
xHam: a *Mathematica* package for Hamiltonian analysis

Joffrey Le Grix de la Salle¹

In collaboration with: Eugeny Babichev¹, Nils Albin Nilsson²

¹Université Paris-Saclay, CNRS/IN2P3, IJCLab, 91405 Orsay, France

²Cosmology, Gravity and Astroparticle Physics Group, Center for Theoretical Physics of the Universe, Institute for Basic Science, Daejeon 34126, Korea

Meeting day GdR Gravitational Waves, 27/05/2026

Plan

Context and motivations

The Dirac's recipe

The code

Conclusion and perspectives

Context and motivations

GR is not enough

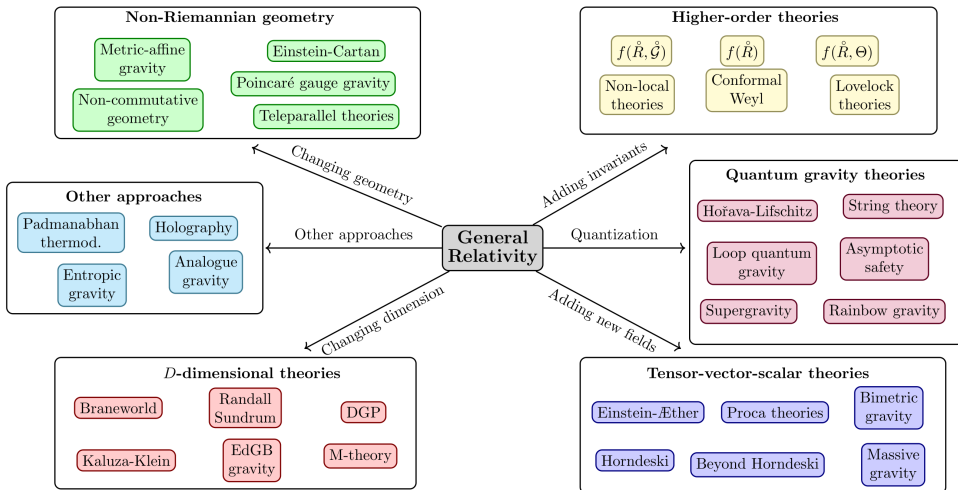
Einstein-Hilbert action :

$$S = \int d^4x \sqrt{-g} \left(\frac{1}{2\kappa} R + \mathcal{L}_m \right) \implies R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = \kappa T_{\mu\nu} \quad (1)$$

- ▶ Singularities
- ▶ Cosmological tensions
- ▶ Closed time-like geodesics
- ▶ Incompatible with quantum mechanics

Going Beyond

Sebastian Bahamonde et al 2023 Rep. Prog. Phys. 86 026901



A brief example

Let's consider $\mathcal{L} = \frac{1}{2}(\square\phi)^2$. Thus the equation of motion is :

$$\square^2\phi = 0$$

4 Cauchy data needed \implies 2 d.o.fs !

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Moreover, the additional degree of freedom is unstable.

Hence, when introducing higher order derivatives/couplings, one needs to know how many degrees of freedom are actually propagating

Motivations for a code

- ▶ Hamiltonian analysis (HA) is robust but hard to perform by hand. Computers are way more reliable.
- ▶ *Mathematica* : powerful and very efficient CAS, with a wide and popular family of packages for modified gravity calculations : **xAct**. But the software is not free...
- ▶ No such code exists for now (almost...)
- ▶ HA is one of the most used tools in modified gravity papers.

→ **There is something to try here !**



The Dirac's recipe

Dirac-Bergmann algorithm

The recipe is very simple in theory, but experimentally awful. Here is how to do :

First step : Primary constraints

Take a Lagrangian \mathcal{L} , and computes the hessian with respect to velocities of fields $\{\dot{\phi}_A\}$:

$$\mathcal{K}_{AB} \equiv \frac{\partial^2 \mathcal{L}}{\partial \dot{\phi}_A \partial \dot{\phi}_B} \quad (2)$$

If $\det \mathcal{K} = 0$, then the system is degenerate : there are constraints.

Note : For covariant Lagrangian, this requires a $3 + 1$ decomposition.

Dirac-Bergmann algorithm

Second step : Total Hamiltonian

Since we have some primary constraints ψ_A , the Hamiltonian is no longer unique on-shell. We need to introduce the **total Hamiltonian** :

$$H_T = \int_{\Sigma_3} d^3x \mathcal{H}_c + \sigma^A \psi_A \quad (3)$$

with σ^A being some arbitrary functions (for now !) of phase space variables.

Dirac-Bergmann algorithm

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→ How to uniquely determine the system's evolution if we have some arbitrariness in our Hamiltonian ?

Dirac-Bergmann algorithm

Third step : Consistency conditions

For now, nothing guarantees that $\psi_A \approx 0$ remains true with time... This has to be imposed :

$$\dot{\psi}_A \equiv \partial_t \psi_A + \{\psi_A; H_T\} \approx 0 \quad (4)$$

We fall in one of this cases :

- ▶ $\dot{\psi}_A \approx 0$ fixes one of the σ^A ;
- ▶ $\dot{\psi}_A \approx 0$ is a linear combination of already known constraints ;
- ▶ $\dot{\psi}_A \approx 0$ gives an additional relation phase space variables must satisfy \Rightarrow **secondary constraints**

Some subtleties must be managed, like the presence of distributions

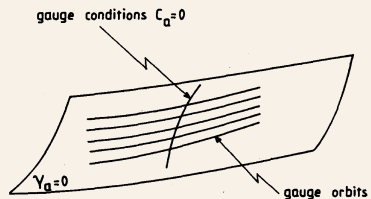
Then, we simply repeat until no new constraint emerges.

Dirac-Bergmann algorithm

Last step : Dirac constraint matrix

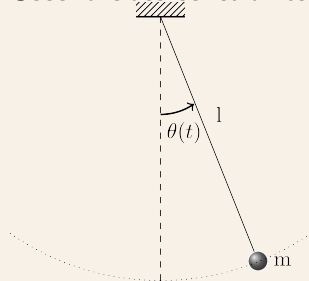
Is the dynamics on sub-manifold defined by the set of constraints well defined? → Maybe not.
There may be some degeneracy because of the so called first class constraints!

First class constraints



"Quantization of Gauge Systems", M. Henneaux & C. Teitelboim

Second class constraints



Dirac-Bergmann algorithm

Last step : Dirac constraint matrix

Is the dynamics on sub-manifold defined by the set of constraints well defined? → Maybe not. There may be some degeneracy because of the so called first class constraints!

$$M_{AB} \equiv \{C_A, C_B\} \quad (5)$$

The kernel of the dirac matrix M gives the first class constraints in the system.

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This is the hard part !

A quick example : GR

We first perform an ADM decomposition of the Einstein-Hilbert Lagrangian :

$$\mathcal{L} = \sqrt{-g}R = N\sqrt{\gamma} (K_{ij}K^{ij} - K^2 + \mathcal{R} - 2\nabla_{\mu}(a^{\mu} - Kn^{\mu})) \quad (6)$$

with $K_{ij} = -\frac{1}{2N}(\partial_t\gamma_{ij} - 2D_{(i}N_{j)})$. We find :

$$P_N = 0 ; P_i = 0 ; \Pi^{ij} = -\sqrt{\gamma} (K^{ij} - K\gamma^{ij})$$

$$H_T = \int_{\Sigma_3} d^3x N\mathcal{H}_0 + N^i\mathcal{H}_i + \sigma P_N + \lambda^i P_i \quad (7)$$

with

$$\mathcal{H}_0 \equiv \frac{1}{\sqrt{\gamma}} \left(\Pi^{ij}\Pi_{ij} - \frac{1}{2}\Pi^2 - \gamma\mathcal{R} \right) ; \mathcal{H}_i \equiv D_j\Pi_i^j$$

A quick example : GR

Final set of constraints :

$$\{P_N \approx 0, P_i \approx 0, \mathcal{H}_0 \approx 0, \mathcal{H}_i \approx 0\}$$

They all (weakly) Poisson commute, *i.e* $M_{AB} \approx 0$. The eight constraints are first class. Since we started from $(1 + 3 + 6) \times 2 = 20$ phase space variables, we find that :

$$N_{\text{dof}} = \frac{20 - 2 \times 8 - 0}{2} = 2 \quad (8)$$

degrees of freedom are propagating in GR.

The code

What does xHam do ?

$\mathcal{H}_C + \text{PS variables} + \text{Primaries} \longrightarrow \mathbf{xHam} \longrightarrow \text{Constraints} + \text{Dirac matrix} + \text{D.O.Fs}$

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$\mathcal{H}_C + \text{PS variables} + \text{Primaries} \longrightarrow \mathbf{xHam} \longrightarrow \text{Constraints} + \text{Dirac matrix} + \text{D.O.Fs}$

- ▶ Reliable to find constraints
- ▶ Only detects obvious FCC in the Dirac matrix.
- ▶ Still a bit slow
- ▶ ADM decomposition has to be done by hand

GR

What about GR?

```
In[254]:= ClearAssumptions[];
Vars = {{h, Lapse, Shift}, {Ph, PN, PNi}};
$PrimaryConstraints = {PN[], PNi[-a]};
$UserAssumptions = {};
```

```
In[263]:= Hc = Lapse[]  $\left( \frac{\text{Ph}[-a, -b] \times \text{Ph}[a, b] - \text{Ph}[-a, a] \times \text{Ph}[-b, b] / 2 - \text{Deth}[] \times \text{RicciScalarCD3D}[]}{\text{Sqrt}[\text{Deth}[]]} \right) - 2 \text{Shift}[a] \times \text{CD3D}[-b][\text{Ph}[b, -a]]$ 
```

```
Out[263]=
```

$$\frac{N \left(\tilde{\pi}_{ab} \tilde{\pi}^{ab} - \frac{1}{2} \tilde{\pi}_a^a \tilde{\pi}_b^b - \tilde{h} R[D] \right)}{\sqrt{\tilde{h}}} - 2 N^a (D_b \tilde{\pi}^b_a)$$

GR

What about GR?

```
In[266]:= ({FCC, SCC} = DBAnalysis[Hc, Vars, CD3D]) // AbsoluteTiming
                                         [durée absolue
```

There is/are at least 8 first-class constraint(s).

There is/are at most 0 second-class constraint(s).

There is/are at most 2 physical degree(s) of freedom.

```
Out[266]=
```

```
{7.78237, {{P̃N, P̃Na, 2 π̃ab π̃ab - π̃aa π̃bb - 2 h̃ R[D], Db π̃aab}, {}}}
```

Einstein-Maxwell (vacuum)

Let's now focus en Einstein-Maxwell Lagrangian without any charge :

$$\mathcal{L} = \sqrt{-g} \left(R - \frac{1}{4} F_{\mu\nu} F^{\mu\nu} \right) \quad (9)$$

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```
In[380]:= DBAnalysis[Hc, Vars, CD3D, Verbose -> "Minimal"] // AbsoluteTiming
                                         [durée absolue
```

Total Hamiltonian built.

Starting the algorithm...

-----Generation number 2 computed in 2.99682 seconds.-----

Constraints found in 13.556 seconds.

Computing Constraint matrix...

There is/are at least 10 first-class constraint(s).

There is/are at most 0 second-class constraint(s).

There is/are at most 4 physical degree(s) of freedom.

```
{26.716, {{P̄ϕ, P̄N, P̄Na, Da P̄A^a,
          PA_a PA^a + 4 κ π_ab π^ab - 2 κ π^a_a π^b_b - (ħ R[D] / κ) - ħ (Da Ab) (Db A^a) + ħ (Db Aa) (D^b A^a), PA^b (Da Ab) - PA^b (Db Aa) - 2 (Db π_a^b)}, {}}}
```

Other benchmarks

Let's now focus on Einstein-Maxwell Lagrangian without any charge :

Theory	Nb of DOFs	Time (s)	Correct ?
GR	2	~ 8	Yes
Einstein-Maxwell	4	~ 27	Yes
MCSF	3	~ 11	Yes
K-essence	3	~ 38	Almost
Mimetic gravity	3	~ 11	Almost
SME (Appendix)	3	~ 110	Yes
$R+(\square\phi)^2$	4	~ 72	Almost
G3 Horndeski	?	?	Not anymore

Recent changes worsened the computation time...

Conclusion and perspectives

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- ▶ Classification of constraints needs to be studied in depth
- ▶ Automatic ADM decomposition

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- ▶ Automatic ADM decomposition
- ▶ Faddev-Jackiw method ?

Conclusions and perspective

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- ▶ Classification of constraints needs to be studied in depth
- ▶ Automatic ADM decomposition
- ▶ Faddev-Jackiw method ?

But the code **cannot** evade limitations intrinsic to HA...

Thank you !

$$\mathcal{L} = \sqrt{-g} \left(\frac{1}{2\kappa} R + K(\phi, X) \right) \quad (10)$$

Appendix 1 : K-essence

$$\mathcal{L} = \sqrt{-g} \left(\frac{1}{2\kappa} R + K(\phi, X) \right) \quad (10)$$

```
In[219]:= ClearAssumptions[];  
Vars = {{h, Lapse, Shift,  $\phi$ ,  $\lambda$ ,  $\rho$ }, {Ph, PN, PNi, P $\phi$ , P $\lambda$ , P $\rho$ }};  
$PrimaryConstraints = {PN[], PNi[-a], P $\lambda$ [], P $\rho$ []};  
MakeAssumptions[ $\lambda$ []  $\neq$  0];  
DefLagMult[$PrimaryConstraints];
```

Appendix 1 : K-essence

$$\mathcal{L} = \sqrt{-g} \left(\frac{1}{2\kappa} R + K(\phi, X) \right) \quad (10)$$

```
In[227]:= {FCC, SCC} = DBAnalysis[Hc, Vars, CD3D] // AbsoluteTiming
                                         [durée absolue
```

```
{ {{4, 0}, {3, 0}}, 04, 0, 2 h̃ K(0,1) [ϕ, ρ]2, 0 }
```

```
{ {{3, 0}}, 03, 0, 1 +  $\frac{\tilde{P}\tilde{\phi}^2 K^{(0,2)}[\phi, \rho]}{\tilde{h} K^{(0,1)}[\phi, \rho]^3}$ , 0 }
```

There is/are at least 4 first-class constraint(s).

There is/are at most 8 second-class constraint(s).

There is/are at most 5 physical degree(s) of freedom.

```
Out[227]=
```

```
{ 38.1114, { {P̄N, P̄Na}, {P̄λ, P̄ρ, P̄ϕ2 - 2 h̃ K[ϕ, ρ] λ + 2 p̄ab p̄ab λ - p̄aa p̄bb λ - 2 h̃ R[D] λ + 2 h̃ λ2 ρ + h̃ λ2 (Da ϕ) (Da ϕ),
P̄ϕ (Da ϕ) - 2 (Db p̄aa), -2 P̄ϕ2 + 2 h̃ K[ϕ, ρ] λ - 2 p̄ab p̄ab λ + p̄aa p̄bb λ + 2 h̃ R[D] λ, λ - K(0,1) [ϕ, ρ] } } }
```

Appendix 1b : degenerate K-essence

$$\mathcal{L} = \sqrt{-g} \left(\frac{1}{2\kappa} R + K(\phi) \right) \quad (11)$$

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```
In[232]:= ClearAssumptions[];  
Vars = {{h, Lapse, Shift,  $\phi$ }, {Ph, PN, PNi, P $\phi$ }};  
$PrimaryConstraints = {PN[], PNi[-a], P $\phi$ []};  
$UserAssumptions = {};  
DefLagMult[$PrimaryConstraints];
```

Appendix 1b : degenerate K-essence

$$\mathcal{L} = \sqrt{-g} \left(\frac{1}{2\kappa} R + K(\phi) \right) \quad (11)$$

```
In[259]:= {FCC, SCC} = DBAnalysis[Hc, Vars, CD3D] // AbsoluteTiming|
                                         |durée absolue
```

```
{{{3, 0}}, σ3, 0, K''[φ], 0}
```

There is/are at least 8 first-class constraint(s).

There is/are at most 2 second-class constraint(s).

There is/are at most 2 physical degree(s) of freedom.

```
{11.0704, { {P̃N, P̃Na, 2 h̃ K[φ] - 2 π̃ab π̃ab + π̃aa π̃bb + 2 h̃ R[D], Db π̃ab}, {P̃φ, K'[φ]} } }
```

Appendix 2 : SME models

In the paper [2009.00949] (K. O'Neal-Ault, Q.G. Bailey, and N.A. Nilsson, Phys. Rev. D 103, 044010 (2021)), they consider the Lagrangian :

$$\mathcal{L}_1 = \frac{N\sqrt{\gamma}}{2\kappa} \left[\mathcal{R} + \frac{N^2 - s_{00}}{N^2} (K^{ij} K_{ij} - K^2) + K \left(\frac{2}{N^4} s_{00} (\dot{N} - N N^i a_i) - \frac{1}{N^3} (\dot{s}_{00} - N^i \partial_i s_{00}) \right) \right. \\ \left. + \frac{2}{N^2} s_{00} a^i a_i - \frac{1}{N^2} a^i \partial_i s_{00} \right] + \mathcal{L}_M \quad (12)$$

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```
In[287]:= {FCCf, SCCf} = DBAnalysis[Hc, Vars, CD3D, Verbose -> "Minimal"] // AbsoluteTiming
|durée absolue
```

```
Total Hamiltonian built.
Starting the algorithm...
-----Generation number 2 computed in 0.664519 seconds.-----
Constraints found in 3.48444 seconds.
Computing Constraint matrix...
There is/are at least 6 first-class constraint(s).
There is/are at most 0 second-class constraint(s).
There is/are at most 4 physical degree(s) of freedom.
```

```
Out[287]=
```

```
{5.66935, {{PN~a, PN~ (Da N) - 2 (Db pab)}, {}}}
```