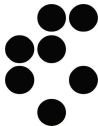


Including theoretical uncertainties in global (flavor) fits

Luiz Vale Silva

Jožef Stefan Inst.

May 15th, 2017



GDR "QCD": *Progresses in algorithms and numerical tools for QCD*
Orsay, France

Outline

- 1 Introduction
- 2 Extraction of V_{CKM} by CKMfitter
- 3 Treatment of theoretical uncertainties
- 4 Conclusions

Statistical and theoretical uncertainties

→ Statistical uncertainties result from the intrinsic variability of data, typically distributed normally

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→ Statistical uncertainties result from the intrinsic variability of data, typically distributed normally

→ Theoretical uncertainties are different in nature: they are modeling parameters (ξ), fixed and unknown, that incorporate our incomplete knowledge about the properties of a distribution [Punzi '01]
(Ex.: truncation of a perturbative series)

Statistical and theoretical uncertainties

→ Though *a priori* theoretical uncertainties are a universal issue, in the context of quark **flavor physics** they are particularly important, due to the **strong dynamics**

(Cf., e.g., EW global fit extraction of $\{M_Z, \alpha_s(M_Z), \dots\}$: statistical uncertainties dominate)

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(Cf., e.g., EW global fit extraction of $\{M_Z, \alpha_s(M_Z), \dots\}$: statistical uncertainties dominate)

→ **Here**: discuss theoretical uncertainties, more specifically in the context of quark **flavor physics**

J. Charles, S. Descotes-G., V. Niess, LVS
Eur.Phys.J. C77 (2017), 214
[hep-ph/1611.04768]

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CKMfitter and required inputs

→ **CKMfitter**: global fit package

▶ CKMfitter

Web interface version (comments are welcomed!)

▶ CKMlive

- Examples of classes of processes that require non-perturbative theoretical inputs:

Meson-mixing	$B_{(s)} \bar{B}_{(s)}$, $K \bar{K}$: bag-parameters \hat{B}_{B_s} , $\hat{B}_{B_s} / \hat{B}_{B_d}$, \hat{B}_K
(semi-)leptonic decays	$\pi \rightarrow l\nu$, $K \rightarrow \pi l\nu$, etc.: decay constants, form factors Ex.: f_π , $f_+^{K \rightarrow \pi}(0)$

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- Nowadays, extraction of non-pert. parameters: Lattice QCD
- Dominance of **systematic uncertainties**
(continuum extrapolation, finite volume, mass inter/extrapolations, etc.)

Statistical approach

- **CKMfitter**: Frequentist statistic based on a χ^2 analysis
- χ^2_{min} : **goodness-of-fit** under SM or NP, **estimators** for V_{CKM}
- $\Delta\chi^2$ (χ^2 -distributed): **Confidence Level** (CL) intervals
- *Range fit* (Rfit) scheme incorporates theoretical uncertainties

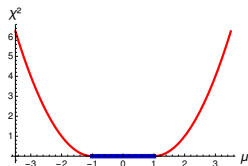
$$\mathcal{L}^{Rfit} = \mathcal{L}_{stat} \times \mathcal{L}_{theo}, \quad \chi^2 = -2 \ln \mathcal{L}$$

\mathcal{L}_{stat} : agreement of data & prediction

\mathcal{L}_{theo} : accuracy of QCD parameters
theo. uncertainties strictly contained
in a range. Ex.: $\xi \in [-\Delta, \Delta]$

Example in 1D,

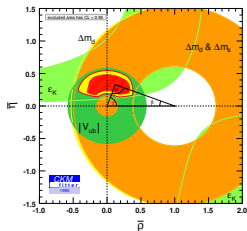
$$0 \pm 1_{stat} \pm 1_{theo}$$



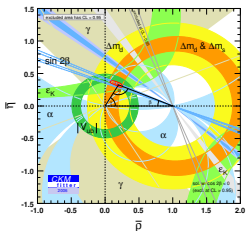
flat bottom, quadratic walls

Extraction of the CKM matrix elements

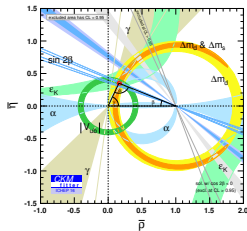
→ Better theoretical control (Lattice QCD), and more accurate data (LEP, KTeV, NA48, BaBar, Belle, CDF, DØ, LHCb, CMS, ...)



1995



2006



2016

→ **Question:** is there a more appropriate statistical approach than Rfit to incorporate theoretical uncertainties, given the present and expected progresses?

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Basic concepts in *frequentist* statistic

Gaussian case, without theoretical uncertainty

→ Consider an apparatus designed to measure the true value “ x_t ” of an observable (the one that is actually realized in nature)

$$g(X; x_t) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left[-\frac{(X-x_t)^2}{2\sigma^2}\right] \quad \text{Ex.: LEP} \quad \Rightarrow \quad \hat{M}_Z^{(1)}, \dots, \hat{M}_Z^{(N)}$$

→ Test statistic T : arbitrary as long as small values attest the agreement between the data and the predicted value(s)

(under a certain hypothesis, $\mathcal{H}_\mu : x_t = \mu$)

$$\text{Ex.: } \mu = M_Z^{SM}$$

→ Maximum Likelihood Ratio (**MLR**):

[Neyman, Pearson]

$$T(\vec{X}_0; \mu) = \sum_{i=1}^N \frac{(X_0^{(i)} - \mu)^2}{\sigma^2}$$

→ From the distribution of the i.i.d. random variable X , we determine the distribution of the test statistic, seen as a function of X

Example: $T(X; \mu) \sim \chi^2(N)$ for each μ

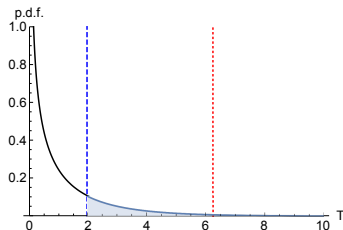
Basic concepts in *frequentist* statistic

→ Given the real data X_0 from a *single* experiment, the probability of measuring a new value of the test statistic in worsen agreement is called the p -value

$$p(X_0; \mu) = \mathcal{P}[T \geq T(X_0; \mu)]$$

$$p(X_0; \mu) \simeq 0.32 \stackrel{1D}{\leftrightarrow} T(X_0; \mu) = 1 \equiv (1\sigma)^2,$$

$$p(X_0; \mu) \simeq 0.05 \stackrel{1D}{\leftrightarrow} T(X_0; \mu) = 4 \equiv (2\sigma)^2,$$

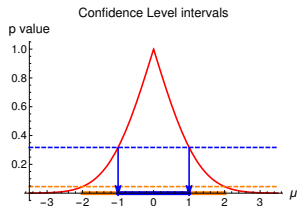
$$\vdots$$


In formulas:

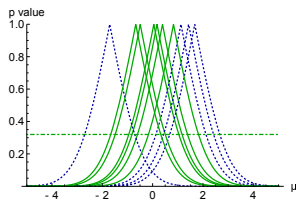
$$h(T|\mathcal{H}_\mu) = \int dX \delta[T - T(X; \mu)] g(X; \mu)$$

$$\mathcal{P}[T < T(X_0; \mu)] = \int_0^{T(X_0; \mu)} dT h(T|\mathcal{H}_\mu)$$

Basic concepts in *frequentist* statistic



Ex.: $x_t = 0$, $\sigma = 1$,
w/ $\{X_0^{(1)}, \dots, X_0^{(10)}\}$



→ Interpretation of $\alpha\%$ CL intervals:
asymptotically, a fraction $\alpha\%$ of the CLs
include the true value x_t

→ A p -value that respects this property
(called coverage) is said to be exact

- CLs $\ni x_t$ in $\alpha\%$ times: *exact*
- ... in $> \alpha\%$ times: *conservative*
- ... in $< \alpha\%$ times: *aggressive*

Modeling theoretical uncertainties

Given the one-dimensional (1D) case: $X \sim X_0 \pm \underbrace{\sigma}_{\text{statistical}} \pm \underbrace{\Delta}_{\text{theoretical}}$

- The true value of the theo. uncertainty ξ is fixed and unknown
- Being unknown, one quotes a range $\xi \in \Omega$ and **vary** ξ
- Usually, one has in mind that $\Omega = [-\Delta, \Delta]$, but this may miss an unexpectedly large value of ξ
- Were ξ known, we would quote instead $(X_0 + \xi) \pm \sigma$

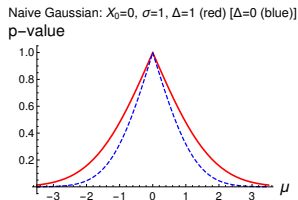
Modeling theoretical uncertainties: random

Random approach

→ Different techniques of calculation lead to different predictions around the exact one (pseudo-randomly distributed)

→ Naive Gaussian (nG): $\xi \sim \mathcal{N}(0, \Delta)$

→ MLR ($\mathcal{H}_\mu : x_t = \mu$): $T(X; \mu) = \frac{(X - \mu)^2}{\sigma^2 + \Delta^2}$



Modeling theoretical uncertainties: external

n -external approach

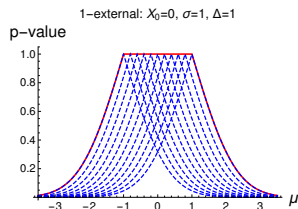
[Scan: Dubois-Felsmann et al.]

→ In a first step, assume that ξ is known

→ Family of hypotheses, $\mathcal{H}_\mu^{(\xi)} : x_t = \mu + \xi$

→ MLR ($\mathcal{H}_\mu^{(\xi)}$): $T(X; \mu) = \frac{(X - \mu - \xi)^2}{\sigma^2}$

→ Combine the p_ξ , for $\xi \in n \times [-\Delta, \Delta]$



Close to what some experiments interpret as theo. uncertainties

Simple 1D case: **Rfit** and **1-external** are equivalent

Modeling theoretical uncertainties: nuisance

$$\text{MLR: } T(X_0; \mu) = -2 \ln \underbrace{\frac{\mathcal{L}_{X_0}(\mu)}{\max_{\mu} \mathcal{L}_{X_0}(\mu)}}_{\text{Simple hypothesis}} \rightarrow -2 \ln \underbrace{\frac{\max_{\xi} \mathcal{L}_{X_0}(\mu, \xi)}{\max_{\mu, \xi} \mathcal{L}_{X_0}(\mu, \xi)}}_{\text{Composite hypothesis}}$$

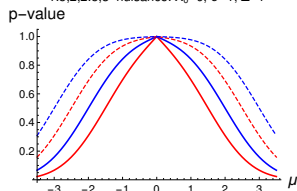
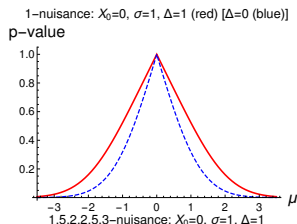
Fixed- n nuisance

$$\rightarrow \sim \text{MLR } (\mathcal{H}_{\mu} : x_t = \mu): T(X; \mu) = \frac{(X - \mu)^2}{\sigma^2 + \Delta^2}$$

$\rightarrow \xi$ strictly found in $n \times [-\Delta, \Delta]$

\rightarrow **Small** n may lead to reasonable CLs, but possibly uncovering

\rightarrow **Large** n avoid uncovering, but lead to large CLs



Modeling theoretical uncertainties: nuisance

Adaptive nuisance

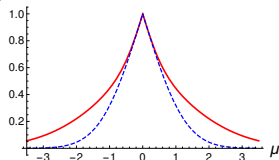
[Charles, Descotes-G., Niess, LVS]

→ \sim MLR ($\mathcal{H}_\mu : x_t = \mu$): $T(X; \mu) = \frac{(X - \mu)^2}{\sigma^2 + \Delta^2}$

→ The interval where we look for ξ grows w/ the CL interval we want to quote

→ n CL intervals: $\xi \in n \times [-\Delta, \Delta]$

Adapt. nuisance: $X_0=0, \sigma=1, \Delta=1$ (red) [$\Delta=0$ (blue)]
p-value



Designed to deal with:

- Metrology/extraction of parameters ($1 - 2 \sigma$ intervals)
- Minimizing Type-II (false positive) errors (above $\sim 5 \sigma$)

adapt. nuisance for a significance $n \equiv n$ -fixed nuisance

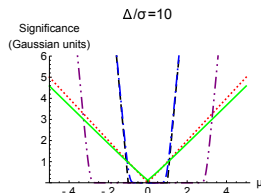
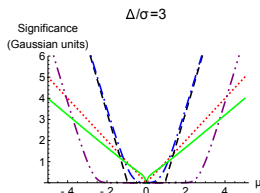
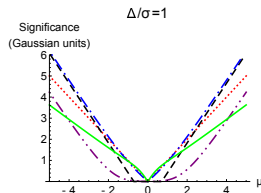
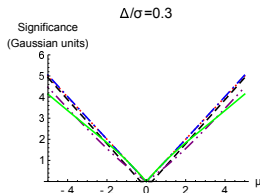
Incorporating theoretical uncertainties

Approaches for dealing with theoretical uncertainties (some guiding principles for choosing a scheme):

- Good coverage properties (at least for the CL significances we are interested in)
- *Useful* metrology: reasonable size of CL intervals
- Propagation of uncertainties: clear separation of statistical and theoretical uncertainties

Illustration of confidence level intervals, 1D

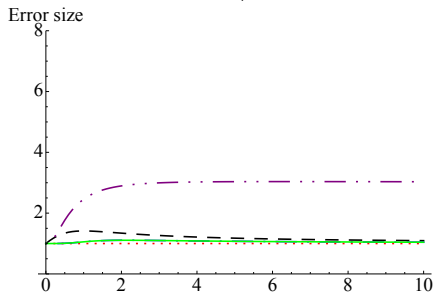
- Consider $0 \pm \sigma \pm \Delta$, w/ fixed $\sigma^2 + \Delta^2 = 1$
- Gaussian units: $\sqrt{2} \operatorname{Erf}^{-1}(1 - p(X_0; \mu))$



(red) naive Gaussian (nG); (black) fixed-1 external/Rfit; (blue) fixed-1 nuisance;
 (purple) fixed-3 nuisance; (green) adaptive nuisance

Illustration of confidence level intervals, 1D

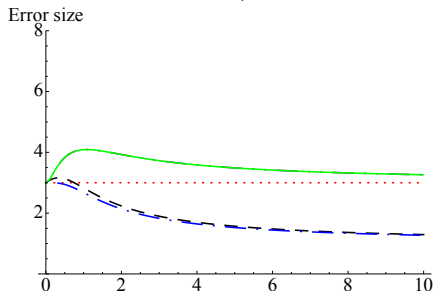
CL interval size vs. Δ/σ ; 1σ significance



(red) naive Gaussian (nG); (black) fixed-1 external/ R_{fit} $\xi \in [-\Delta, \Delta]$;
 (blue) fixed-1 nuisance $\xi \in [-\Delta, \Delta]$; (purple) fixed-3 nuisance $\xi \in 3[-\Delta, \Delta]$;
 (green) adaptive nuisance

Illustration of confidence level intervals, 1D

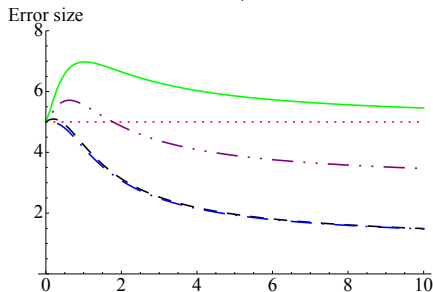
CL interval size vs. Δ/σ ; 3σ significance



(red) naive Gaussian (nG); (black) fixed-1 external/ R_{fit} $\xi \in [-\Delta, \Delta]$;
 (blue) fixed-1 nuisance $\xi \in [-\Delta, \Delta]$; (purple) fixed-3 nuisance $\xi \in 3[-\Delta, \Delta]$;
 (green) adaptive nuisance

Illustration of confidence level intervals, 1D

CL interval size vs. Δ/σ ; 5σ significance



(red) naive Gaussian (nG); (black) fixed-1 external/ R_{fit} $\xi \in [-\Delta, \Delta]$;
 (blue) fixed-1 nuisance $\xi \in [-\Delta, \Delta]$; (purple) fixed-3 nuisance $\xi \in 3[-\Delta, \Delta]$;
 (green) adaptive nuisance

Frequency of coverage of x_t

Limit case: the simulated ξ is at the edge of $[-\Delta, \Delta]$

$\Delta/\sigma = 3, \xi/\Delta = 1$	68.27% CL	95.45% CL	99.73% CL
nG	56.3%	100.0%	100.0%
1-nuisance	68.1%	95.5%	99.7%
adaptive nuisance	68.2%	100.0%	100.0%
1-external/ <i>R</i> fit	84.1%	97.7%	99.9%

Unfortunate case: the simulated ξ is outside $[-\Delta, \Delta]$

$\Delta/\sigma = 3, \xi/\Delta = 3$	68.27% CL	95.45% CL	99.73% CL
nG	0.00%	0.35%	68.7%
1-nuisance	0.00%	0.00%	0.07%
adaptive nuisance	0.00%	9.60%	99.8%
1-external/ <i>R</i> fit	0.00%	0.00%	0.13%

Multi-dimensional case

$$X_0^{(i)} \pm \sigma_i \pm \Delta_i, \xi_i \in [-\Delta_i, \Delta_i] \quad (\text{or } X_0 \pm \sigma \pm \Delta_1 \pm \dots \pm \Delta_N)$$

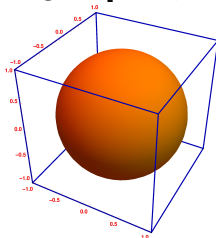
$$\text{Average: } \xi = \sum_{i=1}^N w_i \xi_i, \text{ w/ weights } \sum_{i=1}^N w_i = 1, w_i \geq 0$$

Interval where the bias ξ_i is varied

Hyper-cube: assuming extreme values simultaneously $\hat{\Delta} = \sum_{i=1}^N w_i \Delta_i$

Hyper-ball: $\hat{\Delta} = \sqrt{\sum_{i=1}^N (w_i \Delta_i)^2}$

Edges: $[-\Delta_i, \Delta_i]$

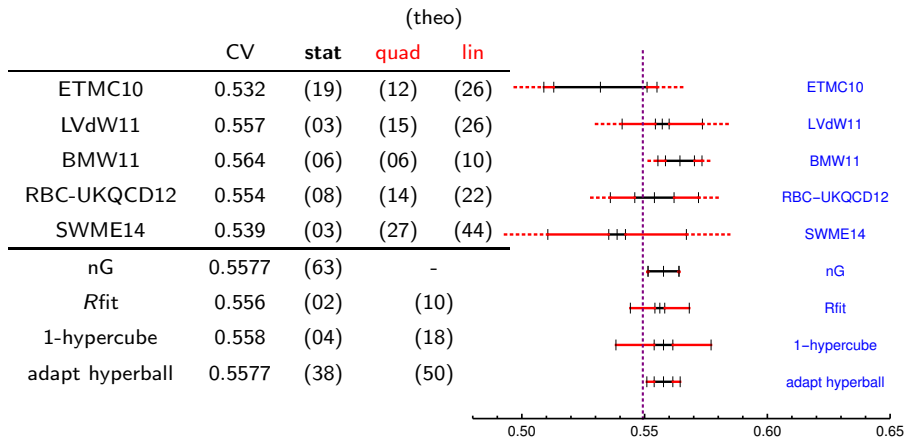


$$\Rightarrow \hat{X}_0 \pm \hat{\sigma} \pm \hat{\Delta}$$

Further issue: “correlated” theoretical uncertainties lead to *deformed hyper-cubes* and *hyper-ellipsoids* (Ex.: 100 % \Rightarrow single ξ)

Combining data

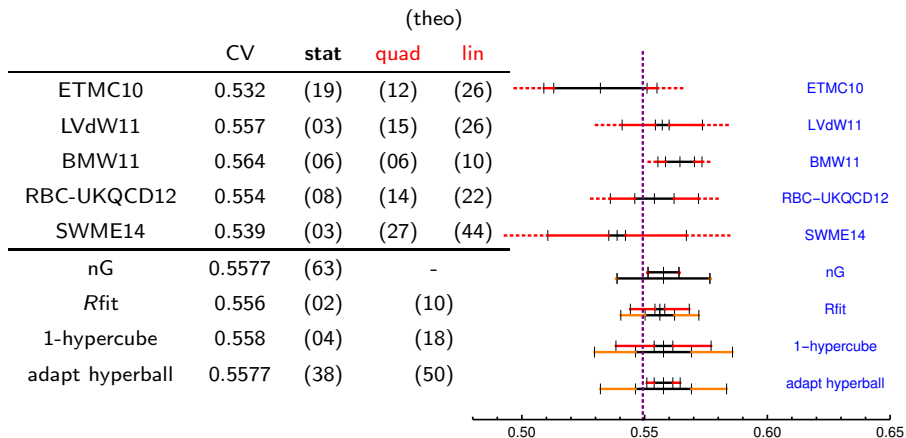
Example: combination of different extractions of $B_K^{\overline{MS}}(2 \text{ GeV})$



(red edges: 1σ ; purple: “naive” average of the CVs)

Combining data

Example: combination of different extractions of $B_K^{\overline{MS}}(2 \text{ GeV})$

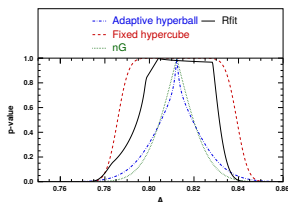


(orange edges: 3σ ; purple: “naive” average of the CVs)

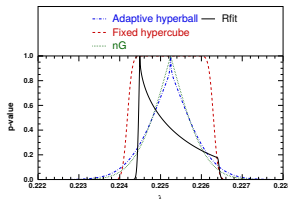
Illustrative global fit extraction of $A, \lambda, \bar{\rho}, \bar{\eta}$

$$\underbrace{|V_{ud}|, |V_{ub}|, |V_{cb}|, \Delta m_d, \Delta m_s}_{\text{theo. dominated}}, \underbrace{\alpha, \sin(2\beta), \gamma}_{\text{stat. dominated}}$$

[Inputs & details: Charles et al. '16]



A		1σ	3σ
Method			
nG		0.812 ± 0.011	0.812 ± 0.033
Rfit		$0.804^{+0.029}_{-0.014}$	$0.804^{+0.038}_{-0.030}$
1-hypercube		0.812 ± 0.029	0.812 ± 0.038
adapt. hyperball		0.812 ± 0.012	0.812 ± 0.042

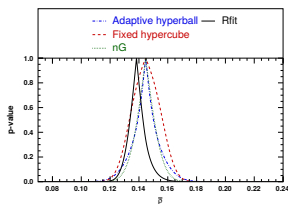


λ		1σ	3σ
Method			
nG		0.2252 ± 0.0007	0.2252 ± 0.0020
Rfit		$0.2245^{+0.0011}_{-0.0001}$	$0.2245^{+0.0020}_{-0.0001}$
1-hypercube		0.2252 ± 0.0011	0.2252 ± 0.0013
adapt. hyperball		0.22525 ± 0.00070	0.2252 ± 0.0022

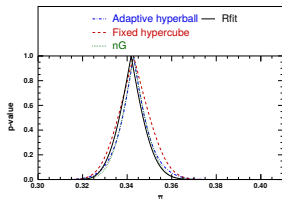
Illustrative global fit extraction of $A, \lambda, \bar{\rho}, \bar{\eta}$

$$\underbrace{|V_{ud}|, |V_{ub}|, |V_{cb}|, \Delta m_d, \Delta m_s}_{\text{theo. dominated}}, \underbrace{\alpha, \sin(2\beta), \gamma}_{\text{stat. dominated}}$$

[Inputs & details: Charles et al. '16]



Method	1σ	3σ
nG	0.145 ± 0.009	0.145 ± 0.027
Rfit	0.138 ± 0.007	$0.138^{+0.028}_{-0.020}$
1-hypercube	0.145 ± 0.015	0.145 ± 0.031
adapt. hyperball	0.145 ± 0.009	0.145 ± 0.036



Method	1σ	3σ
nG	0.343 ± 0.008	0.343 ± 0.023
Rfit	0.342 ± 0.008	$0.342^{+0.024}_{-0.022}$
1-hypercube	0.343 ± 0.011	0.343 ± 0.027
adapt. hyperball	0.343 ± 0.008	0.343 ± 0.028

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Conclusions

- Theoretical uncertainties are omnipresent in flavor analyses and deserve a careful look
- Reported progresses in the modeling of theoretical uncertainties, introducing the adaptive nuisance approach
- The choice of the scheme has an impact on:
 - confidence level intervals,
 - metrology,
 - significance of a tension, etc.

CKMfitter: adaptive nuisance, candidate for further investigation (coverage properties, clear separation of stat. and theo. uncertainties)

Merci !

CKMfitter collaboration

Jérôme Charles	Theory	CPT Marseille (France)
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Sébastien Descotes-Genon	Theory	LPT Orsay (France)
Heiko Lacker	ATLAS/BABAR	Humboldt-Universität Berlin (Germany)
Stéphane Monteil	LHCb	LPC Clermont-Ferrand (France)
José Ocariz	ATLAS/BABAR	LPNHE Paris (France)
Jean Orloff	Theory	LPC Clermont-Ferrand (France)
Alejandro Perez	BABAR	IPHC Strasbourg (France)
Luis Pesantez	Belle/Belle II	Melbourne University (Australia)
Wenbin Qian	LHCb	Warwick University (UK)
Vincent Tisserand	LHCb/BABAR	LAPP Annecy-Le-Vieux (France)
Karim Trabelsi	Belle/Belle II	KEK Tsukuba (Japan)
Philip Urquijo	Belle/Belle II	Melbourne University (Australia)
Luiz Vale Silva	Theory	IJS Ljubljana (Slovenia)

Different significances

$$(a_{muon}^{exp} - a_{muon}^{SM}) \times 10^{11} = 288 \pm 63_{exp} \pm 49_{SM}$$

significance of the tension

nG	3.6σ
1-external/Rfit	3.8σ
1-nuisance	3.9σ
adapt. nuisance	2.7σ

CKMfitter as a numerical tool

Package and computational resources:

- Modular structure: set of files representing different observables \mathcal{O} in a given model (SM or specific NP) in terms of CKM matrix elements, QCD inputs, etc.;
+ experimental data files, etc.
- \mathcal{O} may have a non-linear dependence on the parameters we want to extract; the numerical step (extremization, etc.) is facilitated by calculating the symbolic expressions for the derivatives
- Both steps may be computationally very demanding and may require the use of a cluster (while simple fits can easily be done in a terminal)

▶ CKMlive

- Run dedicated CKM fits from **CKMfitter** package through a web interface
- Global fit (in the SM scenario at this moment) for the extraction of V_{CKM}
- Given set of observables in terms of a given set of parameters
- User chooses the set of observables, and the values of the theoretical and experimental inputs, plus fitting parameters