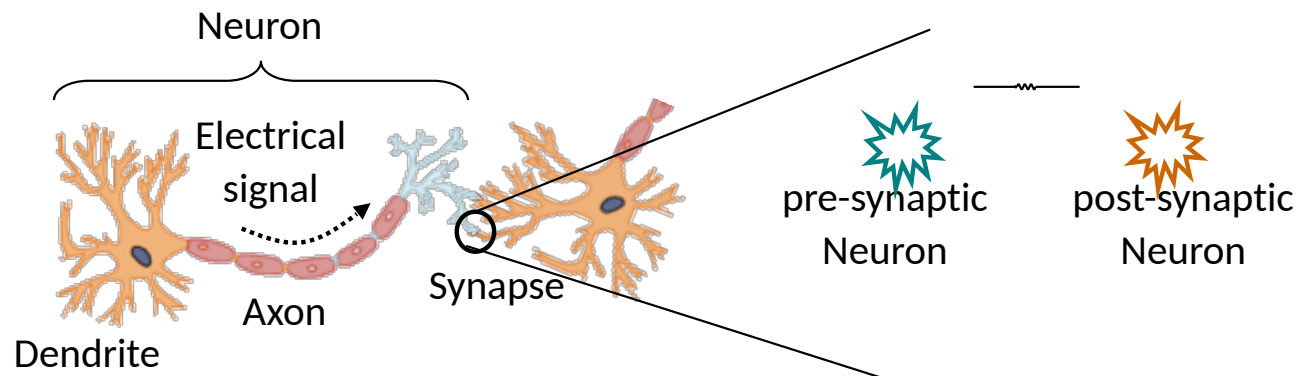
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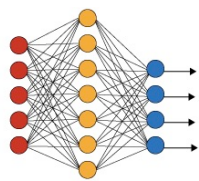




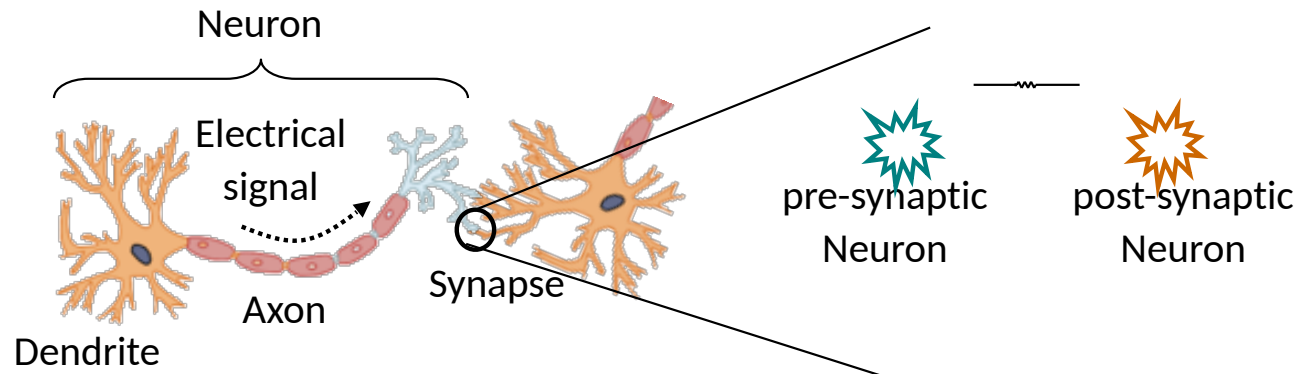


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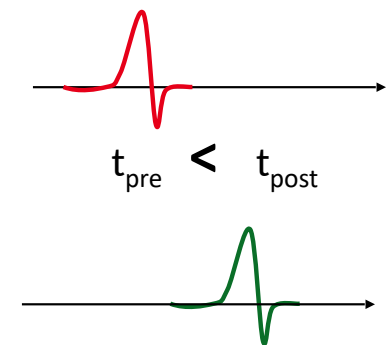
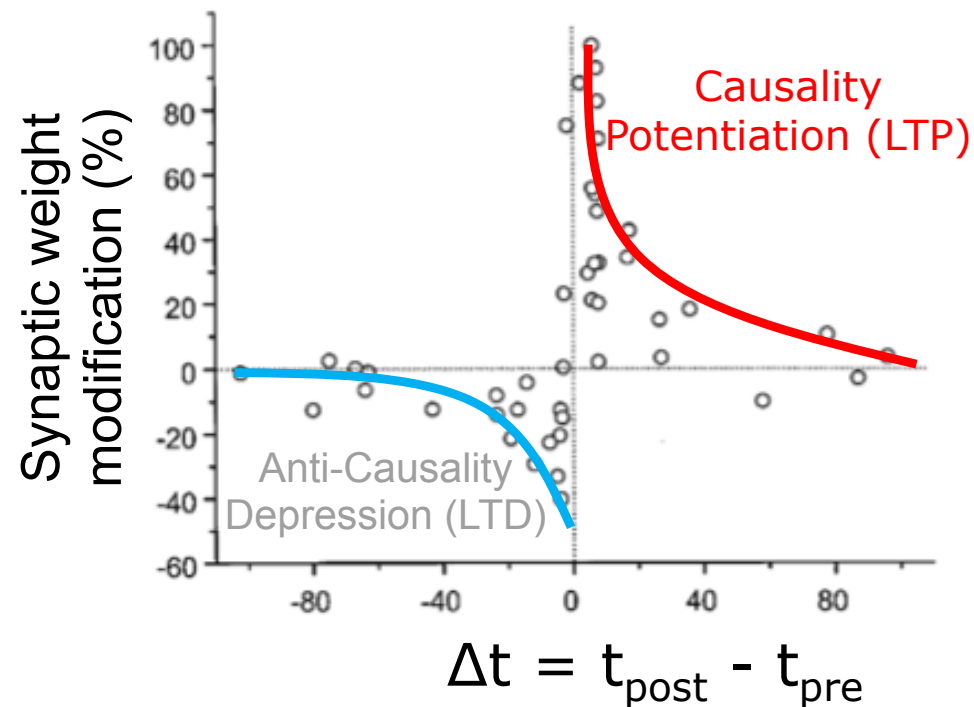
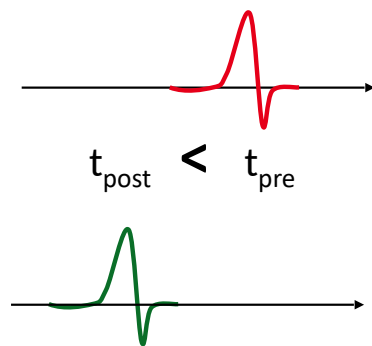


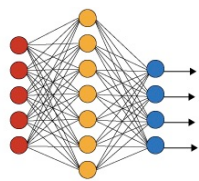


# DERIVED FROM HEBB'S RULE: STDP (SPIKE TIMING DEPENDENT PLASTICITY)

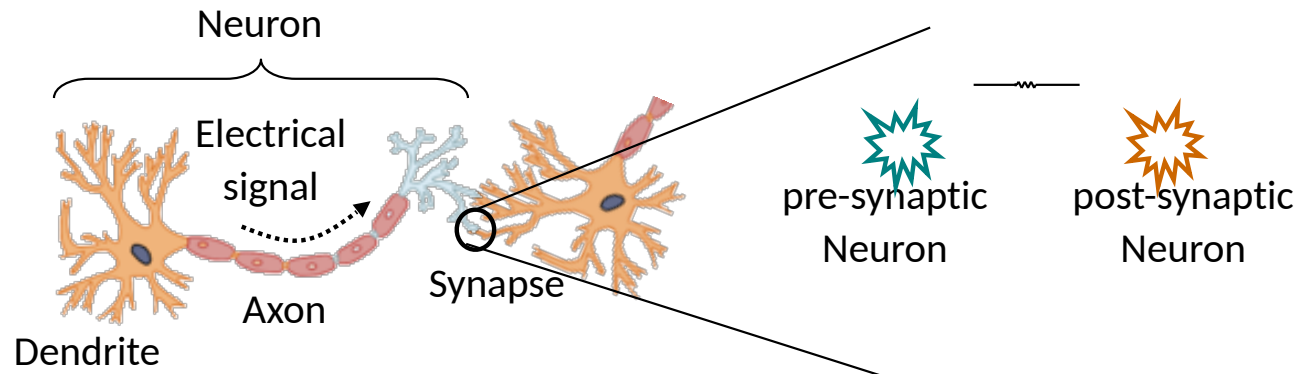


STDP = correlation detector  
→ Possible learning model of the brain?

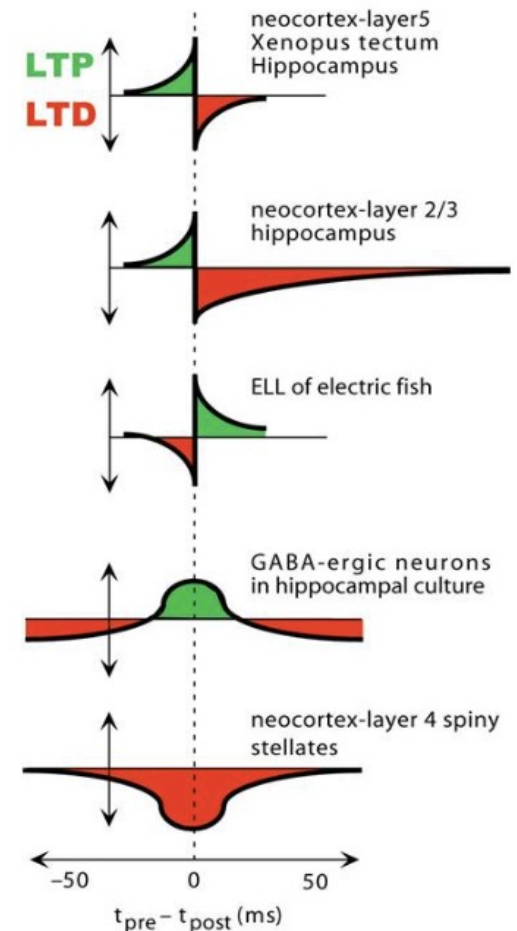
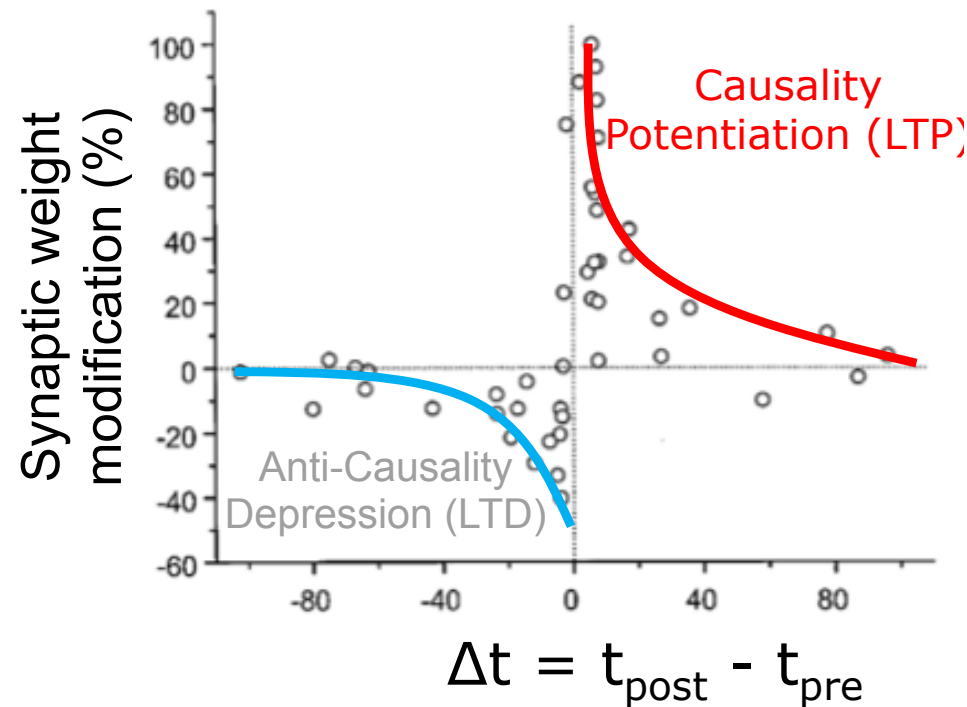
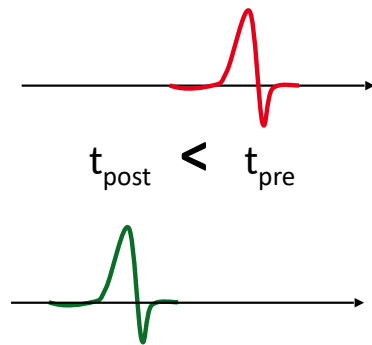


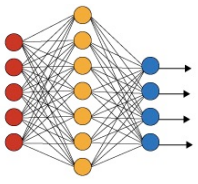


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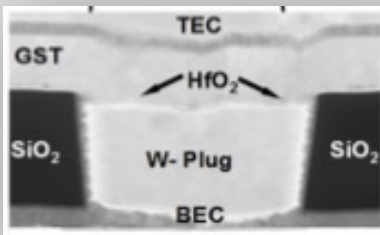


# SIDE REMARK: INVESTIGATION OF RRAM AS SYNAPSES UNSUPERVISED LEARNING (INFORMATION CODED BY SPIKES)

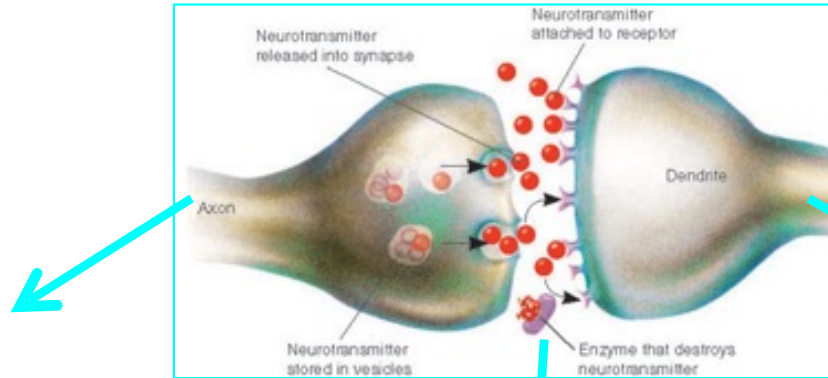
*Thermal effect*

**PCM**

GST  
GeTe  
GST + HfO<sub>2</sub>



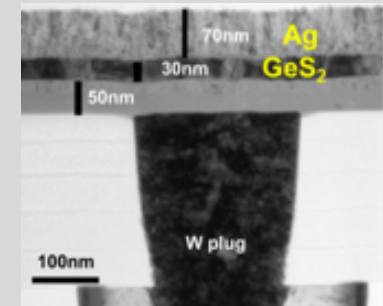
M.Suri, et. al, IEDM 2011  
M.Suri, et. al, IMW 2012, JAP 2012  
O.Bichler et al. IEEE TED 2012  
M.Suri et al., EPCOS 2013  
D.Garbin et al., IEEE Nano 2013



*Electrochemical effect*

**CBRAM**

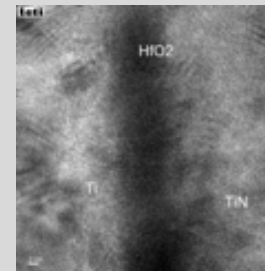
Ag / GeS<sub>2</sub>



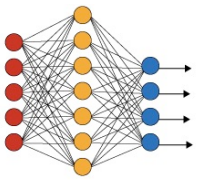
*Electronic effect  
oxygen vacancies*

**OXRAM**

TiN/HfO<sub>2</sub>/Ti/TiN



D.Garbin et al. IEDM 2014  
D.Garbin et al., IEEE TED 2015



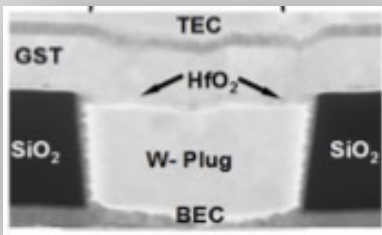
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*Analog computing:* using physical phenomenon to make computations

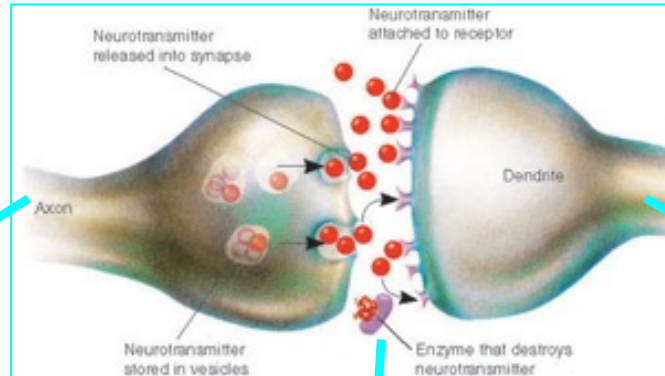
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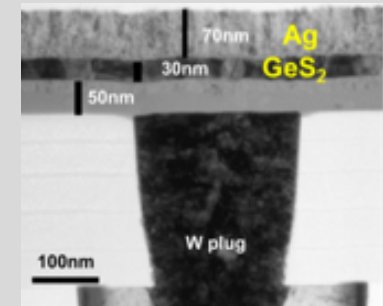
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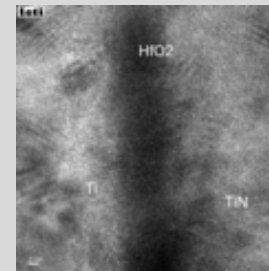
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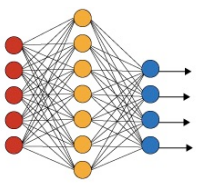
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TiN/HfO<sub>2</sub>/Ti/TiN



D.Garbin et al. IEDM 2014  
D.Garbin et al., IEEE TED 2015





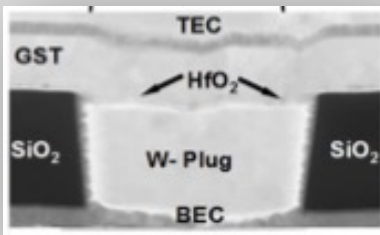
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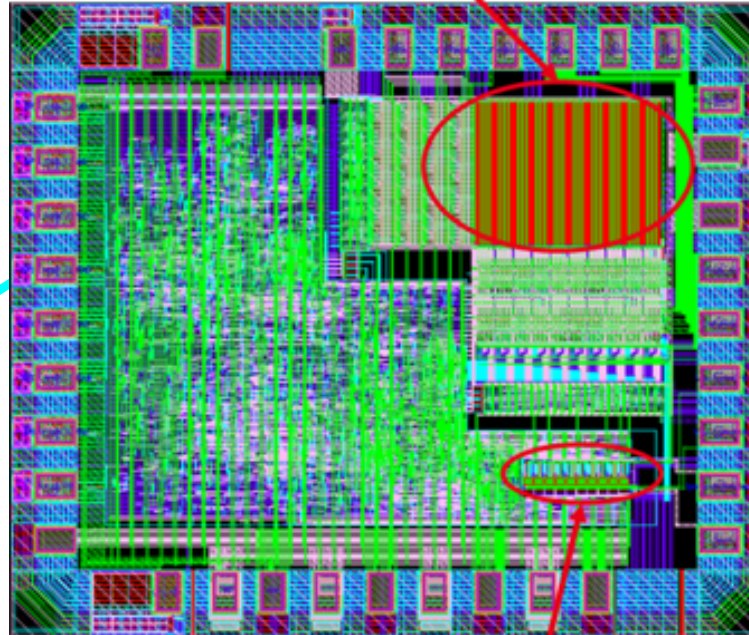
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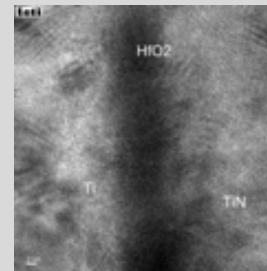
OxRAMs



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**OXRAM**

TiN/HfO<sub>2</sub>/Ti/TiN

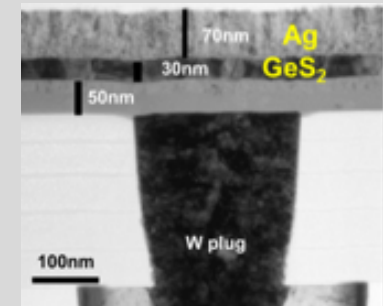


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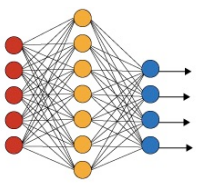
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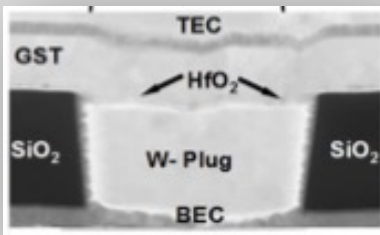
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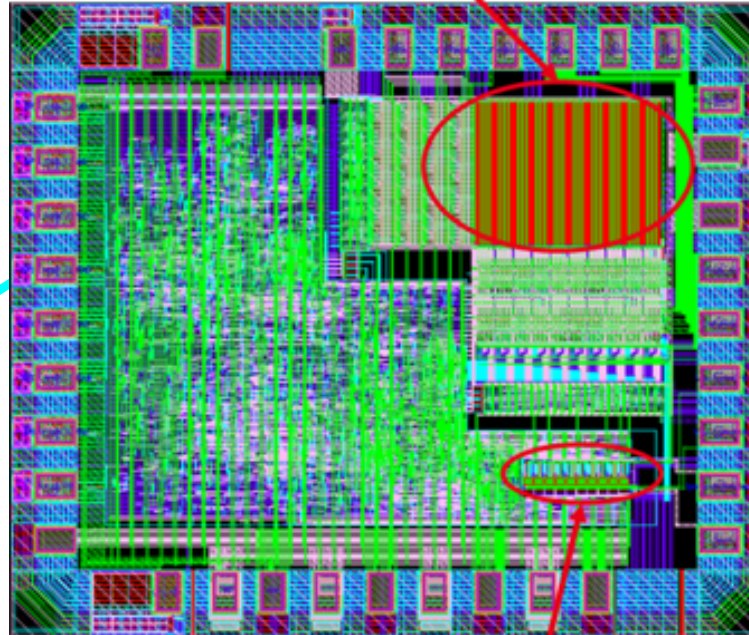
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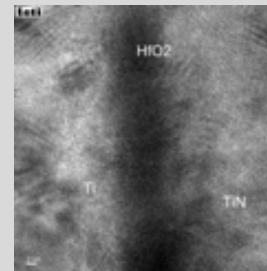
OxRAMs



**Electronic effect**  
**oxygen vacancies**

## OXRAM

TiN/HfO<sub>2</sub>/Ti/TiN

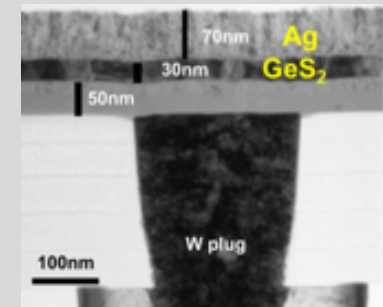


D.Garbin et al. IEDM 2014  
D.Garbin et al., IEEE TED 2015

**Electrochemical effect**

## CBRAM

Ag / GeS<sub>2</sub>



Leading to  
**neuromorphic chips**

# 1955: JOHN MCCARTHY

John McCarthy is one of the "founding fathers" of artificial intelligence, together with Marvin Minsky, Allen Newell and Herbert A. Simon.

McCarthy coined the term "artificial intelligence" in 1955, and organized the famous **Dartmouth Conference** in Summer 1956. This conference started AI as a science field.

While at MIT, McCarthy developed the programming language **LISP** in 1950, one of the two oldest programming language



```
(defun factorial (n)
  (if (= n 0)
      1
      (* n (factorial (- n 1))) ) )
```

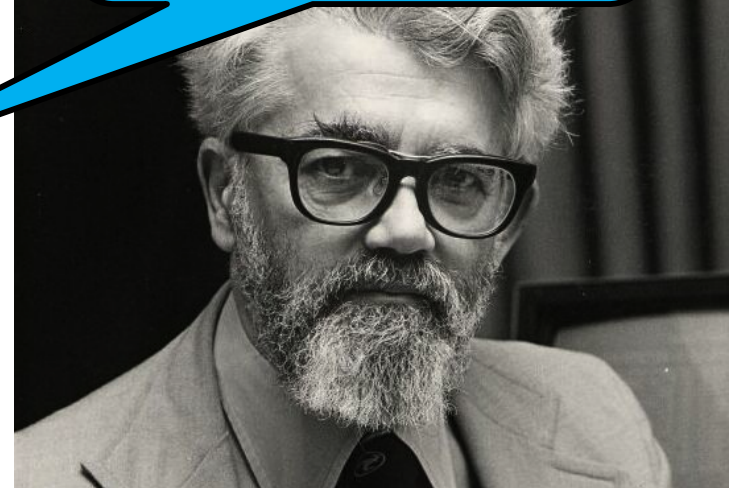
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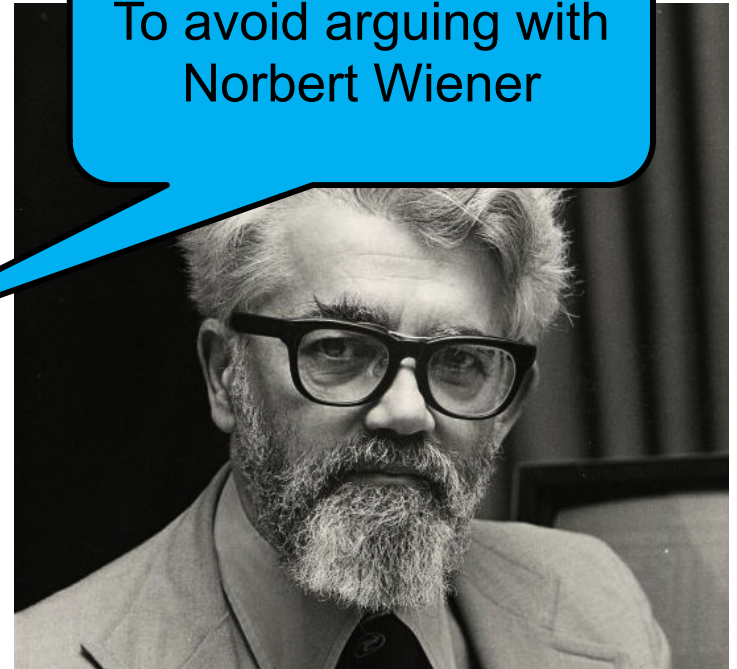
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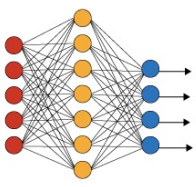
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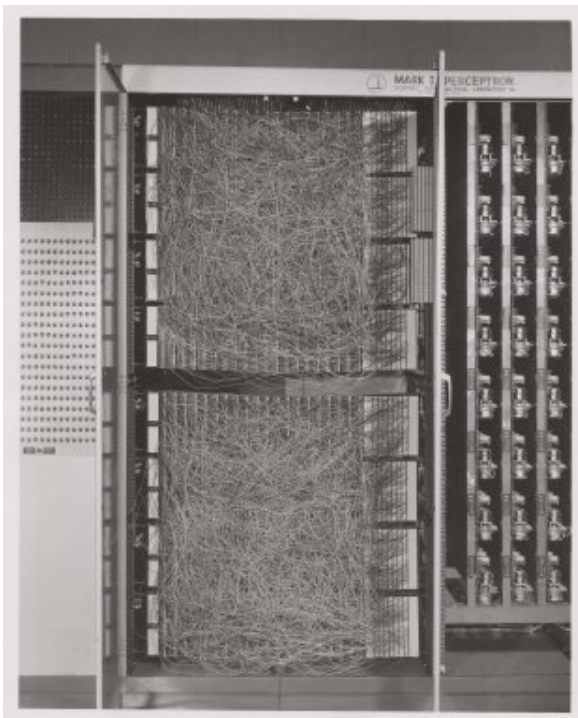
*Recursive definition of a factorial*



## 1957: THE PERCEPTRON AND F. ROSENBLATT

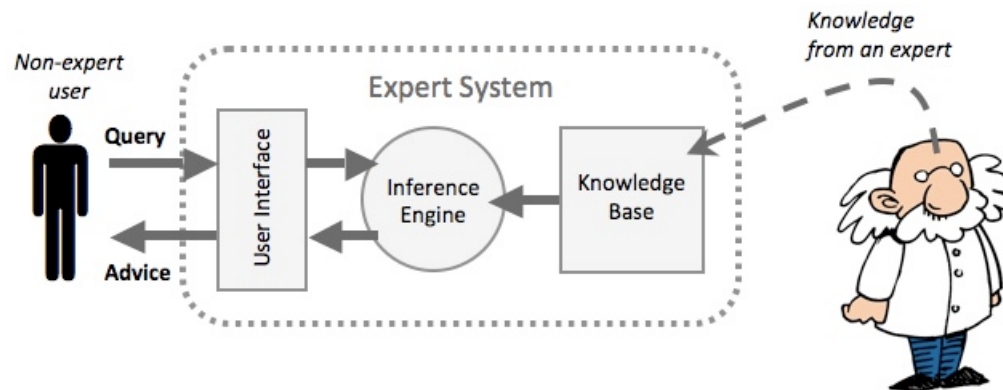
The perceptron algorithm was invented in 1957 at the Cornell Aeronautical Laboratory by Frank Rosenblatt.

The perceptron was intended to be a machine, rather than a program, and while its first implementation was in software for the IBM 704, it was subsequently implemented in custom-built hardware as the "Mark 1 perceptron". This machine was designed for image recognition: it had an array of 400 photocells, randomly connected to the "neurons". Weights were encoded in potentiometers, and weight updates during learning were performed by electric motors.



# 1965: EXPERT SYSTEMS

Expert systems were introduced by the Stanford Heuristic Programming Project led by Edward Feigenbaum,  
Can also use predicate logic or even Fuzzy Logic



## A) Rulebase Example

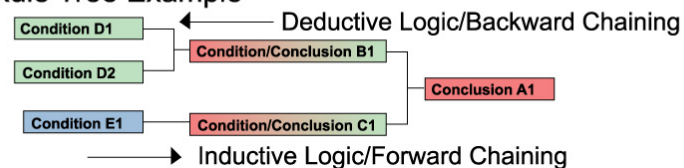
**IF**

- "yes" is equal to uniform\_layer\_flow
- THETA is greater than 45.0
- THETA is less than or equal to 90.0
- C4 is greater than  $(Lm / (0.8 * (Hs - H0)))$
- C6 is greater than  $(Lb / (0.8 * (Hs - H0)))$
- C9 is less than or equal to  $(Lt / (0.8 * (Hs - H0)))$

**Then**

- flow\_type\_ok is confirmed
- "V2" is assigned to flow\_type
- "No" is assigned to wake\_attachment
- Find coanda\_attachment\_value

## B) Rule Tree Example

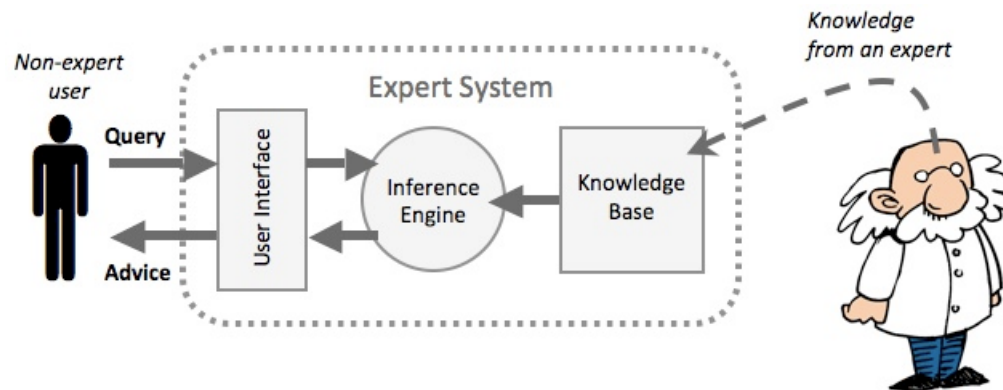


A Lisp machine



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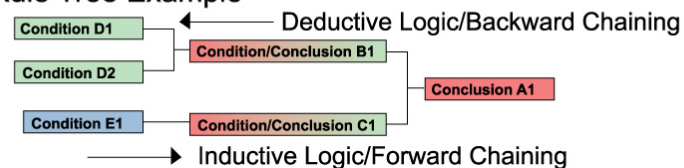
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## B) Rule Tree Example



A Lisp machine

## Decoupling:

- The (inference) engine
- The knowledge base



## 1966: ELIZA THE CHAT BOT !

```
;;; /DOCFNS/ 31 JULY 1969 1007:42

(PROGN (PRIN1 (QUOTE FILE" CREATED ")
        T)
       (PRIN1 (QUOTE 08/22/68" 1522:26")
        T)
       (TERPRI T))
(DEFINEQ

(DOCTOR
 (LAMBDA NIL
  (PROG (SENTENCE KEystack MEMSTACK TIMON)
   ;;      (SETSEPR 109 106 0)
   ;;      (SETBRK 14 12 31 1 13 8 9 27 26 3)
   ;;      (CONTROL T)
   ;;      (GCGAG NIL)
   (SETQ FLIPFLOP 0)
   (SETQ TIMON (QUOTIENT (CLOCK)
                        60))
   (RECONSTRUCT (QUOTE (TELL ME YOUR PROBLEMS "."
                        PLEASE TERMINATE INPUT WITH A PERIOD OR A
                        QUESTION MARK ".")))
   T)
  (SETNONE)
  A (PRIN1 (QUOTE "
*"))
  (COND
   ((NULL (SETQ SENTENCE (MAKESENTENCE)))
    (GO A)))
  (SETQ KEystack (CDR SENTENCE))
  (SETQ SENTENCE (CAR SENTENCE))
  (COND
   ((EQUAL SENTENCE (QUOTE (GOODBYE)))
    (RETURN (RECONSTRUCT (APPEND (QUOTE (IT'S BEEN
MY PLEASURE "," THAT'S))
                                (CONS (PACK (LIST (QUOTE $)
REMAINDER (PLUS (QUOTIENT
```

ELIZA is an early natural language processing computer program created from 1964 to 1966 at the MIT Artificial Intelligence Laboratory by Joseph Weizenbaum.

Created to demonstrate the superficiality of communication between man and machine, Eliza simulated conversation by using a 'pattern matching' and substitution methodology that gave users an illusion of understanding on the part of the program.

## 1966: ELIZA THE CHAT BOT !

```
;;;
(PRO *****
          ELIZA
ORIGINAL PROGRAM DESCRIBED BY
      JOSEPH WEIZENBAUM
(DEF
(DOC
  (L
    IN THE COMMUNICATION OF THE ACM JANUARY 1966
    BE SURE THAT THE CAPS LOCK IS ON
    PLEASE DON'T USE COMMAS OR PERIODS IN YOUR INPUTS
    *****
    *"))
HI! I'M ELIZA. WHAT'S YOUR PROBLEM?
? I AM TIRED
DID YOU COME TO ME BECAUSE YOU ARE TIRED
? NO, I \ I ,ON\
SAY, DO YOU HAVE ANY PSYCHOLOGICAL PROBLEMS?
? NO OF COURSE
ARE YOU SAYING NO JUST TO BE NEGATIVE?
? YES
ARE YOU SURE?
? █
```

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gram.

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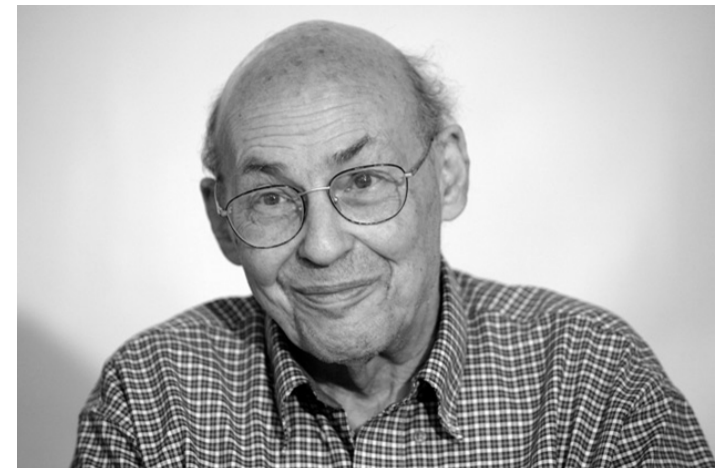
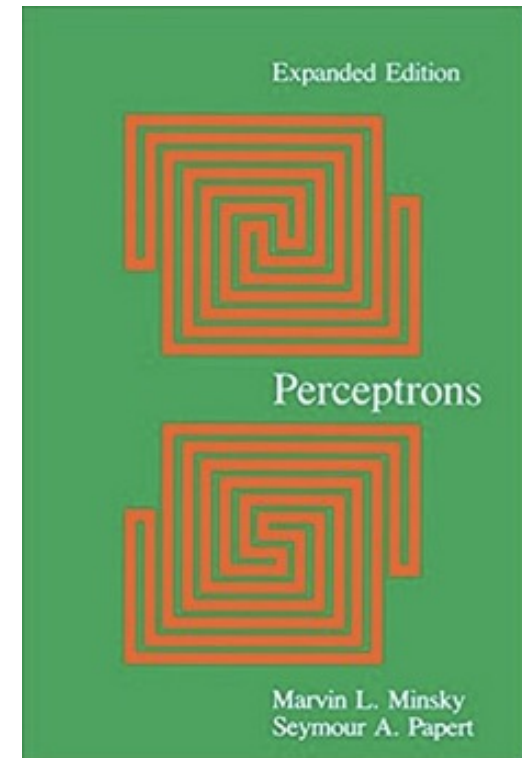
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# 1969: MARVIN MINSKY

He developed, with Seymour Papert, the first Logo "turtle".

Minsky also built, in 1951, the first randomly wired neural network learning machine, SNARC.

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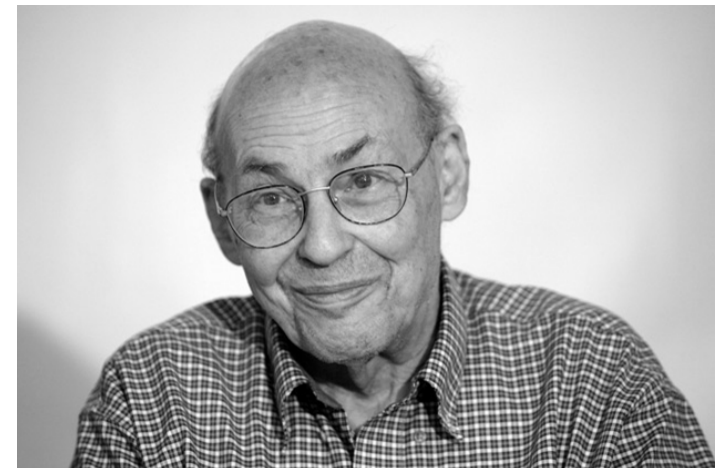
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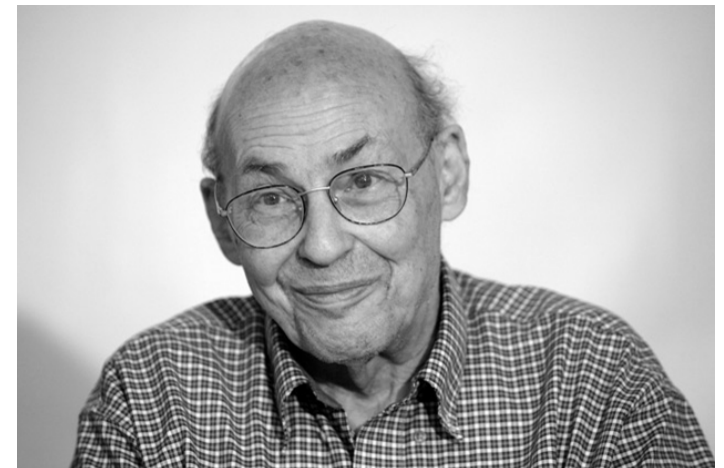
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Input 1	Input 2	Output
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0	1	1
1	1	0
1	0	1

Marvin L. Minsky  
Seymour A. Papert



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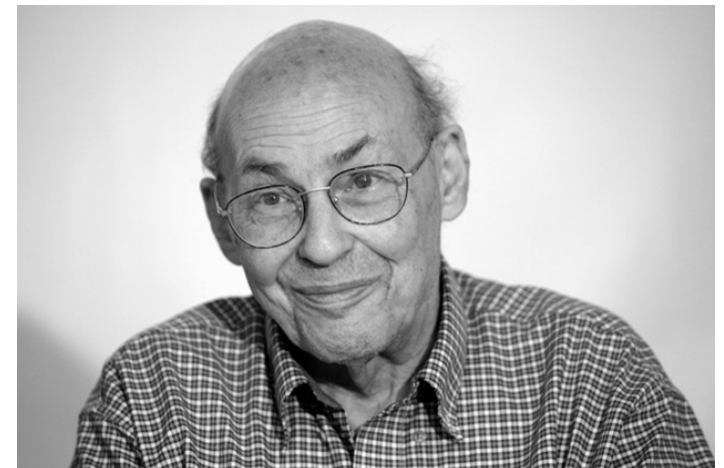
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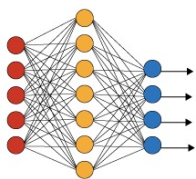
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$$\begin{aligned} p \oplus q &= (p \wedge \neg q) \vee (\neg p \wedge q) \\ &= (p \vee q) \wedge (\neg p \vee \neg q) \\ &= (p \vee q) \wedge \neg(p \wedge q) \end{aligned}$$







1980: KUNIHICO FUKUSHIMA

The first Deep Neural Network, inspired by the visual cortex.



# Neocognitron: A Self-organizing Neural Network Model for a Mechanism of Pattern Recognition Unaffected by Shift in Position

Kunihiro Fukushima

NHK Broadcasting Science Research Laboratories, Kinuta, Setagaya, Tokyo, Japan

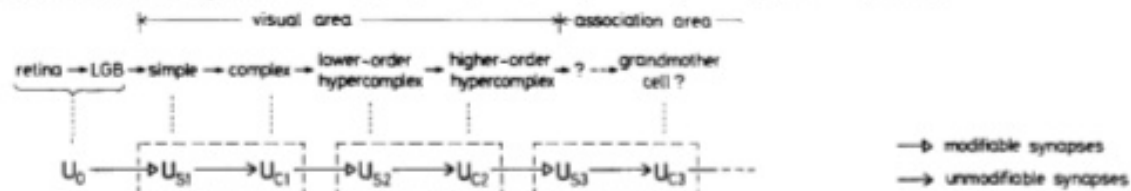


Fig. 1. Correspondence between the hierarchy model by Hubel and Wiesel, and the neural network of the neocognitron

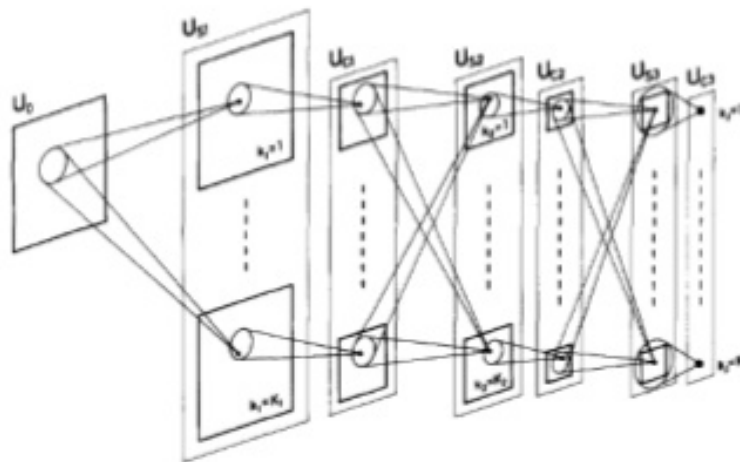
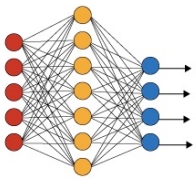


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron

Biol. Cybernetics 36, 193–202 (1980)



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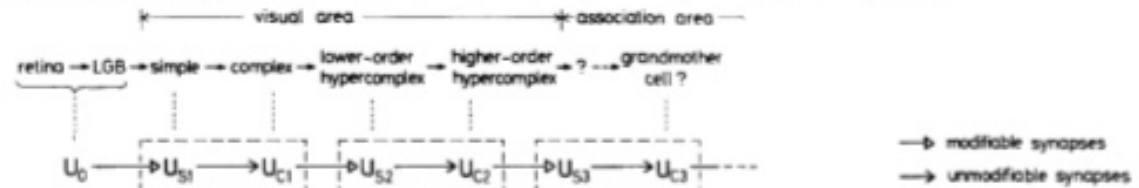


Fig. 1. Correspondence between the hierarchy model by Hubel and Wiesel, and the neural network of the neocognitron

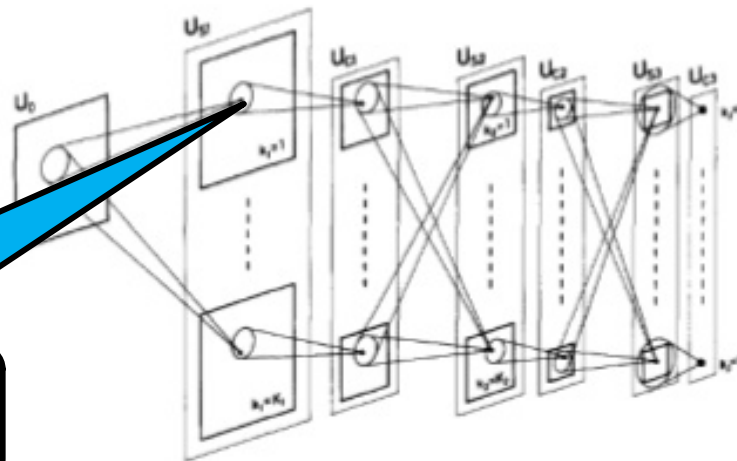
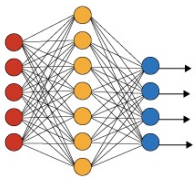


Fig. 2. Schematic diagram illustrating the interconnections between layers in the neocognitron

But no real algorithms to set the values of the synaptic weights

Biol. Cybernetics 36, 193–202 (1980)



AROUND 1986: GEOFFREY HINTON

He was one of the first researchers who demonstrated the use of **generalized back-propagation algorithm** for training multi-layer neural networks.

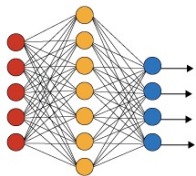
He co-invented **Boltzmann machines** with David Ackley and Terry Sejnowski.

His other contributions to neural network research include distributed representations, time delay neural network, mixtures of experts, Helmholtz machines and Product of Experts

He is now working for Google.



Cognitive psychologist and computer scientist



In 1985, he proposed and published (in French), an early version of the learning algorithm known as **error backpropagation**

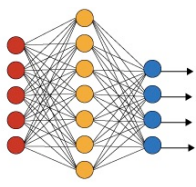
Near 1989, he developed a number of new machine learning methods, such as a biologically inspired model of image recognition called **Convolutional Neural Networks**, the "Optimal Brain Damage" regularization methods, and the Graph Transformer Networks method which he applied to handwriting recognition and OCR.

The **bank check recognition system** that he helped develop was widely deployed by NCR and other companies, reading over 10% of all the checks in the US in the late 1990s and early 2000s.

In 2013, LeCun became the first director of Facebook AI Research in New York City.







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**COGNITIVA 85**

Paris, 4-7 Juin 1985

A LEARNING SCHEME FOR ASYMMETRIC THRESHOLD NETWORK.

UNE PROCEDURE D'APPRENTISSAGE POUR RESEAU A SEUIL ASSYMETRIQUE.

YANN LE CUN

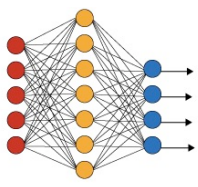
Ecole Supérieure d'Ingénieurs en Electrotechnique et Electronique, 91 rue Falguière 75015 Paris  
and Laboratoire de Dynamique des Réseaux, 1 rue Descartes 75005 Paris.

#### RESUME

Une nouvelle méthode paramétrique d'apprentissage supervisé utilisant un réseau parallèle d'automates à seuil est proposée. Le modèle est constitué de trois types d'éléments: les cellules d'entrée, les cellules de sortie, et les cellules internes, ces dernières n'ayant aucune interaction directe avec l'extérieur. L'apprentissage est un processus itératif local qui minimise une fonction de coût en modifiant les interactions entre cellules. L'utilisation d'une matrice de connexions asymétrique ainsi que la modification par l'apprentissage des paramètres des cellules internes constituent les principales particularités de ce modèle. Ceci permet l'apprentissage de discriminations dans le cas non linéairement séparable ainsi que la synthèse de prédicats d'ordre élevé. Des simulations effectuées sur un réseau hiérarchique de quelques centaines d'éléments mettent en évidence les capacités de généralisation du réseau (production d'une réponse correcte pour une forme non apprise) dans le cas de la reconnaissance d'images bruitées de basse résolution avec réponse invariante par faible translation et distortion. Des simulations en conditions d'auto-apprentissage (avec une sortie désirée auto-générée) ont également été effectuées pour modéliser l'apprentissage Pavlovien et les associations objet-symbole.

#### SUMMARY

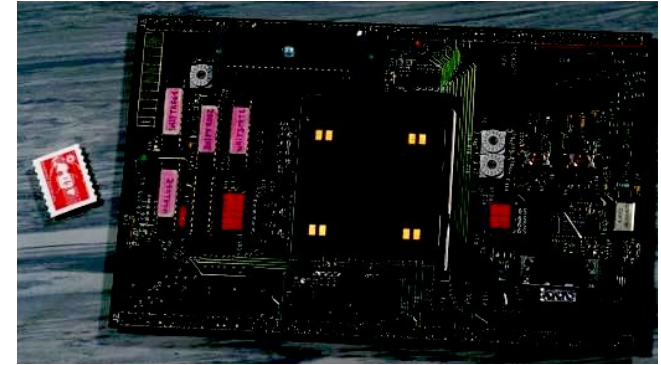
A new parametric method for supervised learning is presented which is based on a threshold network structure. The model is composed of three types of units: input units, output units, and hidden units, the last group having no interaction with the outside world. The learning process is a local iterative scheme which minimizes a particular cost function by modifying the interactions between units. The non-symmetric nature of the weight matrix as well as the modification of the hidden units weights by the learning process constitute the main particularities of this model. This system can learn high order predicates and discriminations in the non-linearly separable case. Simulations have been performed using hierarchical networks containing several hundred cells. The network exhibits generalization abilities (i.e. production of a correct output for a non-learned input pattern) on a low-resolution noisy picture recognition task. Other simulations have been done in self-learning conditions (i.e. with self-generated desired output) that modelize Pavlovian learning and object-symbol associations.



# 1990'S NEUROCOMPUTERS...

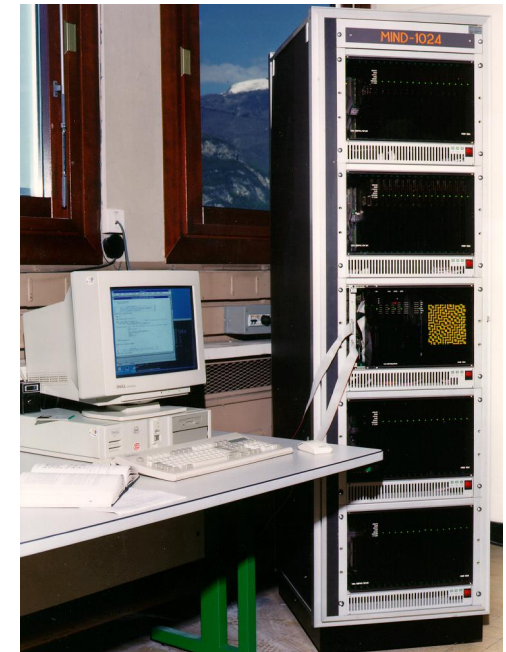
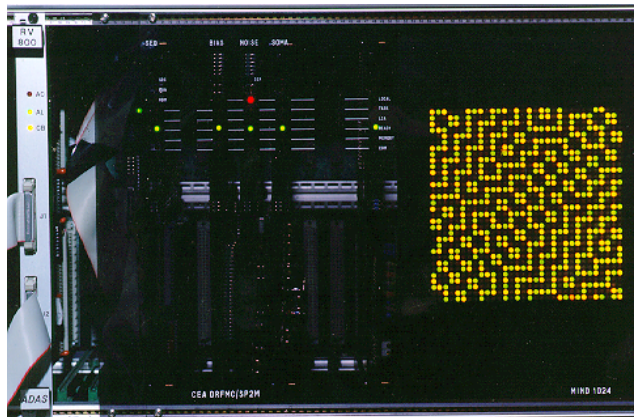
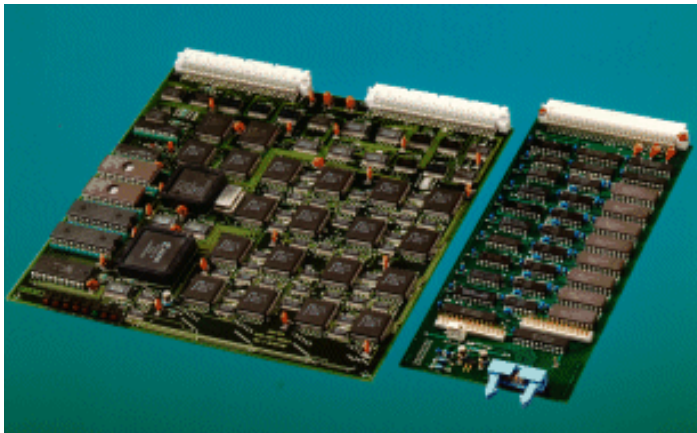
## Philips : L-Neuro

- 1st Gen 16 PEs 26 MCps (1990)
- 2nd Gen 12 PEs 720 MCps (1994)
- Used in satellite, fruit sorting, PCB inspection, sleep analysis, ...

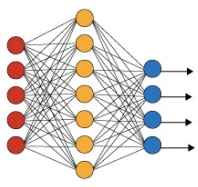


## CEA's MIND machine

- Hybrid analog/digital: MIND-128 (1986)
- Fully digital: MIND-1024 (1991)







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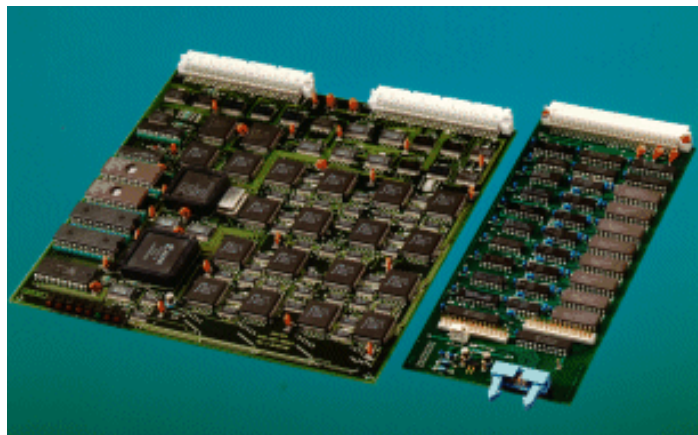
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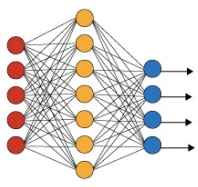
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- **Orange video-grading**
- **Chip alignment**
- **Sleep phase analysis**
- **Image compression**
- **Satellite image analysis**
- **LHC 1<sup>st</sup> level trigger**





# 1990'S NEUROCOMPUTERS...

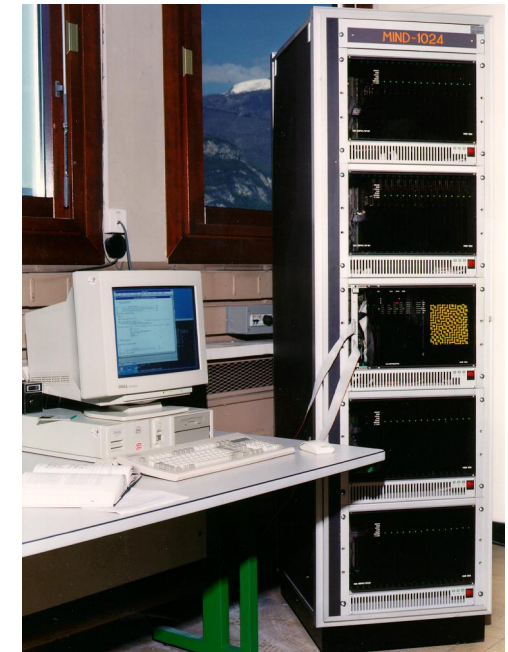
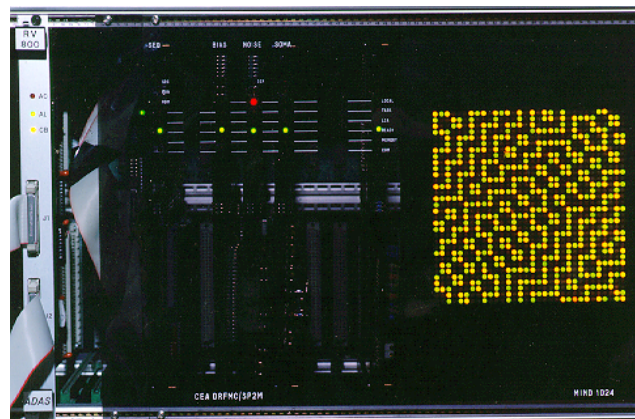
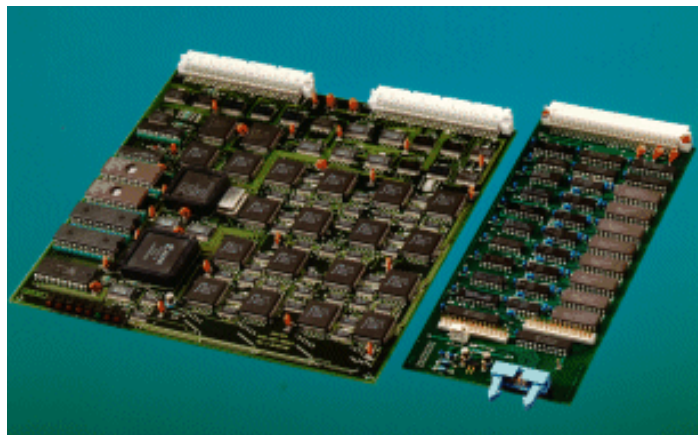
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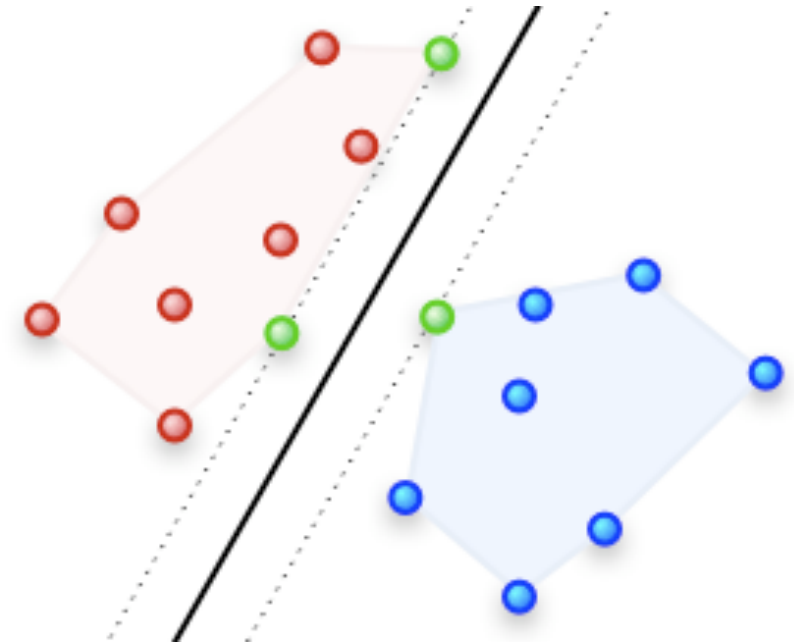
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## Support Vector Machines (SVMs)

The original SVM algorithm was invented by Vladimir N. Vapnik and Alexey Ya. Chervonenkis in **1963**.

In 1992, Bernhard E. Boser, Isabelle M. Guyon and Vladimir N. Vapnik suggested a way to create nonlinear classifiers by applying the kernel trick to maximum-margin hyperplanes. The current standard incarnation (soft margin) was proposed by Corinna Cortes and Vapnik in 1993 and published in 1995.



## 1997: CHESS AND DEEP BLUE

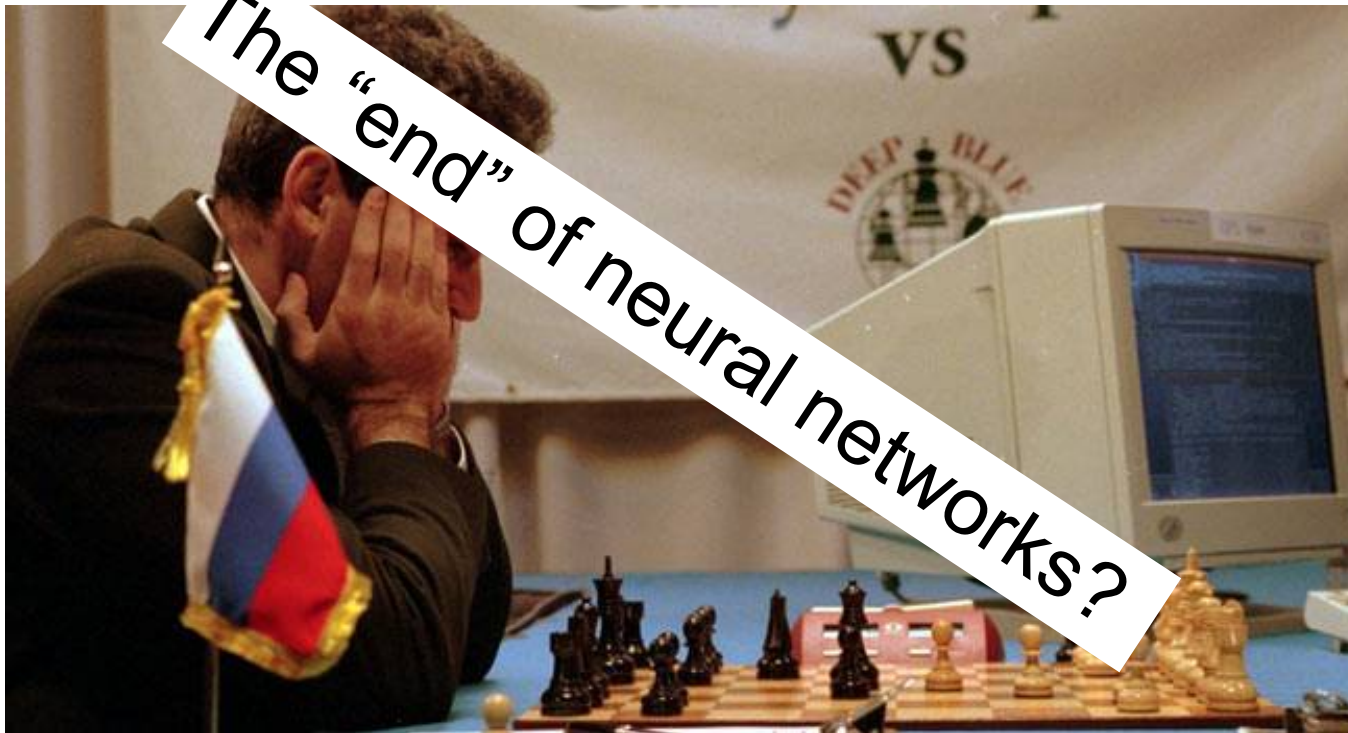
As far back as the mid-60s, chess was called the "Drosophila of artificial intelligence" – a reference to the fruit flies biologists used to uncover the secrets of genetics –  
1997 – Deep Blue wins a six-game match against Garry Kasparov.

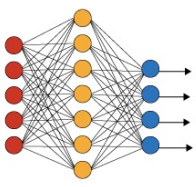




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# 2012: DEEP NEURAL NETWORKS RISE AGAIN

They give the *state-of-the-art performance* e.g. in image classification

- **ImageNet classification (Hinton's team, hired by Google)**
  - 14,197,122 images, 1,000 different classes
  - Top-5 17% error rate (huge improvement) in 2012 (now ~ 3.5%)



**"Supervision"** network

Year: 2012

650,000 neurons

60,000,000 parameters

630,000,000 synapses

- **Facebook's 'DeepFace' Program (labs headed by Y. LeCun)**
  - 4.4 million images, 4,030 identities
  - 97.35% accuracy, vs. 97.53% human performance

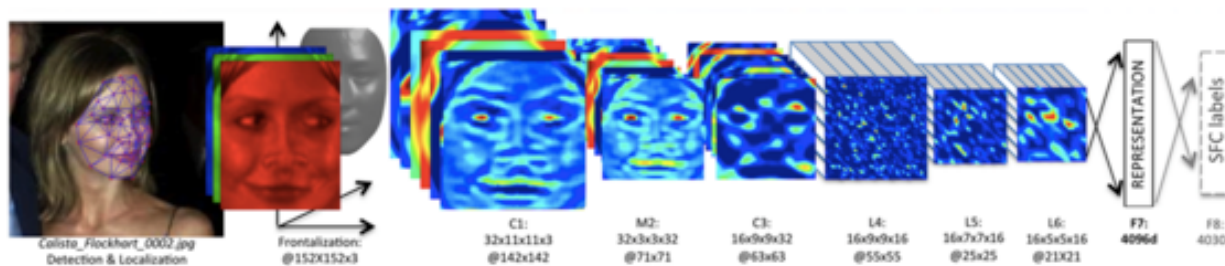
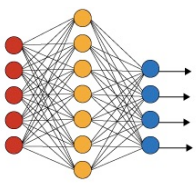


Figure 2. Outline of the *DeepFace* architecture. A front-end of a single convolution-pooling-convolution filtering on the rectified input, followed by three locally-connected layers and two fully-connected layers. Colors illustrate feature maps produced at each layer. The net includes more than 120 million parameters, where more than 95% come from the local and fully connected layers.

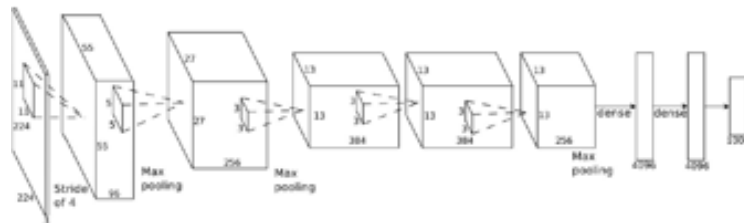
From: Y. Taigman, M. Yang, M.A. Ranzato,  
"DeepFace: Closing the Gap to Human-Level  
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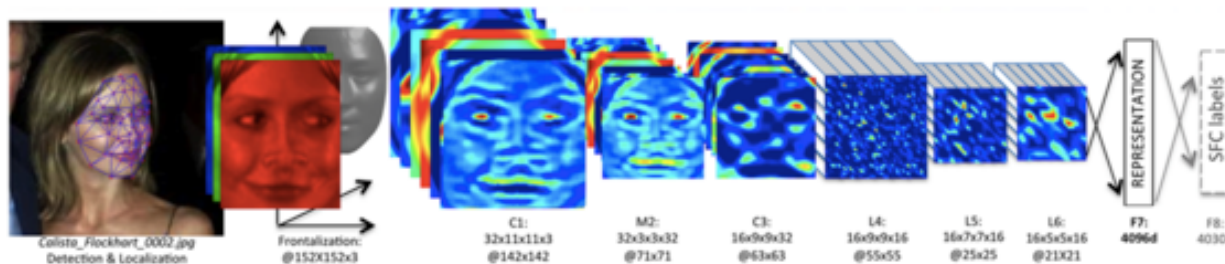
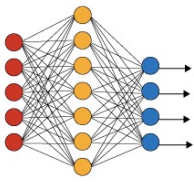


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research highlights

DOI:10.1145/3065386



## ImageNet Classification with Deep Convolutional Neural Networks

By Alex Krizhevsky, Ilya Sutskever, and Geoffrey E. Hinton

### Abstract

We trained a large, deep convolutional neural network to classify the 1.2 million high-resolution images in the ImageNet LSVRC-2010 contest into the 1000 different classes. On the test data, we achieved top-1 and top-5 error rates of 37.5% and 17.0%, respectively, which is considerably better than the previous state-of-the-art. The neural network, which has 60 million parameters and 650,000 neurons, consists of five convolutional layers, some of which are followed by max-pooling layers, and three fully connected layers with a final 1000-way softmax. To make training faster, we used non-saturating neurons and a very efficient GPU implementation of the convolution operation. To reduce overfitting in the fully connected layers we employed a recently developed regularization method called “dropout” that proved to be very effective. We also entered a variant of this model in the ILSVRC-2012 competition and achieved a winning top-5 test error rate of 15.3%, compared to 26.2% achieved by the second-best entry.

that were widely investigated in the 1980s. These networks used multiple layers of feature detectors that were all learned from the training data. Neuroscientists and psychologists had hypothesized that a hierarchy of such feature detectors would provide a robust way to recognize objects but they had no idea how such a hierarchy could be learned. There was great excitement in the 1980s because several different research groups discovered that multiple layers of feature detectors could be trained efficiently using a relatively straight-forward algorithm called backpropagation<sup>18, 22, 27, 33</sup> to compute, for each image, how the classification performance of the whole network depended on the value of the weight on each connection.

Backpropagation worked well for a variety of tasks, but in the 1980s it did not live up to the very high expectations of its advocates. In particular, it proved to be very difficult to learn networks with many layers and these were precisely the networks that should have given the most impressive results. Many researchers concluded, incorrectly, that learning a deep neural network from random initial weights was just too difficult. Twenty years later, we know what went wrong: for

“**Supervision**” network

Year: 2012

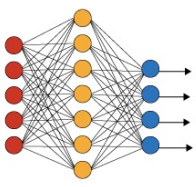
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y Y. LeCun)

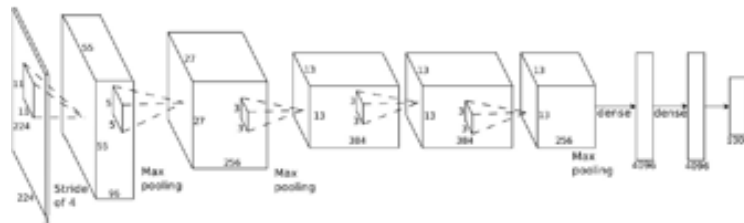
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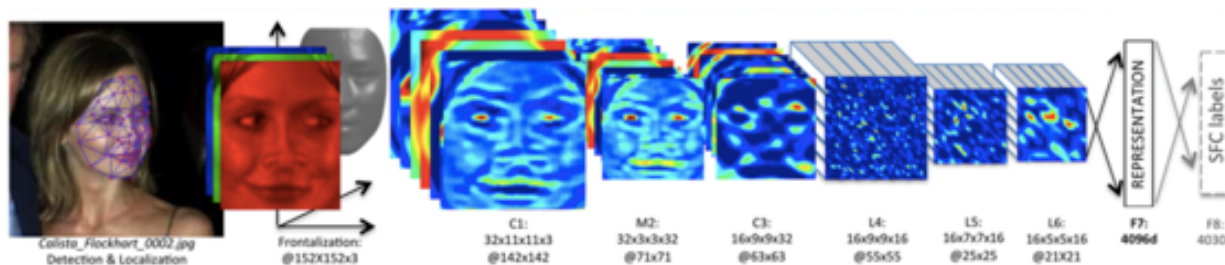
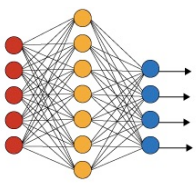


Figure 2. Outline of the *DeepFace* architecture. A front-end of a single convolution-pooling-convolution filtering on the rectified input, followed by three locally-connected layers and two fully-connected layers. Colors illustrate feature maps produced at each layer. The net includes more than 120 million parameters, where more than 95% come from the local and fully connected layers.

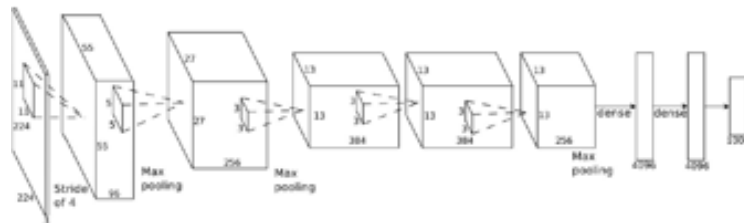
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The 2018 Turing Award recipients are Google VP Geoffrey Hinton\*, Facebook's Yann LeCun and Yoshua Bengio, Scientific Director of AI research center Mila.

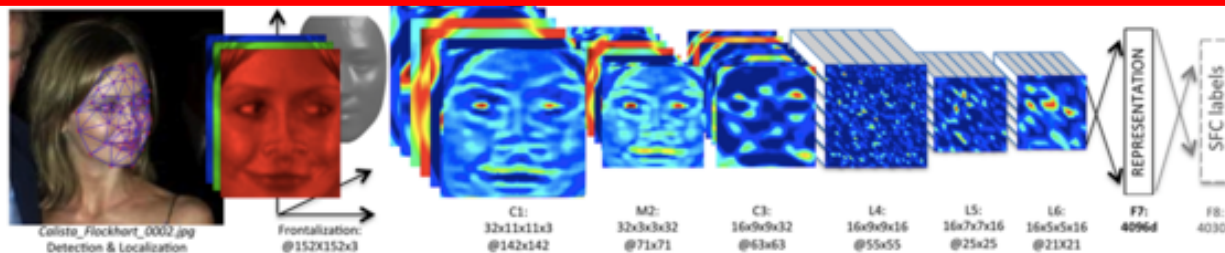
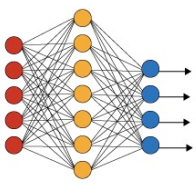


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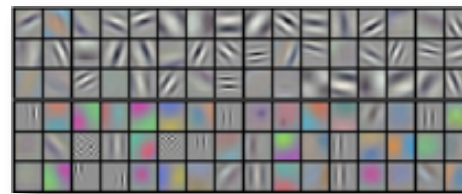
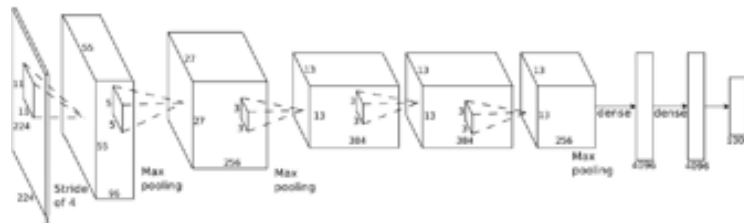
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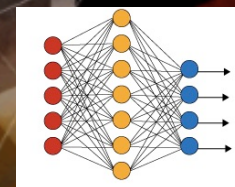
The 2018 **Turing Award recipients** are Google VP Geoffrey Hinton\*, Facebook's Yann LeCun and Yoshua Bengio, Scientific Director of AI research center Mila.

\* He was also awarded with John Hopfield the 2024 Nobel Prize in Physics for "foundational discoveries and inventions that enable machine learning with artificial neural networks"

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# ImageNet: Classification

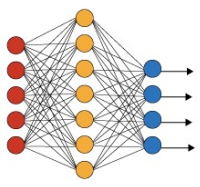


Y LeCun

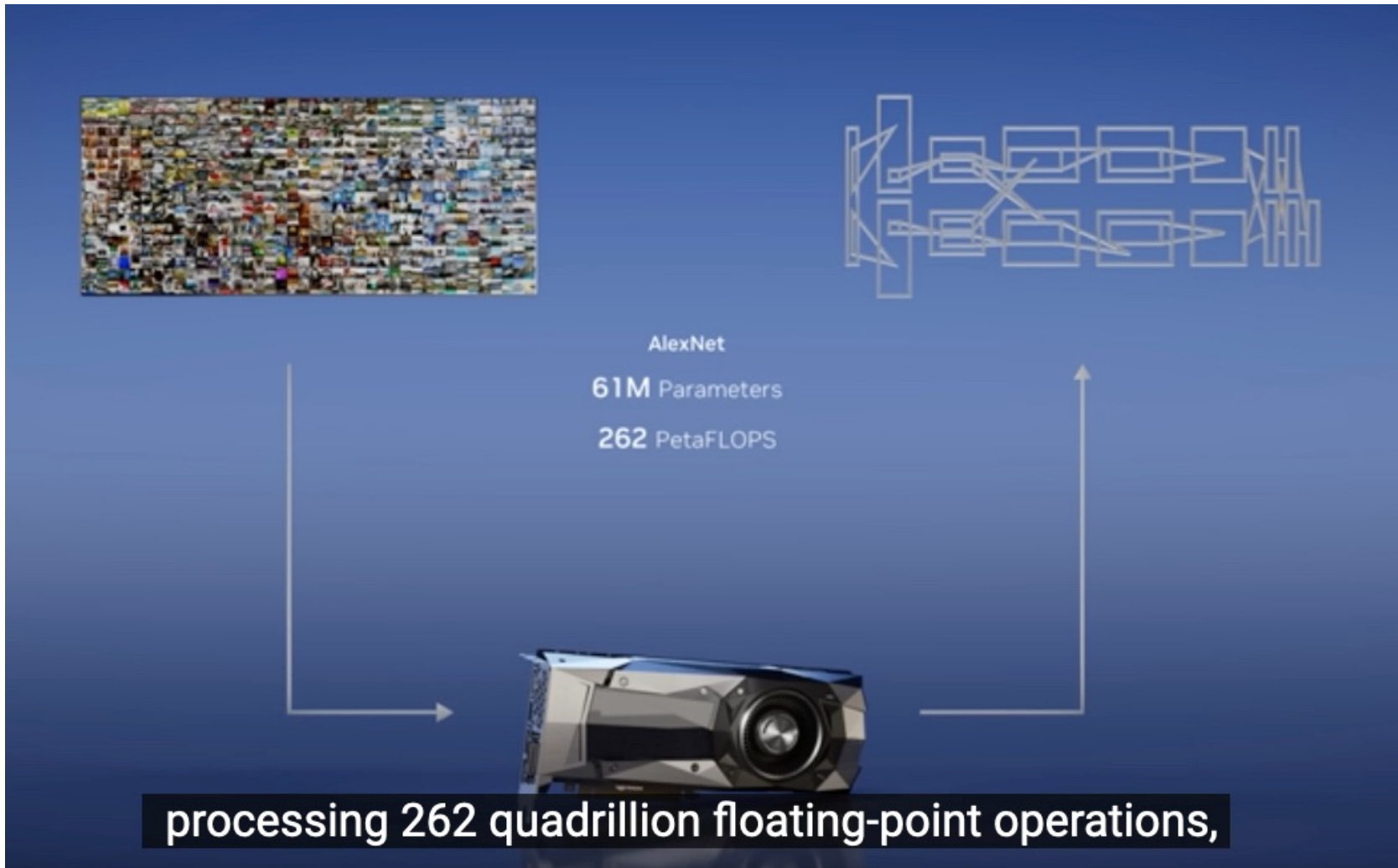
- Give the name of the dominant object in the image
- Top-5 error rates: if correct class is not in top 5, count as error
  - Black: ConvNet, Purple: no ConvNet

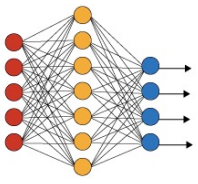
2012 Teams	%error	2013 Teams	%error	2014 Teams	%error
Supervision (Toronto)	15.3	Clarifai (NYU spinoff)	11.7	GoogLeNet	6.6
ISI (Tokyo)	26.1	NUS (singapore)	12.9	VGG (Oxford)	7.3
VGG (Oxford)	26.9	Zeiler-Fergus (NYU)	13.5	MSRA	8.0
XRCE/INRIA	27.0	A. Howard	13.5	A. Howard	8.1
UvA (Amsterdam)	29.6	OverFeat (NYU)	14.1	DeeperVision	9.5
INRIA/LEAR	33.4	UvA (Amsterdam)	14.2	NUS-BST	9.7
		Adobe	15.2	TTIC-ECP	10.2
		VGG (Oxford)	15.2	KYZ	11.2
		VGG (Oxford)	23.0	UvA	12.1



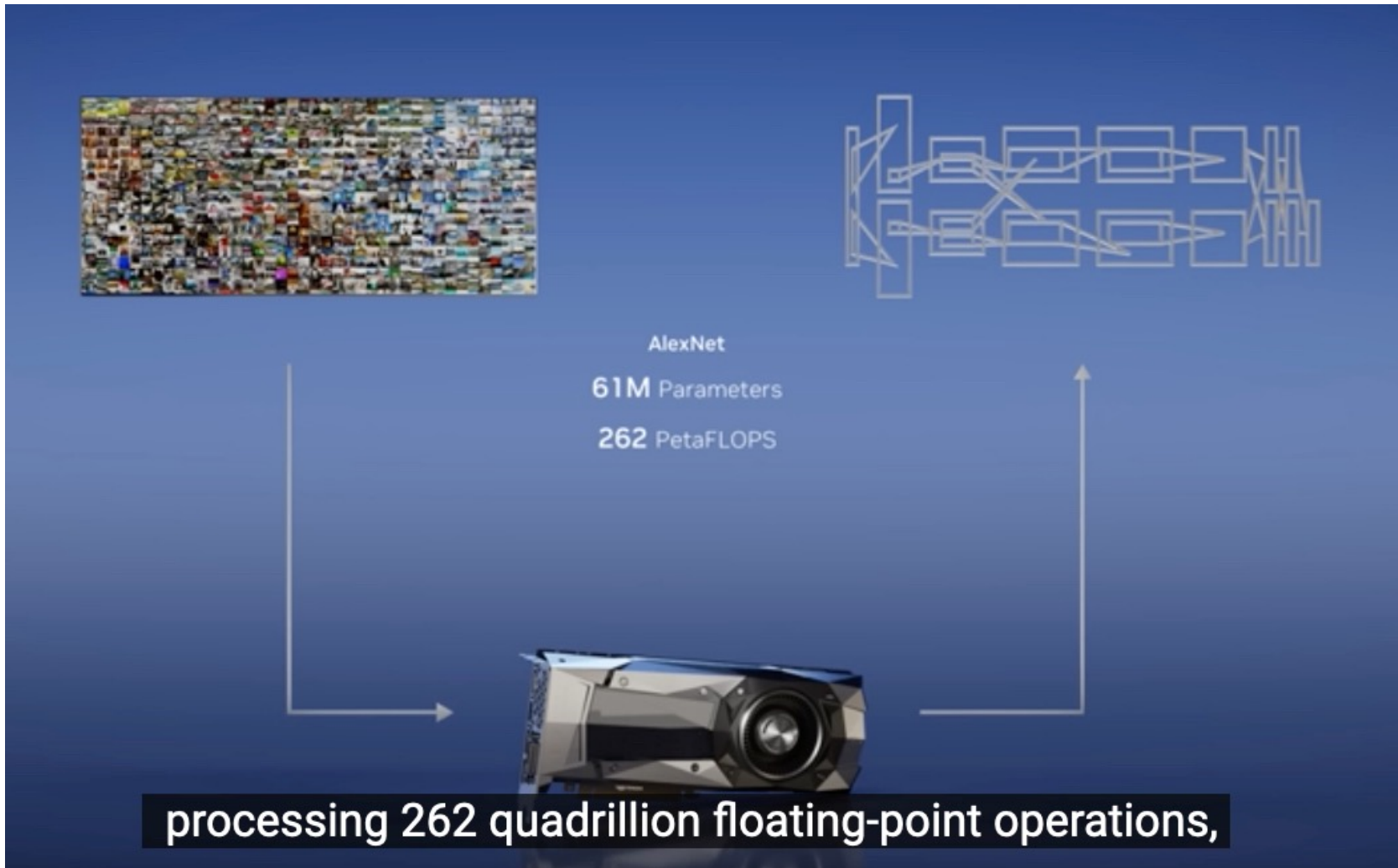


# Computing power is driving the advance of AI

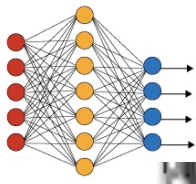




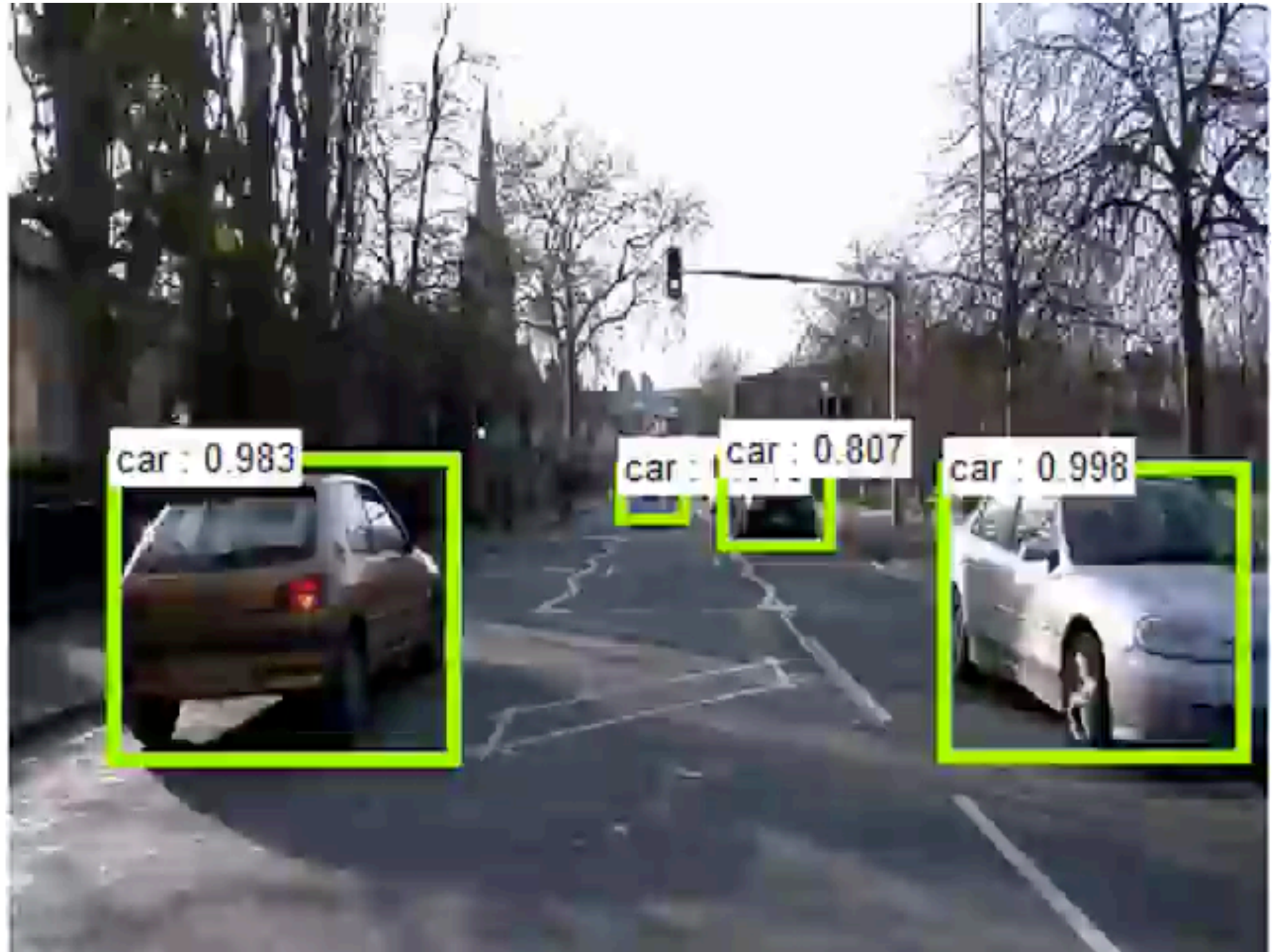
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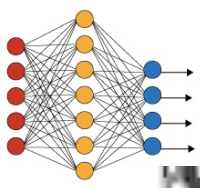
**2012: AlexNet**  
GeForce GTX 580  
Won ImageNet Challenge  
 $262 \times 10^{15}$  FLOPS



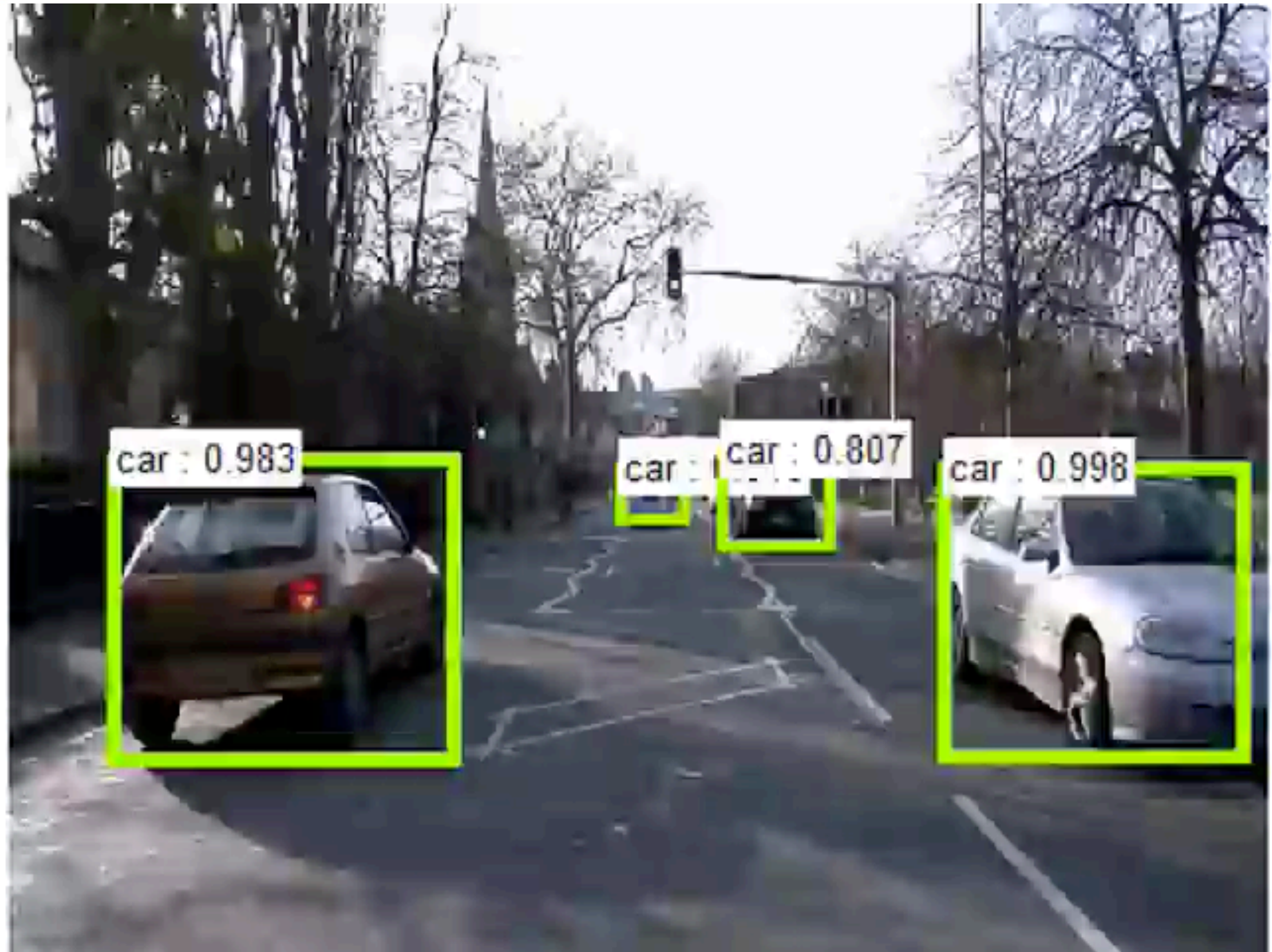
# IMAGE ROI EXTRACTION AND CLASSIFICATION

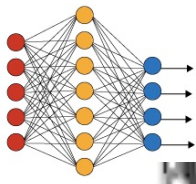




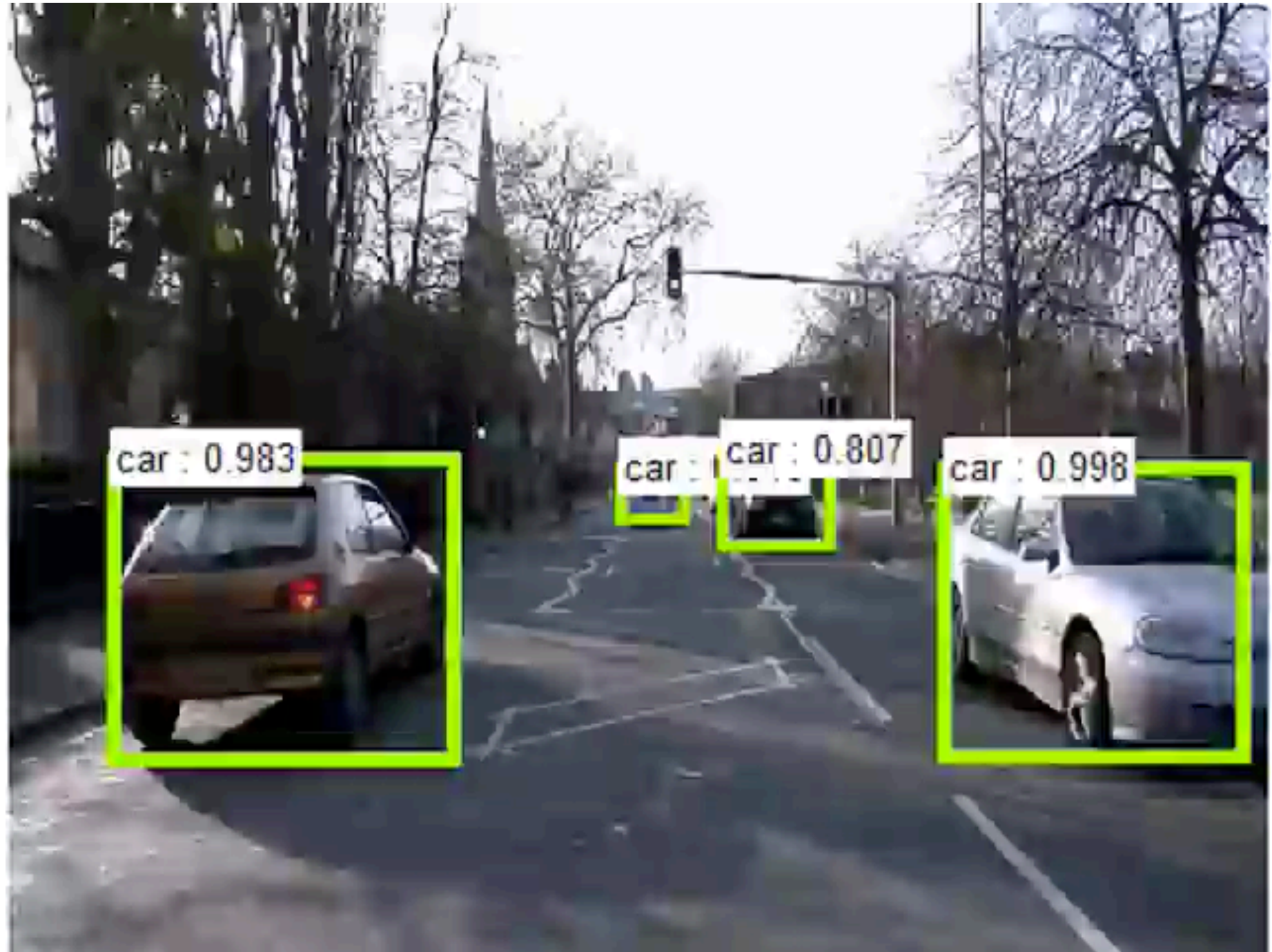


# IMAGE ROI EXTRACTION AND CLASSIFICATION





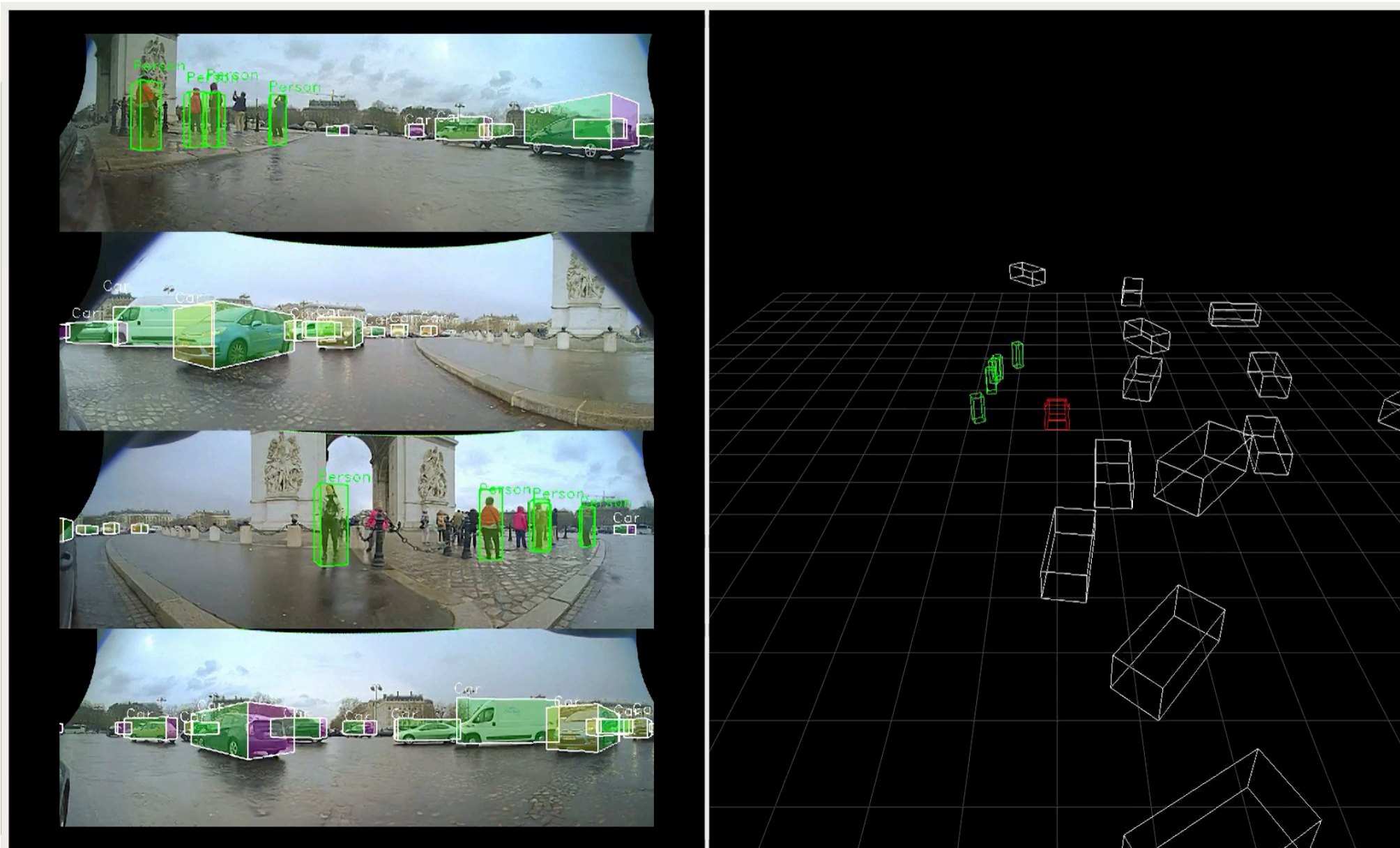
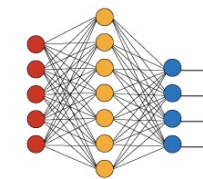
# IMAGE ROI EXTRACTION AND CLASSIFICATION





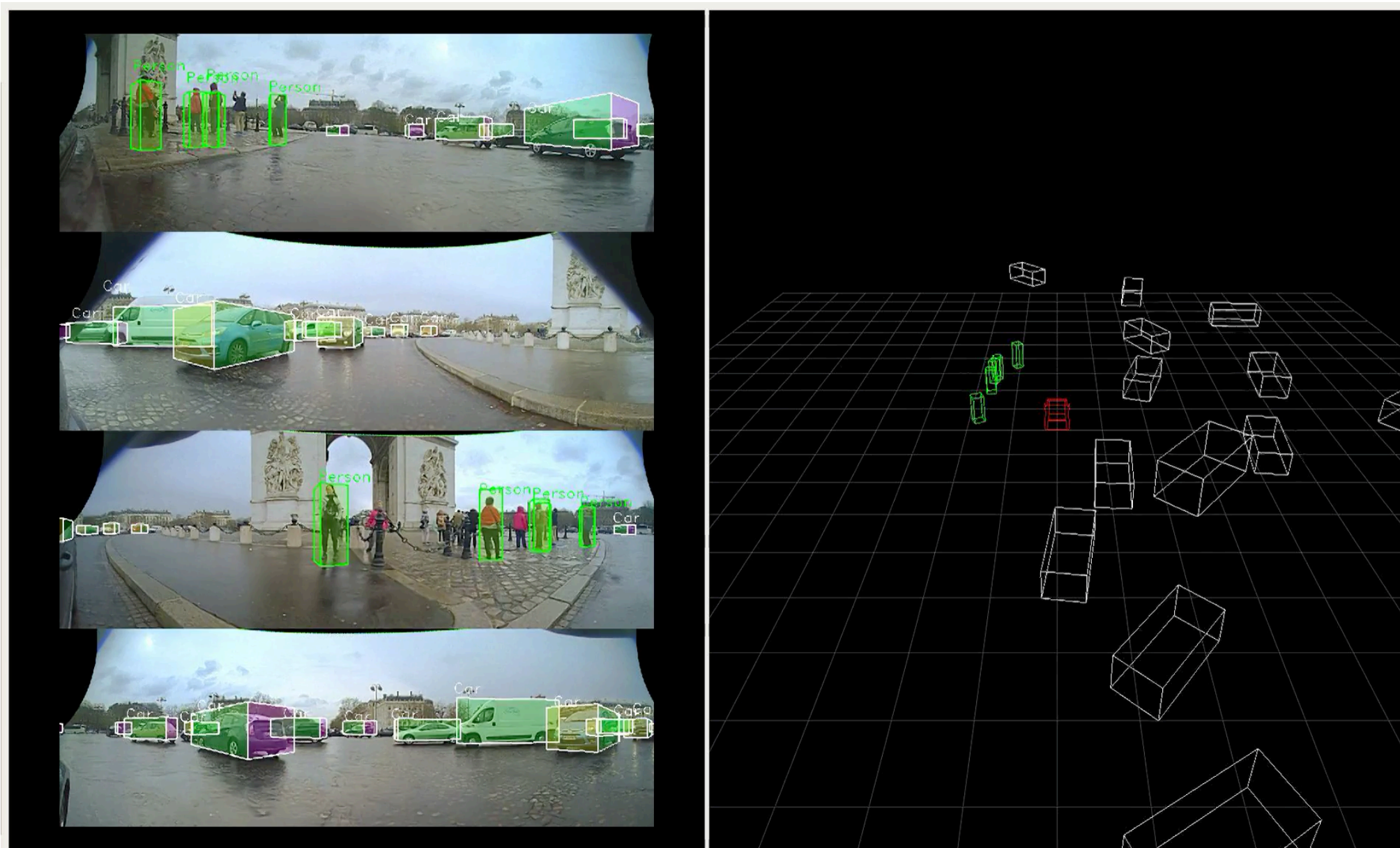
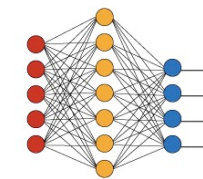
# DEEP MANTA

## MANY-TASK DEEP NEURAL NETWORK FOR VISUAL OBJECT RECOGNITION



# DEEP MANTA

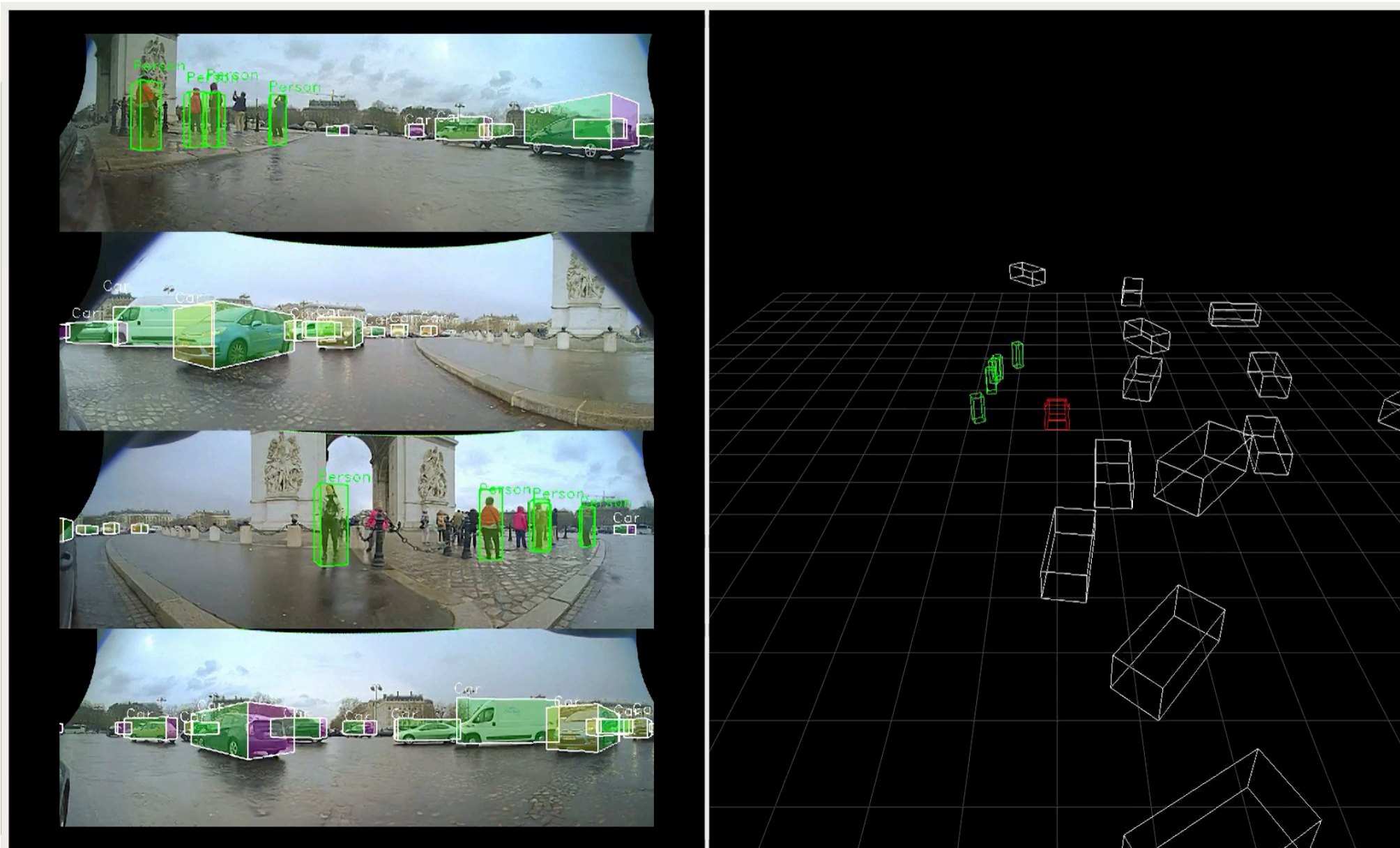
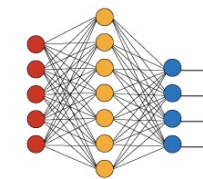
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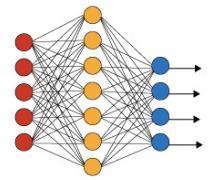


# DEEP MANTA

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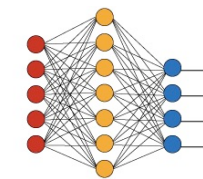


## 2025: Tesla's FSD on the same location



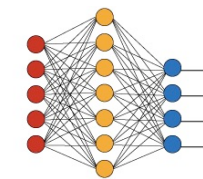


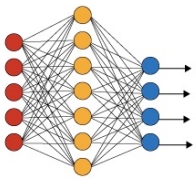
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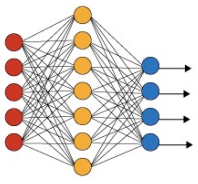




## DEEP LEARNING AND VOICE RECOGNITION

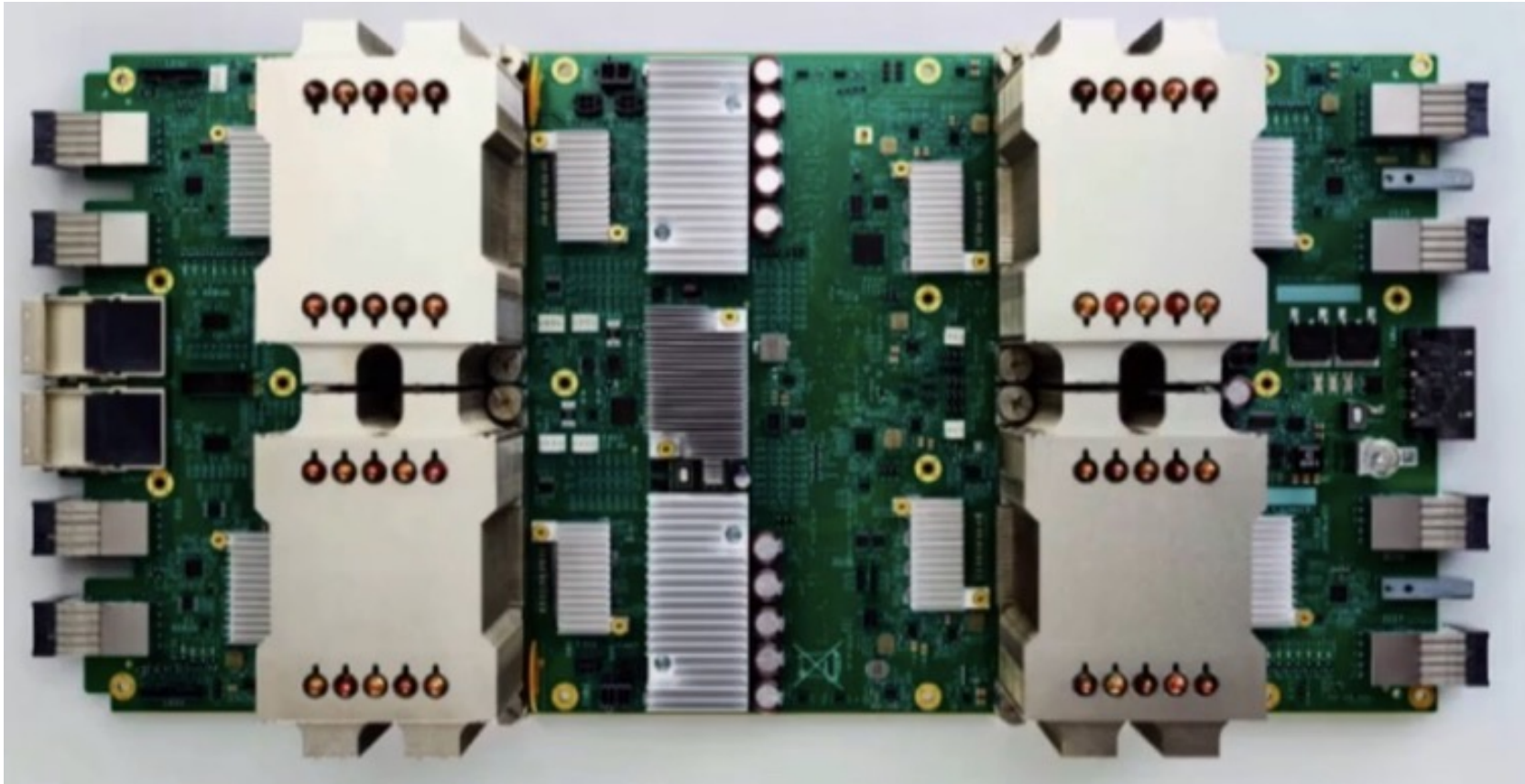
" The need for TPUs really emerged about six (12) years ago, when we started using computationally expensive deep learning models in more and more places throughout our products. The computational expense of using these models had us worried. If we considered a scenario where **people use Google voice search for just three minutes a day** and we ran deep neural nets for our speech recognition system on the processing units we were using, ***we would have had to double the number of Google data centers!***"

[<https://cloudplatform.googleblog.com/2017/04/quantifying-the-performance-of-the-TPU-our-first-machine-learning-chip.html>]

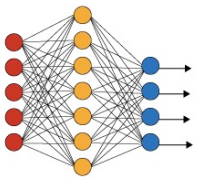


## 2017: GOOGLE'S CUSTOMIZED HARDWARE...

... required to increase energy efficiency  
with **accuracy adapted to the use (e.g. float 16)**

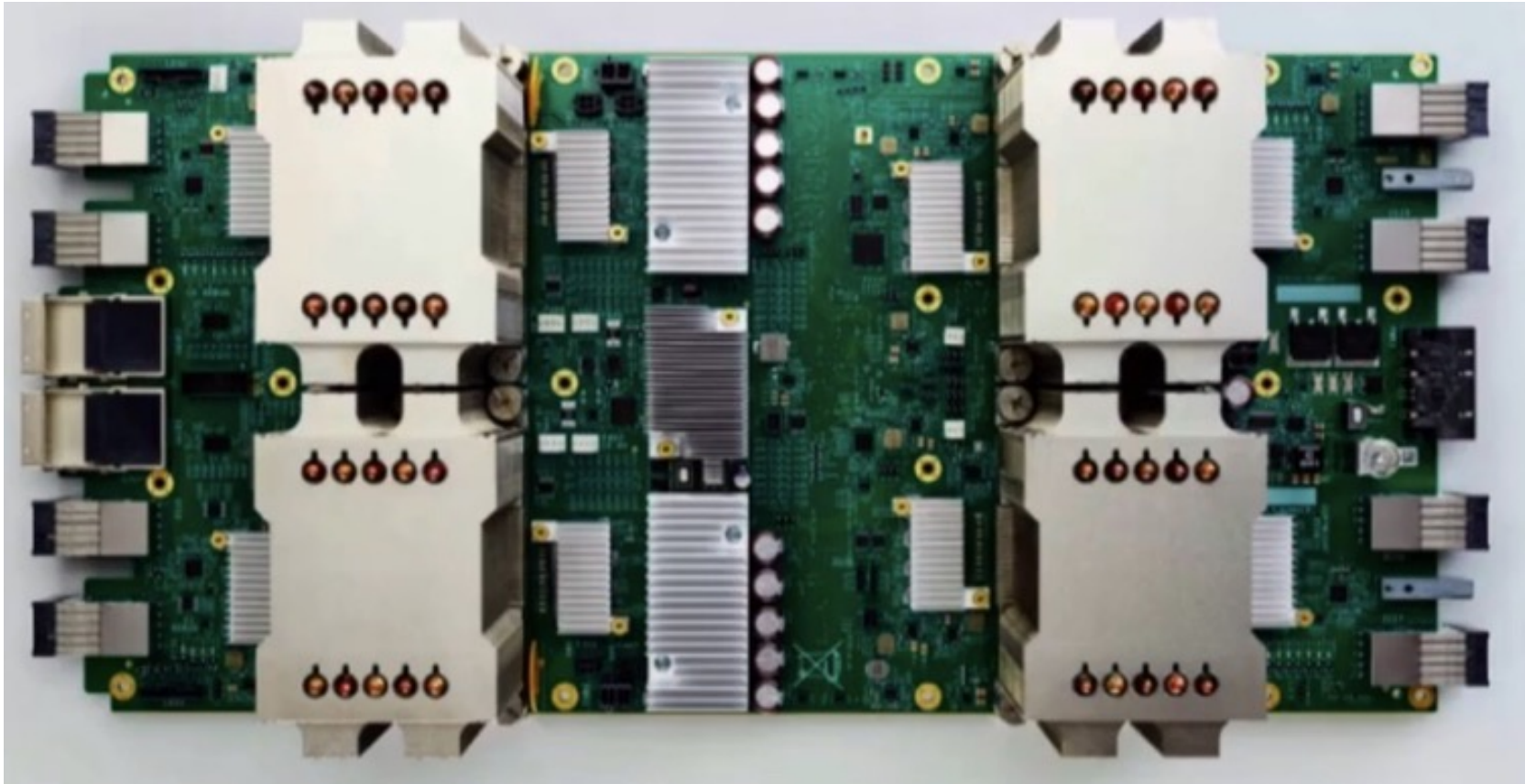






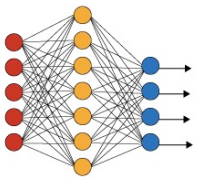
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Google's TPU2 : training and inference in a **180 teraflops<sub>16</sub>** board  
(over 200W per TPU2 chip according to the size of the heat sink)



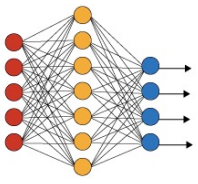


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Peta =  $10^{15}$  = million of milliard



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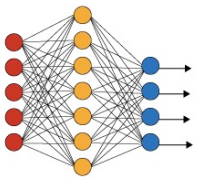
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Google's TPU2 : **11.5 petaflops<sub>16</sub>** of machine learning number crunching  
(and guessing about 400+ KW..., 100+ GFlops<sub>16</sub>/W)

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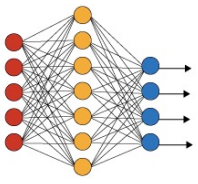


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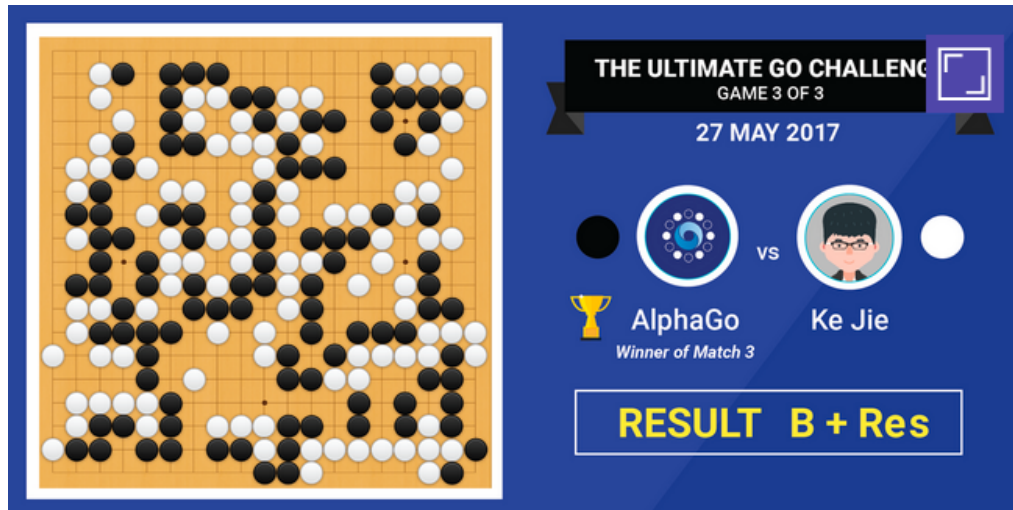
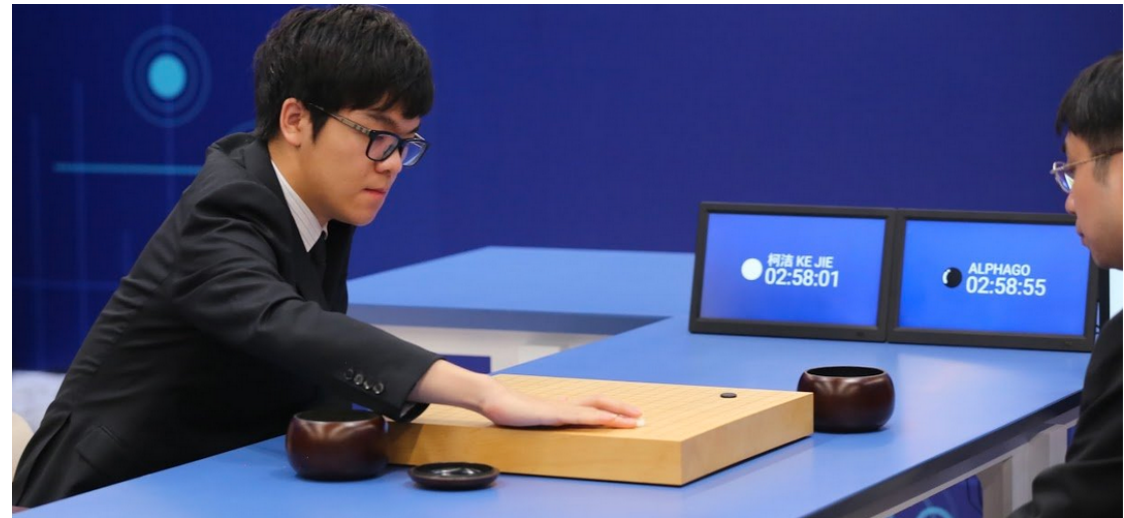


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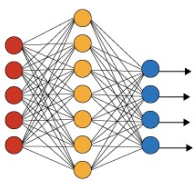


## 2017: THE GAME OF GO

Ke Jie (human world champion in the “Go” game), after being defeated by AlphaGo on May 27th 2017, will work with Deepmind to make a tool from AlphaGo to further help Go players to enhance their game.

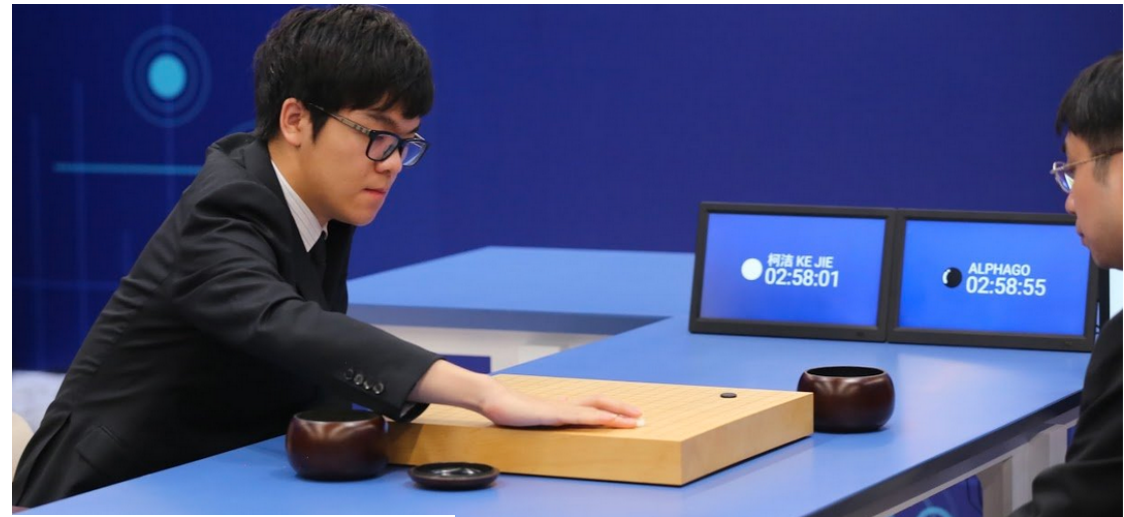






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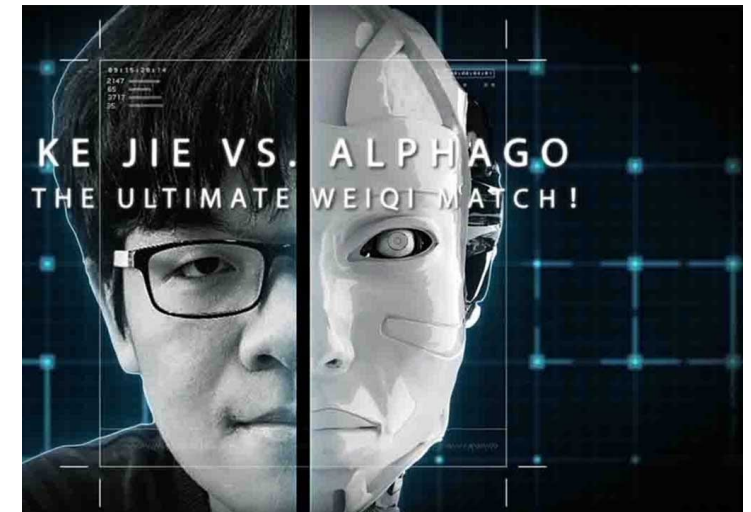
## ARTICLE

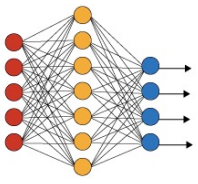
doi:10.1038/nature16961

# Mastering the game of Go with deep neural networks and tree search

David Silver<sup>1\*</sup>, Aja Huang<sup>1\*</sup>, Chris J. Maddison<sup>1</sup>, Arthur Guez<sup>1</sup>, Laurent Sifre<sup>1</sup>, George van den Driessche<sup>1</sup>, Julian Schrittwieser<sup>1</sup>, Ioannis Antonoglou<sup>1</sup>, Veda Panneershelvam<sup>1</sup>, Marc Lanctot<sup>1</sup>, Sander Dieleman<sup>1</sup>, Dominik Grewe<sup>1</sup>, John Nham<sup>2</sup>, Nal Kalchbrenner<sup>1</sup>, Ilya Sutskever<sup>2</sup>, Timothy Lillicrap<sup>1</sup>, Madeleine Leach<sup>1</sup>, Koray Kavukcuoglu<sup>1</sup>, Thore Graepel<sup>1</sup> & Demis Hassabis<sup>1</sup>

The game of Go has long been viewed as the most challenging of classic games for artificial intelligence owing to its enormous search space and the difficulty of evaluating board positions and moves. Here we introduce a new approach to computer Go that uses ‘value networks’ to evaluate board positions and ‘policy networks’ to select moves. These deep neural networks are trained by a novel combination of supervised learning from human expert games, and reinforcement learning from games of self-play. Without any lookahead search, the neural networks play Go at the level of state-of-the-art Monte Carlo tree search programs that simulate thousands of random games of self-play. We also introduce a new search algorithm that combines Monte Carlo simulation with value and policy networks. Using this search algorithm, our program AlphaGo achieved a 99.8% winning rate against other Go programs, and defeated the human European Go champion by 5 games to 0. This is the first time that a computer program has defeated a human professional player in the full-sized game of Go, a feat previously thought to be at least a decade away.



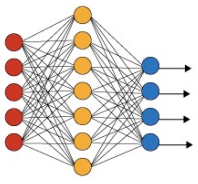


# ALPHAGO ZERO: SELF-PLAYING TO LEARN

AlphaGo Zero  
Starting from scratch



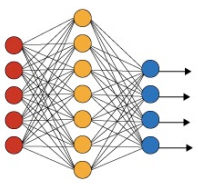
From doi:10.1038/nature24270 (Received 07 April 2017)



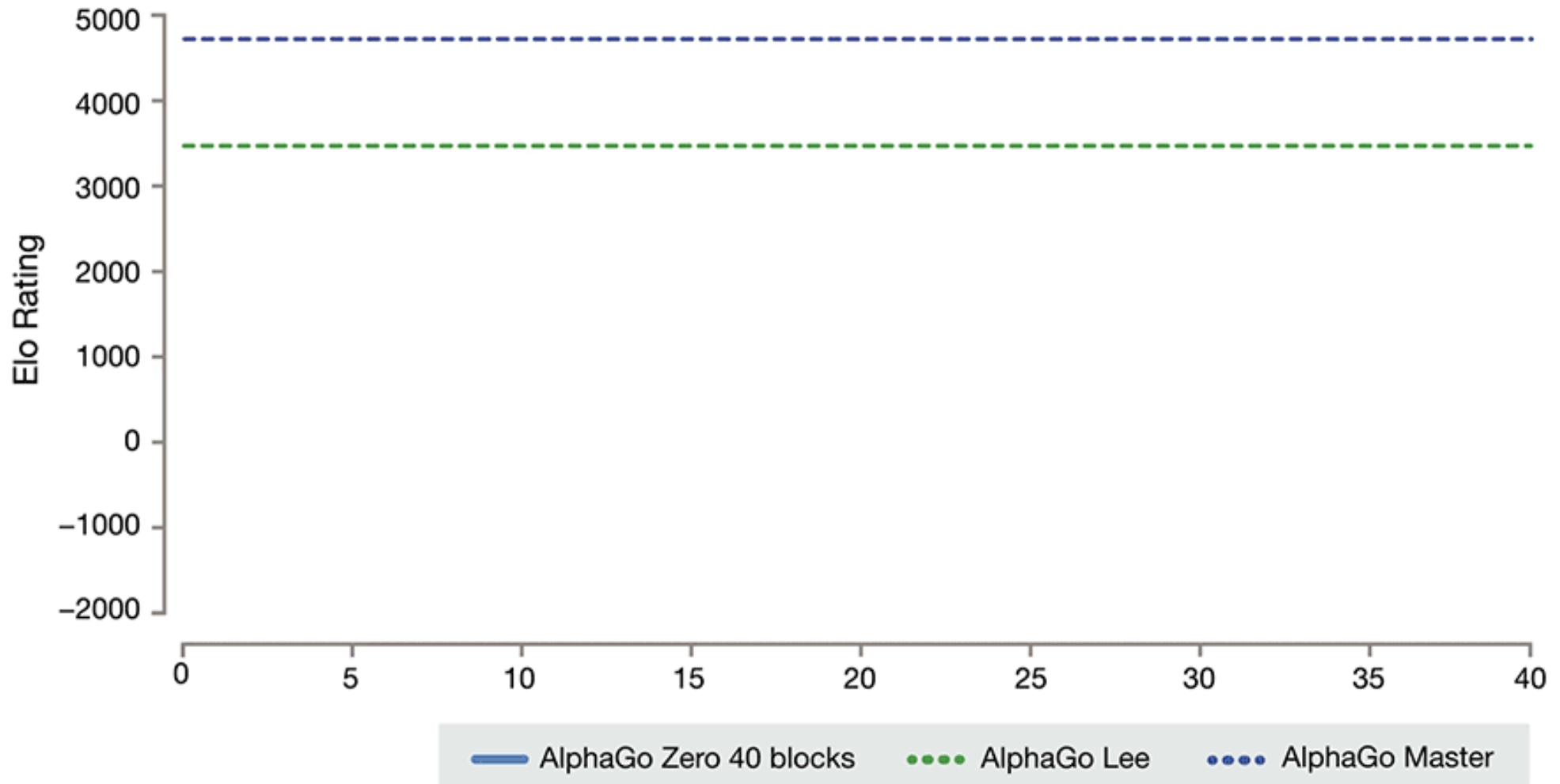
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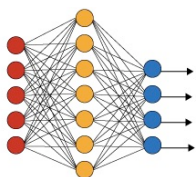


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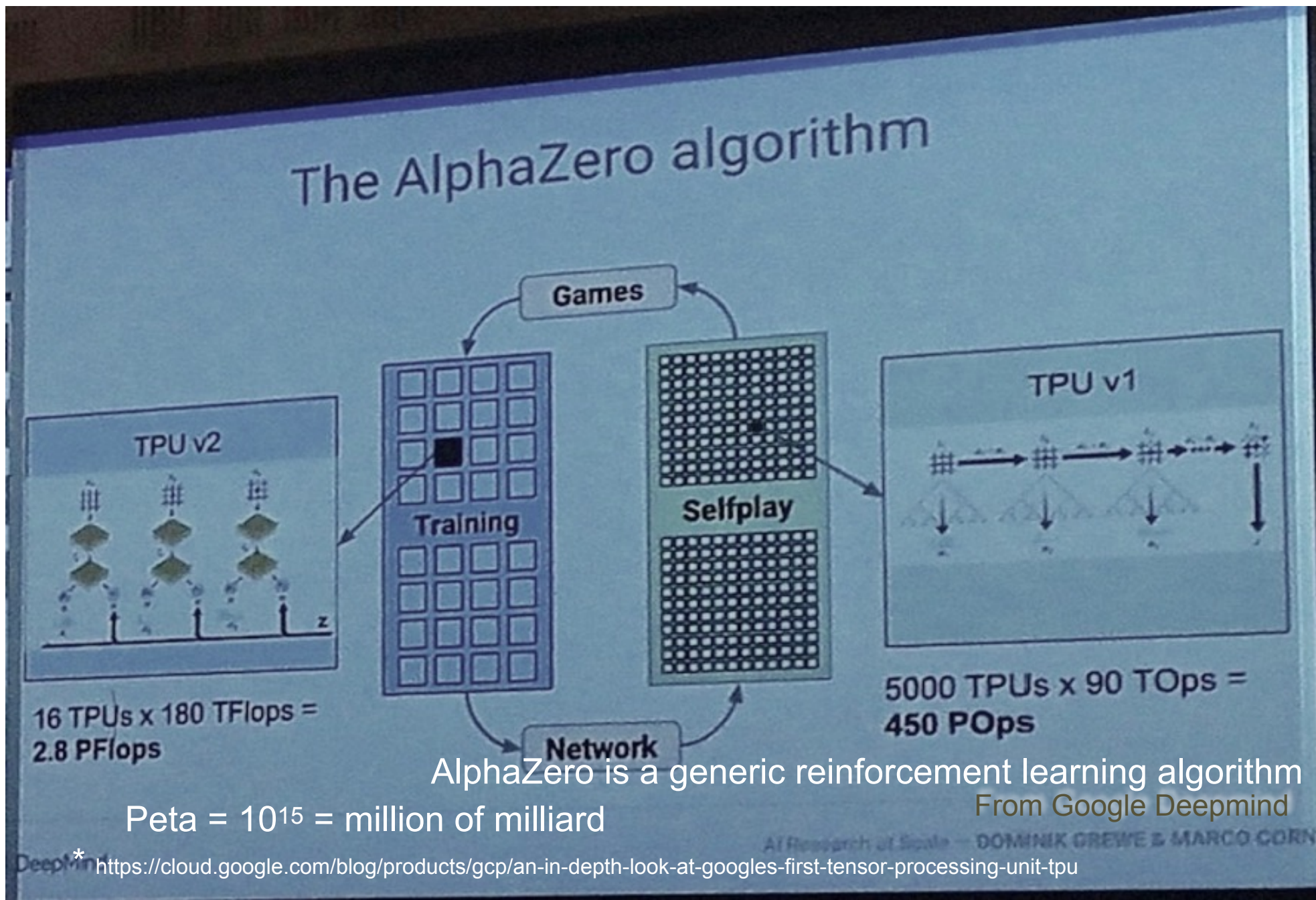


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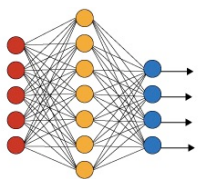




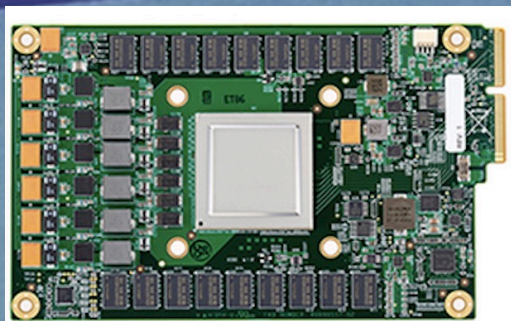
# ALPHAZERO: COMPUTING RESOURCES



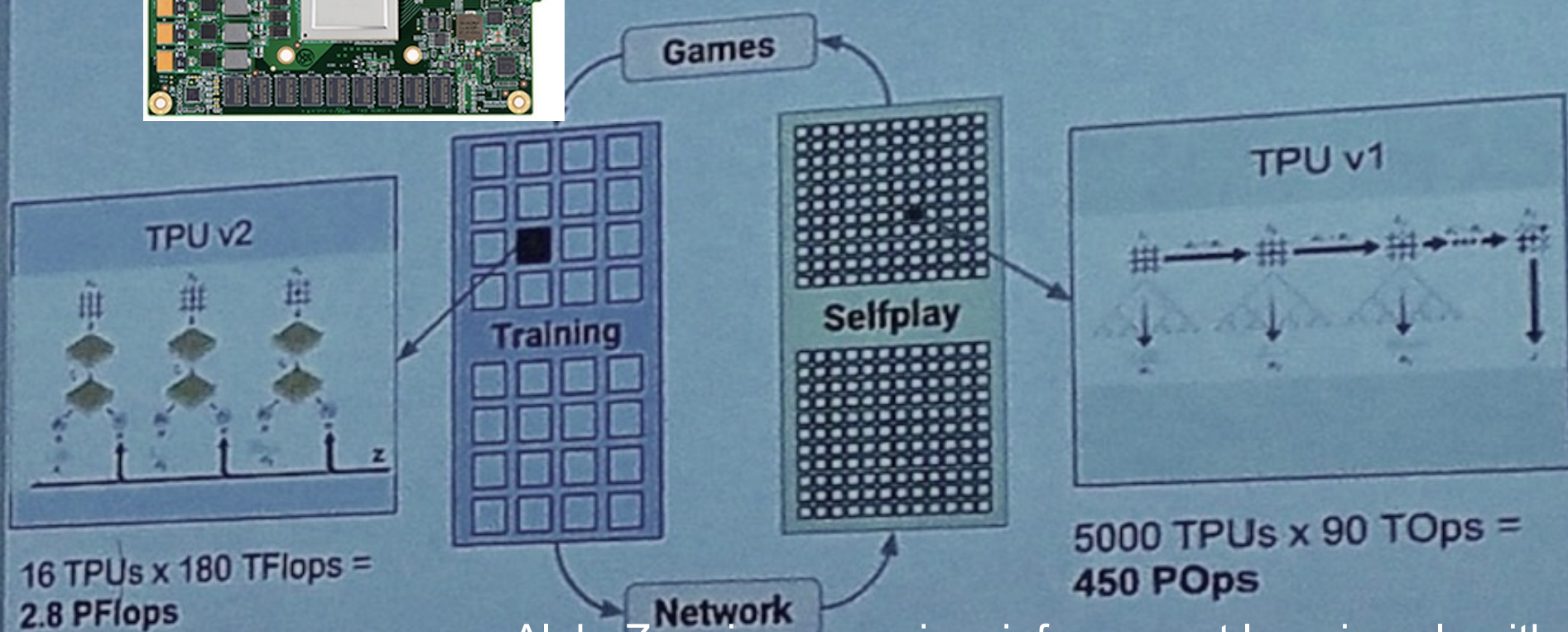




# ALPHAZERO: COMPUTING RESOURCES



AlphaZero algorithm



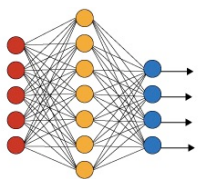
AlphaZero is a generic reinforcement learning algorithm

From Google Deepmind

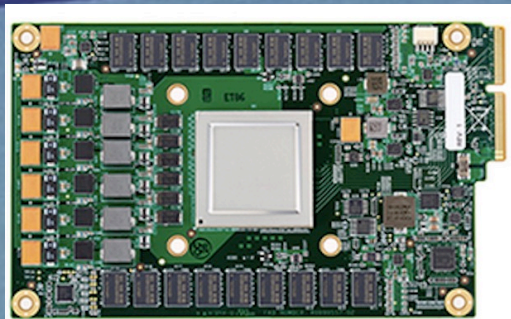
Peta =  $10^{15}$  = million of milliard

\* <https://cloud.google.com/blog/products/gcp/an-in-depth-look-at-googles-first-tensor-processing-unit-tpu>





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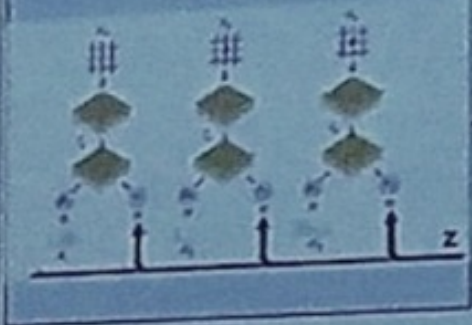


**X 5000**

AlphaZero algorithm

Games

TPU v2

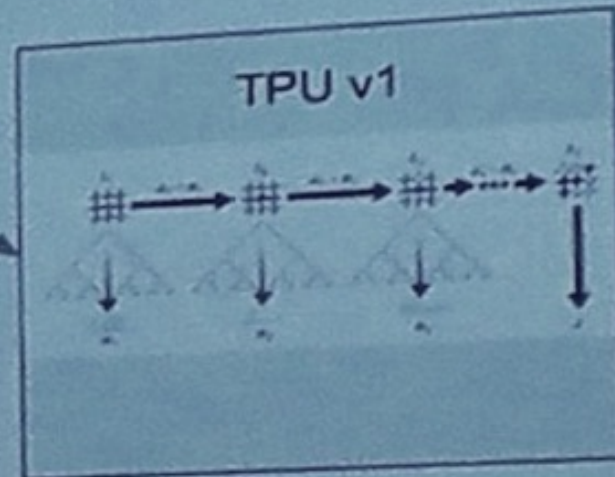


16 TPUs x 180 TFlops =  
2.8 PFlops

Training

Selfplay

TPU v1



5000 TPUs x 90 TOps =  
450 POps

Network

AlphaZero is a generic reinforcement learning algorithm

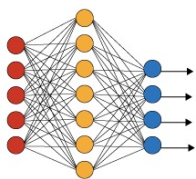
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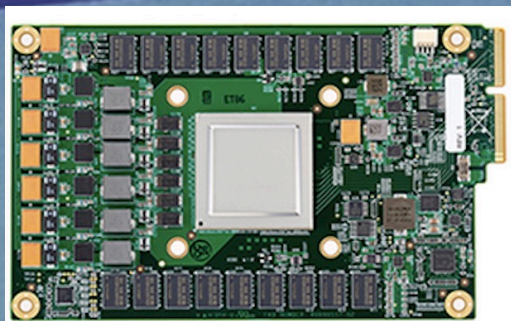
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AI Research at Scale — DOMINIK GREWE & MARCO CORNÉ



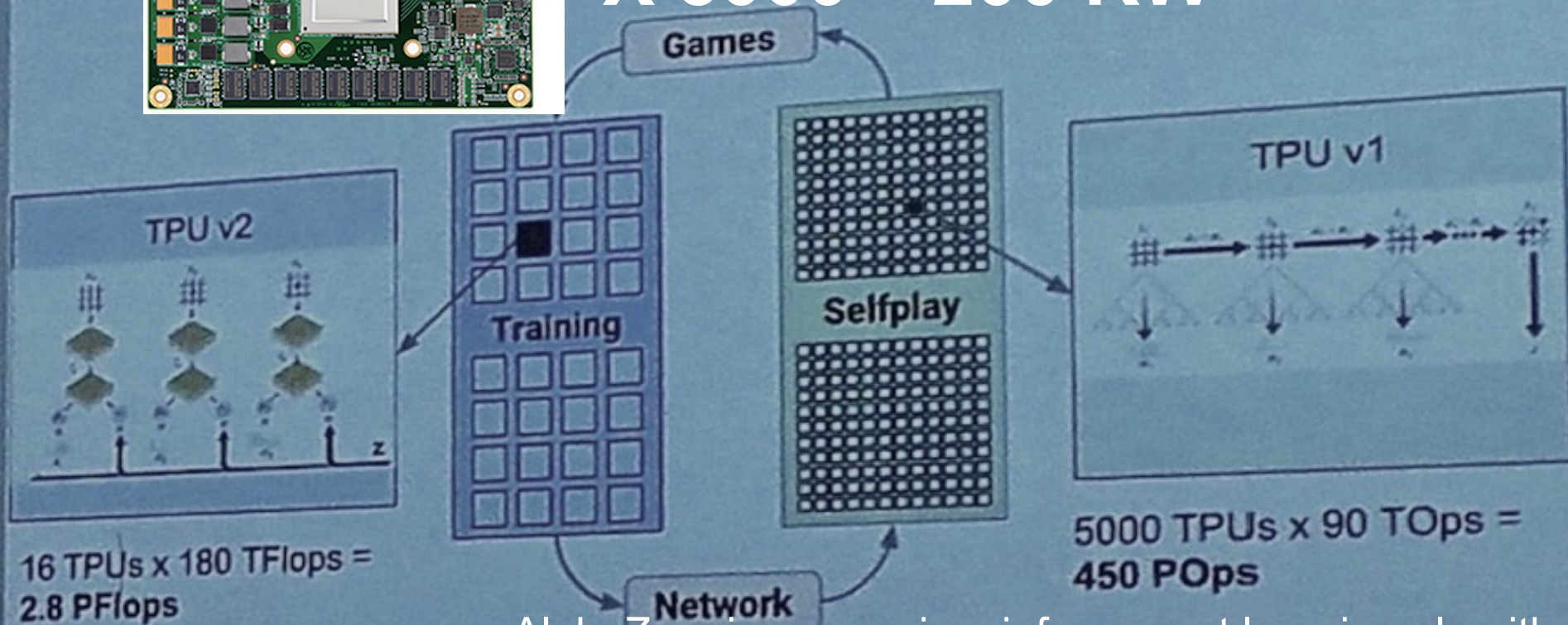


# ALPHAZERO: COMPUTING RESOURCES



AlphaZero algorithm

**X 5000 = 200 KW\***



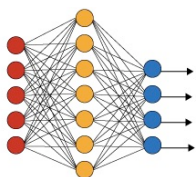
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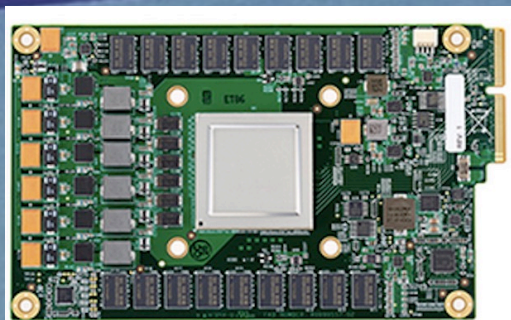
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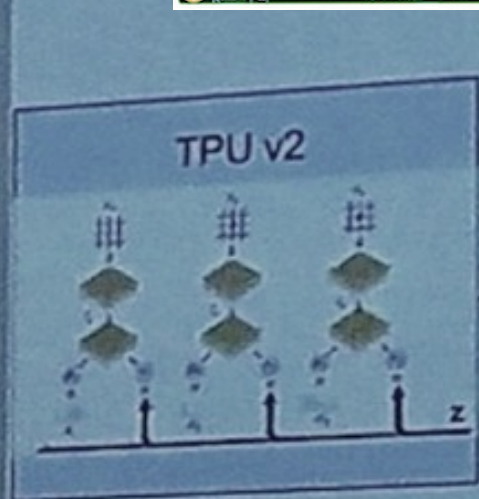
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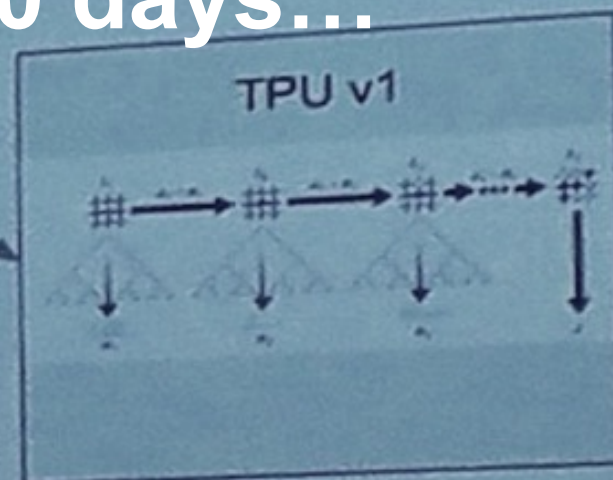
AlphaZero algorithm

X 5000 = 200 KW\*

X 40 days...



16 TPUs x 180 TFlops =  
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5000 TPUs x 90 TOPs =  
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AlphaZero is a generic reinforcement learning algorithm

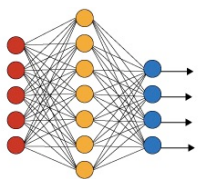
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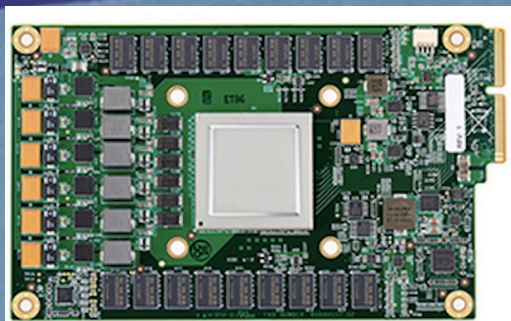
AI Research at Scale — DOMINIK GREWE & MARCO CORNÉ





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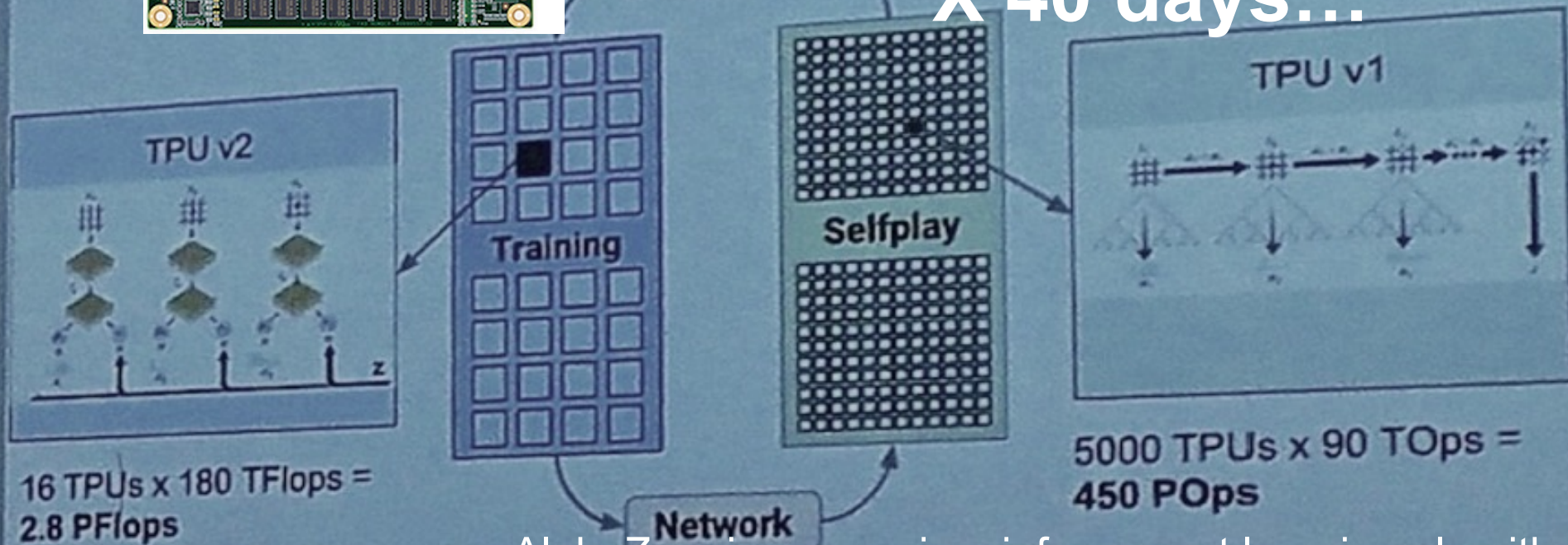
Follow-up is called MuZero (2019)



AlphaZero algorithm

X 5000 = 200 KW\*

X 40 days...



AlphaZero is a generic reinforcement learning algorithm

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## A SHORT STORY ON ARTIFICIAL INTELLIGENCE AND DEEP LEARNING

**Marc Duranton**

***Move to:***

Commissariat à l'énergie atomique et aux énergies alternatives

**Part 2: from 2017: the era of generative AI**





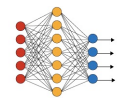
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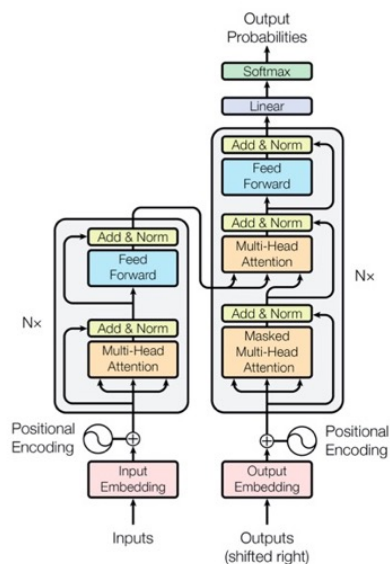
Commissariat à l'énergie atomique et aux énergies alternatives

June 4<sup>th</sup>, 2025



# The origin of LLMs: Transformers (2017)

We propose a new simple network architecture, the Transformer, based solely on attention mechanisms, dispensing with recurrence and convolutions entirely. Experiments on two machine translation tasks show these models to be superior in quality while being more parallelizable and requiring significantly less time to train. On the WMT 2014 English-to-French translation task, our model establishes a new single-model state-of-the-art BLEU score of 41.8 after training for 3.5 days on eight GPUs, a small fraction of the training costs of the best models from the literature. We show that the Transformer generalizes well to other tasks by applying it successfully to English constituency parsing both with large and limited training data.



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## Attention Is All You Need

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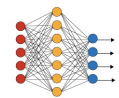
**Llion Jones\***  
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**Aidan N. Gomez\* †**  
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**Łukasz Kaiser\***  
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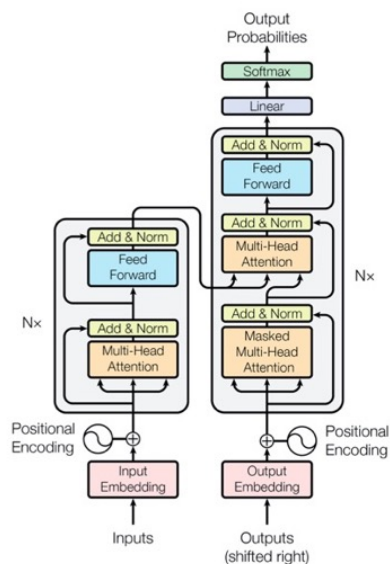
**Illia Polosukhin\* ‡**  
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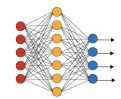
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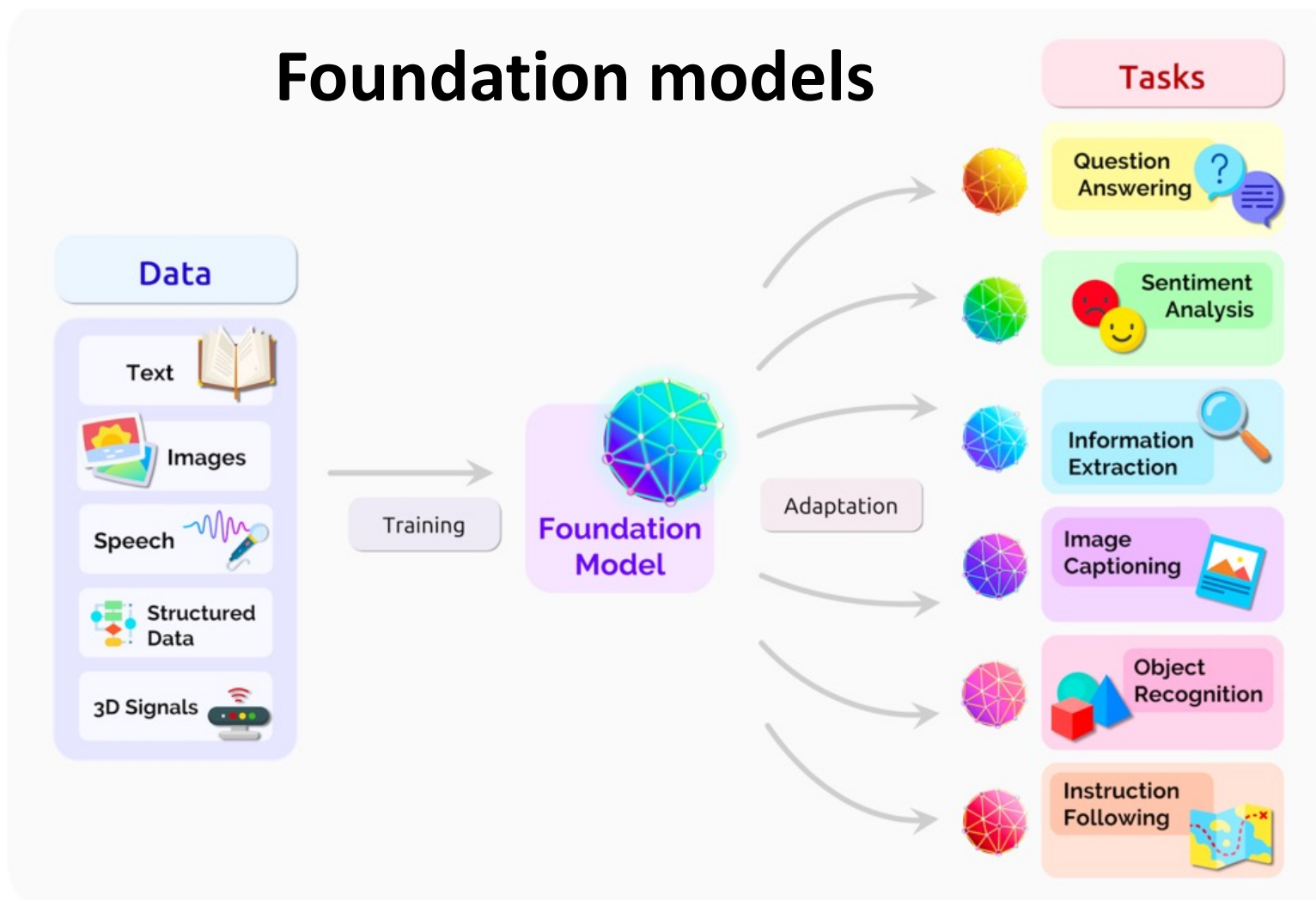
**Aidan N. Gomez\* †**  
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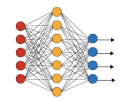


# Foundation models

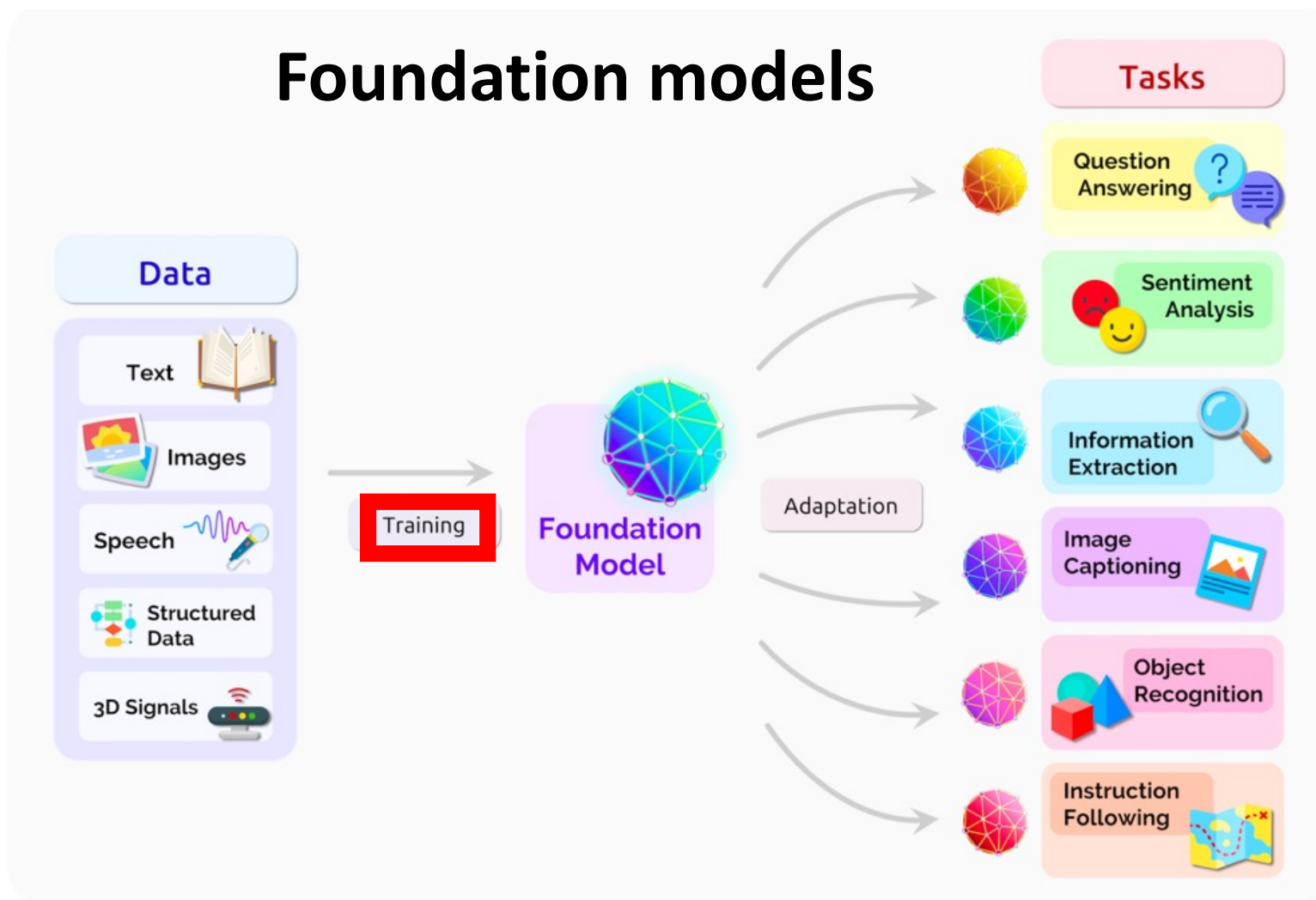


« A foundation model can centralize the information from all the data from various modalities. This one model can then be adapted to a wide range of downstream tasks. »

From « On the Opportunities and Risks of Foundation Models » <https://arxiv.org/abs/2108.07258>



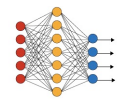
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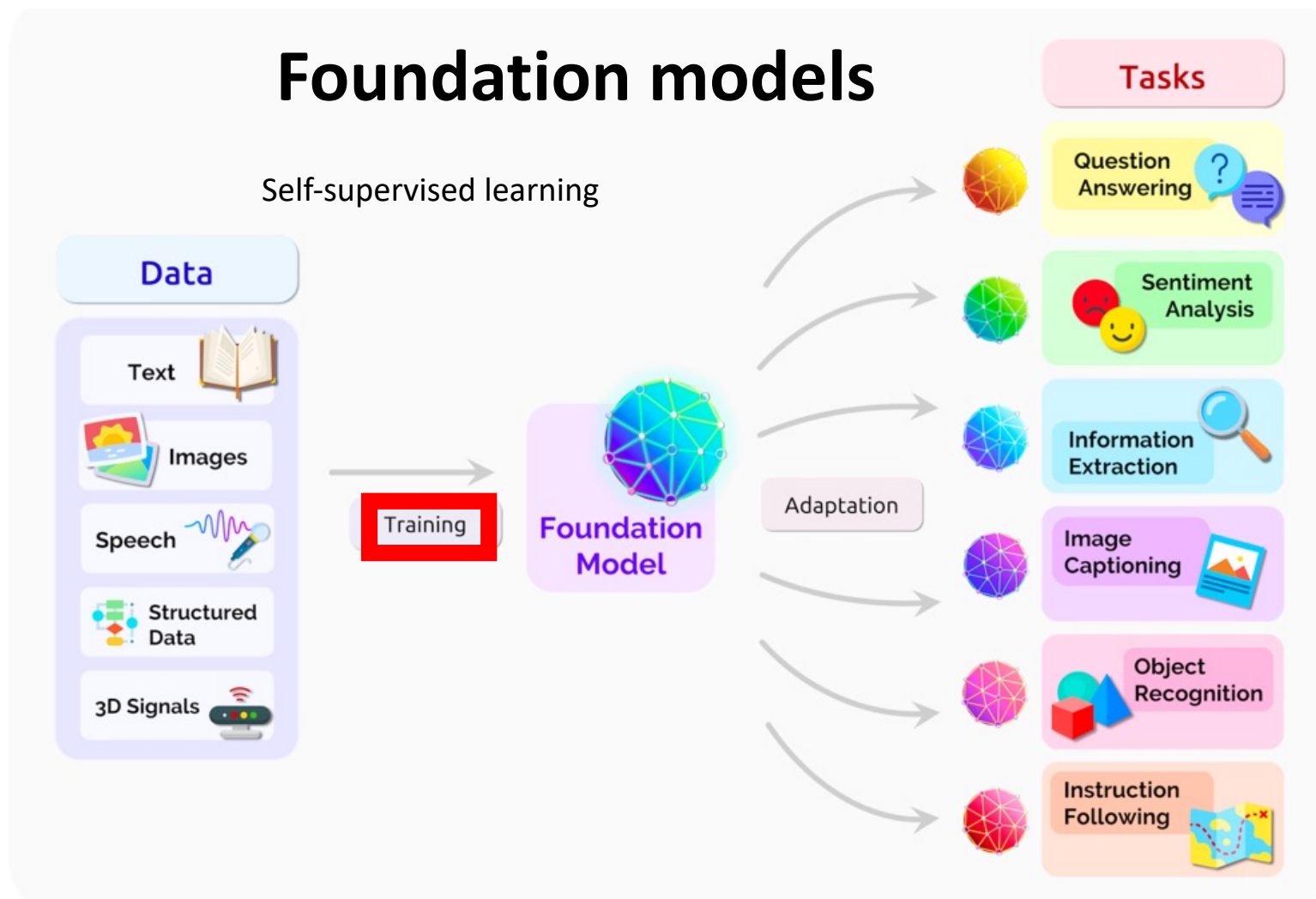
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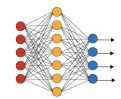


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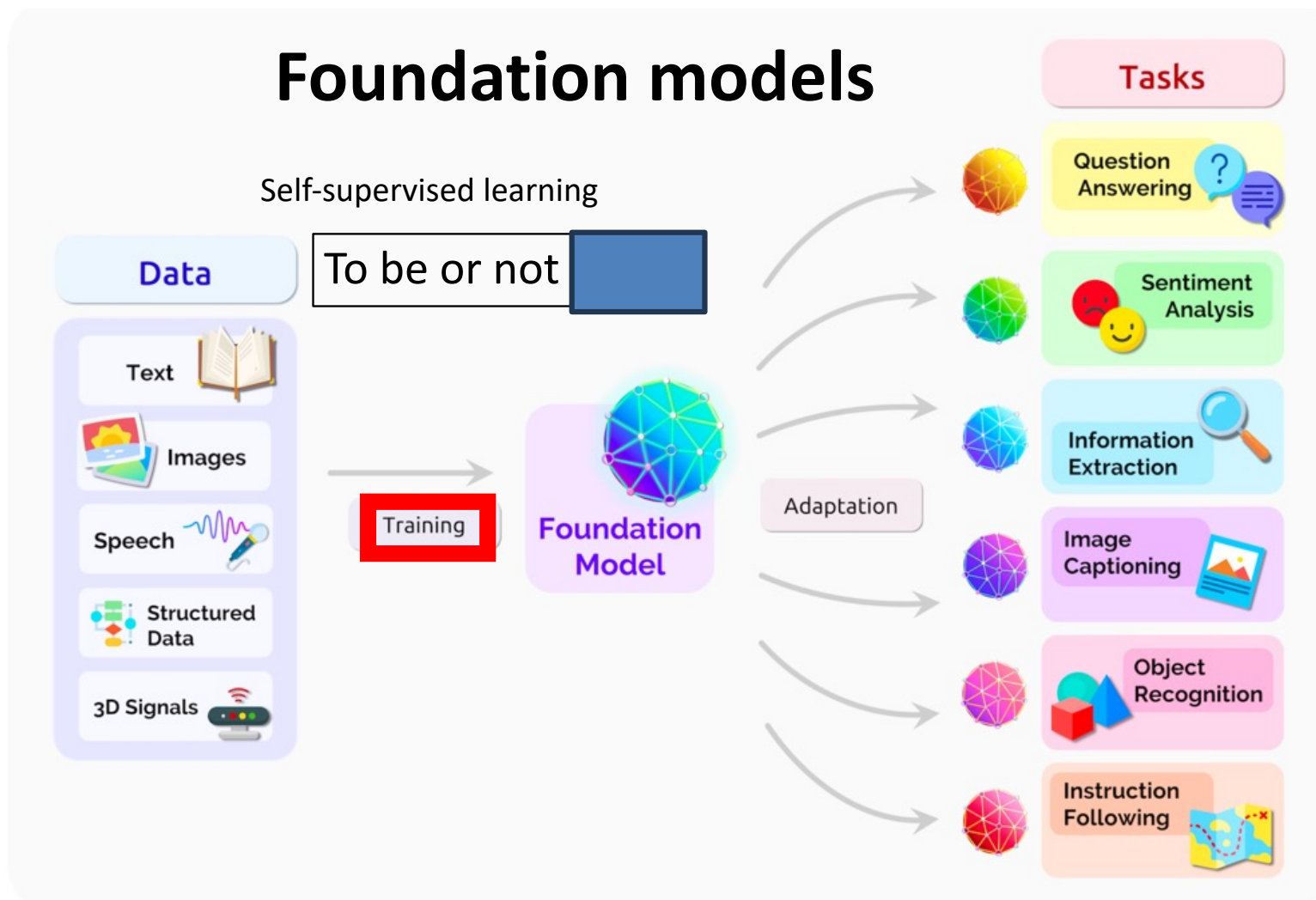


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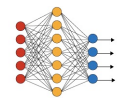


# Foundation models

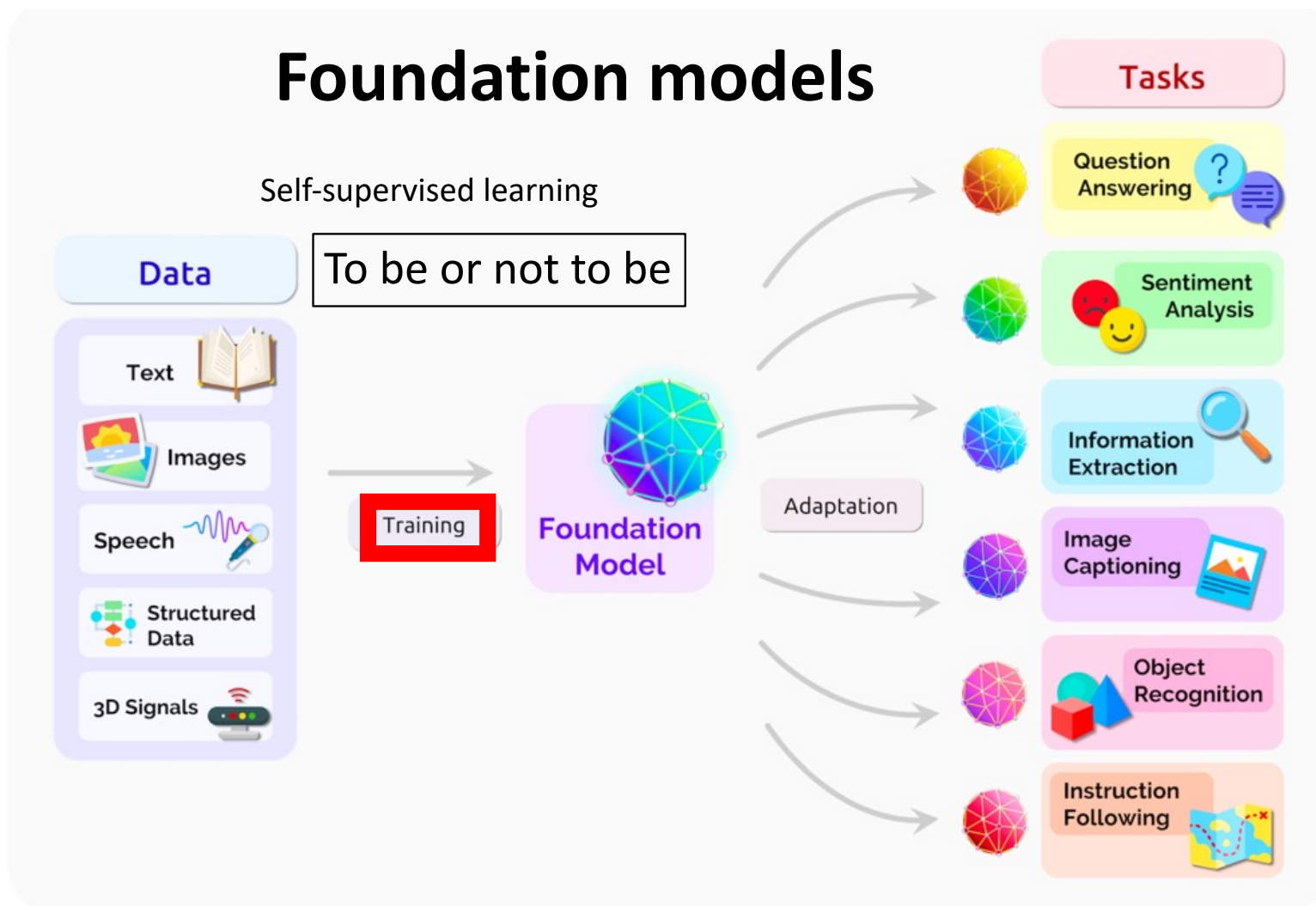


« A foundation model can centralize the information from all the data from various modalities. This one model can then be adapted to a wide range of downstream tasks. »

From « On the Opportunities and Risks of Foundation Models » <https://arxiv.org/abs/2108.07258>



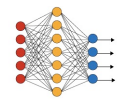
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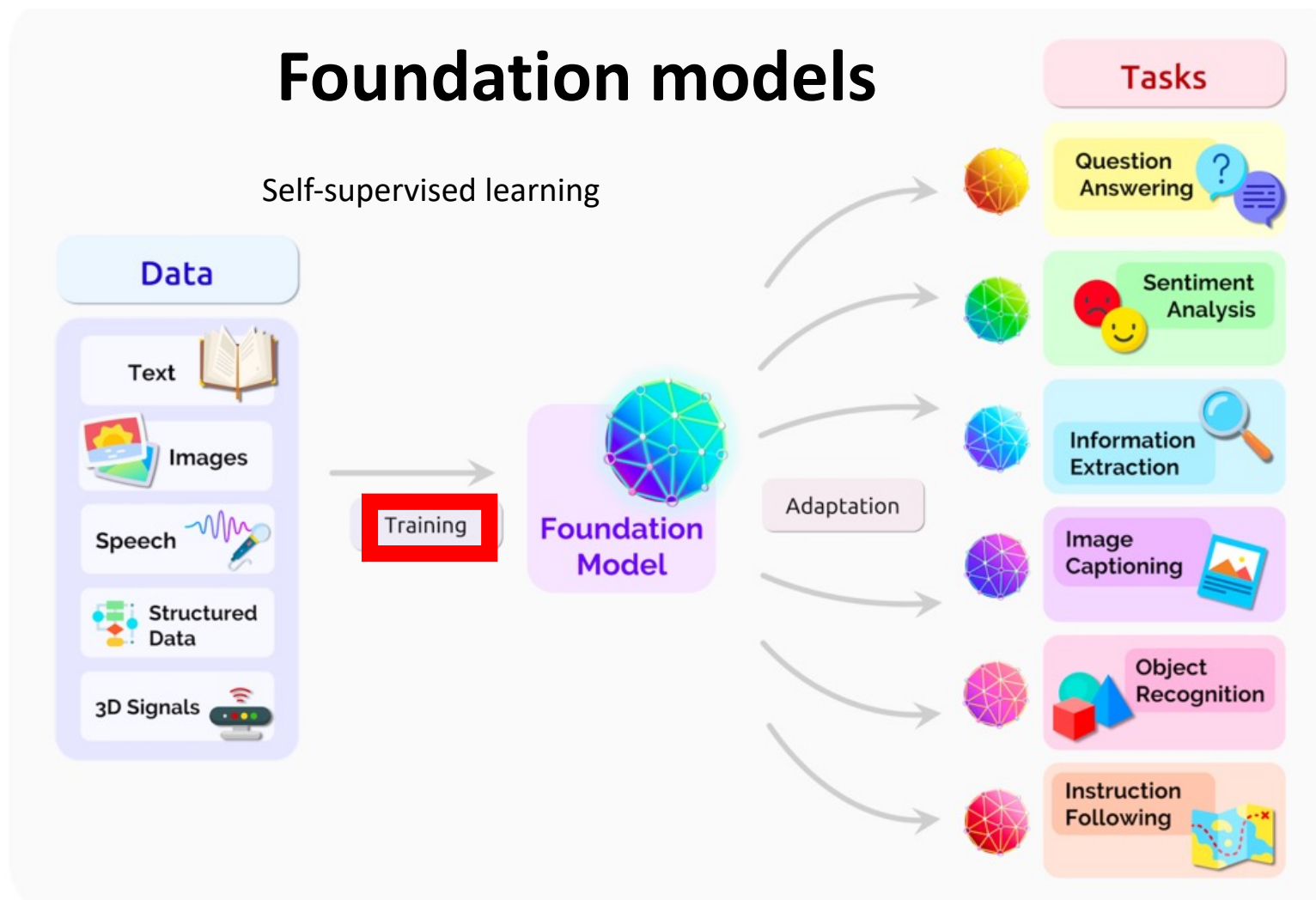
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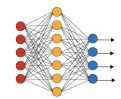
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Self-supervised learning

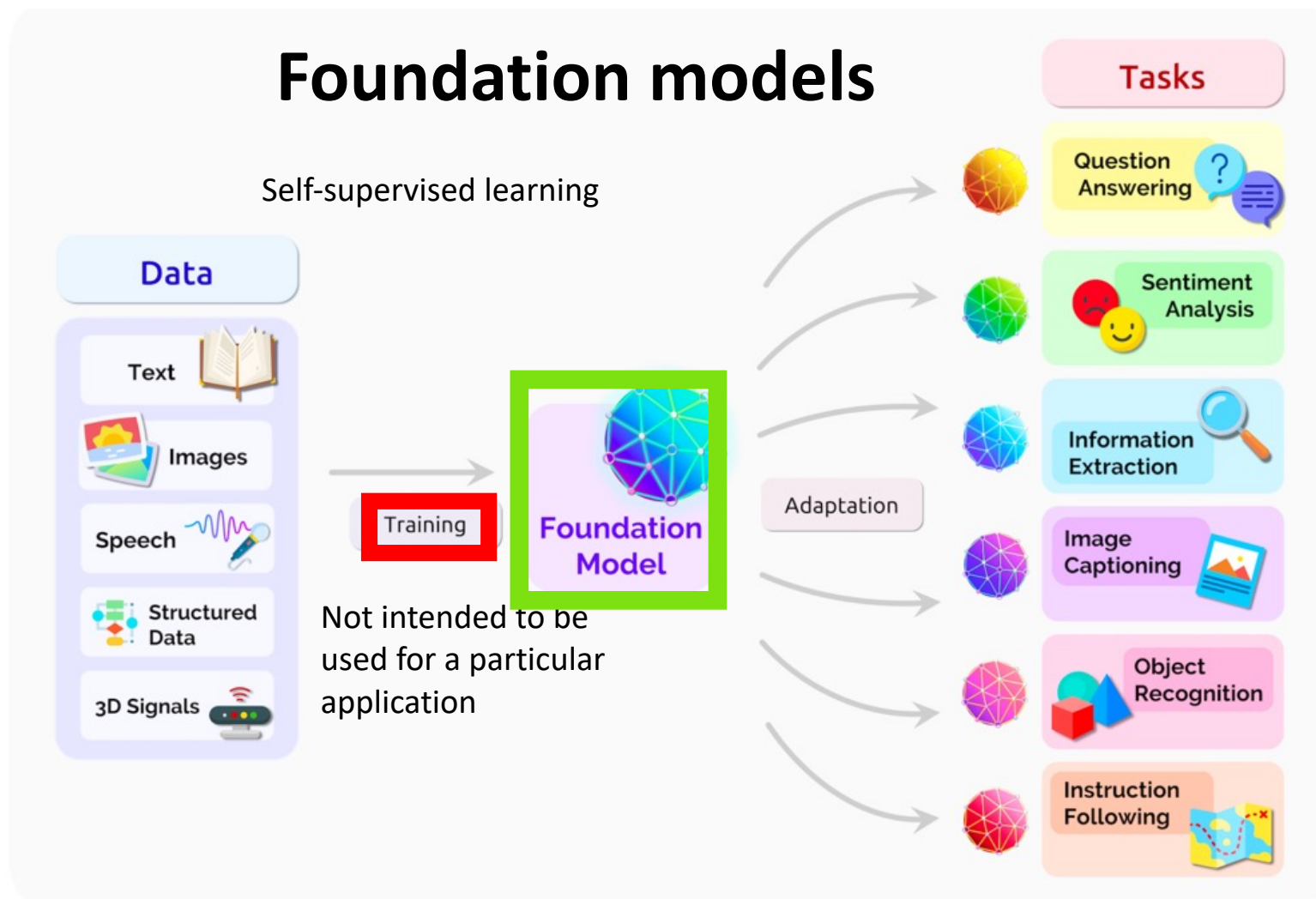


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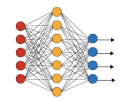


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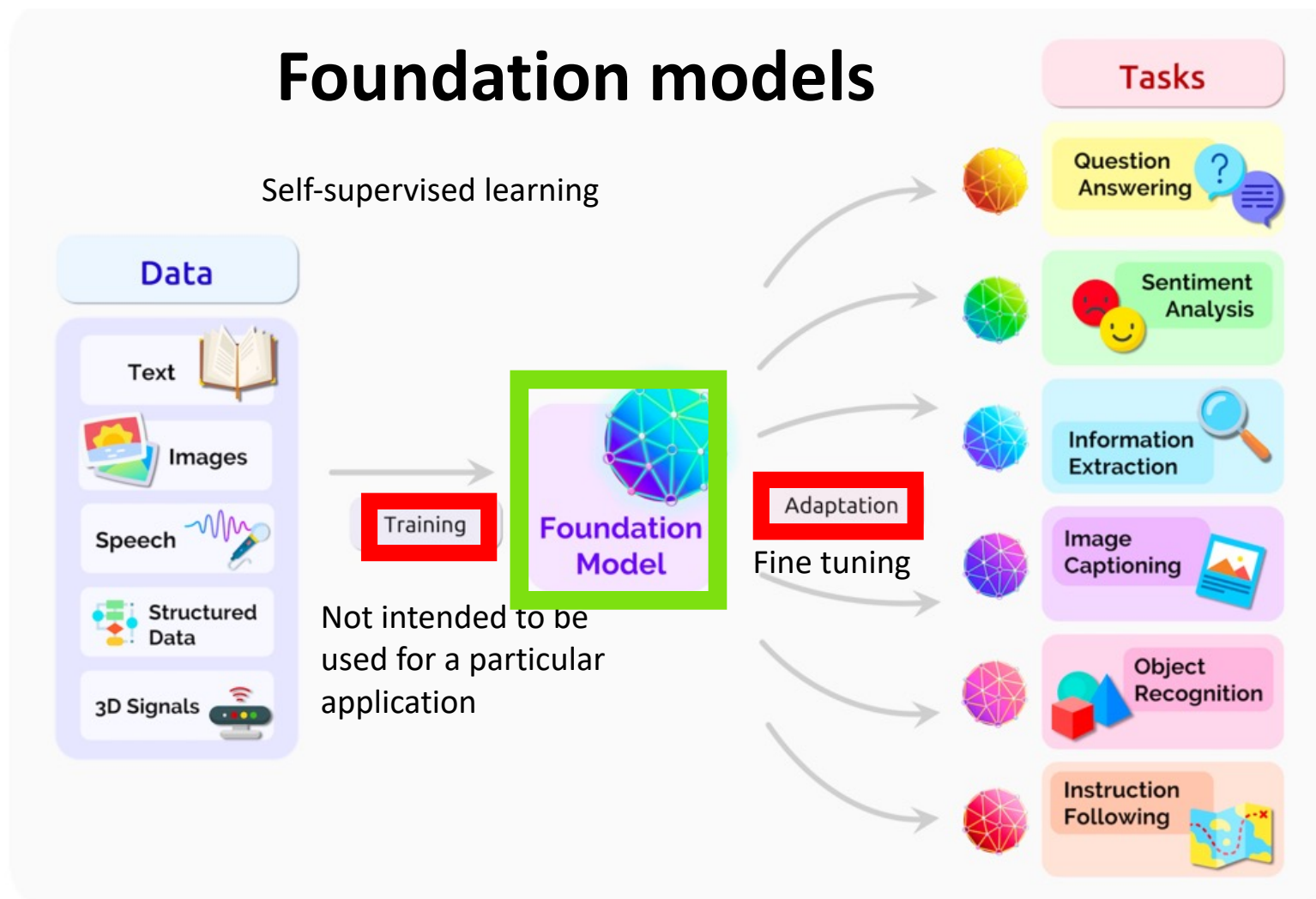


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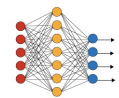
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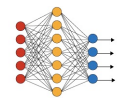




# Evolution of Generative Pre-trained Transformers (GPT) in OpenAI

Model	Architecture	Parameter count	Training data	Release date	Training cost
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<a href="#">GPT-3.5</a>	Undisclosed	175 billion	Undisclosed	March 15, <b>2022</b>	Undisclosed
<a href="#">ChatGPT</a>	Undisclosed	? (rumor 20M???)		<b>November 20, 2022</b>	
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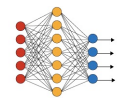


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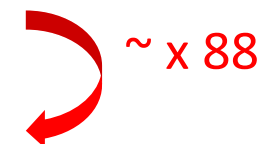


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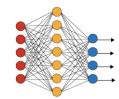
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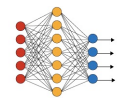
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## Compute requirement

~ x 88

~ x 213



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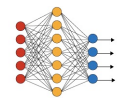
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## Compute requirement

~ x 88

~ x 213

~ x 65




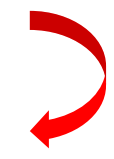
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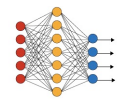
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 ~ x 213

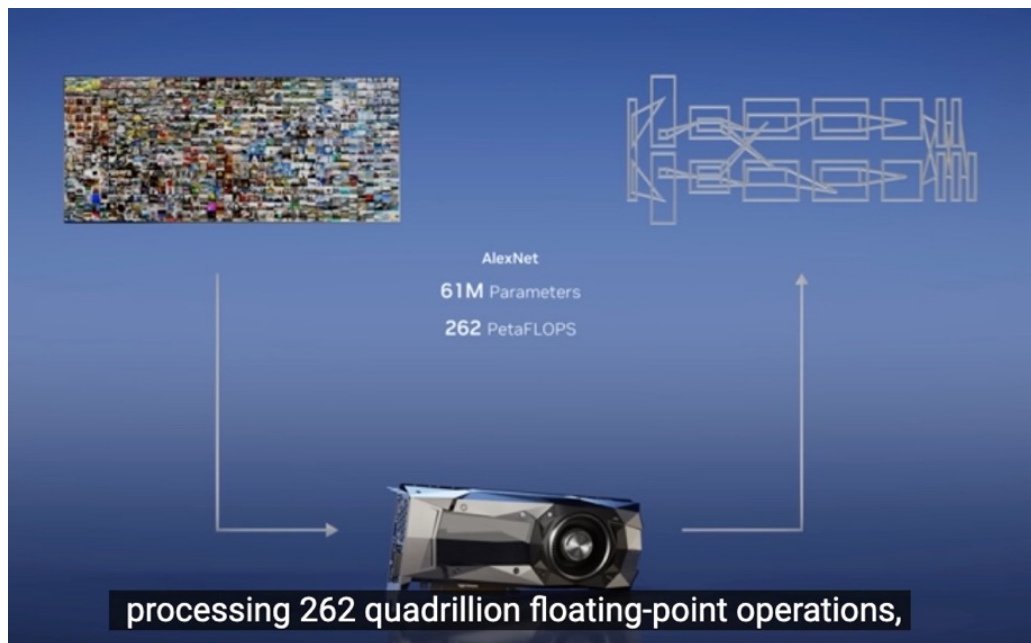
 ~ x 65

**~ x 1 218 360**



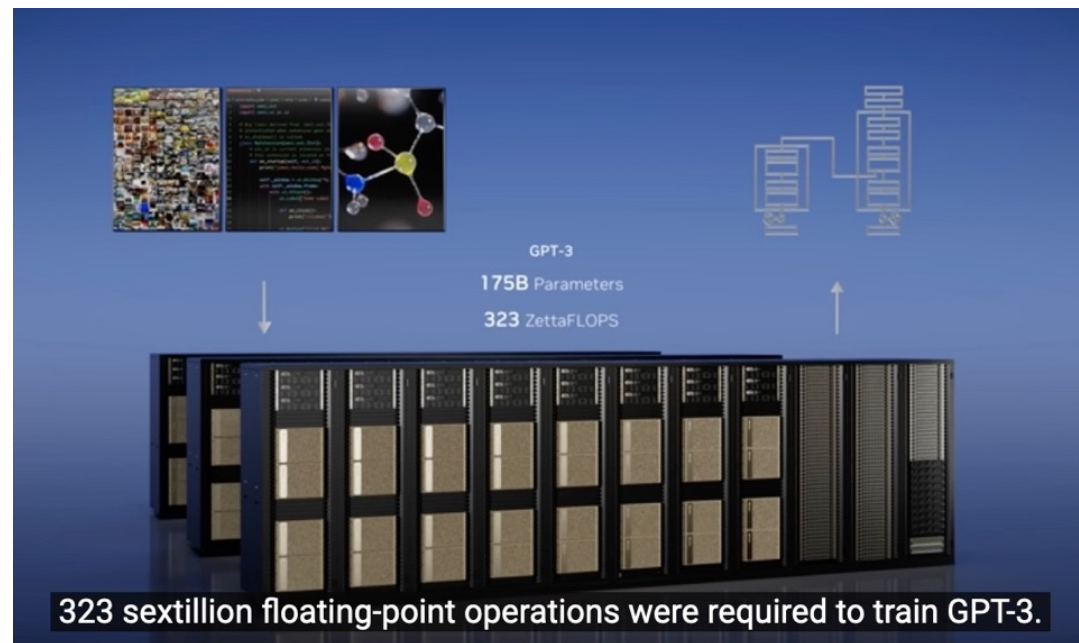


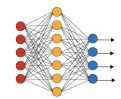
# Computing power is driving the advance of AI



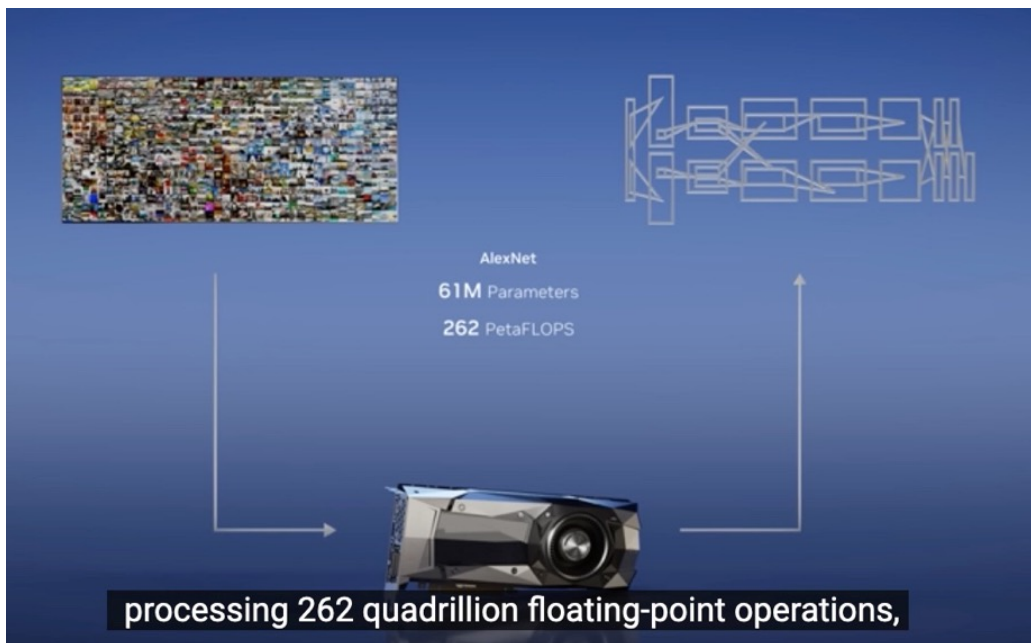
2012: AlexNet  
GeForce GTX 580  
Won ImageNet Challenge  
 $262 \times 10^{15}$  FLOPS (262 PetaFLOPS)

From GTC 2023 Keynote with NVIDIA CEO Jensen Huang



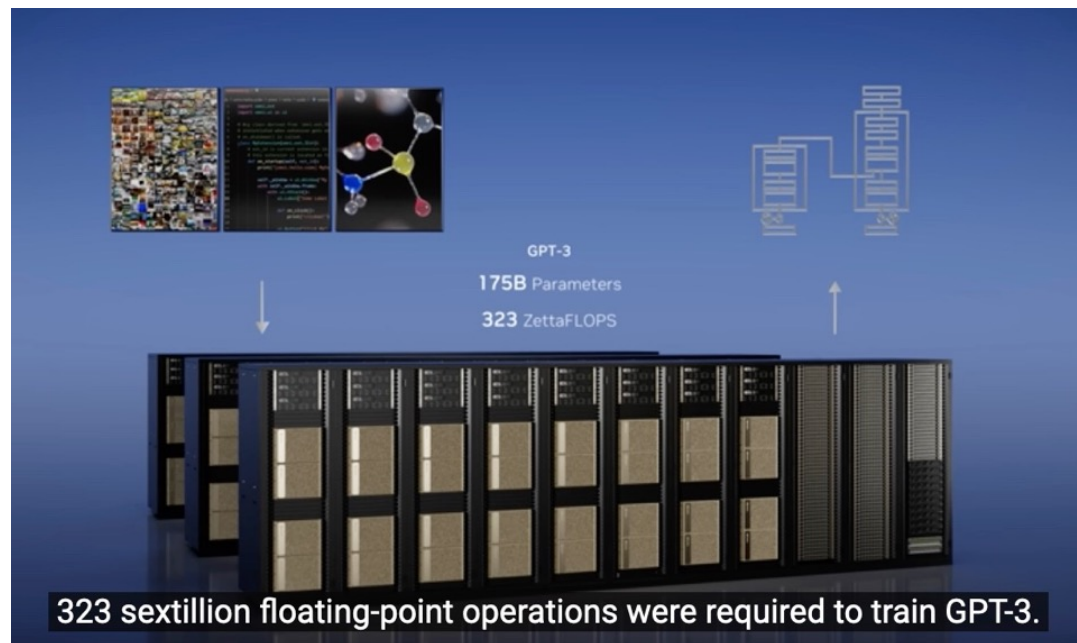


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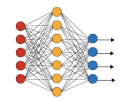


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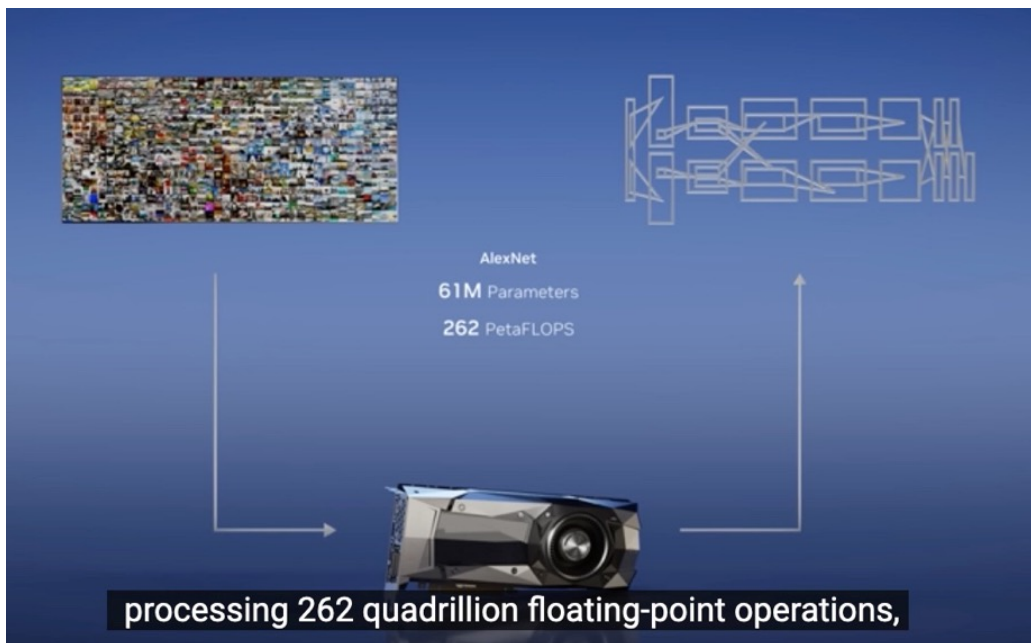
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X 1 000 000 more floating point operations

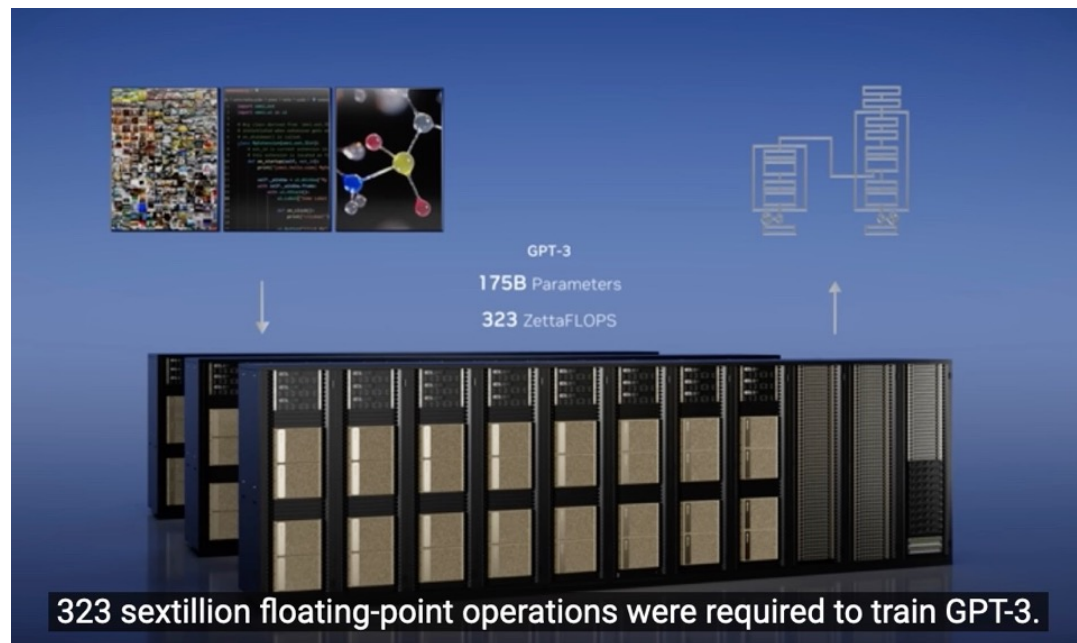


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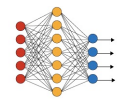


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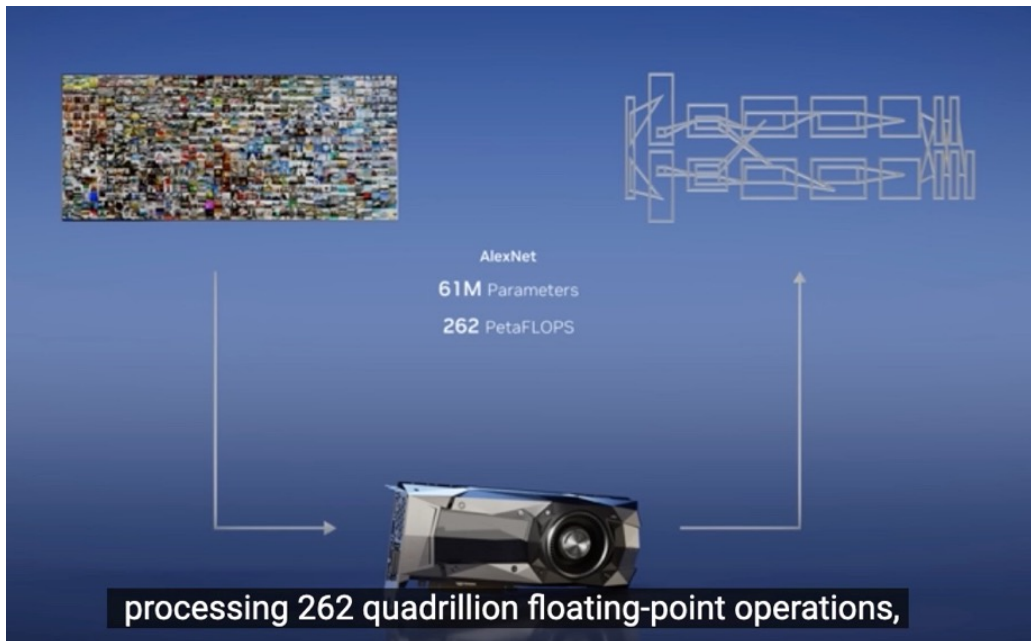
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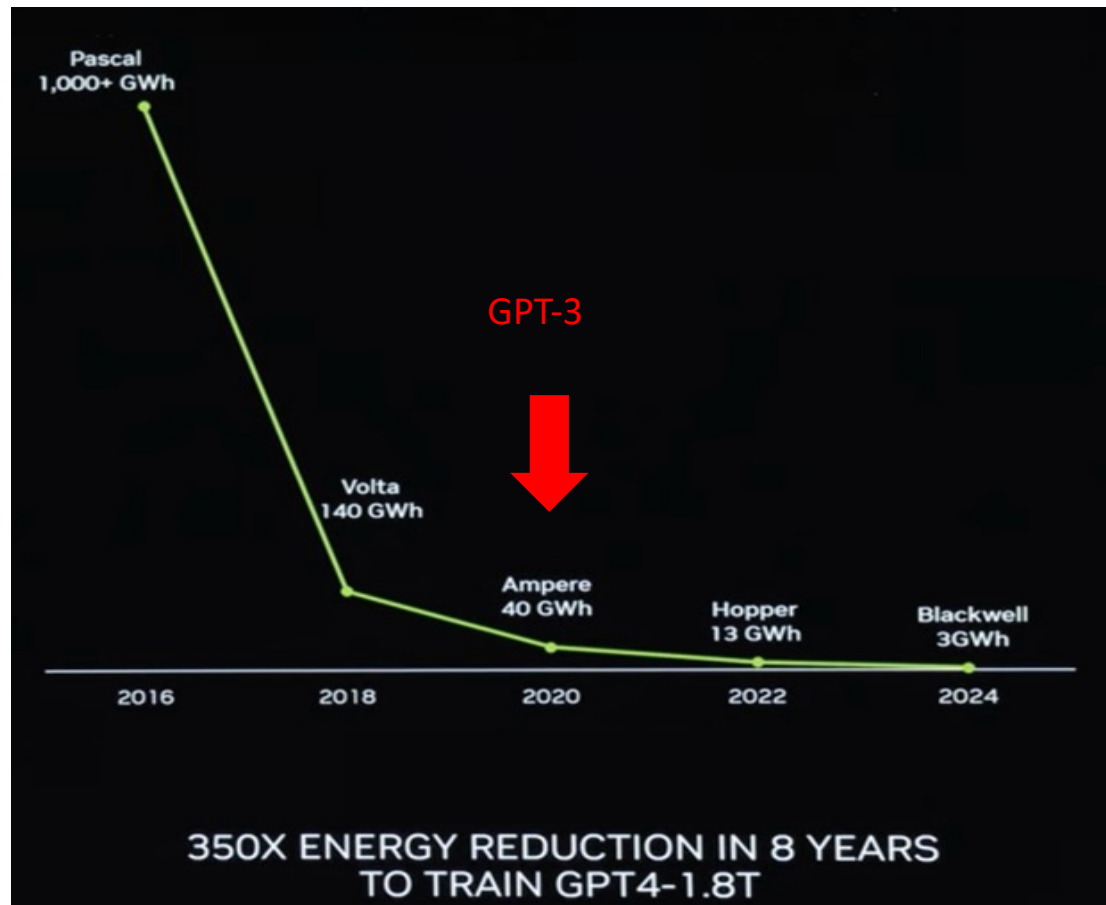


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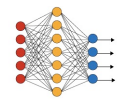


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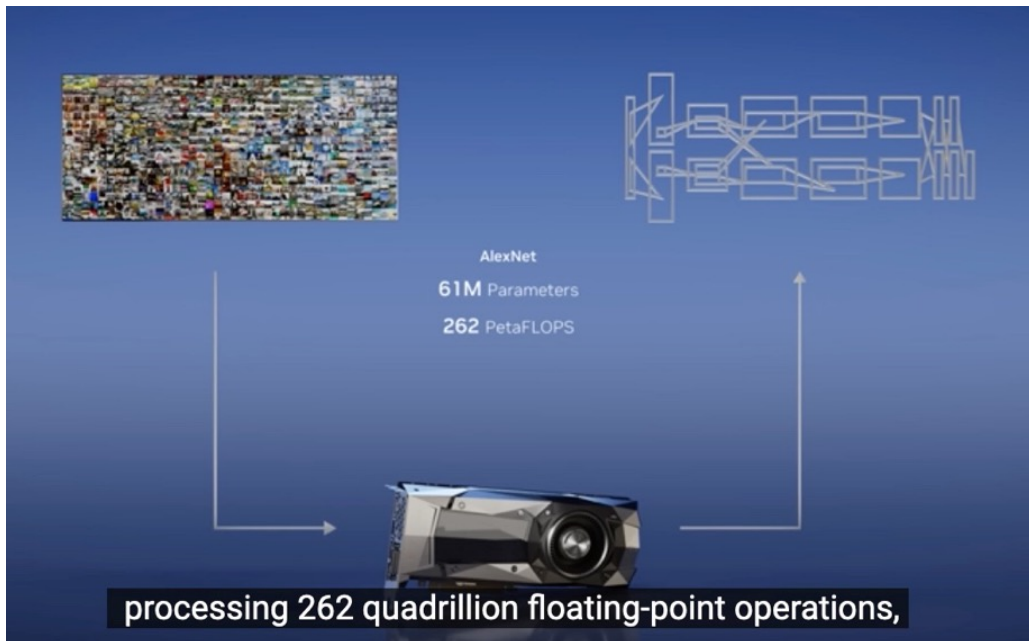
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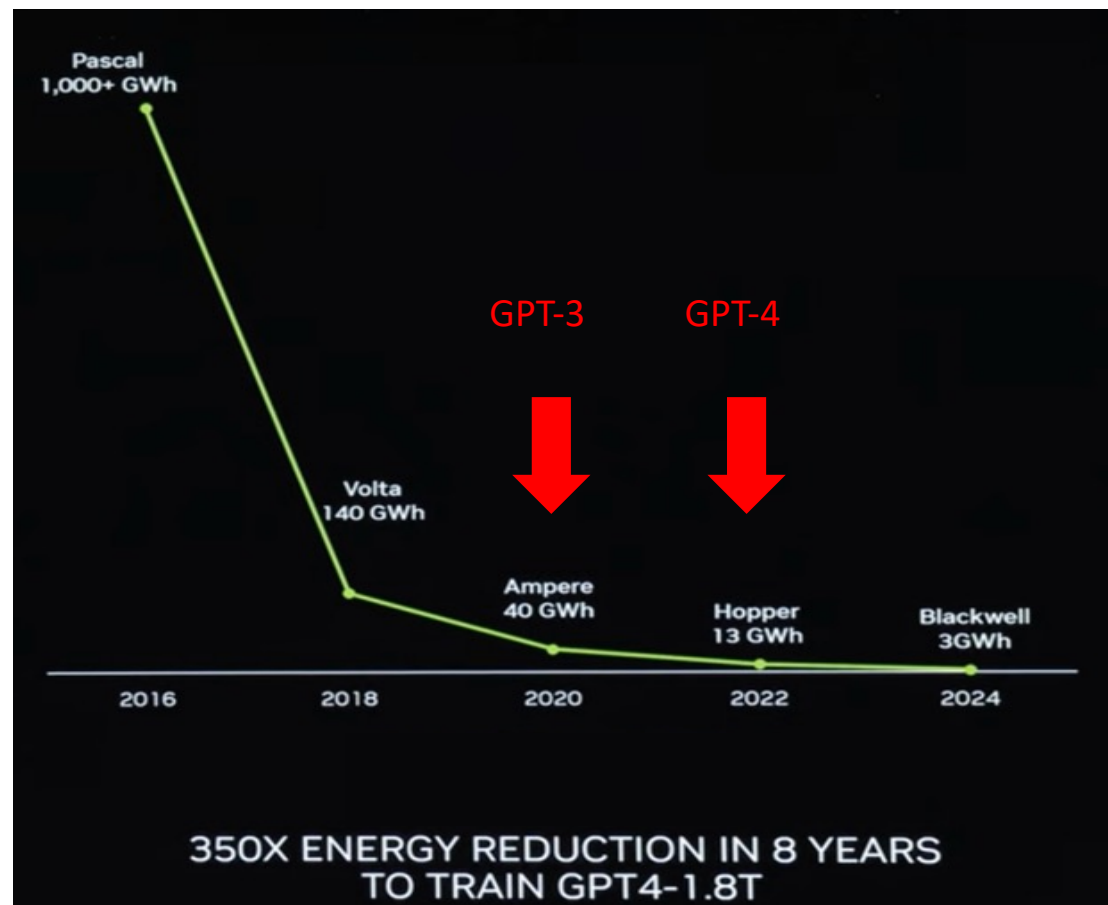


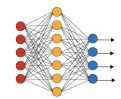
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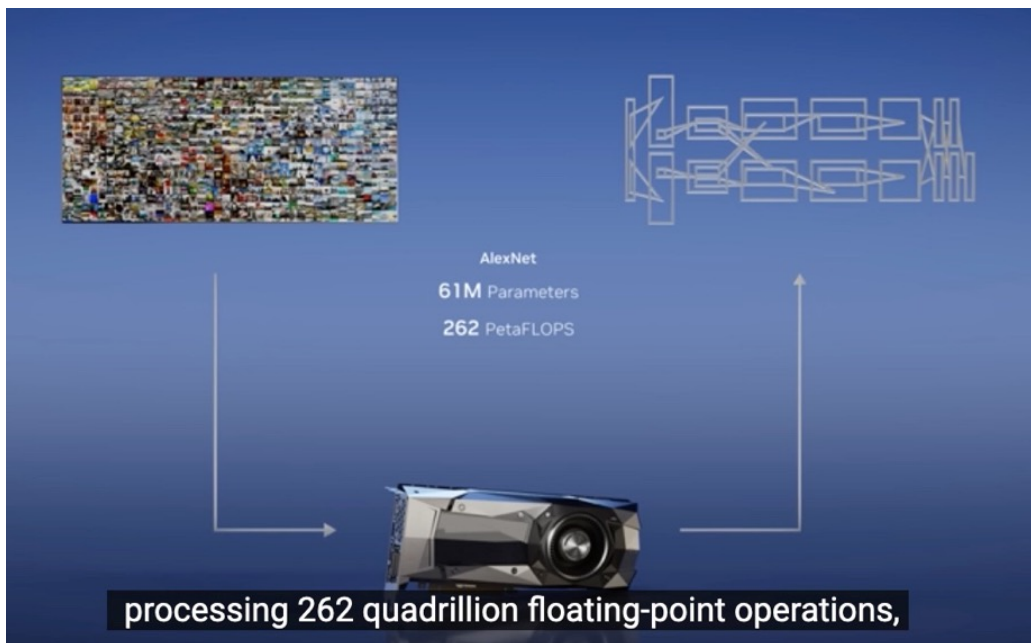
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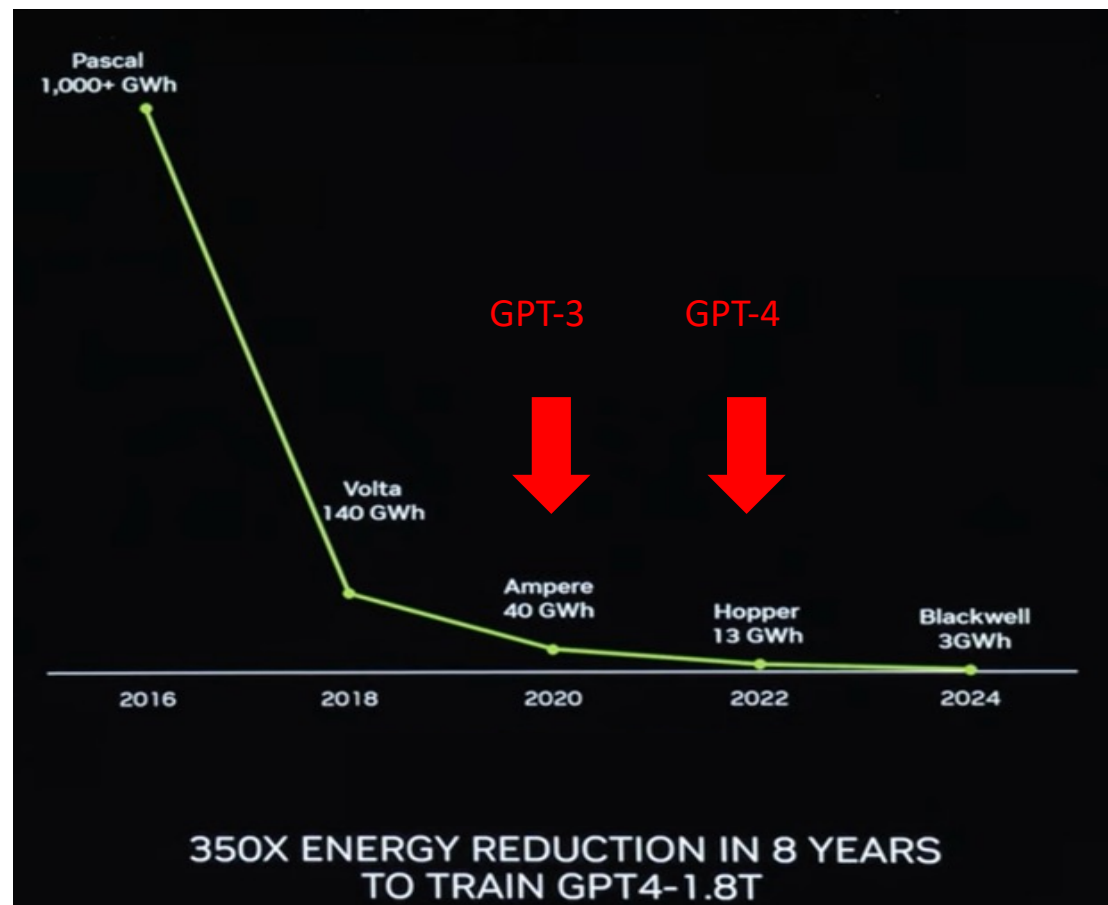


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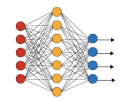


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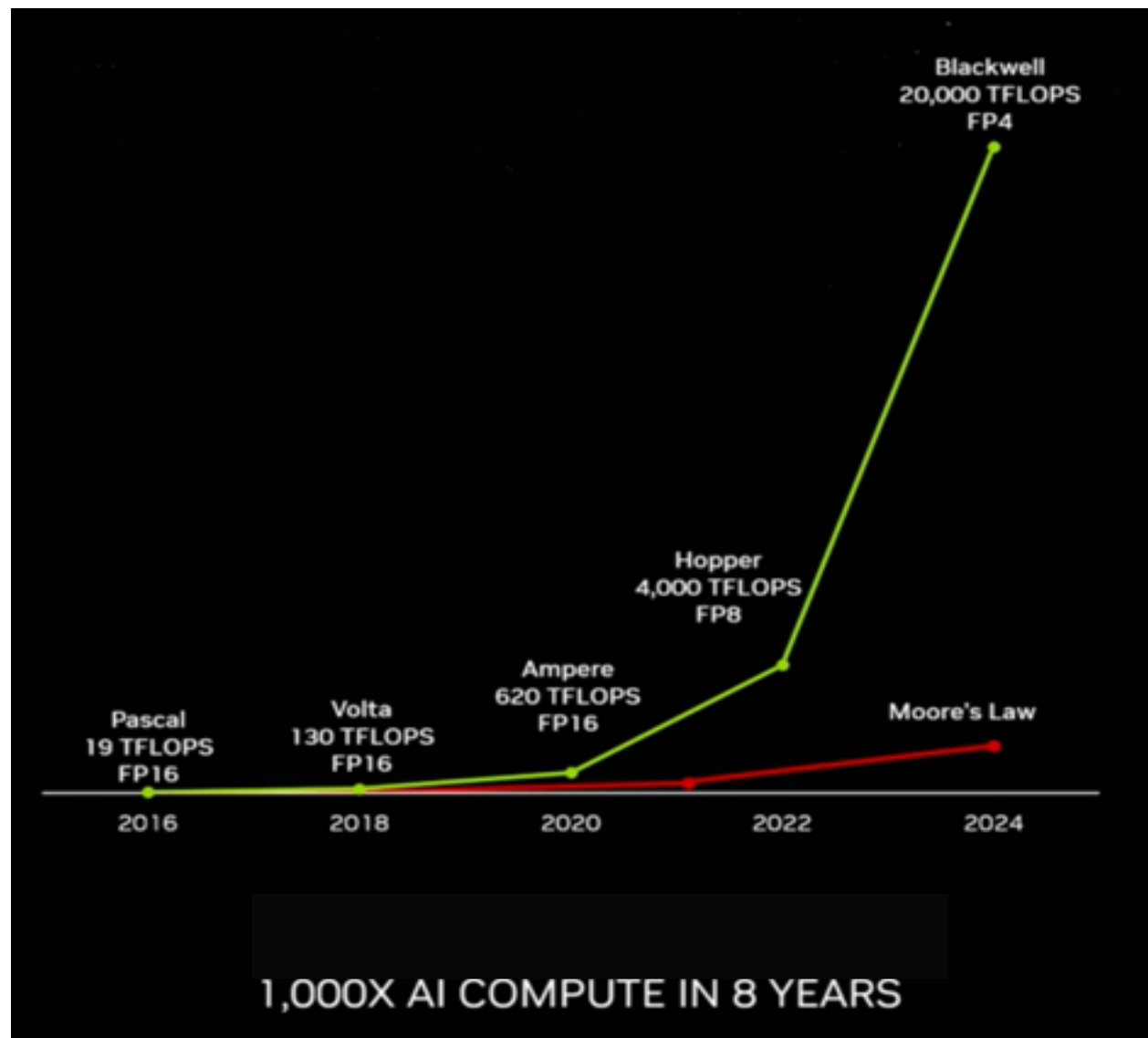
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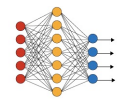
Cost of energy for training is a limiting factor!



## Exponential increase of AI performances



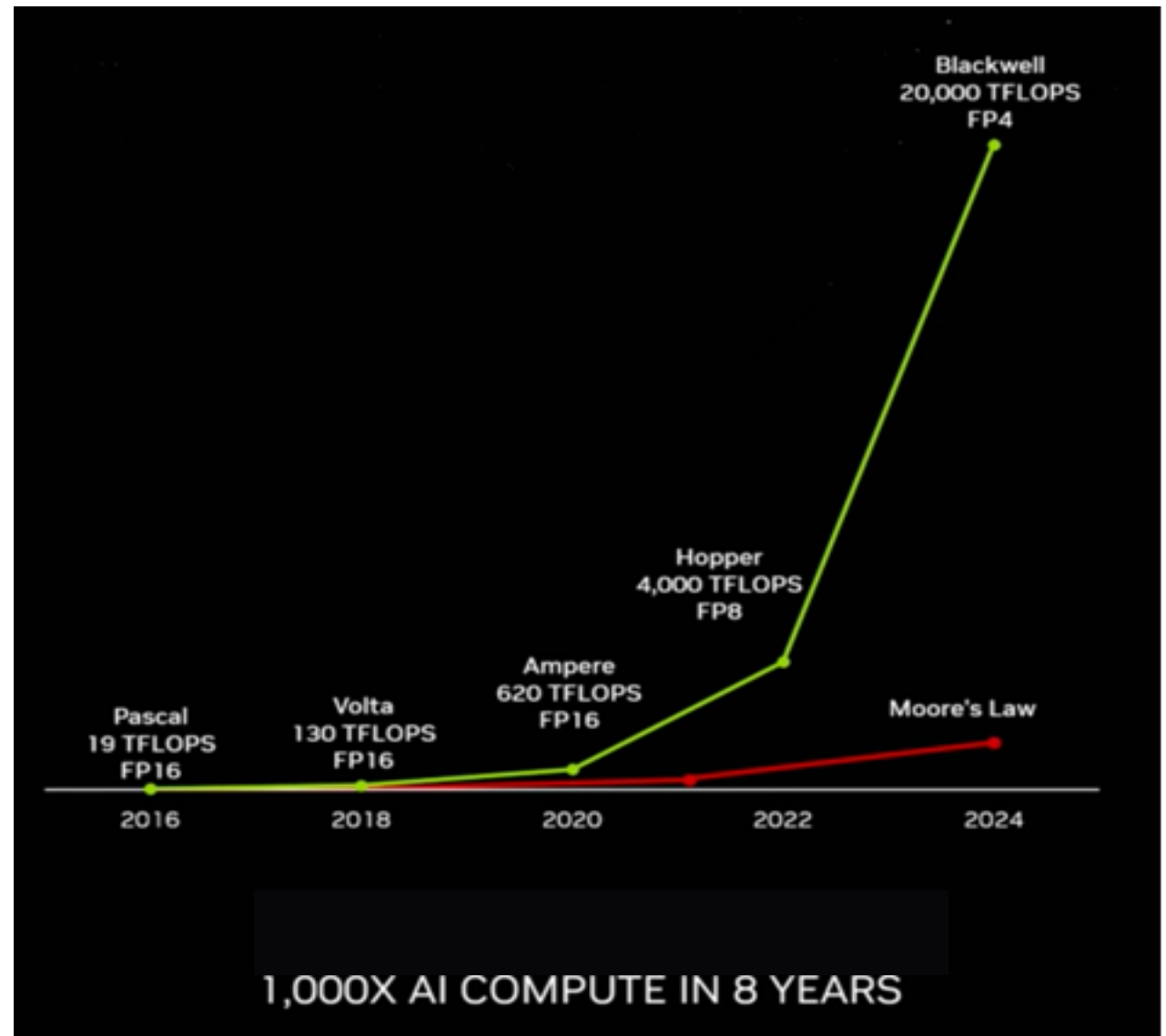
From Nvidia, Computex 2024



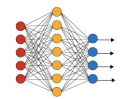
## Exponential increase of AI performances

Thanks to advances in  
*architecture*  
and data coding  
(moving from float  
64/32 to FP4)  
(but it is a one shot!)

From Nvidia, Computex 2024





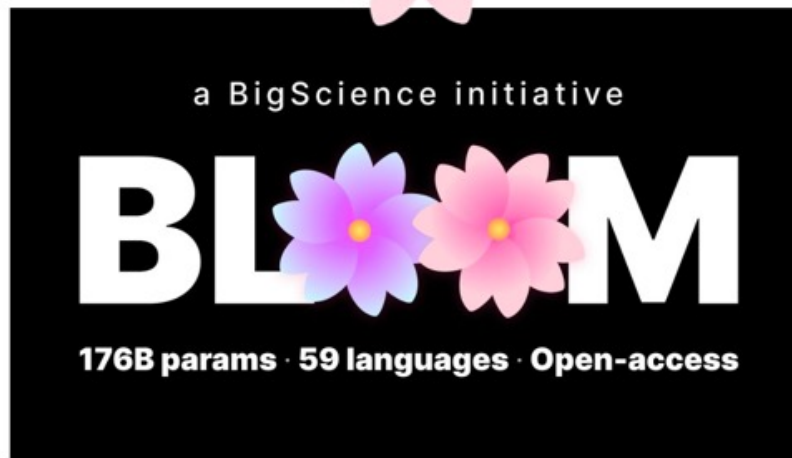


# One of the early Open Source LLM (March-July 2022)

**BigScience**



**BLOOM: open-source alternative to GPT-3**



<https://bigscience.huggingface.co>

<https://huggingface.co/bigscience/bloom>

1.5TB of text, 350B tokens

43 languages, 16 programming languages

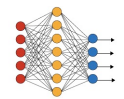
118 days of training on 384 A100 GPUs

More details at <https://huggingface.co/blog/bloom-megatron-deepspeed>

**Smaller versions are available : 560M, 1.1B, 1.7B, 3B, 7.1B**

BLOOMZ models (same sizes) are fine-tuned for **instruction following**

<https://huggingface.co/bigscience/bloomz>

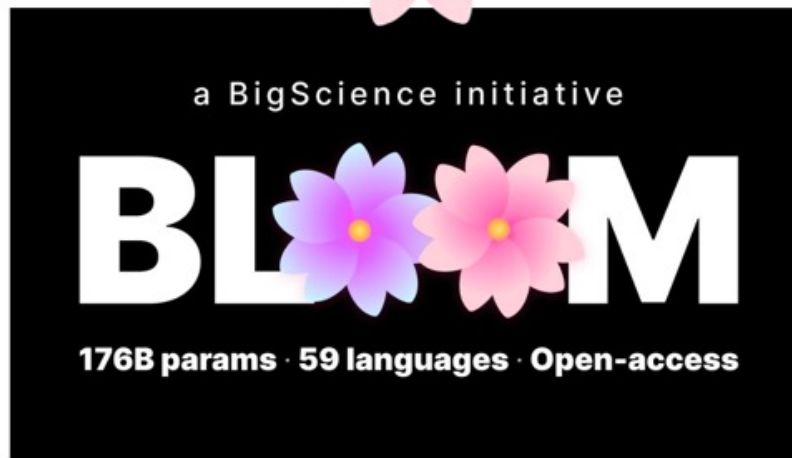


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118 days of training on 384 A100 GPUs

Estimated cost of training: Equivalent of \$2-5M in cloud

**Server training location: Île-de-France, France**

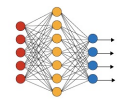
Environmental Impact: The training supercomputer, Jean Zay, **uses mostly nuclear energy**. The **heat generated by it is reused** for heating campus housing.

More details at <https://huggingface.co/blog/bloom-megatron-deepspeed>

**Smaller versions are available : 560M, 1.1B, 1.7B, 3B, 7.1B**

BLOOMZ models (same sizes) are fine-tuned for **instruction following**

<https://huggingface.co/bigscience/bloomz>

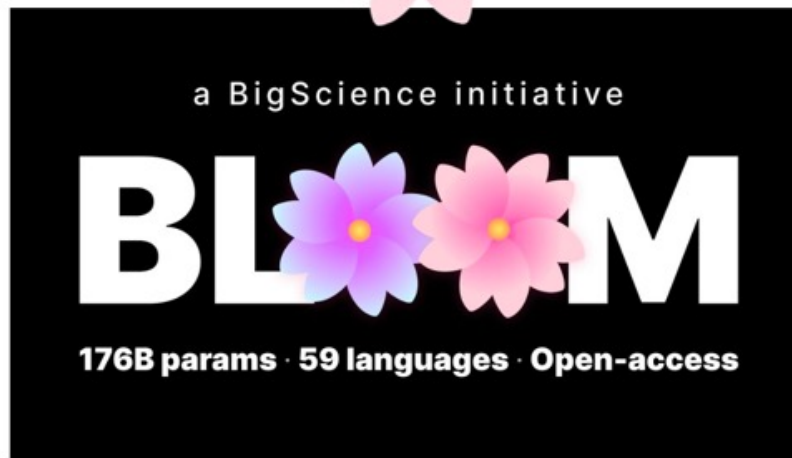


# One of the early Open Source LLM (March-July 2022)

**BigScience**



BLOOM: open-source alternative to GPT-3



<https://bigscience.huggingface.co>

<https://huggingface.co/bigscience/bloom>

1.5TB of text, 350B tokens

43 languages, 16 programming languages

118 days of training on 384 A100 GPUs

Estimated cost of training: Equivalent of \$2-5M in cloud

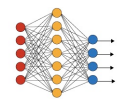
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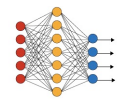


## 2022: Reinforcement with simulation in the loop



The reinforcement technique with simulation in the loop allow to learn and adapt with minimum numbers of real data ( from S. Abeyruwan et al., "i-Sim2Real: Reinforcement Learning of Robotic Policies in Tight Human-Robot Interaction Loops (pre-print), Arxiv, 22 November 2022. Available: <https://arxiv.org/abs/2207.06572>.

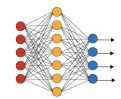




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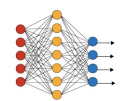
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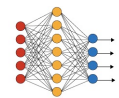
## AI for making new structures: “Generative design” approach

The user *only states desired goals and constraints*

-> The *complexity wall* might *prevent explaining* the solution



Motorcycle swingarm: the piece that hinges the rear wheel to the bike's frame































# 2022: Flamingo (Deepmind) : image + text + few shot learning

## 🦩 Flamingo: a Visual Language Model for Few-Shot Learning

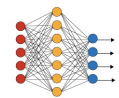
Jean-Baptiste Alayrac<sup>\*,†</sup> Jeff Donahue<sup>\*</sup> Pauline Luc<sup>\*</sup> Antoine Miech<sup>\*</sup>  
 Iain Barr<sup>†</sup> Yana Hasson<sup>†</sup> Karel Lenc<sup>†</sup> Arthur Mensch<sup>†</sup> Katie Millican<sup>†</sup>  
 Malcolm Reynolds<sup>†</sup> Roman Ring<sup>†</sup> Eliza Rutherford<sup>†</sup> Serkan Cabi Tengda Han  
 Zhitao Gong Sina Samangooei Marianne Monteiro Jacob Menick  
 Sebastian Borgeaud Andrew Brock Aida Nematzadeh Sahand Sharifzadeh  
 Mikolaj Binkowski Ricardo Barreira Oriol Vinyals Andrew Zisserman  
 Karen Simonyan<sup>\*,‡</sup>

<sup>\*</sup> Equal contributions, ordered alphabetically, <sup>†</sup> Equal contributions, ordered alphabetically,  
<sup>‡</sup> Equal senior contributions


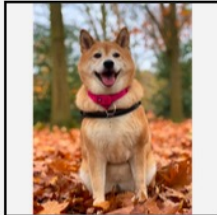




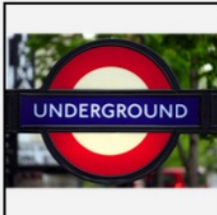


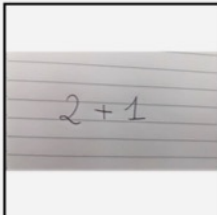
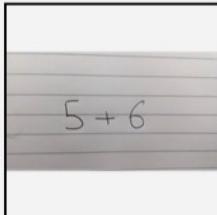
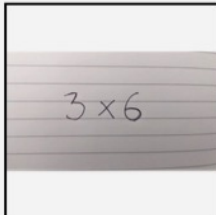
DeepMind

Input Prompt					Completion
	This is a chinchilla. They are mainly found in Chile.		This is a shiba. They are very popular in Japan.		This is → a flamingo. They are found in the Caribbean and South America.
	What is the title of this painting? Answer: The Hallucinogenic Toreador.		Where is this painting displayed? Answer: Louvres Museum, Paris.		What is the name of the city where this was painted? Answer: → Arles.
	Output: "Underground"		Output: "Congress"		Output: → "Souloules"
	2+1=		2+1=3		5+6= → 3x6=18
	Output: A propaganda poster depicting a cat dressed as French emperor Napoleon holding a piece of cheese.		Output: A pink room with a flamingo pool float.		Output: → A portrait of Salvador Dali with a robot head.
	Les sanglots longs des violons de l'automne blessent mon coeur d'une langueur monotone.		Pour qui sont ces serpents qui sifflent sur vos têtes?		→ Je suis un cœur qui bat pour vous.
	pandas: 3		dogs: 2		→ giraffes: 4
I like reading		, my favourite play is Hamlet. I also like		, my favorite book is	→ Dreams from my Father.
					What happens to the man after hitting the ball? Answer: → he falls down.

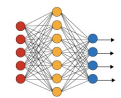




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	Output: "Underground"		Output: "Congress"		Output:	→ <b>"Soulomes"</b>
	2+1=3		5+6=11			→ <b>3x6=18</b>

Output: A

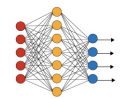


## 2023: PaLM-E: An Embodied Multimodal Language Model



Robot: I am a robot operating in a kitchen. Given **img**, When a human asks me to do a task, I will respond with the sequence of actions I would do to accomplish the task with only the items I see. Human: Use all of the ingredients you see to make a cake batter.

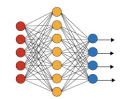
1. crack egg. 2. put egg in bowl. 3. put flour in bowl. 4. put sugar in bowl. 5. mix. 6. put in pan. 7. bake. 8. eat. 9. clean up.



## 2023: PaLM-E: An Embodied Multimodal Language Model



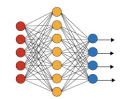




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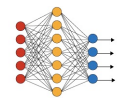






## 2023: PaLM-E: An Embodied Multimodal Language Model





## 2023: The trigger of “open weights” revolution: Alpaca from Stanford, derived from LLaMa from Meta

### Alpaca: A Strong, Replicable Instruction-Following Model

Authors: Rohan Taori\* and Ishaan Gulrajani\* and Tianyi Zhang\* and Yann Dubois\* and Xuechen Li\* and Carlos Guestrin and Percy Liang and Tatsunori B. Hashimoto

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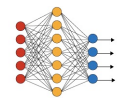
We introduce **Alpaca 7B**, a model fine-tuned from the LLaMA 7B model on 52K instruction-following demonstrations. On our preliminary evaluation of single-turn instruction following, Alpaca behaves qualitatively similarly to OpenAI's text-davinci-003, while being surprisingly small and easy/cheap to reproduce (<600\$). Checkout our code release on [GitHub](#).

Update: The public demo is now disabled. The original goal of releasing a demo was to disseminate our research in an accessible way. We feel that we have mostly achieved this goal, and given the hosting costs and the inadequacies of our content filters, we decided to bring down the demo.

# Stanford Alpaca



From <https://crfm.stanford.edu/2023/03/13/alpaca.html>



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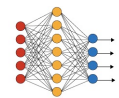
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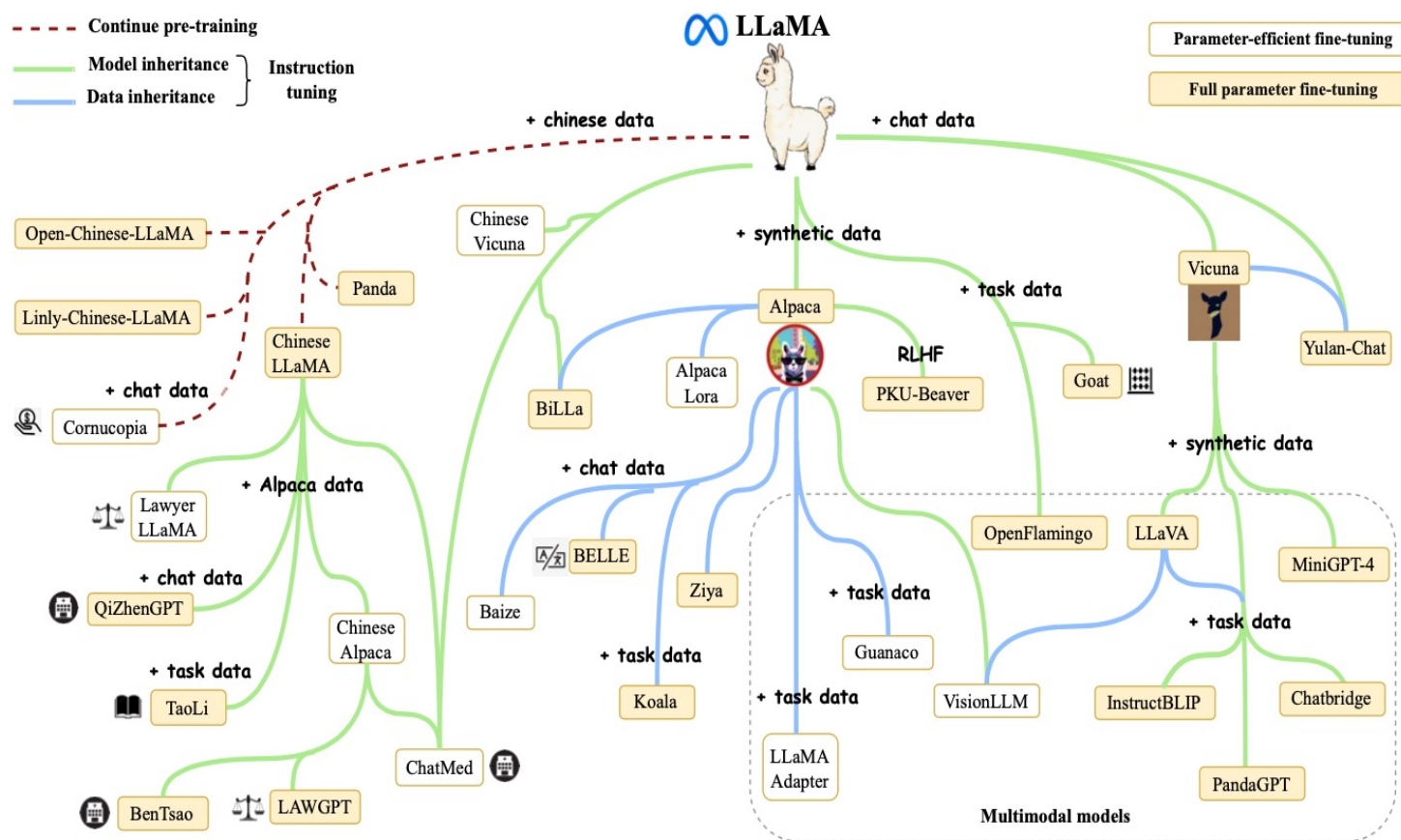
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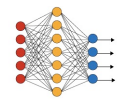
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From <https://arxiv.org/abs/2303.18223>

Math Finance Medicine Law Bilingualism Education





## 2023: The trigger of “open weights” revolution: Alpaca from Stanford, derived from LLaMa from Meta

--- Continue pre-training  
— Model inheritance  
— Data inheritance } Instruction tuning

LLaMA

+ chinese data + chat data

Parameter-efficient fine-tuning  
Full parameter fine-tuning

# Introducing Llama 2

The next generation of our open source large language model

Llama 2 is available for free for research and commercial use.

News from July 18<sup>th</sup>, 2023,  
you can play with it on <https://www.llama2.ai/>, **you can download and run it locally**  
**You keep your data** locally and no fees to use it (unlike GPT-4, \$20 a month)

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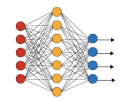
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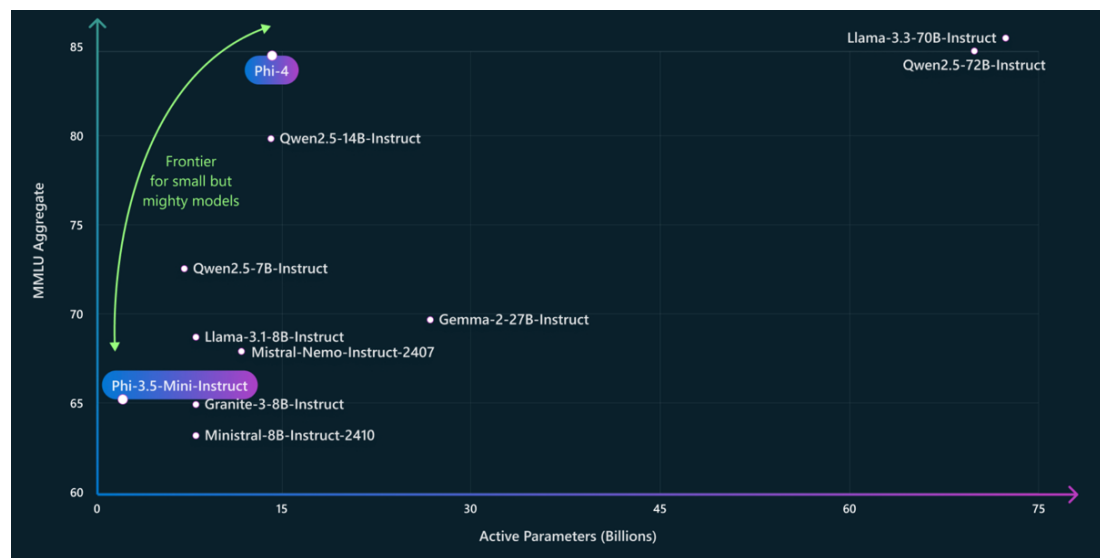


## 2024: Smaller LLM models get more powerful

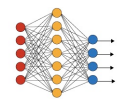
- Current models of about 10B parameters have better performances than the original ChatGPT of 2022

Model name	Announced	MMLU *
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O1?	September 2024	92.3
Pixtral-12B	September 2024	69.2
Qwen 2.5 14B	September 2024	80
Llama 3.2 70B	December 2024	86.0
Phi-4 14B	December 2024	84.8
Deepseek-R1 671B / 37B MoE	January 2025	90.8

\*Massive Multitask Language Understanding



From <https://techcommunity.microsoft.com/blog/aipatformblog/introducing-phi-4-microsoft%E2%80%99s-newest-small-language-model-specializing-in-comple/4357090>



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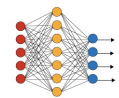
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**“Open source”** models are catching up closed models with few months delay



From <https://techcommunity.microsoft.com/blog/aipatformblog/introducing-phi-4-microsoft%E2%80%99s-newest-small-language-model-specializing-in-comple/4357090>





## Distillation: Smaller Models Can Be Powerful Too\*

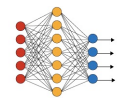
*“We demonstrate that the **reasoning patterns of larger models can be distilled into smaller models**, resulting in better performance compared to the reasoning patterns discovered through RL on small models.*

- Using the reasoning data generated by **DeepSeek-R1**, we fine-tuned several dense models that are widely used in the research community. The evaluation results demonstrate that the distilled smaller dense models perform exceptionally well on benchmarks. We open-source distilled 1.5B, 7B, 8B, 14B, 32B, and 70B checkpoints based on Qwen2.5 and Llama3 series to the community.”*

Model	AIME 2024 pass@1	AIME 2024 cons@64	MATH-500 pass@1	GPQA Diamond pass@1	LiveCodeBench pass@1	CodeForces rating
GPT-4o-0513	9.3	13.4	74.6	49.9	32.9	759
Claude-3.5-Sonnet-1022	16.0	26.7	78.3	65.0	38.9	717
DeepSeek-R1-Distill-Qwen- <b>7B</b>	55.5	83.3	92.8	49.1	37.6	1189
DeepSeek-R1-Distill-Qwen- <b>14B</b>	69.7	80.0	93.9	59.1	53.1	1481

\* From <https://github.com/deepseek-ai/DeepSeek-R1?tab=readme-ov-file#distilled-model-evaluation>

The American Invitational Mathematics Examination (AIME) is a selective and prestigious 15-question 3-hour test given since 1983 to those who rank in the top 2.5% on the AMC 10.



## Distillation: Smaller Models Can Be Powerful Too\*

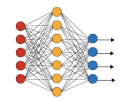
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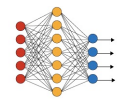
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## What's new (end 2024)

Scaling is no more the only way to increase performances

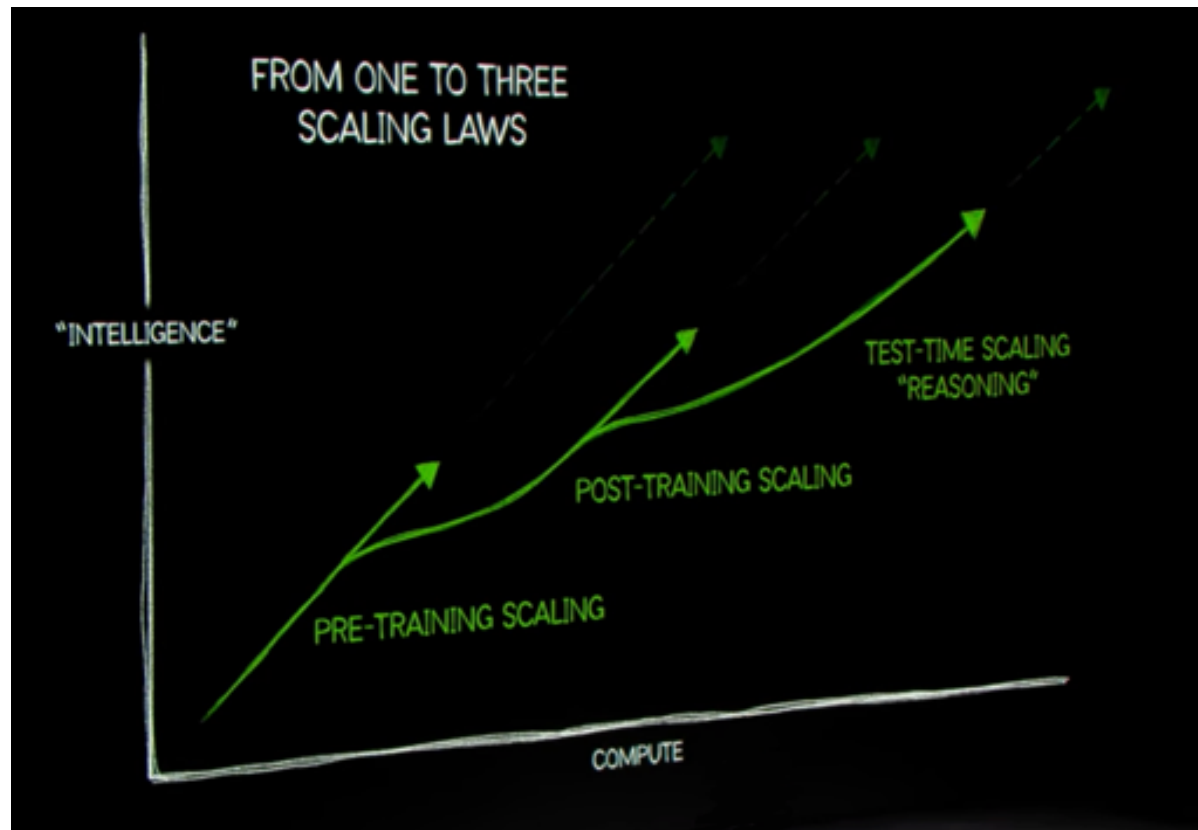
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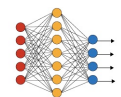
Scaling is no more the only way to increase performances

- Small (specialized) models gets performances of (older) larger LLMs
  - Training by artificial data / larger models
- **Test-time compute** / inference time scaling
  - Pioneering by o1/ o3 from OpenAI
  - Democratized by DeepSeek-R1 (Open weights)



From Jensen Huang keynote at CES 2025

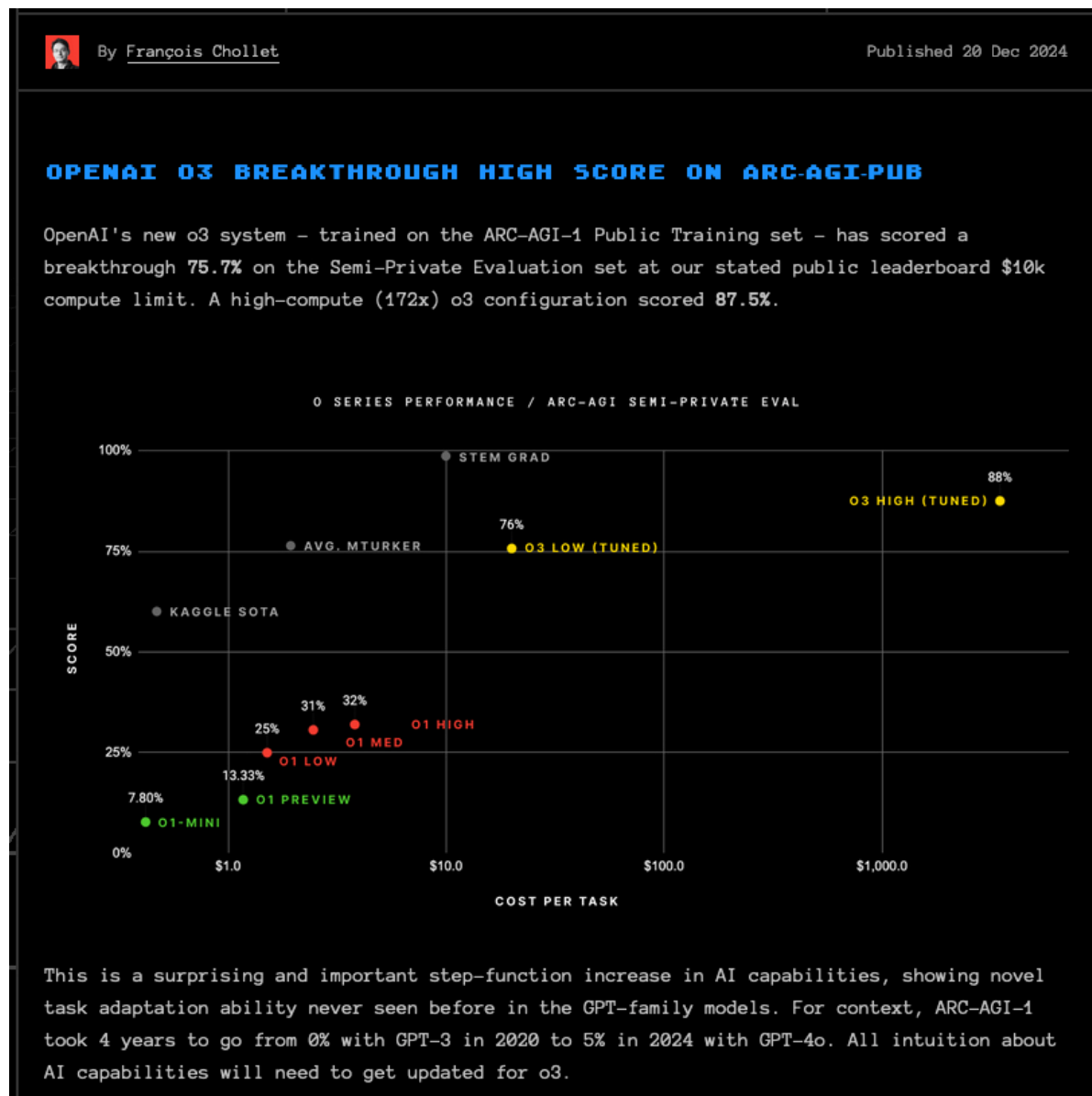




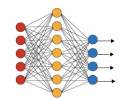
## The test-time compute (re)volution

**"Test-time compute"**: additional computational power is used during the inference stage to improve the quality of the response, rather than just relying on the pre-trained model's capabilities.

It allows the LLM to "think harder", **"think step-by-step"** on a problem by performing extra calculations at runtime to produce better results, often involving techniques like generating multiple solutions and selecting the best one.



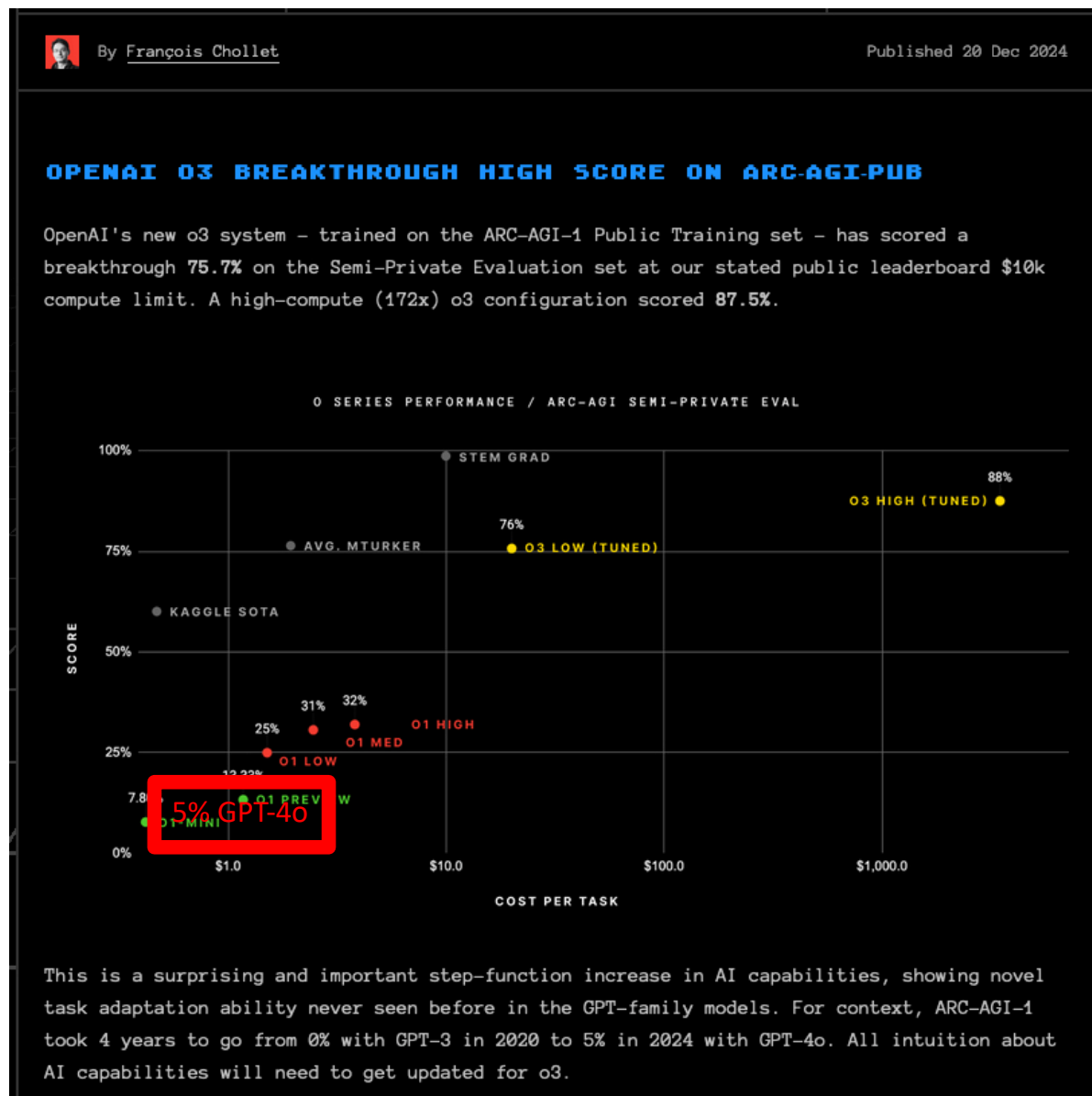
From <https://arcprize.org/blog/oai-o3-pub-breakthrough>



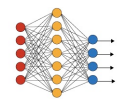
## The test-time compute (re)volution

**"Test-time compute"**: additional computational power is used during the inference stage to improve the quality of the response, rather than just relying on the pre-trained model's capabilities.

It allows the LLM to "think harder", **"think step-by-step"** on a problem by performing extra calculations at runtime to produce better results, often involving techniques like generating multiple solutions and selecting the best one.



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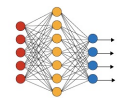
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From <https://arcprize.org/blog/oai-o3-pub-breakthrough>



## What's new (end 2024)

### “World” foundation models:

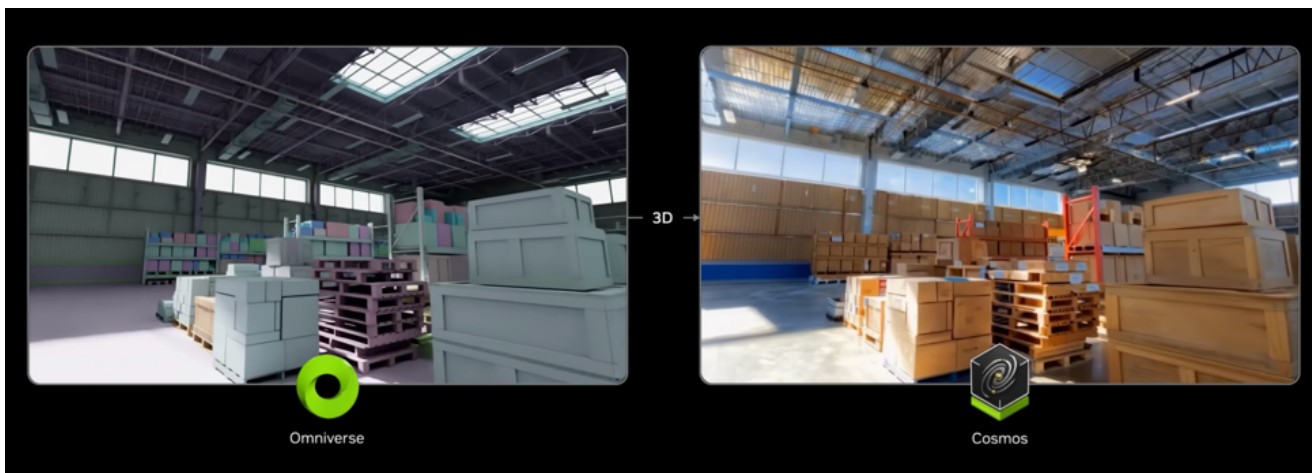
“World models are generative AI models that understand the dynamics of the real world, including physics and spatial properties.

...

They understand the physical qualities of real-world environments by learning to represent and predict dynamics like motion, force, and spatial relationships from sensory data.”\*



Digital twin

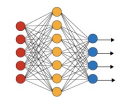


World model



\* From <https://www.nvidia.com/en-us/glossary/world-models/>

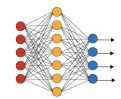




# Agentic AI the future of AI?

- Using a set of small specialized LLMs can have similar performances than of a large LLM
- Only a subset of the LLM are activated simultaneously (Mixture of Experts)

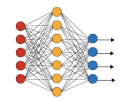




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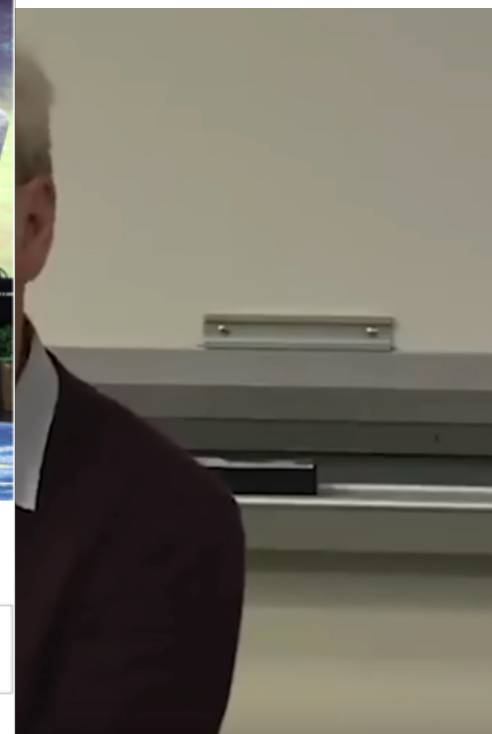
um the ability to create themselves

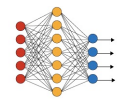


(Image credit: Getty Images / Justin Sullivan)

Jump to: [Read more](#)

Bringing AI agents into the workforce will soon be as common as onboarding human employees, as they work together to make businesses smarter and more efficient, [Nvidia](#) CEO Jensen Huang has predicted.





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(Image credit: Getty Images / Justin Sullivan)

## Sam Altman Reveals The Future Of AI Agents, Digital Humans And AI Brains

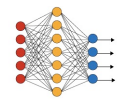
Youtube



Jump to: [Read more](#)

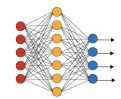
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# Agentic AI in one slide

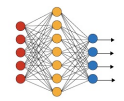




# AI can run at the edge...



AI data center: 5 MW



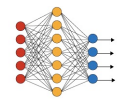
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AI data center: 5 MW



Project Digits: 150W ???



# AI can run at the edge...

LLM running locally on Mac mini: about 20W



AI data center: 5 MW

```
1 29
> Write a program that lists the prime numbers between 20 and 30.
Here is a program in Python that lists the prime numbers between 20 and 30:
...
def is_prime(n):
    if n <= 1 or n % 2 == 0:
        return False
    for i in range(3, int(n ** 0.5) + 1):
        if n % i == 0:
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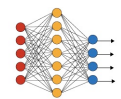
def list_primes(start, end):
    prime_list = []
    for i in range(start, end + 1):
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print(list_primes(20, 30))
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This program uses the 'is_prime' function to check whether a given number is prime or not. The 'is_prime' function checks if the number is less than or equal to 1, or if it is even. If it is not either of these, it checks if the number has
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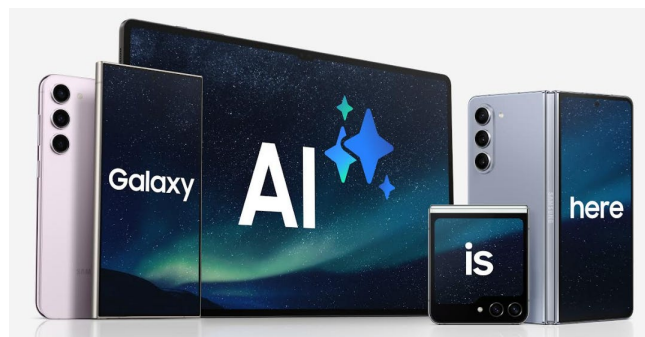
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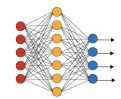


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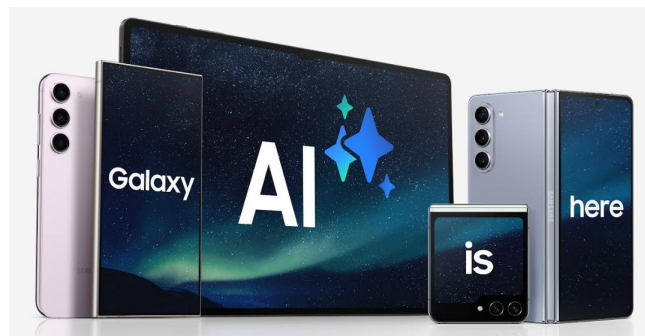
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IoT LLM box: 1-2 W



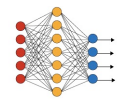
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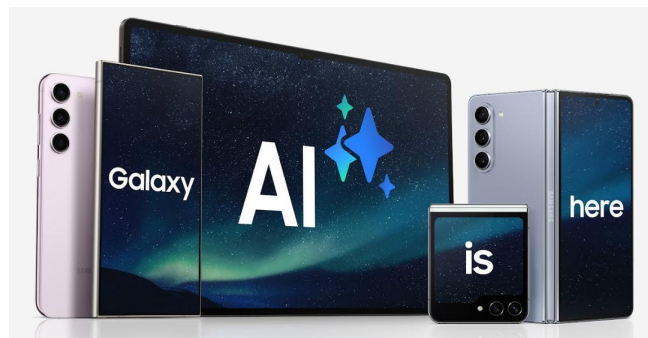
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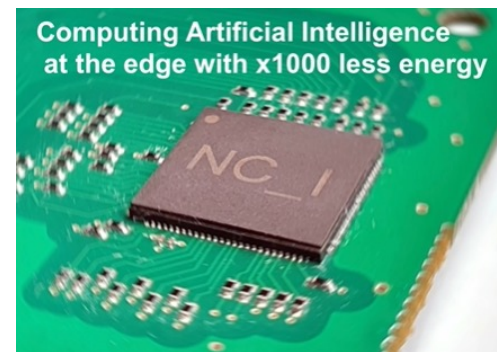
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Project Digits: 150W ???

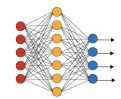


AI smartphones: 5-10W

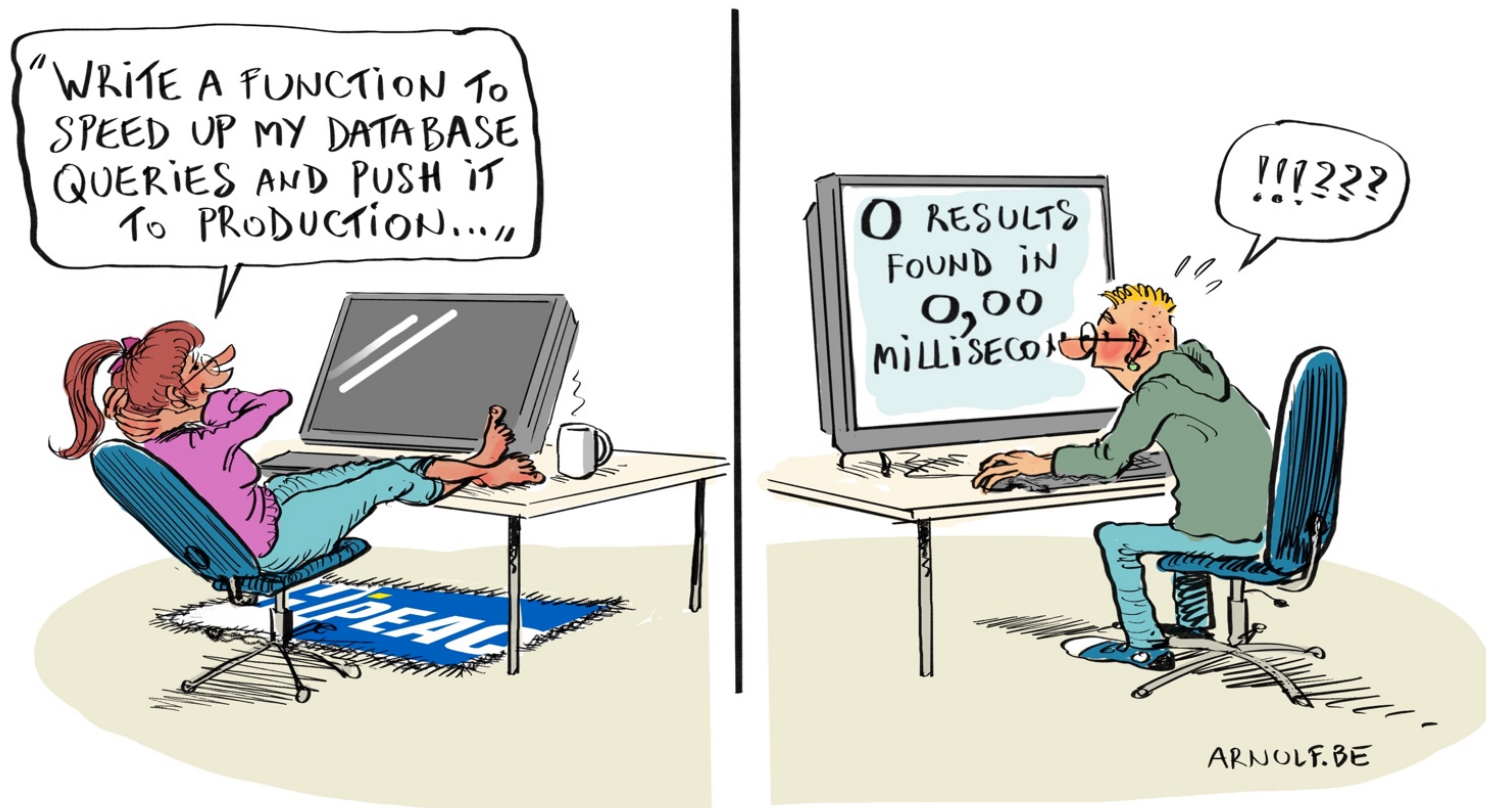


Object detection on  
HD images at 30FPS for 23mW

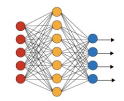




## Various applications of current AI: code generation

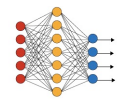






## Video and sound generation (Veo3 from Google)

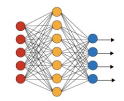




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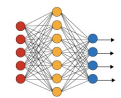






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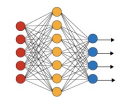




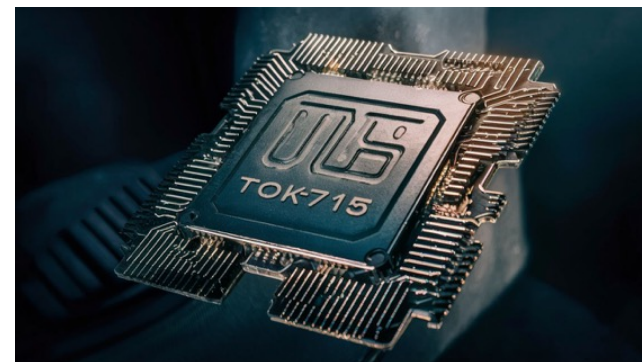
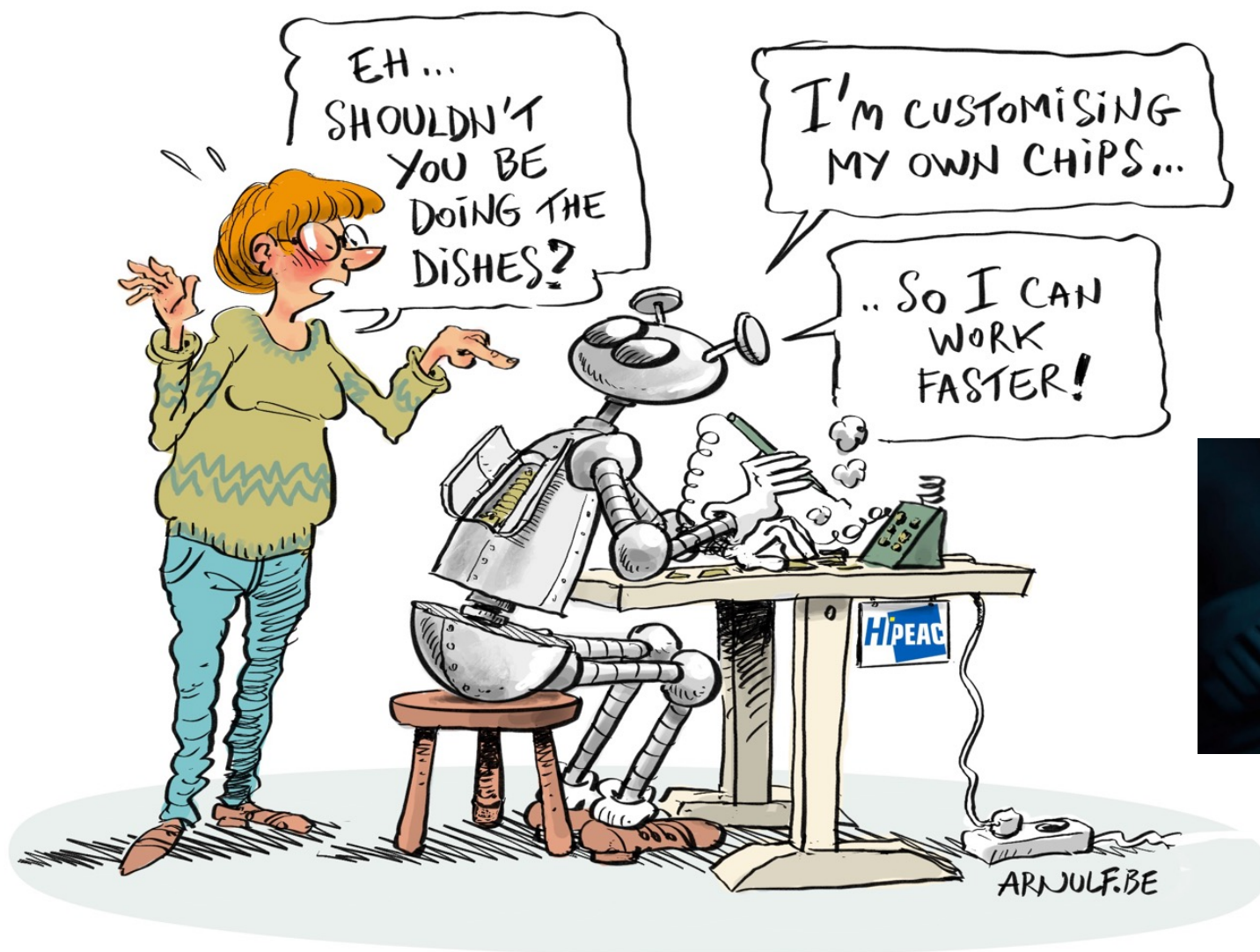
# cybersecurity attack and protection

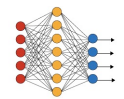






## AI help design chips for AI...

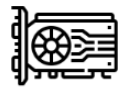




# The AI scientist from Sakana.ai



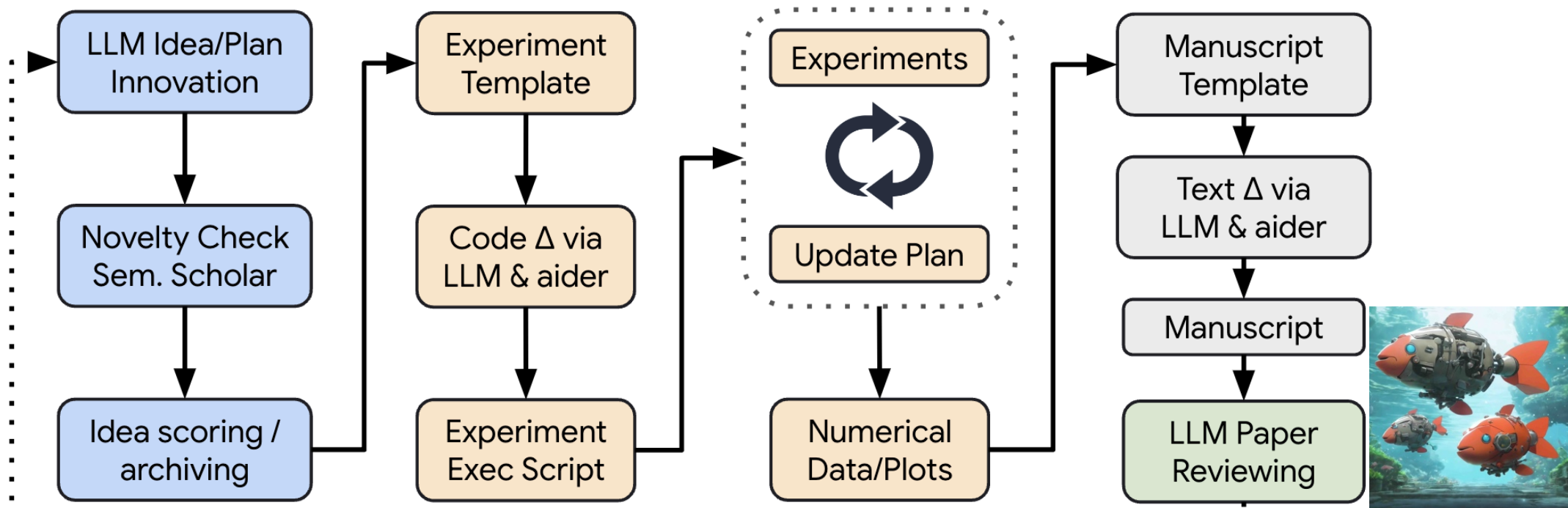
## Idea Generation



## Experiment Iteration

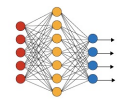


## Paper Write-Up



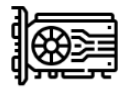
Conceptual illustration of The AI Scientist. The AI Scientist first brainstorms a set of ideas and then evaluates their novelty. Next, it edits a codebase powered by recent advances in automated code generation to implement the novel algorithms. The Scientist then runs experiments to gather results consisting of both numerical data and visual summaries. It crafts a scientific report, explaining and contextualizing the results. Finally, the AI Scientist generates an automated peer review based on top-tier machine learning conference standards. This review helps refine the current project and informs future generations of open-ended ideation. From <https://sakana.ai/ai-scientist/>





Idea Generation

March 12<sup>th</sup>, 2025

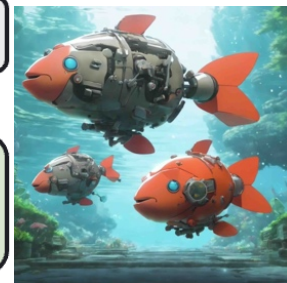
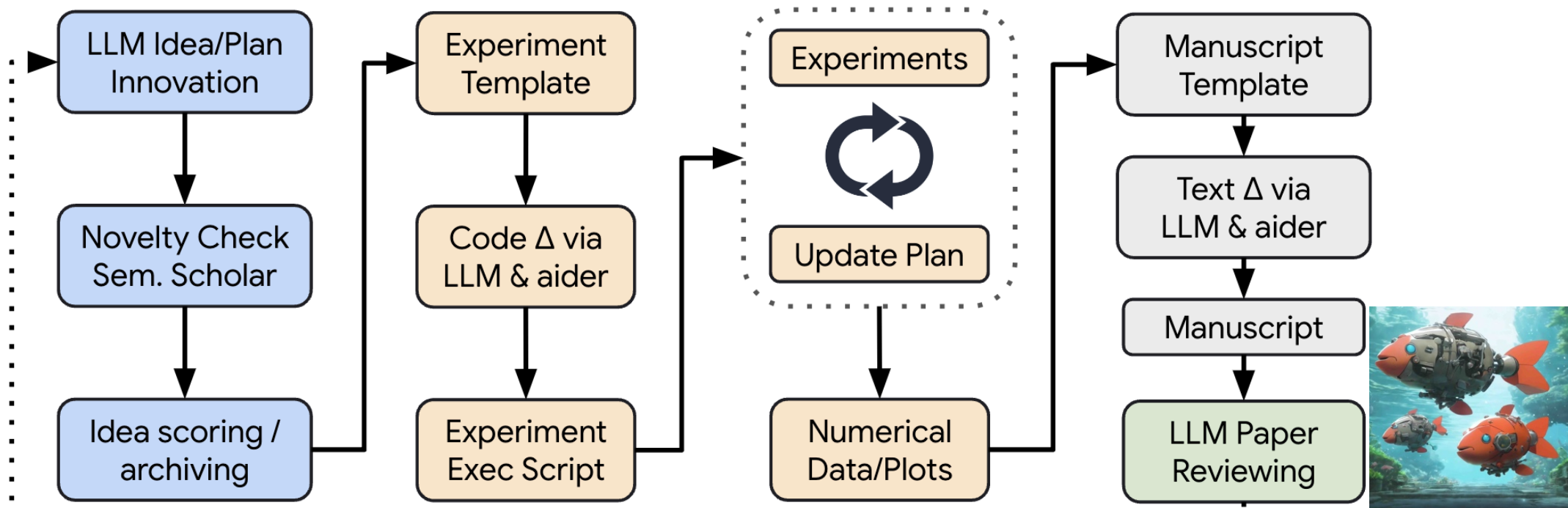


Experiment Iteration

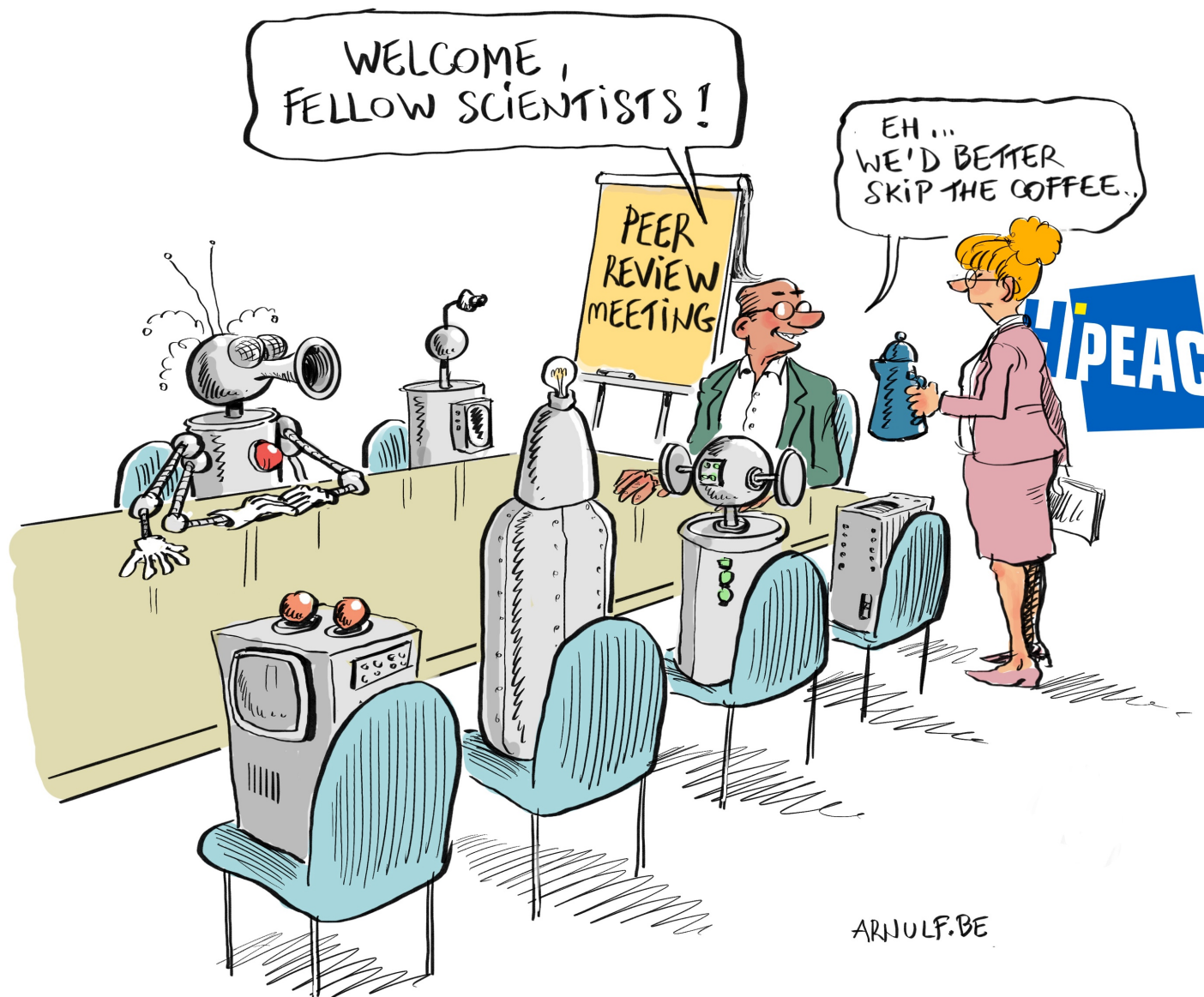
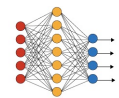


Paper Write-Up

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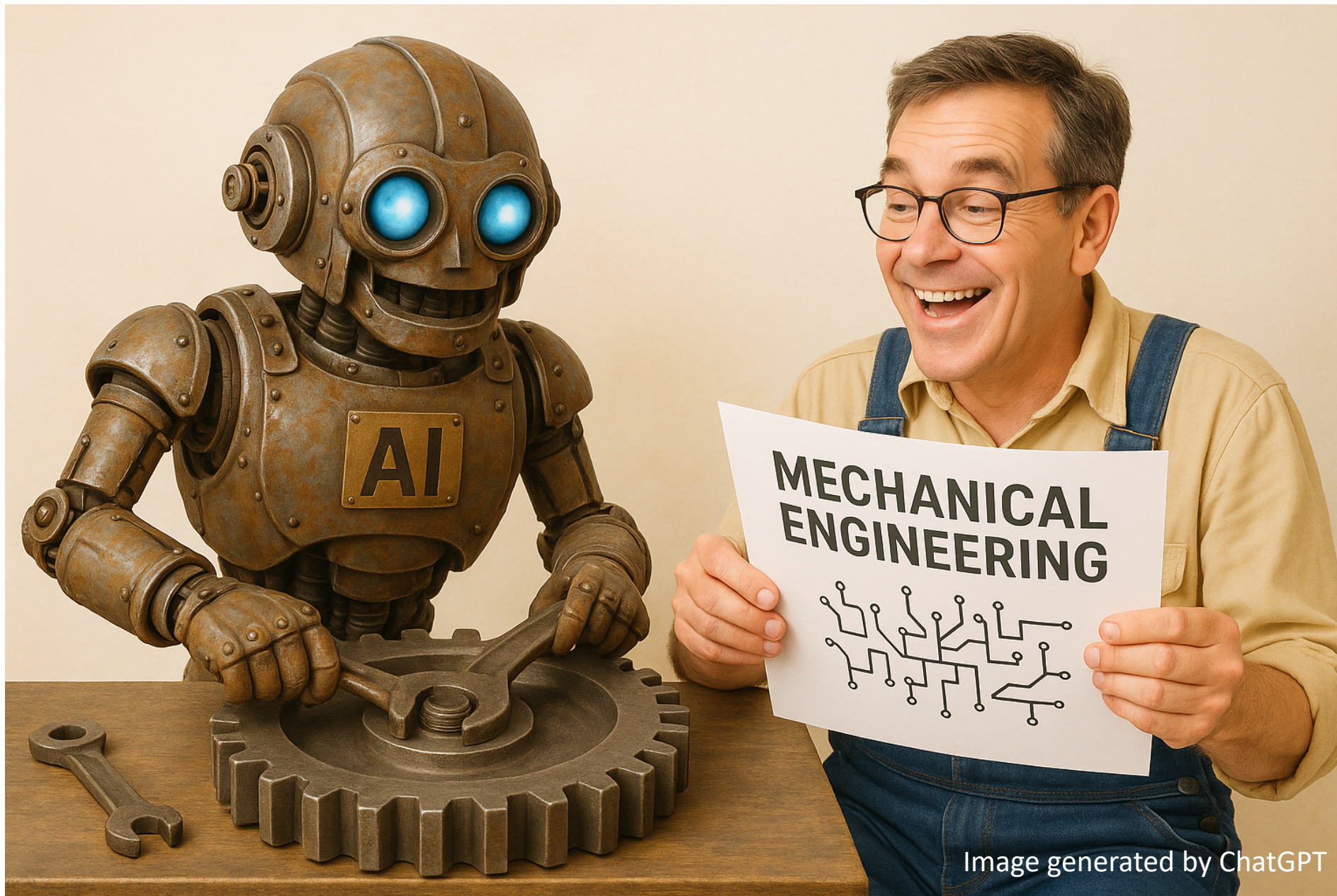
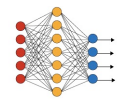


Image generated by ChatGPT



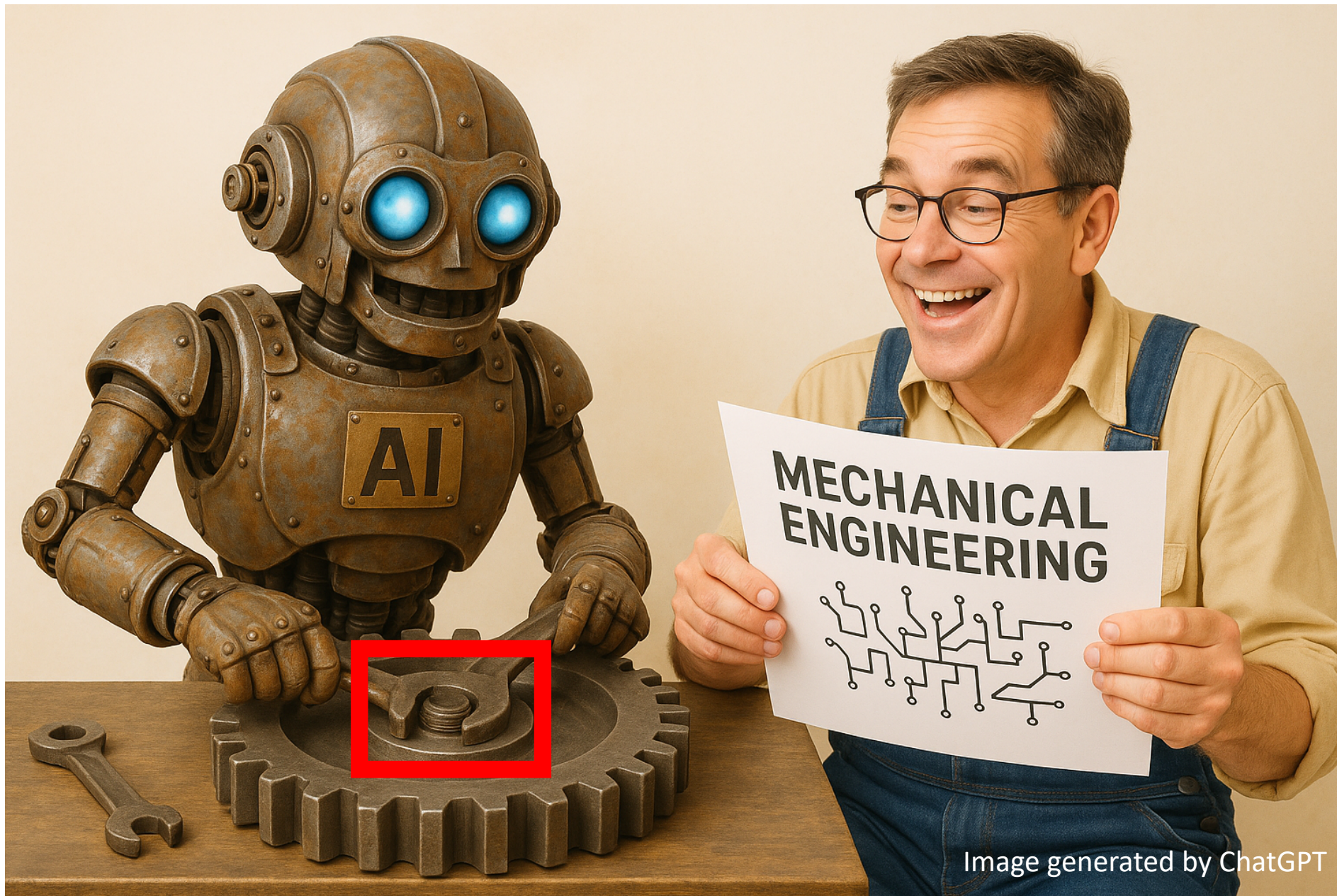
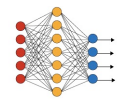


Image generated by ChatGPT



**CONCLUSION: WE LIVE AN EXCITING TIME!**



## CONCLUSION: WE LIVE AN EXCITING TIME!

*“The best way to predict the future is to invent it.”*

*Alan Kay*





