

COCO: objectives

- function testbed:
 - should “reflect reality”
 - mainly **non-convex** and **non-separable**
 - **scalable** with the search space dimension
 - **not too easy** to solve, but yet **comprehensible**
- provide **data acquisition** at the interface of solver and objective function
 - lean but sufficient data for quantitative analyses
- data presentation yields **quantitative assessment**, stratified by function properties...

BBOB in practice

The screenshot shows a Google search results page for the query "bbob 2009". The browser window title is "bbob 2009 - Google ...". The search bar contains "bbob 2009" and the search button is labeled "Search". Below the search bar, there are navigation links for "Web", "Images", "Videos", "Maps", "News", "Shopping", "Google Mail", and "more". The search results are displayed in a list format, with the first result being "BBOB 2009 - bbob-2009 [Comparing Continuous Optimisers: COCO]". The second result is "bbob-2009-downloads [Comparing Continuous Optimisers: COCO]". The third result is "Benchmarking sep-CMA-ES on the BBOB-2009 function testbed". The fourth result is "Benchmarking the NEWUOA on the BBOB-2009 noisy testbed". The fifth result is "Baby On Board (2009) m720p-AdiT - Free Download Of Movies ...".

Invited Talks, Semina... x bbob 2009 - Google ... x

http://www.google.co.uk/search?sourceid=chrome&ie=UTF-8&q=bbob+2009

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Search: the web pages from the UK

Web [+ Show options...](#) Results 1 - 10 of about 180,000 for **bbob 2009**. (0.26 seconds)

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A partly time and space linear CMA-ES is benchmarked on the **BBOB-2009** noiseless function testbed. This algorithm with a multistart strategy with increasing ...
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BBOB in practice

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[[bbob-2009-downloads]] COMPARING CONTINUOUS OPTIMISERS: COCO

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BBOB 2009 (Version 3.6) (30MB) is all that you need to prepare a workshop paper and contains the following files

- CODE:
 - tar code in Matlab/Octave
 - tar code in C
 - tar post-processing Python package + workshop paper LaTeX templates
 - soon available: post-processing Python package including comparing analysis
- DOCS:
 - pdf description of experimental procedure
 - pdf (13MB) noiseless functions documentation with figures
 - pdf noiseless functions documentation, version without figures
 - pdf (20MB) noisy function documentation with figures
 - pdf noisy function documentation, version without figures
 - pdf software user documentation
- TECHNICAL DOCS:
 - html post-processing package documentation

[Here are the results from the workshop in July 2009](#)

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BBOB in practice

Matlab script:

```
for dim = [2,3,5,10,20,40] % small dimensions first, for CPU reasons
    for ifun = benchmarks('FunctionIndices') % or benchmarksnoisy(...)
        for iinstance = [1:5, 1:5, 1:5] % first 5 fct instances, three times
            fgeneric('initialize', ifun, iinstance, datapath);

            MY_OPTIMIZER('fgeneric', dim, ... % necessary parameters
                fgeneric('ftarget')); % optional termination parameter

            fgeneric('finalize');
        end
        disp(['        date and time: ' num2str(clock, ' %.0f')]);
    end
    disp(sprintf('---- dimension %d-D done ----', dim));
end
```

BBOB in practice

Post-processing at the OS shell:

```
python codepath/bbob_pproc/run.py datapath  
pdflatex templateACMarticle.tex
```

Black-Box Optimization Benchmarking Template for Noiseless Function Testbed

Draft version *
Forename Name

ABSTRACT

Categories and Subject Descriptors
G.1.6 [Numerical Analysis]: Optimization—global optimization, unconstrained optimization; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

General Terms

Algorithms

Keywords

Benchmarking, Black-box optimization, Evolutionary computation

1. RESULTS

Results from experiments according to [7] on the benchmark functions given in [7, 7] are presented in Figures 1 and 2 and in Table 1.

*Camera-ready paper due April 17th.

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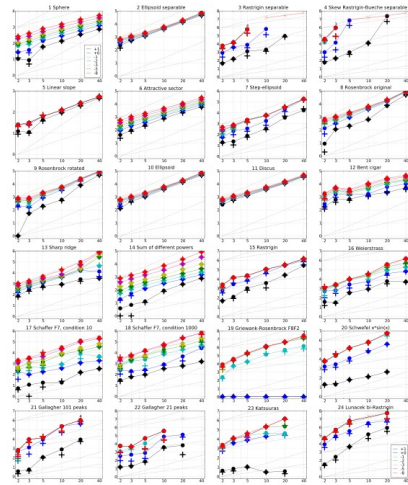


Figure 1: Expected Running Time (ERT) (●) to reach $f_{opt} + \Delta f$ and median number of function evaluations of successful trials (†), shown for $\Delta f = 10.1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-4}, 10^{-5}, 10^{-6}$ (the exponent is given in the legend of f_i and f_j) versus dimension in log-log presentation. The ERT(Δf) equals to $\#FE_{\text{succ}}(\Delta f)$ divided by the number of successful trials, where a trial is successful if $f_{\text{best}} + \Delta f$ was surpassed during the trial. The $\#FE_{\text{succ}}(\Delta f)$ are the total number of function evaluations while $f_{\text{best}} + \Delta f$ was not surpassed during the trial from all respective trials (successful and unsuccessful), and f_{best} denotes the optimal function value. Crosses (†) indicate the total number of function evaluations $\#FE_{\text{succ}}(\infty)$. Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.

Table 1: Shown are, for a given target difference to the optimal function value Δf , the number of successful trials (†); the expected running time to our pass ($f_{\text{best}} + \Delta f$) (ERT, see Figure 1); the 10%-ile and 90%-ile of the bootstrap distribution of ERT; the average number of function evaluations in successful trials or, if none was successful, as last entry the median number of function evaluations to reach the best function value ($\#FE_{\text{succ}}(\infty)$). If $f_{\text{best}} + \Delta f$ was never reached, figures in $\#FE_{\text{succ}}$ denote the best achieved Δf -value of the median trial and the 10% and 90%-ile trial. Furthermore, N denotes the number of trials, and $\#FE_{\text{succ}}$ denotes the maximum number of function evaluations executed in one trial. See Figure 1 for the names of functions.

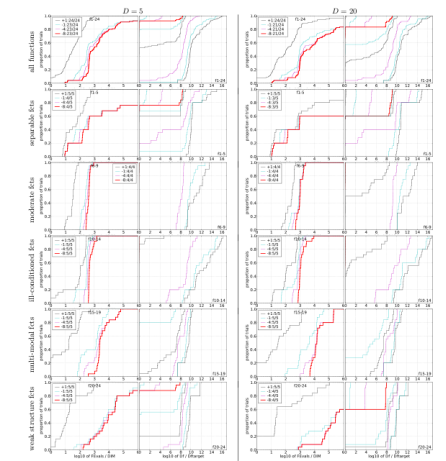


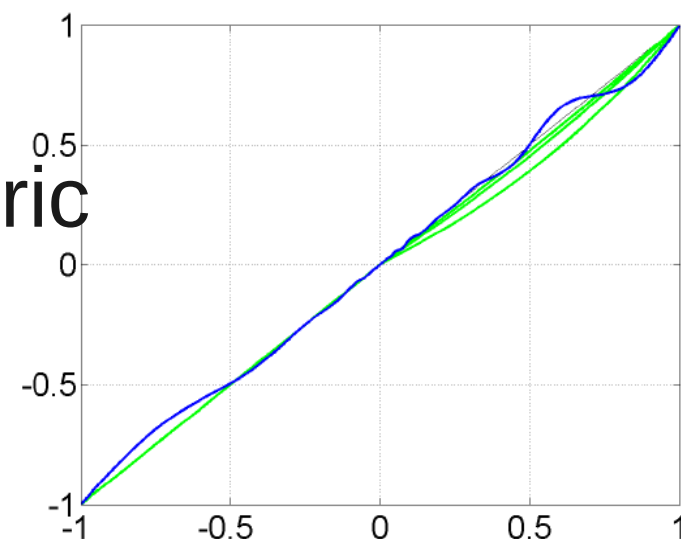
Figure 2: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left subplots) or versus Δf (right subplots). The thick red line represents the best achieved results. Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension D , to fall below $f_{\text{best}} + \Delta f$ with $\Delta f = 10^k$, where k is the first value in the legend. Right subplots: ECDF of the best achieved Δf divided by 10^k (upper left lines in continuation of the left subplots), and best achieved Δf divided by 10^k for running times of $D, 10D, 100D$. — function evaluations (from right to left: cycling black-cyan-magenta). Top row: all functions; second row: separable functions; third row: nice, moderate functions; fourth row: ill-conditioned functions; fifth row: multi-modal functions with adequate structure; last row: multi-modal functions with weak structure. The legends indicate the number of functions that were solved in at least one trial. $\#FE_{\text{succ}}$ denotes number of function evaluations, D and DIM denote search space dimension, and Δf and DI denote the difference to the optimal function value.

COCO: the noiseless functions

24 functions within **five sub-groups**

- **Separable** functions
- Essential unimodal functions
- **Ill-conditioned** unimodal functions
- **Multimodal structured** functions
- **Multimodal** functions with weak or without structure

functions are not perfectly symmetric
and are locally deformed



COCO: the noisy functions

three noise-“models”, so-called:

- Gauss, Uniform (severe), Cauchy (outliers)
- Utility-free noise

$$E(f(x)) \leq E(f(y)) \Rightarrow U(f(x)) \leq U(f(y)) \quad \forall x, y, U$$

30 functions with three sub-groups

- 2x3 functions with weak noise
- 5x3 unimodal functions
- 3x3 multimodal functions

How should we measure performance?

Evaluation of Search Algorithms

needs

- Meaningful **quantitative measure** on benchmark functions or real world problems
- Account for **meta-parameter tuning**
tuning to specific problems can be quite expensive
- Account for **invariance properties**
prediction of performance is based on “similarity”, ideally equivalence classes of functions
- Account for **algorithm internal costs**
often negligible, depending on the objective function cost

A performance measure

should be

- **quantitative**, with a ratio scale
- well-**interpretable with a meaning**
- **relevant** in the “real world”
- simple

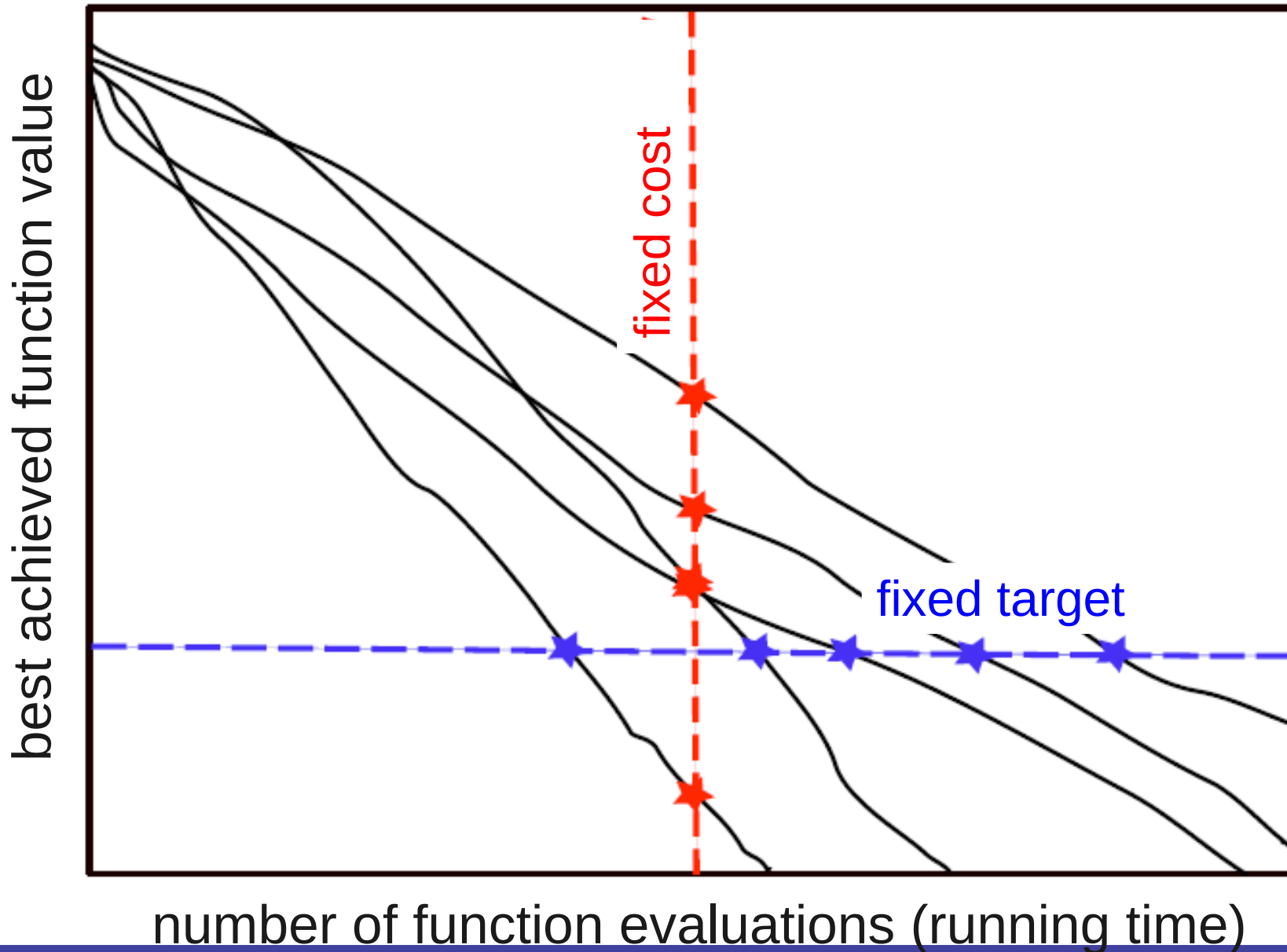
(recall) Black-Box Optimization

Two objectives:

- Find solution with a smallest possible **function value**
- With the least possible **search costs** (number of function evaluations)
- For measuring performance: fix one and measure the other

How should we measure performance?

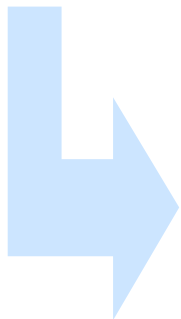
fixed-cost versus fixed-target



A performance measure

should be

- **quantitative**, with a ratio scale
- well-**interpretable with a meaning**
- **relevant** in the “real world”
- simple



running time

- empirical distribution [Hoos & Stützle 1998]
- expectation, median, ...

We measure runtime in number of function evaluations

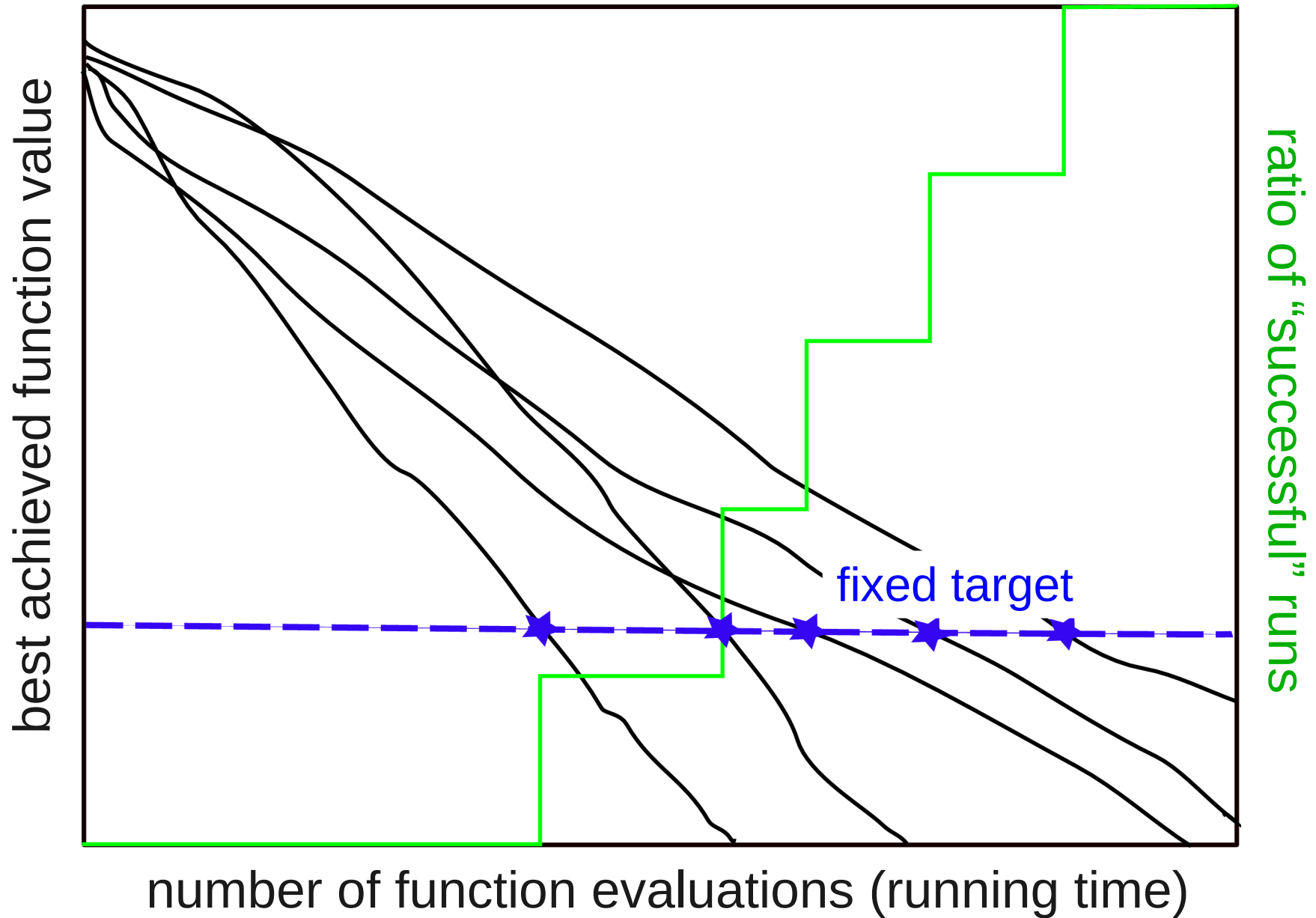
- As a distribution of runtimes
- As expected runtime ERT

For success probability $0 < p < 1$: (simulated) restarts until a successful run is observed.

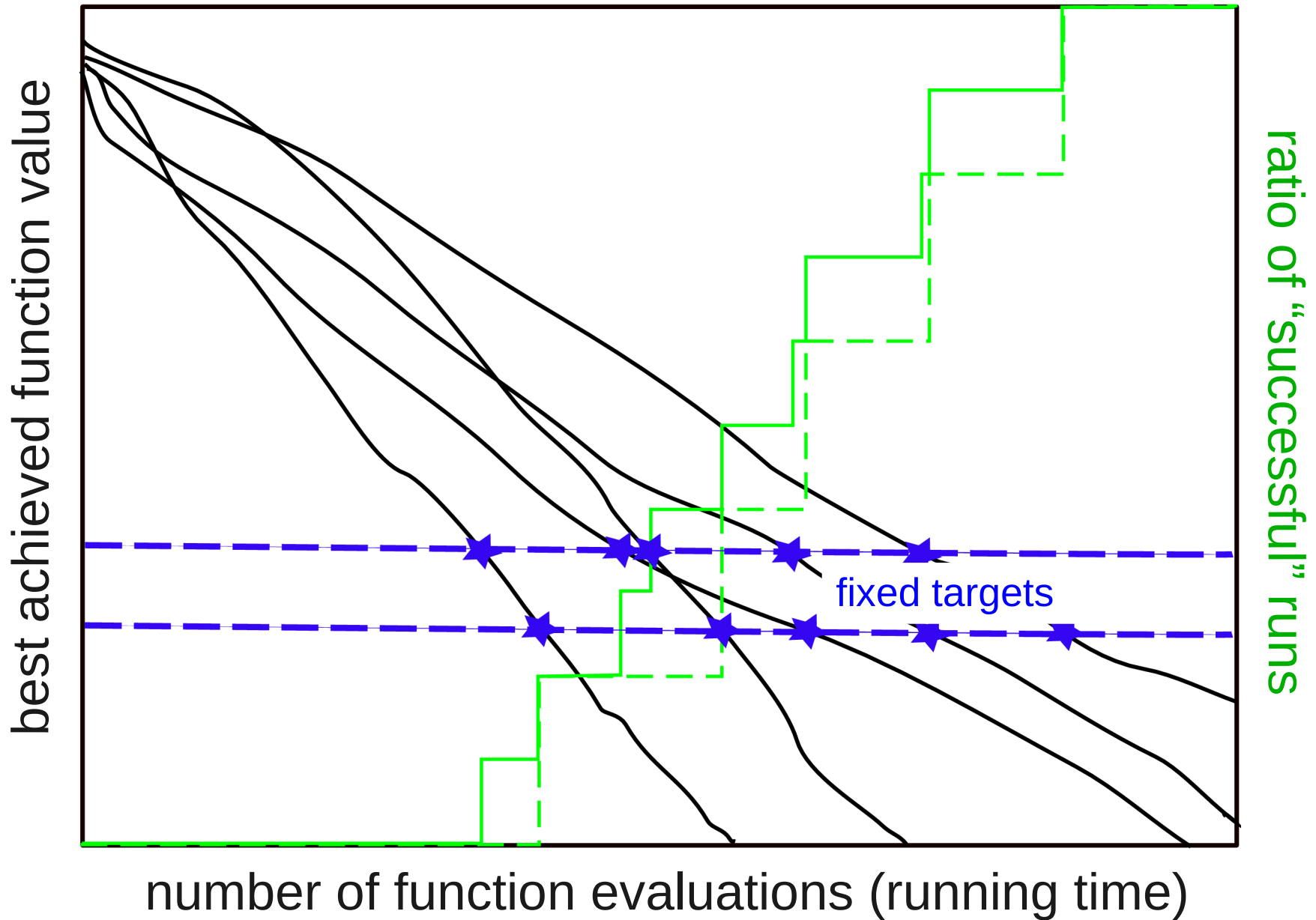
$$\begin{aligned} RT &= RT_{\text{succ}} + \sum RT_{\text{unsucc}} \\ &\approx E(RT_{\text{succ}}) + \frac{1-p}{p} E(RT_{\text{unsucc}}) \end{aligned}$$

Feature/drawback: termination method for unsuccessful trials can be critical

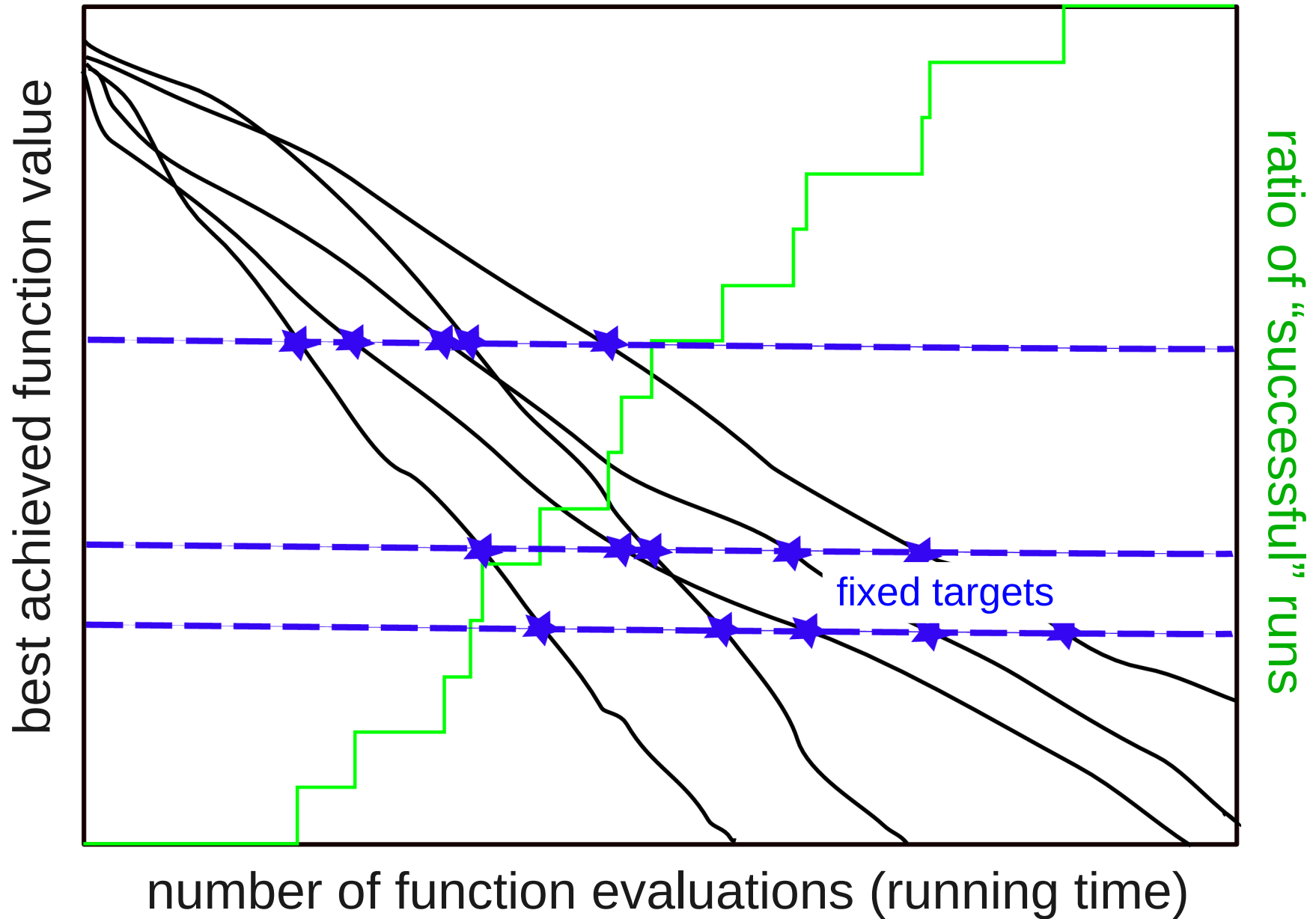
Measuring Performance with given target values



Measuring Performance with given target values



Measuring Performance with given target values

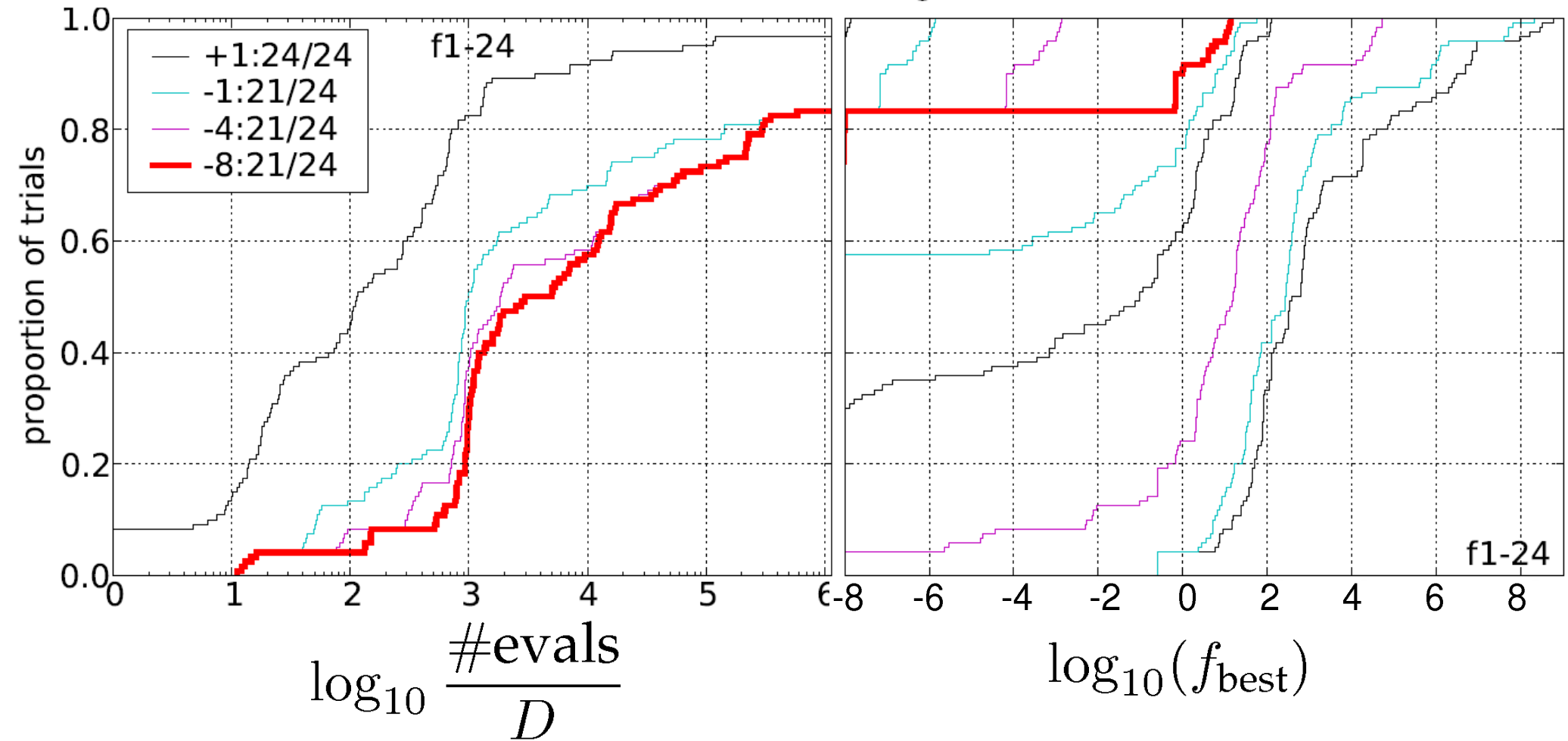


Cumulative Distribution of Runtimes

- Given a **set of functions** and for each function a (weighted) **set of target values**, the cumulative distribution of (simulated) RTs captures all(?) aspects of the **performance in a single graph**
- Remark: this performance measure can **aggregate** over any set of functions and target values
- Here: 50 target values, log-uniform in $[1e-8, 100]$ and 15 trials per function

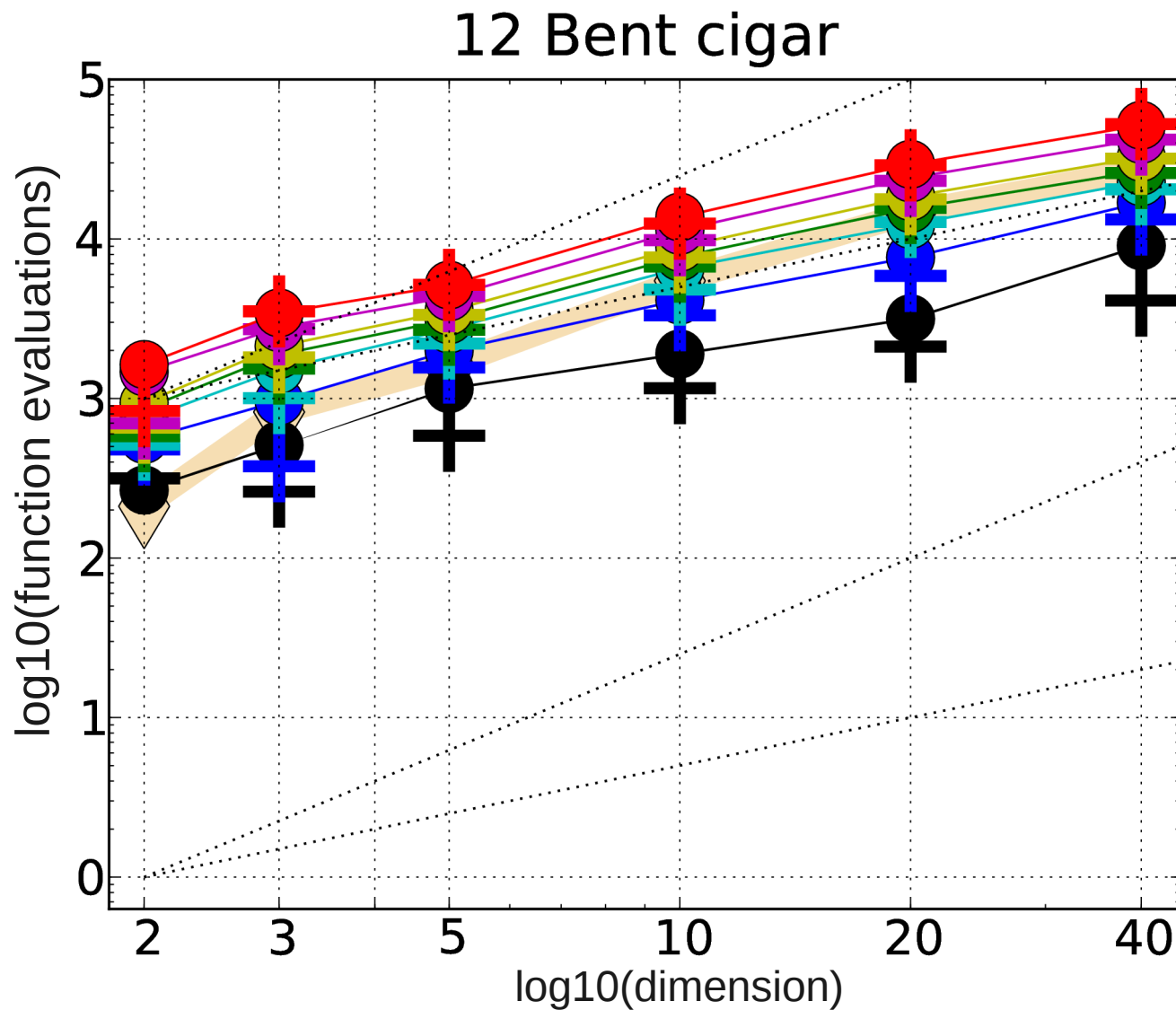
Example for ECDFs

$D = 20$



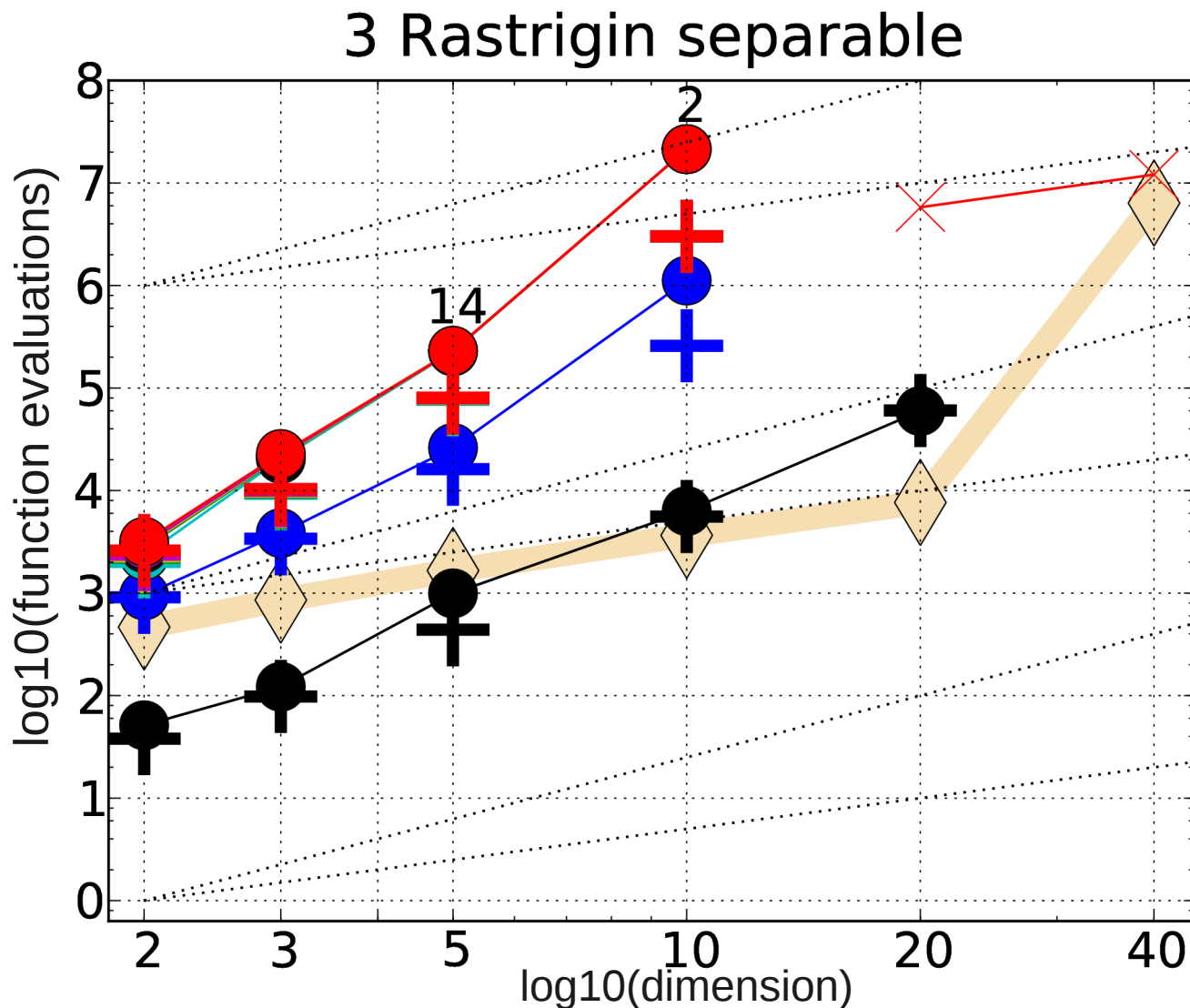
Empirical cumulative distribution functions (ECDFs) of running lengths (left) and function values (right)

Example: Scaling Behaviour



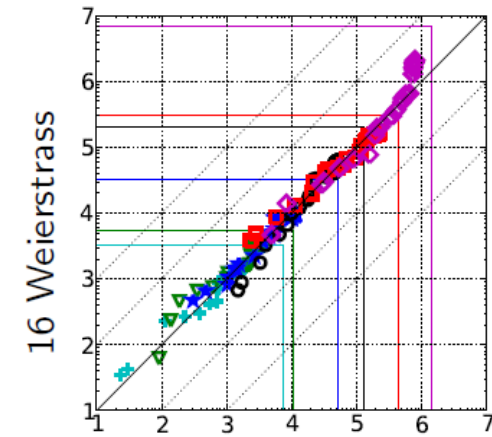
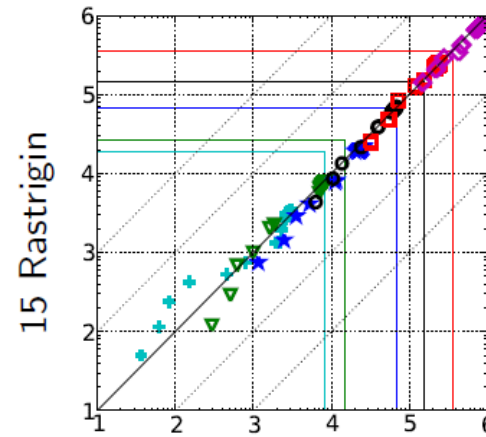
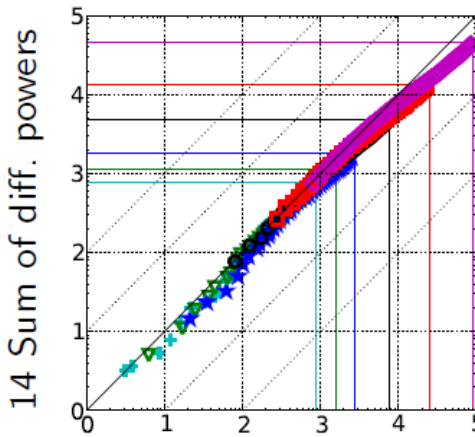
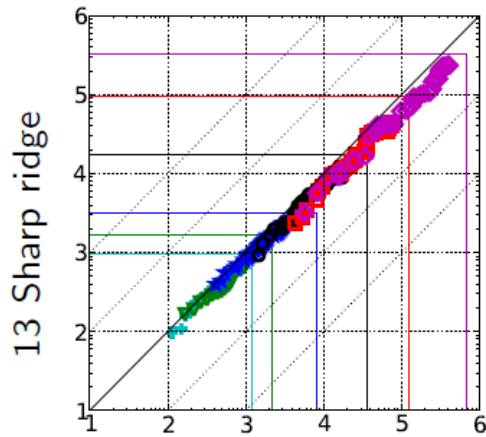
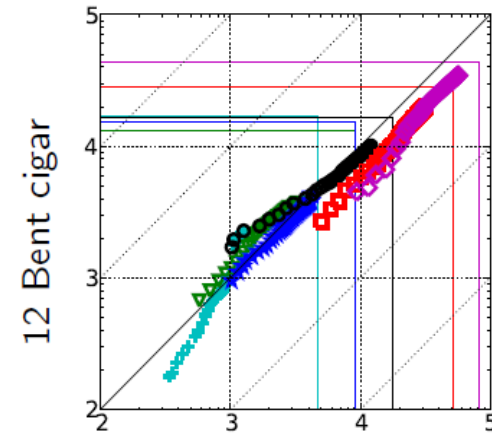
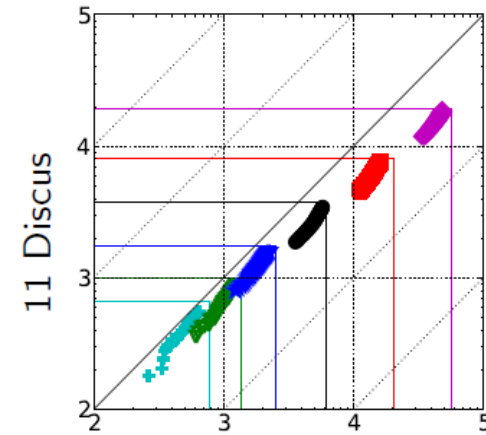
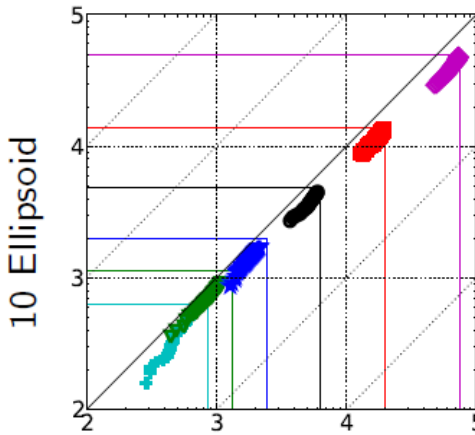
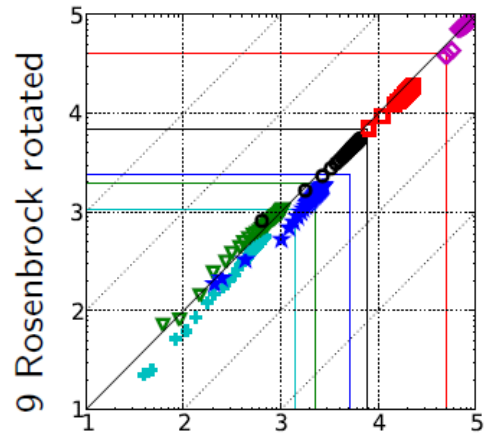
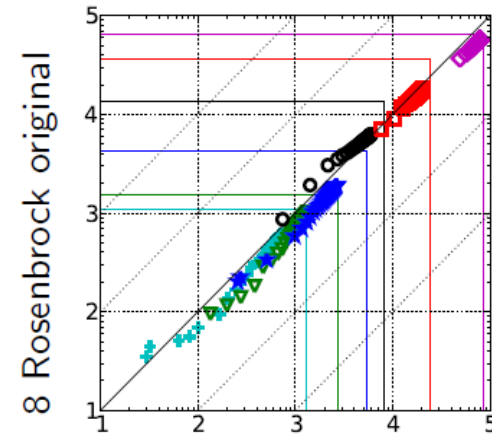
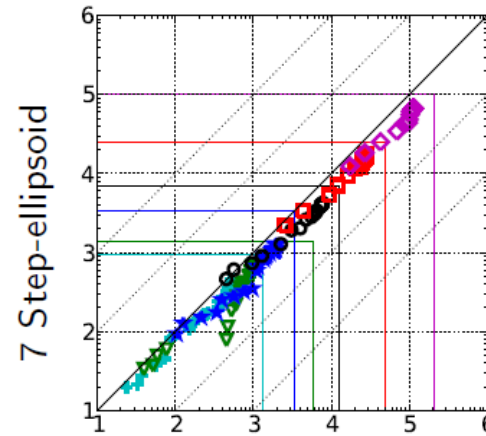
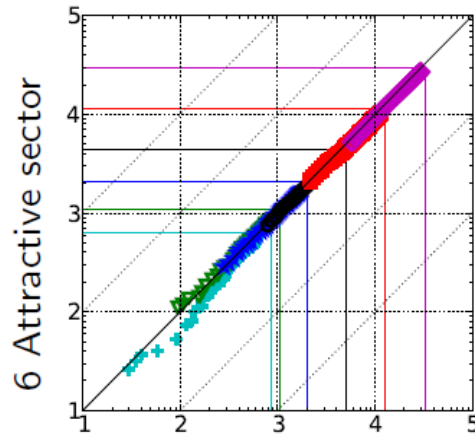
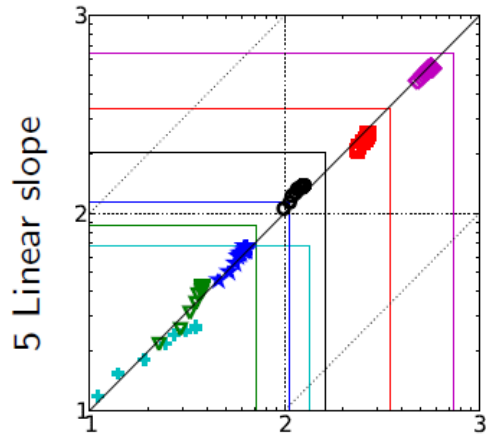
- ERT on f12: linear scaling of BIPOP-CMA-ES

Example: Scaling Behaviour



- Experiments in >100 -D are more often than not virtually superfluous

ERT scatter plots comparing two algorithms all dimensions & targets



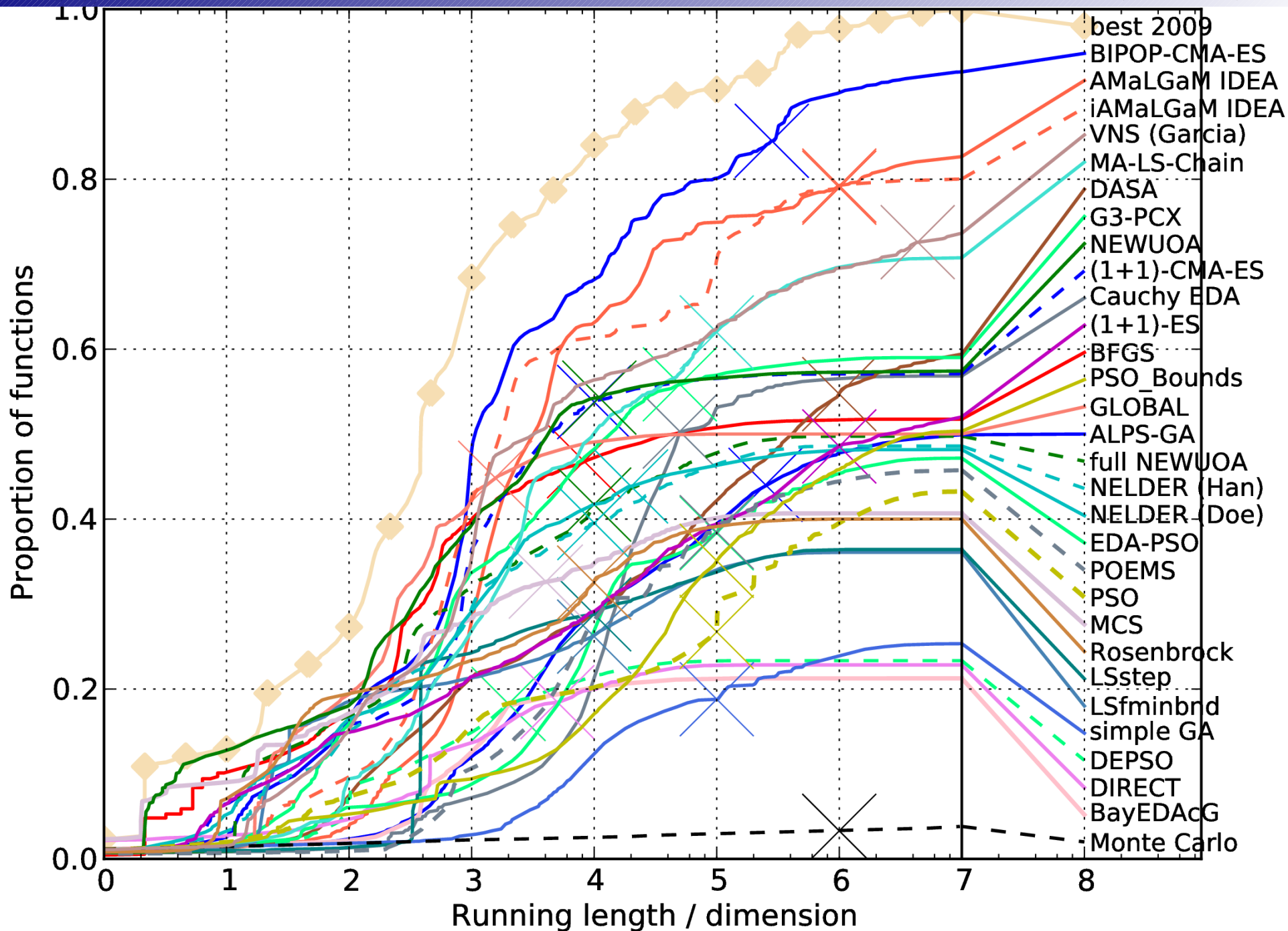
Overall Collected Data Sets

during the *Black-Box Optimization Benchmarking (BBOB) workshops* at the *Genetic and Evolutionary Computation Conference GECCO*

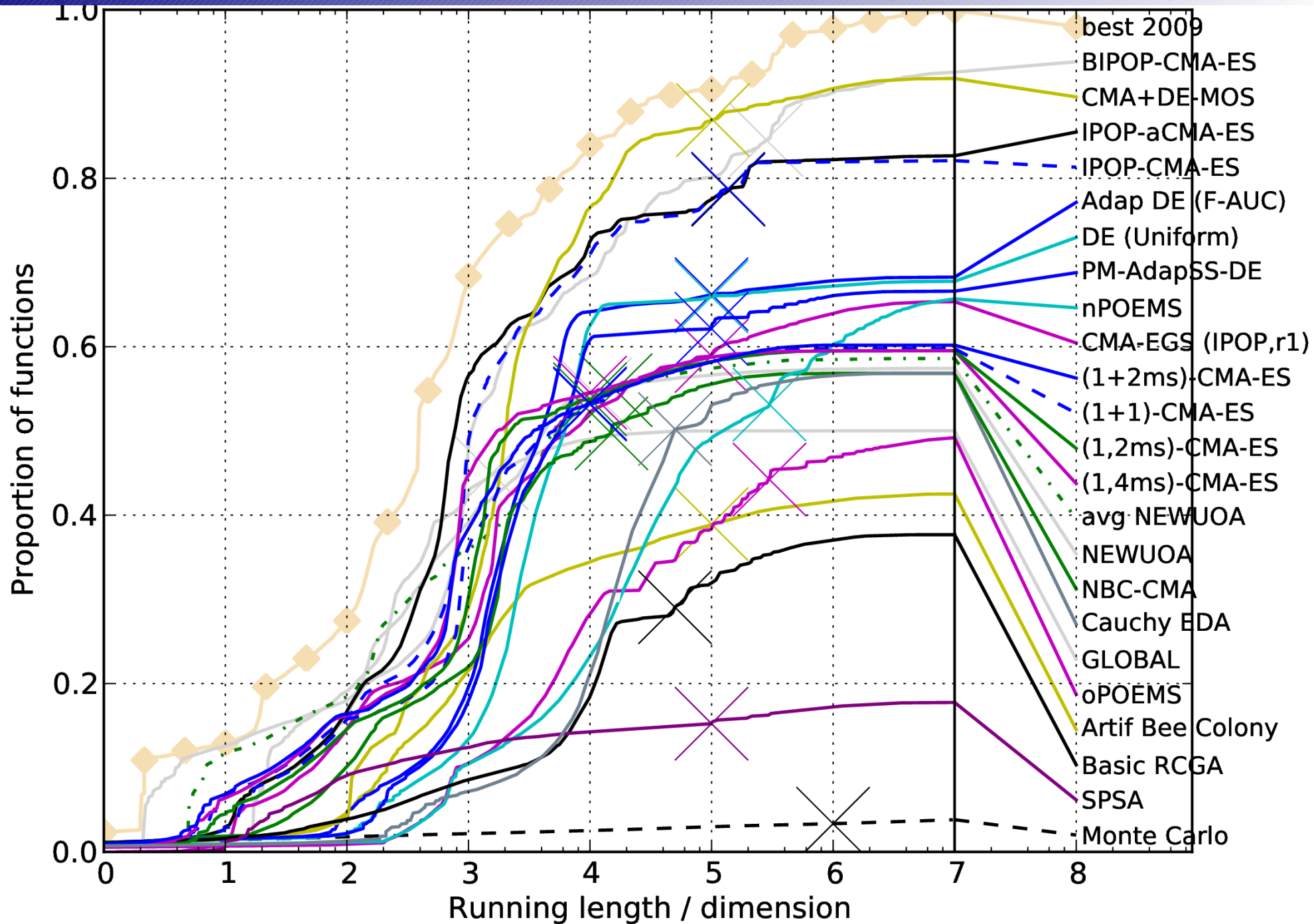
- 2009: 31 noiseless and 21 noisy “data sets”
- 2010: 24 noiseless and 16 noisy “data sets”
- **Algorithms**: RCGAs (eg plain, PCX), EDAs (eg IDEA), BFGS & (many) other “classical” methods, ESs (eg CMA), PSO, DE, Ant-Stigmergy Alg, Bee Colony, EGS, SPSA, Meta-Strategies...

Results

Results of 2009 (noise-free, 20-D)

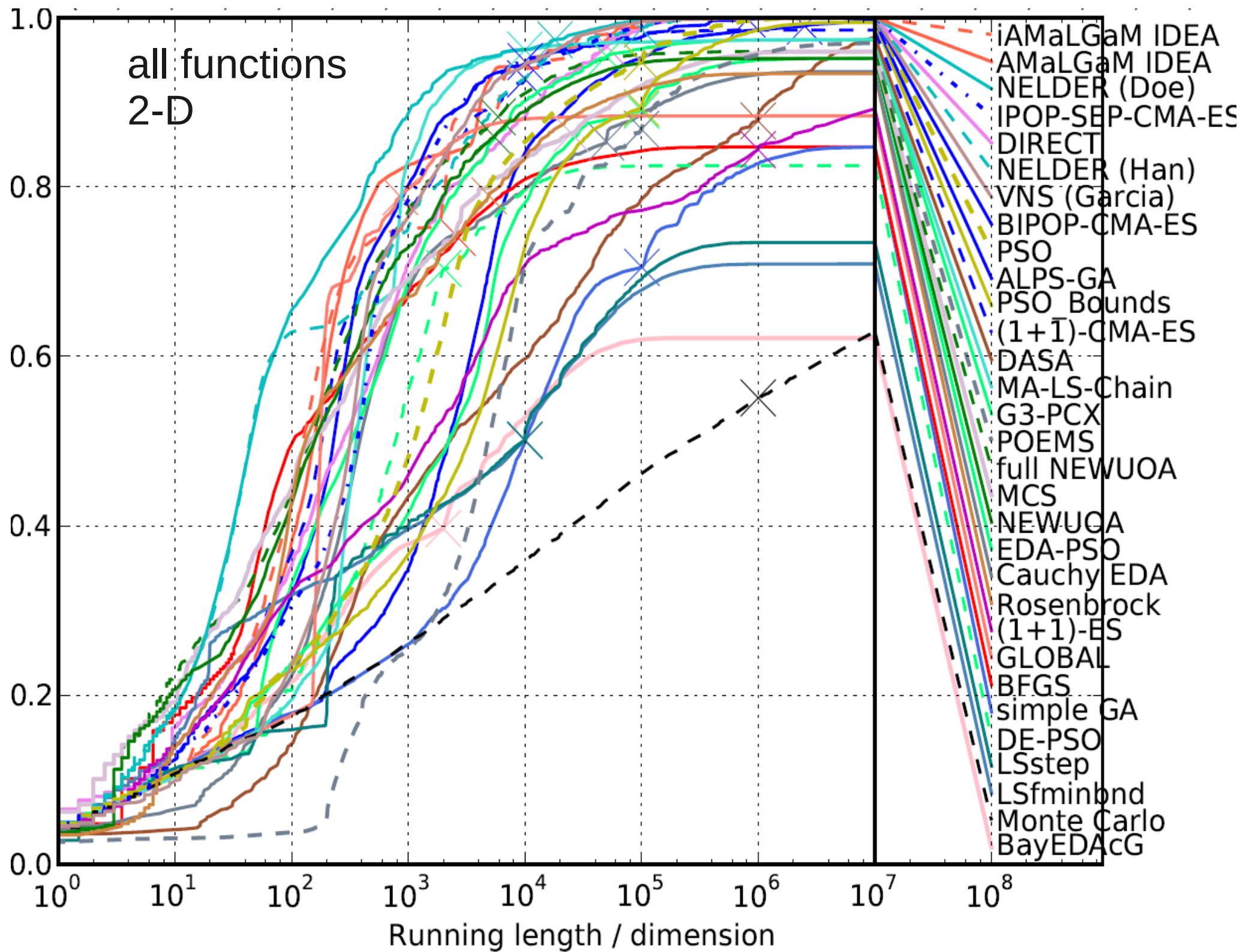


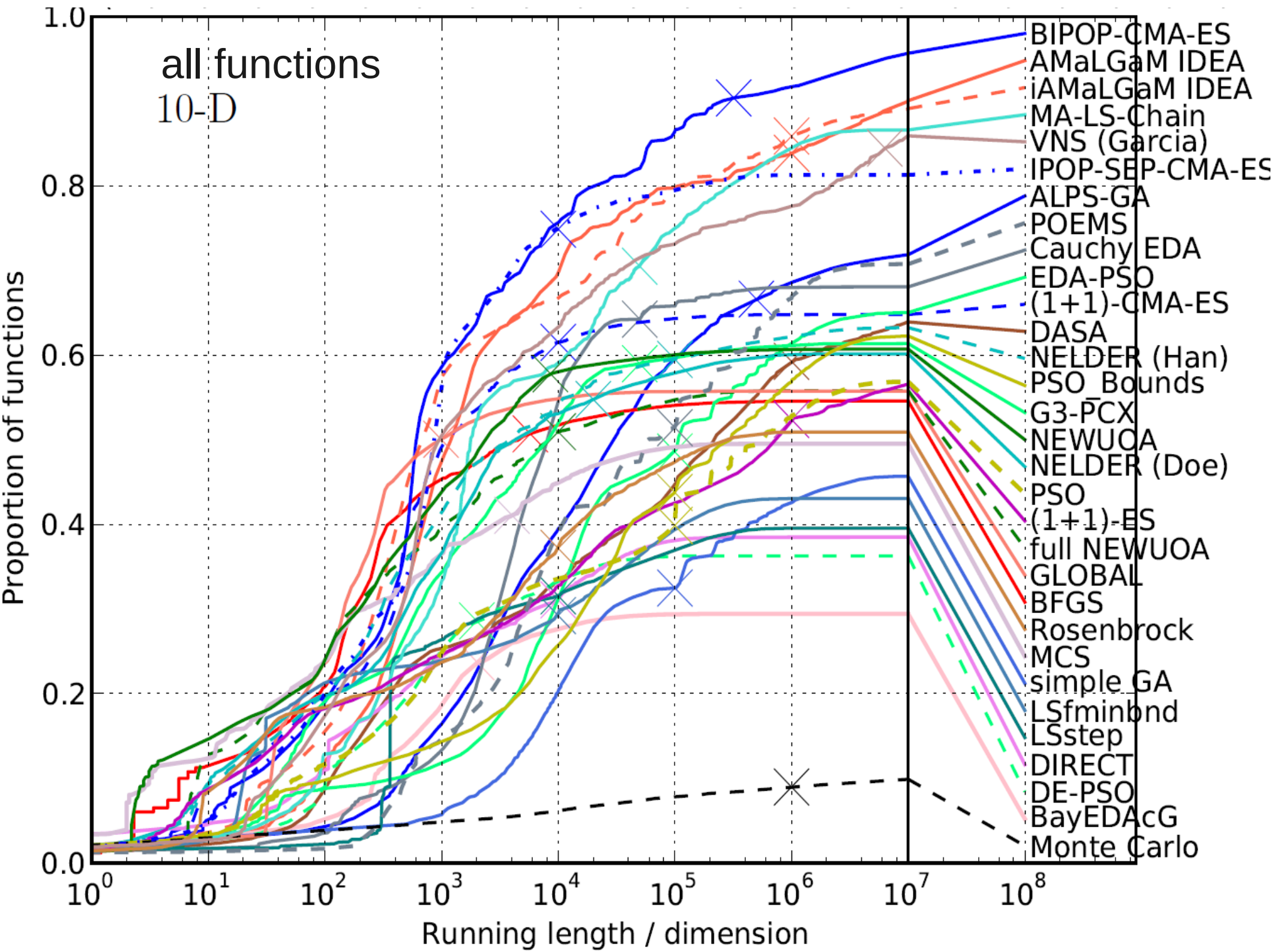
Results of 2010 (noise-free, 20-D)

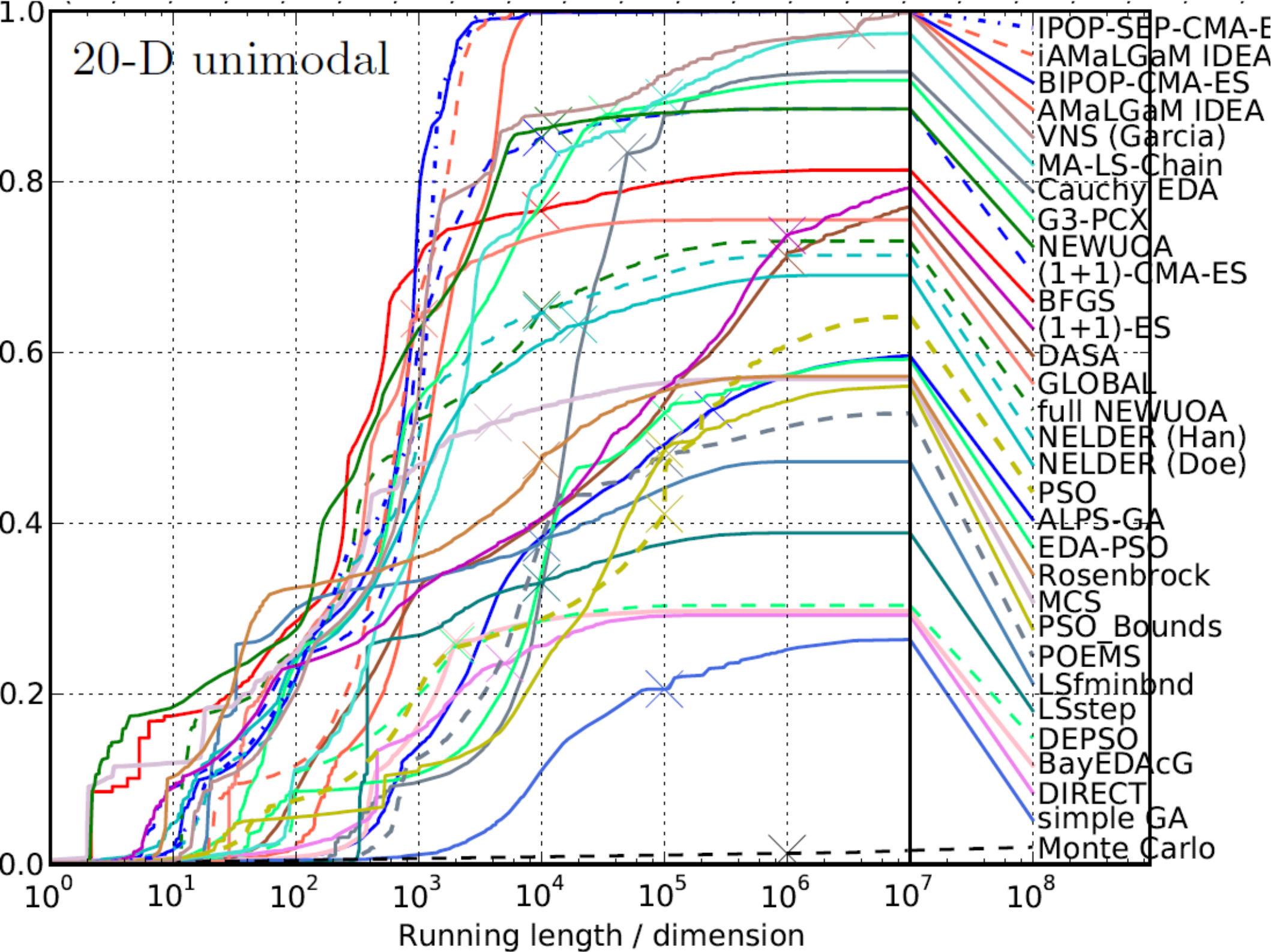


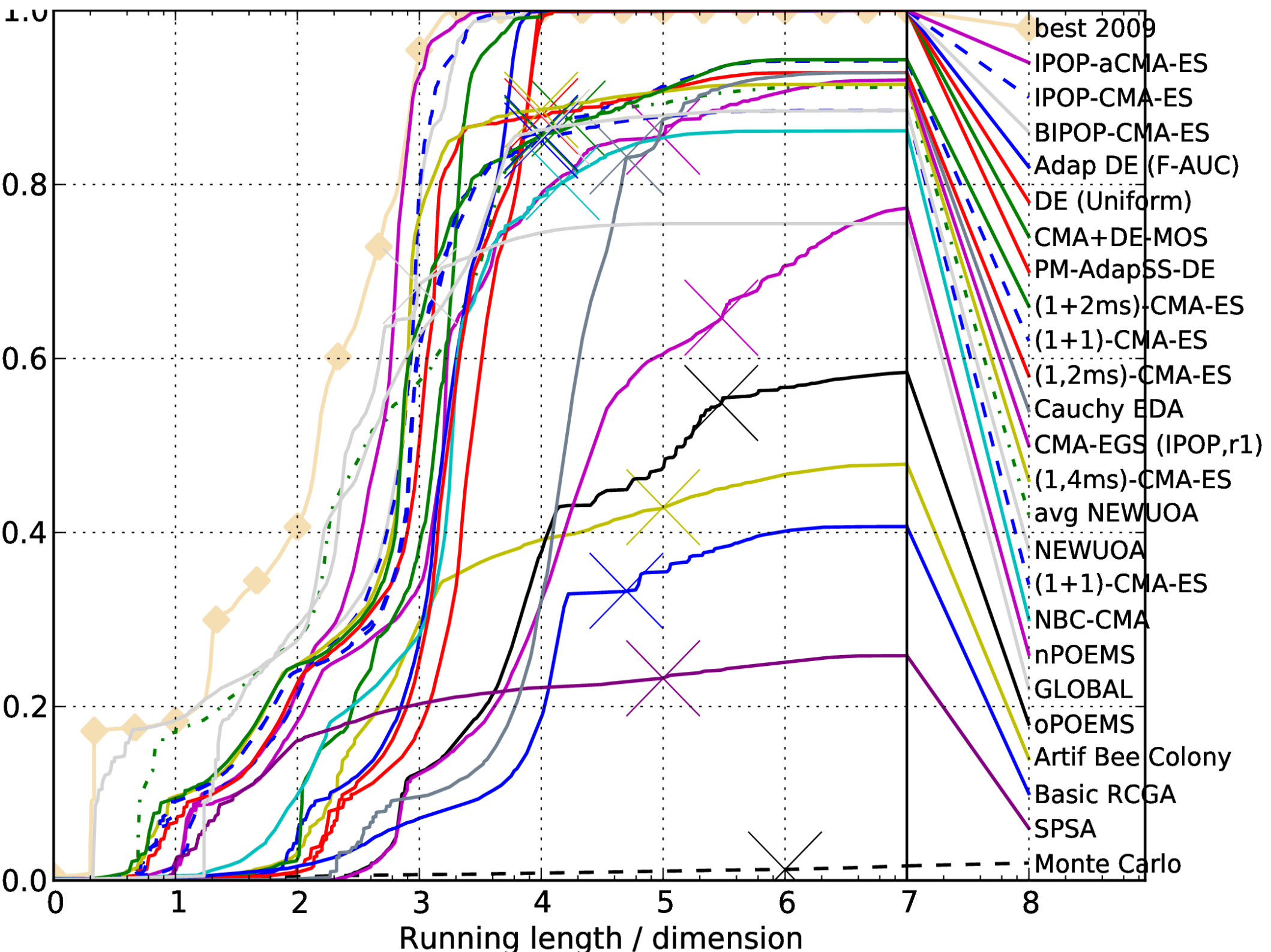
- Functions are not that easy to solve: the best algorithms need 10000 D function evaluations to solve 75% of the problems (function-target pairs)
- Given **at most 500 D evaluations**: MCS, NEWUOA and GLOBAL do well
- Given **more evaluations**: variants of CMA-ES and AMaLGaM-IDEA do well
- In very low dimension Nelder-Mead is superior

all functions
2-D

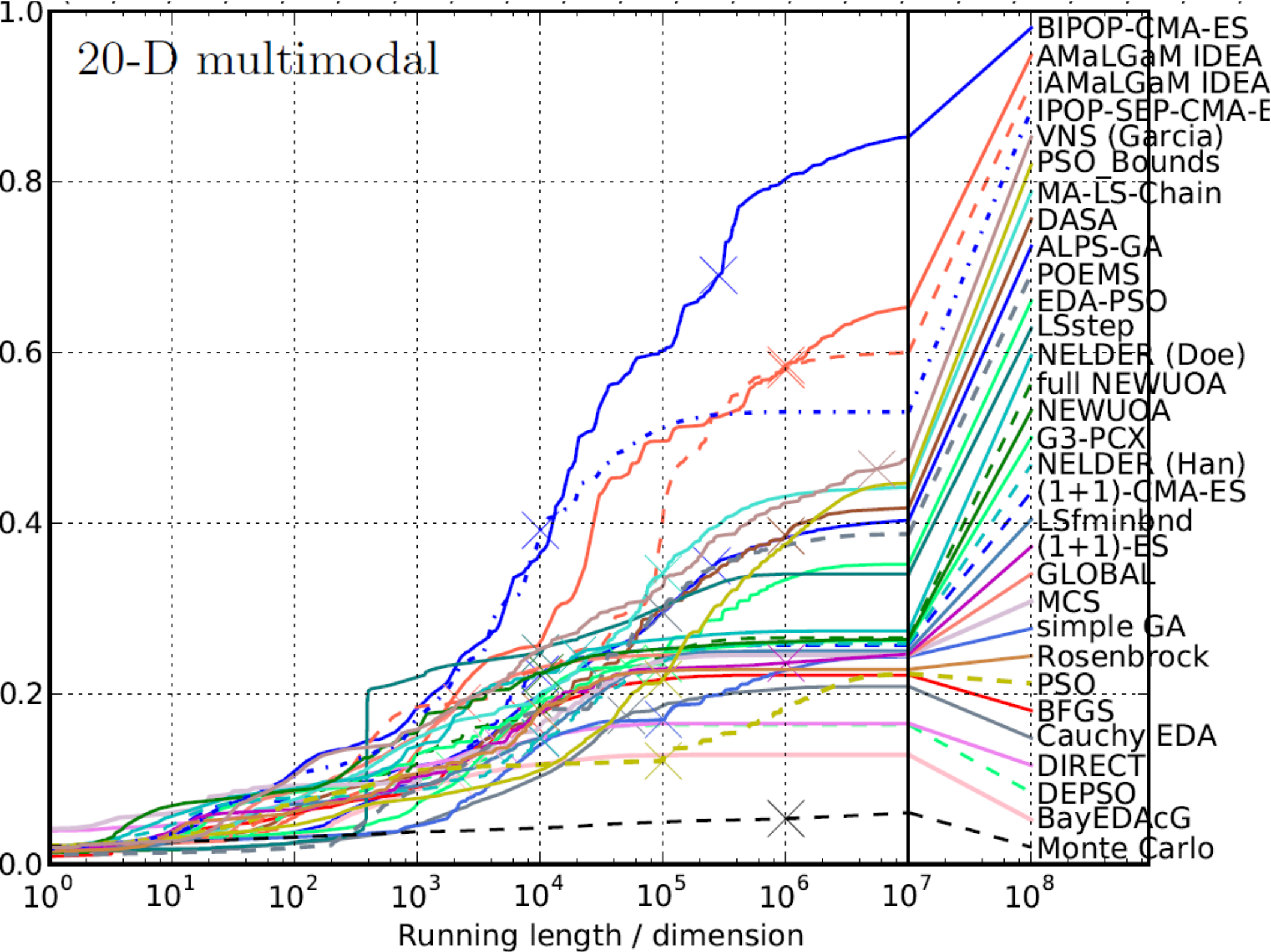


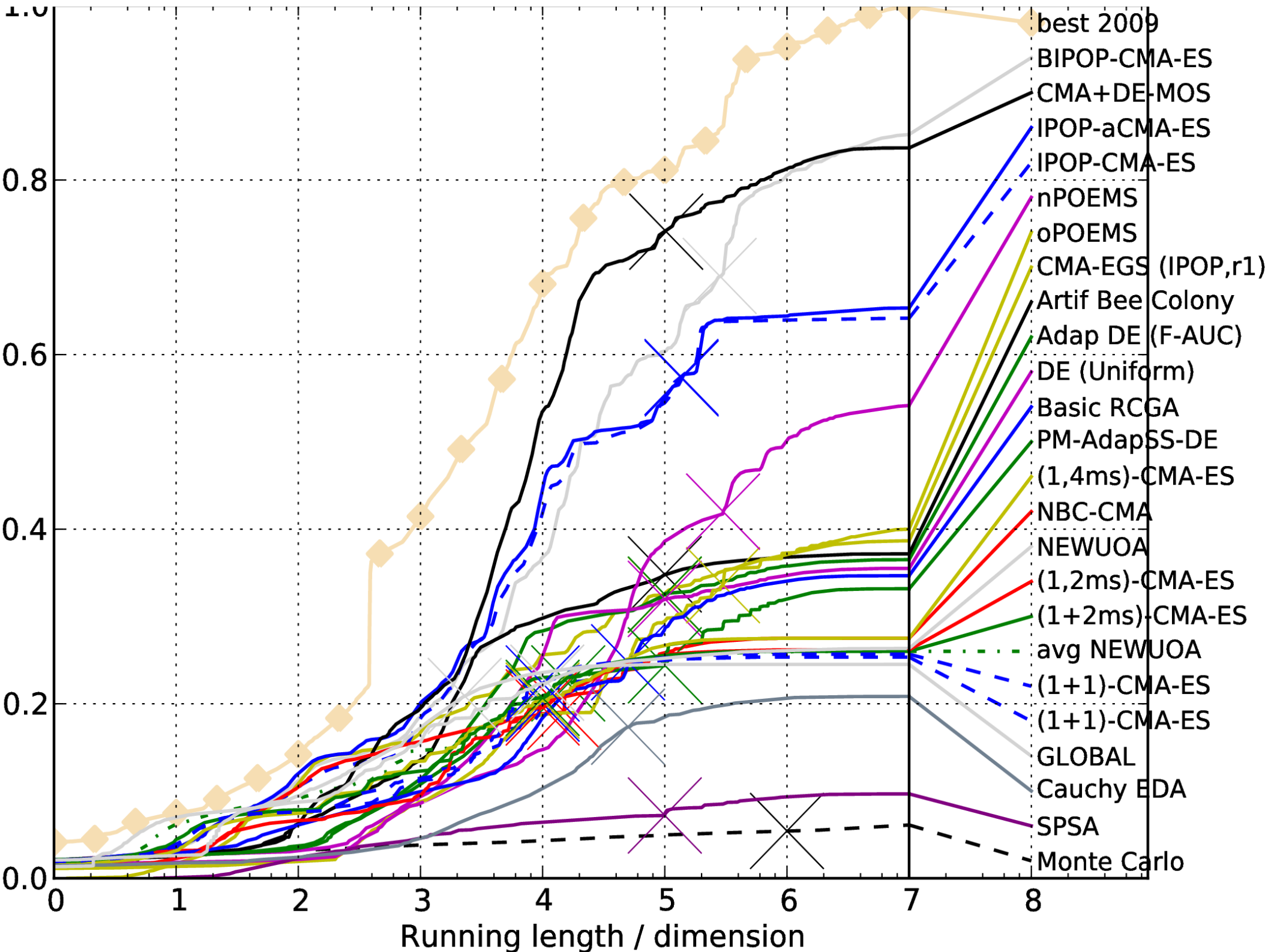






20-D multimodal





% SEPARABLE

- 1 Sphere
- 2 Ellipsoid separable with monotone x-transformation, condition 1e6
- 3 Rastrigin separable with both x-transformations "condition" 10
- 4 Skew Rastrigin-Bueche separable, "condition" 10, skew-"condition" 100
- 5 Linear slope, neutral extension outside the domain (not flat)

% LOW OR MODERATE CONDITION

- 6 Attractive sector function
- 7 Step-ellipsoid, condition 100
- 8 Rosenbrock, original
- 9 Rosenbrock, rotated

% HIGH CONDITION

- 10 Ellipsoid with monotone x-transformation, condition 1e6
- 11 Discus with monotone x-transformation, condition 1e6
- 12 Bent cigar with asymmetric x-transformation, condition 1e6
- 13 Sharp ridge, slope 1:100, condition 10
- 14 Sum of different powers

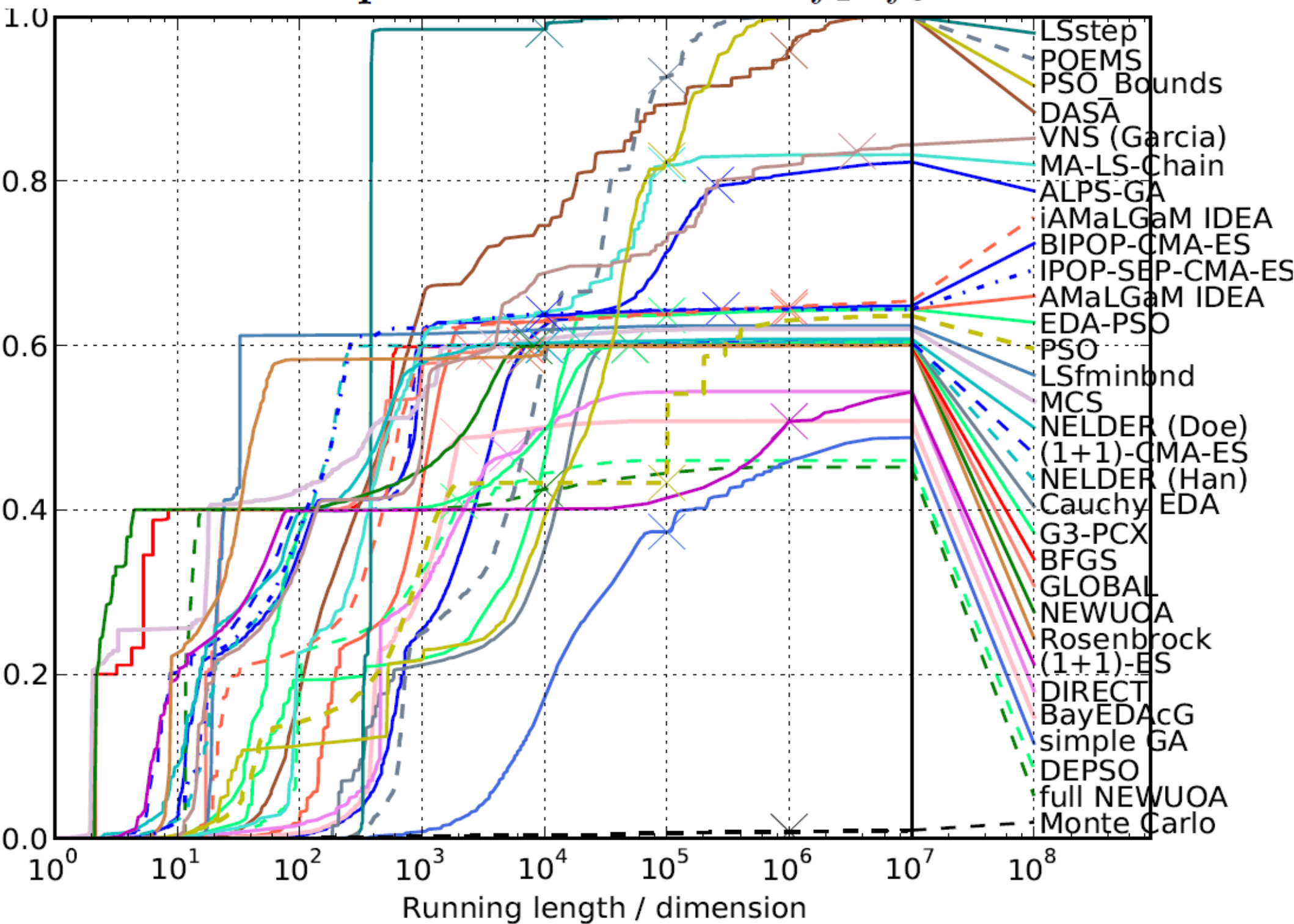
% MULTI-MODAL

- 15 Rastrigin with both x-transformations, condition 10
- 16 Weierstrass with monotone x-transformation, condition 100
- 17 Schaffer F7 with asymmetric x-transformation, condition 10
- 18 Schaffer F7 with asymmetric x-transformation, condition 1000
- 19 F8F2 composition of 2-D Griewank-Rosenbrock

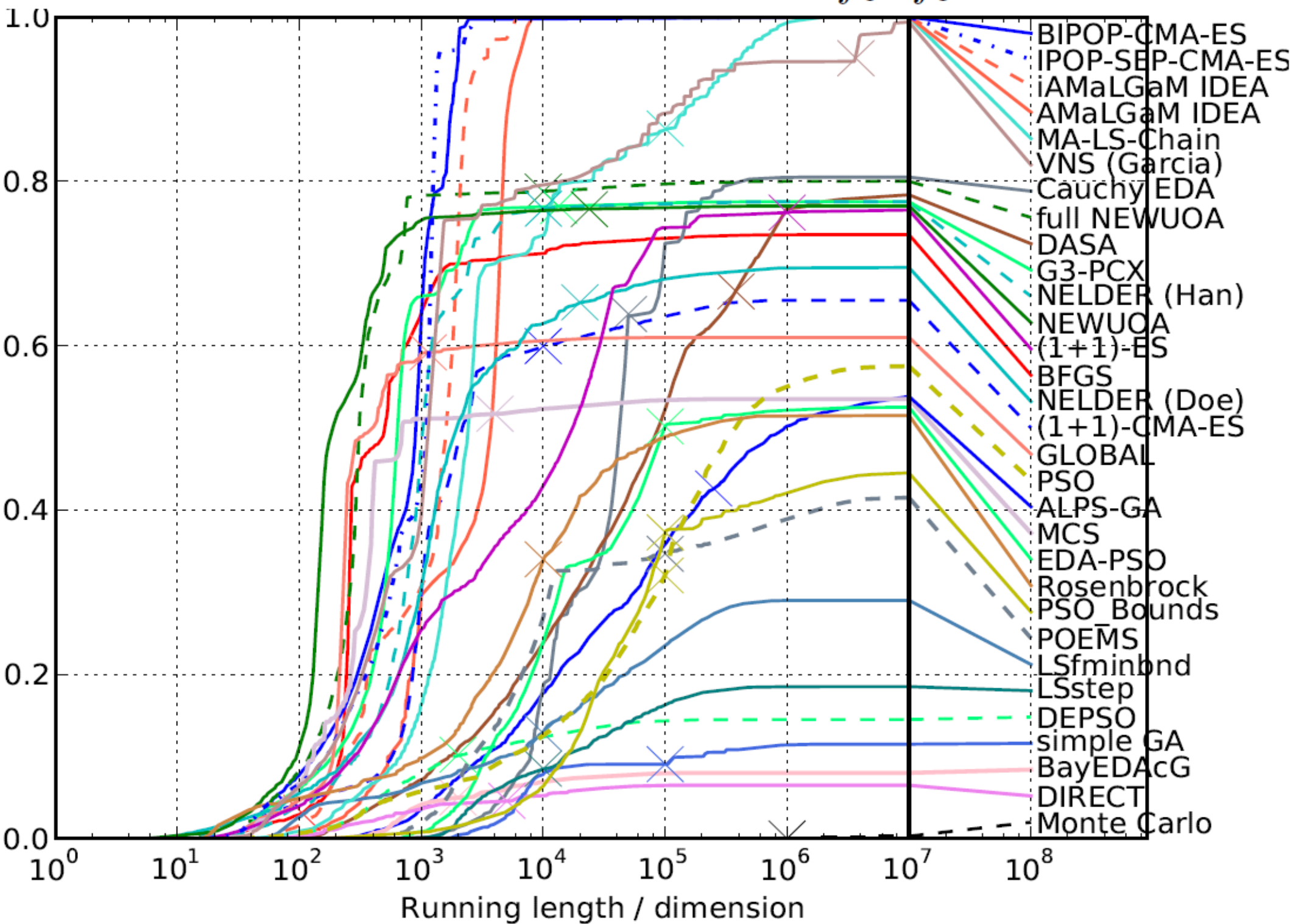
% MULTI-MODAL WITH WEAK GLOBAL STRUCTURE

- 20 Schwefel $x \cdot \sin(x)$ with tridiagonal transformation, condition 10
- 21 Gallagher 101 Gaussian peaks, condition up to 1000
- 22 Gallagher 21 Gaussian peaks, condition up to 1000, 1000 for global opt
- 23 Katsuuras repetitive rugged function
- 24 Lunacek bi-Rastrigin, condition 100

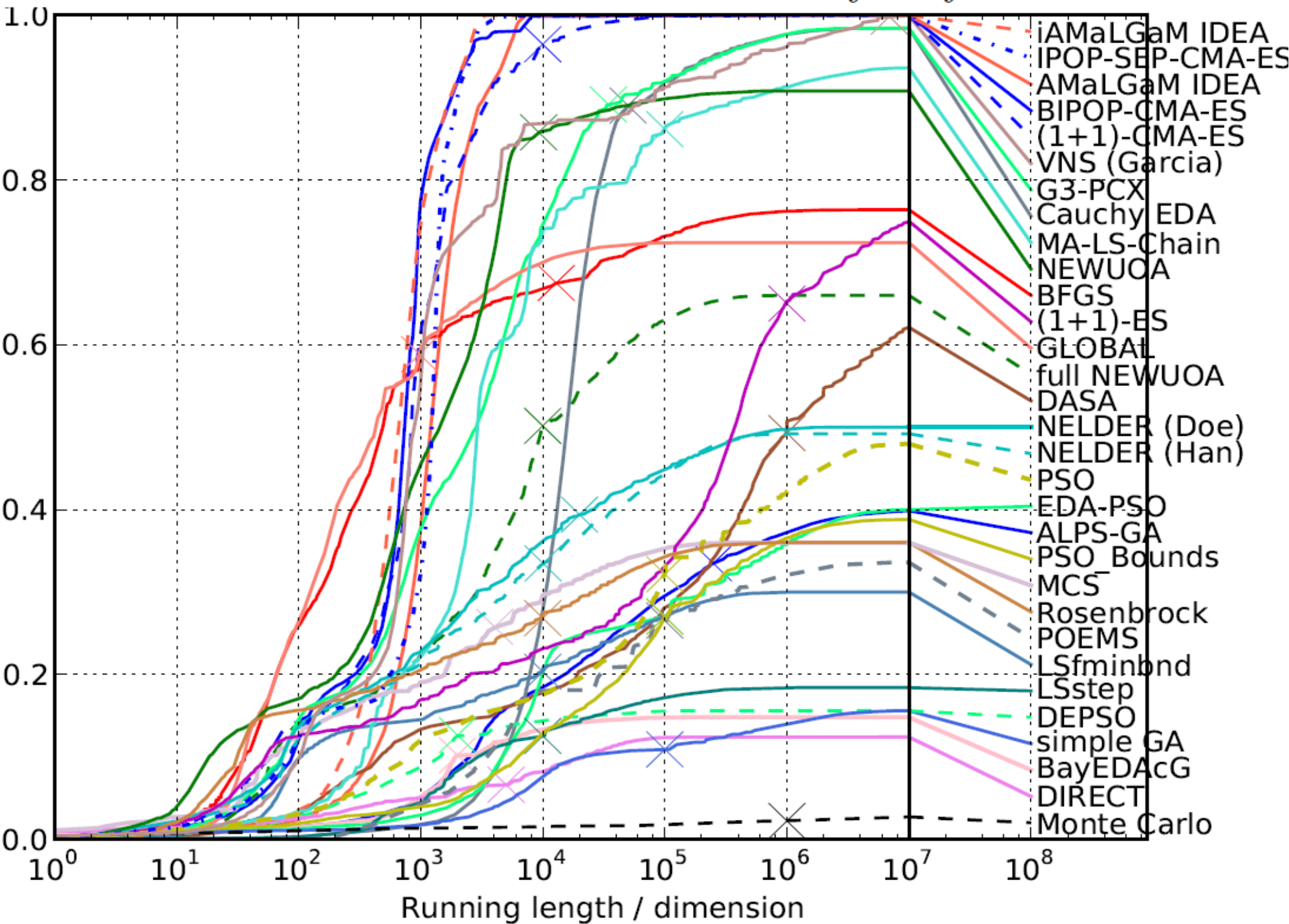
Separable functions f_1-f_5



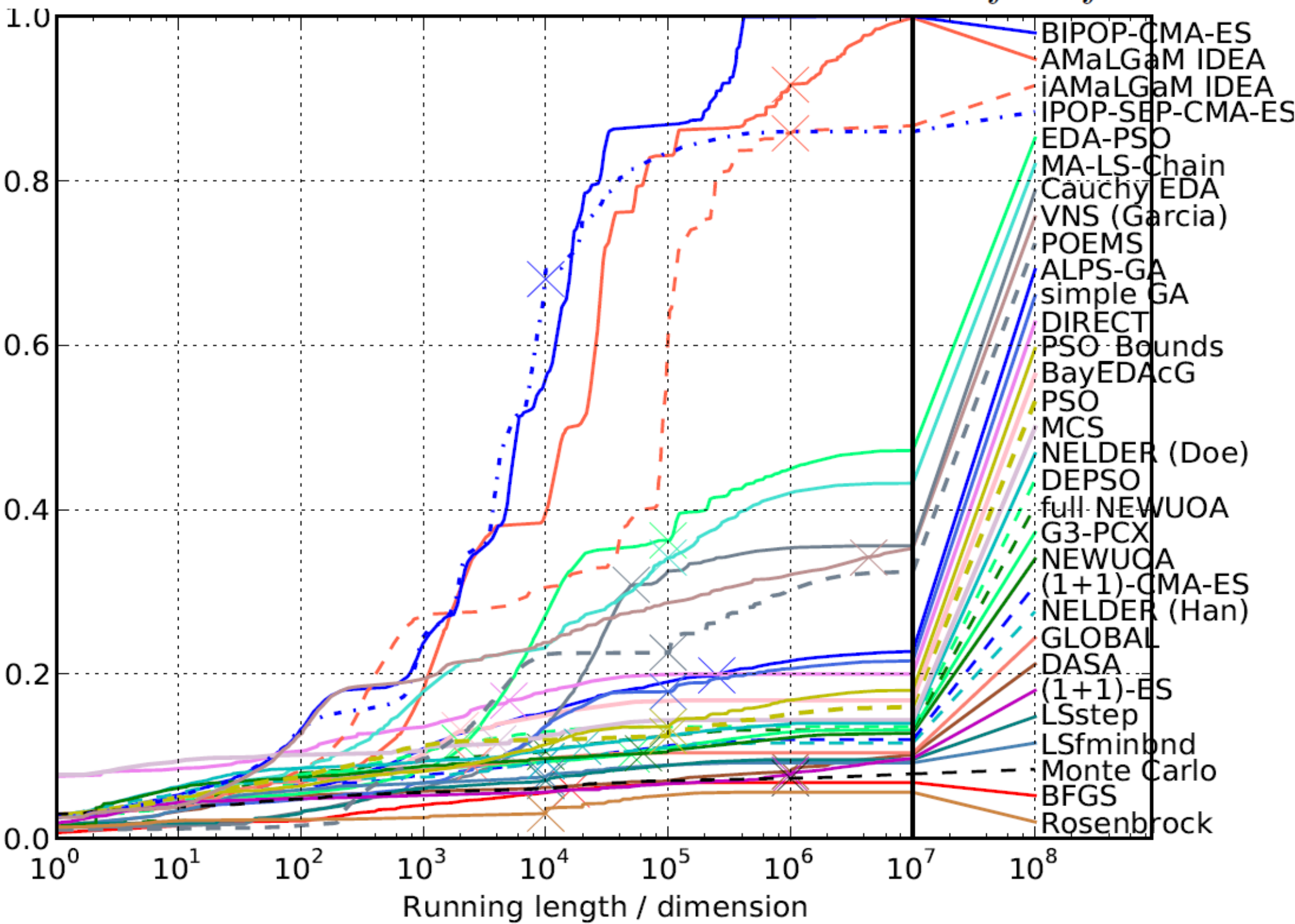
Moderate functions f_6-f_9

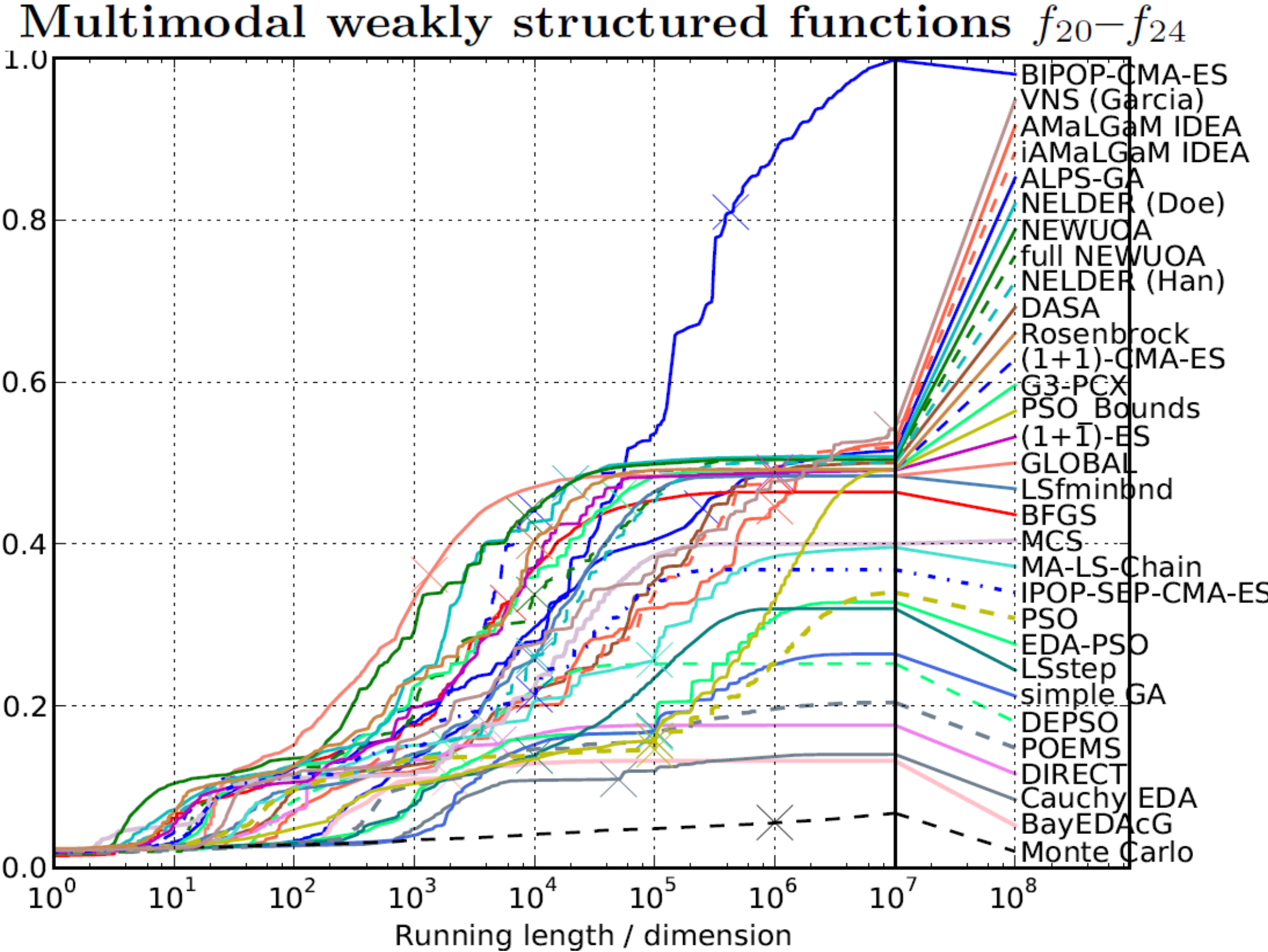


Ill-conditioned functions $f_{10}-f_{14}$

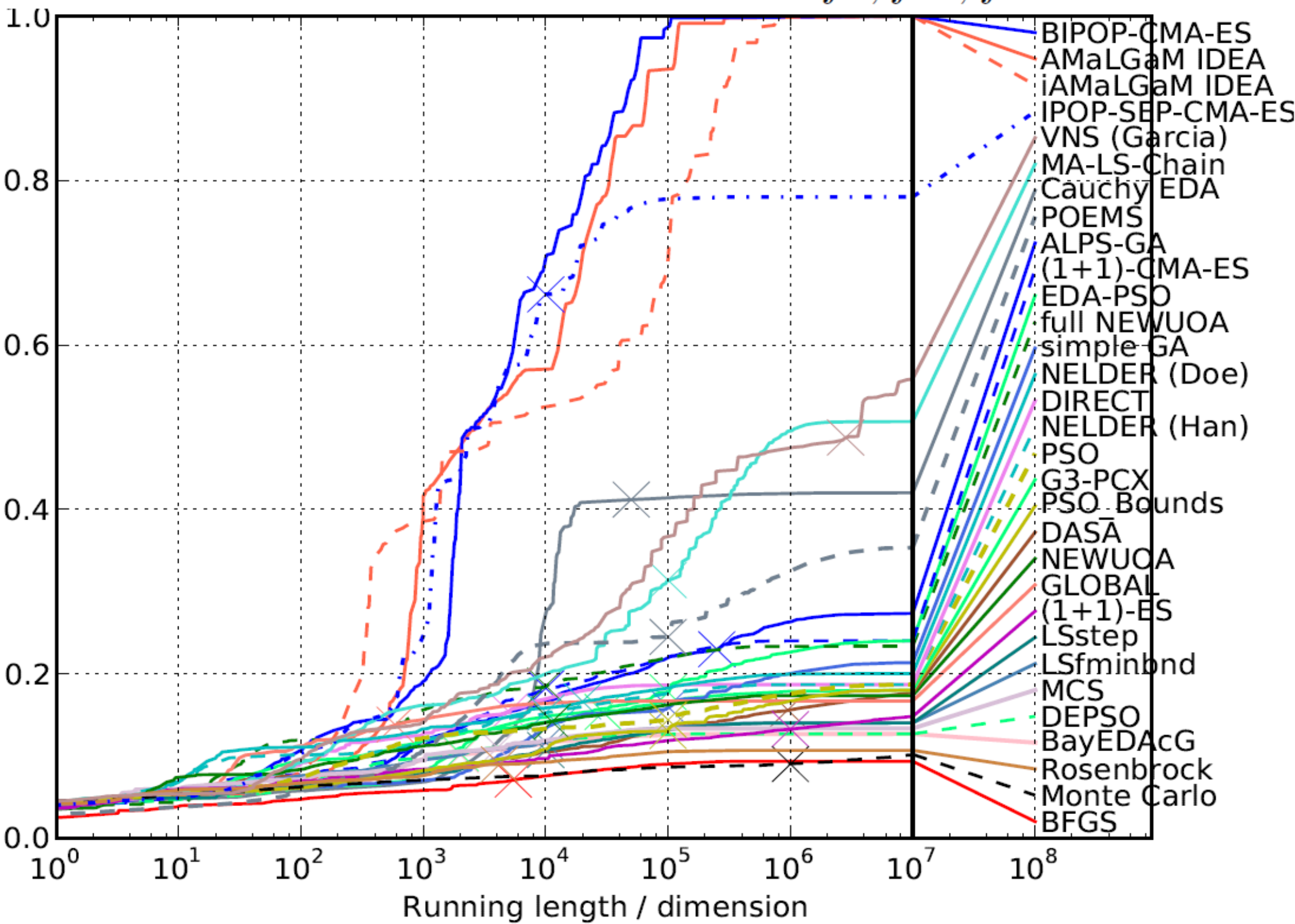


Multimodal structured functions $f_{15}-f_{19}$





Non-smooth functions f_7, f_{16}, f_{23}



Single Function Table

Table 6: 20-D, running time excess ERT/ERT_{best} on f_6 , in italics is given the median final function value and the median number of function evaluations to reach this value divided by dimension

	6 Attractive sector										
Δf_{target}	1e+03	1e+02	1e+01	1e+00	1e-01	1e-02	1e-03	1e-04	1e-05	1e-07	Δf_{target}
ERT _{best} /D	4.03	26	64.7	87.2	123	152	184	219	248	309	ERT _{best} /D
ALPS	59	25	34	54	64	78	100	150	370	<i>14e-7/2e5</i>	ALPS [17]
AMaLGaM IDEA	26	22	19	22	21	22	22	21	22	22	AMaLGaM IDEA [4]
avg NEWUOA	2.3	1.1	1	1	1	1	1	1	1	1	avg NEWUOA [31]
BayEDAcG	46	41	<i>60e+0/2e3</i>	BayEDAcG [10]
BFGS	2.2	2.7	3.6	4.7	4.7	4.9	5	4.8	4.9	61	BFGS [30]
Cauchy EDA	6200	1500	1e3	1700	<i>17e-1/5e4</i>	Cauchy EDA [24]
BIPOP-CMA-ES	2.9	2.2	1.5	1.7	1.6	1.6	1.6	1.5	1.6	1.6	BIPOP-CMA-ES [15]
(1+1)-CMA-ES	1.9	4.5	13	180	1200	<i>13e-1/1e4</i>	(1+1)-CMA-ES [2]
DASA	12	6.8	9.9	19	25	33	49	58	63	74	DASA [19]
DEPSO	11	7.5	12	64	<i>13e-1/2e3</i>	DEPSO [12]
DIRECT	18	31	<i>40e+0/5e3</i>	DIRECT [25]
EDA-PSO	27	46	40	45	44	44	44	44	44	44	EDA-PSO [6]
full NEWUOA	5	1.9	1.5	1.4	1.4	1.4	1.4	1.4	1.4	1.4	full NEWUOA [31]
G3-PCX	4.1	1.4	1.4	2	2.1	2.1	2.2	2.2	2.3	2.4	G3-PCX [26]
simple GA	320	130	2e3	<i>11e+0/1e5</i>	simple GA [22]
GLOBAL	5	2.9	3.6	4.9	8.5	<i>42e-3/2e3</i>	GLOBAL [23]
iAMaLGaM IDEA	5.1	5.6	5.4	6.8	7.1	7.7	7.8	7.7	8	8.3	iAMaLGaM IDEA [4]
LSfminbnd	9	31	160	760	1100	960	<i>72e-1/1e4</i>	.	.	.	LSfminbnd [28]
LSstep	140	260	2300	<i>59e+0/1e4</i>	LSstep [28]
MA-LS-Chain	11	4.9	7.5	8.9	8	7.7	7.2	6.7	6.5	6	MA-LS-Chain [21]
MCS (Neum)	1.8	33	<i>42e+0/4e3</i>	MCS (Neum) [18]
NELDER (Han)	2.2	2.4	2.7	3.3	3.2	3.5	3.5	3.5	4	7.4	NELDER (Han) [16]
NELDER (Doe)	1.5	2.3	9.1	20	28	65	110	430	<i>46e-5/2e4</i>	.	NELDER (Doe) [5]
NEWUOA	1	1	1	1.3	1.4	1.5	1.6	1.6	1.7	1.7	NEWUOA [31]
(1+1)-ES	2	2.2	2.1	2.8	3.9	5.2	6.1	6.5	6.4	6.7	(1+1)-ES [1]
POEMS	89	26	31	37	36	36	36	35	36	37	POEMS [20]
PSO	6.4	280	1100	1400	980	820	710	620	570	790	PSO [7]
PSO_Bounds	9.5	45	120	150	140	140	140	130	160	220	PSO_Bounds [8]
Monte Carlo	2.4e5	<i>48e+1/1e6</i>	Monte Carlo [3]
Rosenbrock	2.1	3.9	31	76	210	230	810	<i>21e-2/1e4</i>	.	.	Rosenbrock [27]
IPOP-SEP-CMA-ES	3.2	2.1	1.7	1.9	1.9	1.9	1.9	1.9	2	2	IPOP-SEP-CMA-ES [29]
VNS (Garcia)	5	2.8	1.9	1.9	1.7	1.7	1.7	1.6	1.6	1.6	VNS (Garcia) [11]

Overview of best algorithms (20-D)

Functions	short runtime	long runtime
separable	NEWUOA (BFGS), LS-fminbnd	LS-step
moderate	NEWUOA (BFGS, GLOBAL)	IPOP-aCMA-ES
ill-conditioned	(NEWUOA) BFGS, GLOBAL	IPOP-aCMA-ES
non-smooth (2009)	IDEA (CMA-ES)	CMA-ES, IDEA
multimodal	(MCS, DIRECT, CMA-ES, IDEA)	IPOP-CMA-ES (ID
weak structure	(NEWUOA) GLOBAL	(BIPOP-CMA-ES)
noisy	(MCS, CMA-ES)	IPOP-aCMA-ES

(more) questions?

Any intelligent fool can make things bigger, more complex, and more violent. It takes a touch of genius, and a lot of courage, to move in the opposite direction.

Albert Einstein