

Tools for hyperparameter tuning

Siminole meeting

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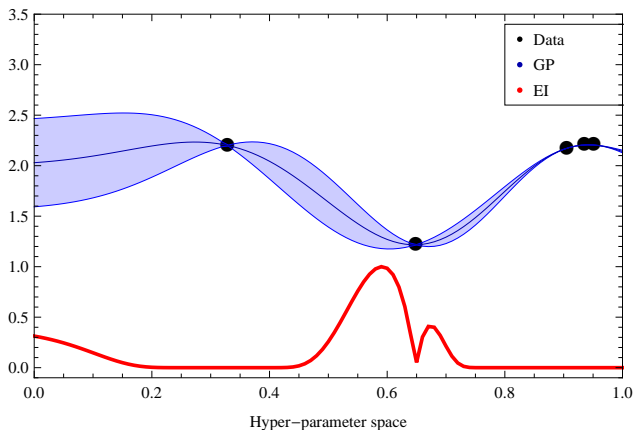
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SMBO(target f , model M_0 , Criterion S , T)

```
1    $\mathcal{H} \leftarrow \emptyset$ ,  
2   For  $t \leftarrow 1$  to  $T$ ,  
3        $x^* \leftarrow \operatorname{argmin}_x S(x, M_{t-1})$ ,  
4       Evaluate  $f(x^*)$ ,       $\triangleright$  Expensive step  
5        $\mathcal{H} \leftarrow \mathcal{H} \cup (x^*, f(x^*))$ ,  
6       Fit a new model  $M_t$  to  $\mathcal{H}$ .  
7   return  $\mathcal{H}$ 
```

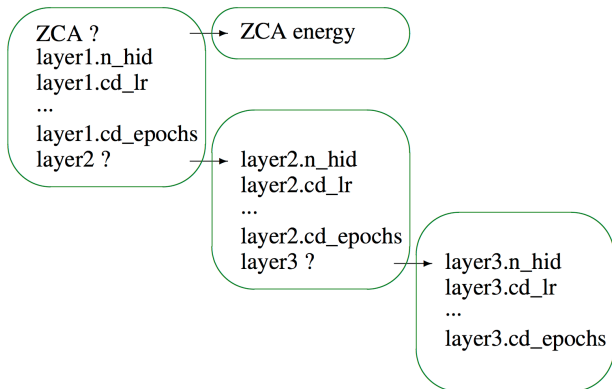
- ▶ Especially useful when target evaluation is costly.

Gaussian Processes and Expected Improvement



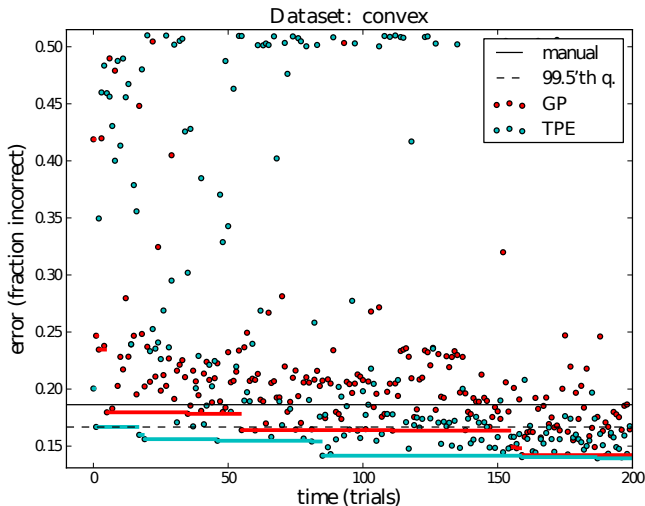
- ▶ GPs are priors over functions that are **closed under sampling**.
- ▶ $\text{EI}(x) := \mathbb{E}((\min_i f(x_i) - f(x)) \wedge 0 | \mathcal{F}_n)$.

- ▶ Deep Belief Nets have **lots of conditional hyperparameters**,



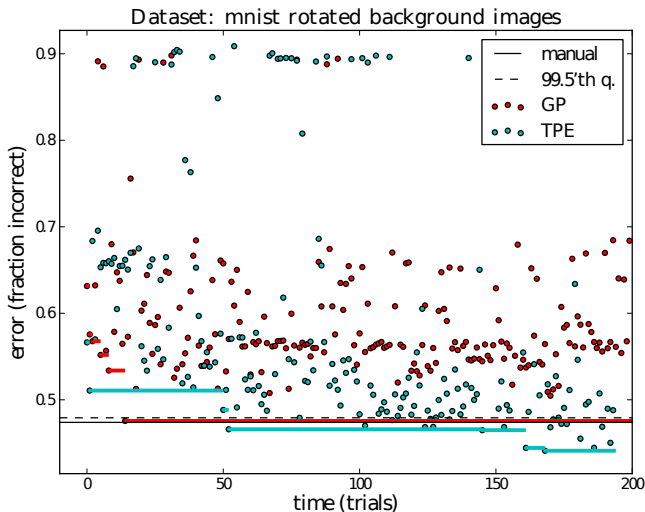
A recent application to hyperparameter tuning

- ▶ We used SMBO, using GPs+EI and a tree-based model+EI in Bergstra, Bardenet, Kégl and Bengio, NIPS'11.



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- ▶ Idea is to place a GP over an **augmented feature+hyperparameters space**.
- ▶ But error rates coming from different datasets are not comparable!
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Idea

- 1 Store the pairwise rankings given by the evaluation of your algorithm on single datasets.
- 2 Infer a **flat latent function** that preserves ranking:

$$u \prec v \Leftrightarrow \ell(u) < \ell(v).$$

- ▶ GPs need to be tuned.
- ▶ Usually, it's done by maximizing the marginal likelihood of the hyperparameters of the GP.
- ▶ This approach is irrelevant here, as one does **not even know the values** of the latent function.
- ▶ **Chu and Gharamani, NIPS'05** proposed an algorithm that takes as input the pairwise rankings and that **simultaneously**
 - estimate the ranking-preserving latent function,
 - and tune a GP placed over it.
- ▶ Very expensive. Replaced by SVMrank (**Joachims, '02**) on our preliminary experiments.

Thanks for your attention. Now, back to Matthias!