The High Energy Physics Tracking Machine Learning challenge

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CDS pitching day 8th Nov 2017

LHC purpose in a nutshell

Collision de protons

$E=mc^2$

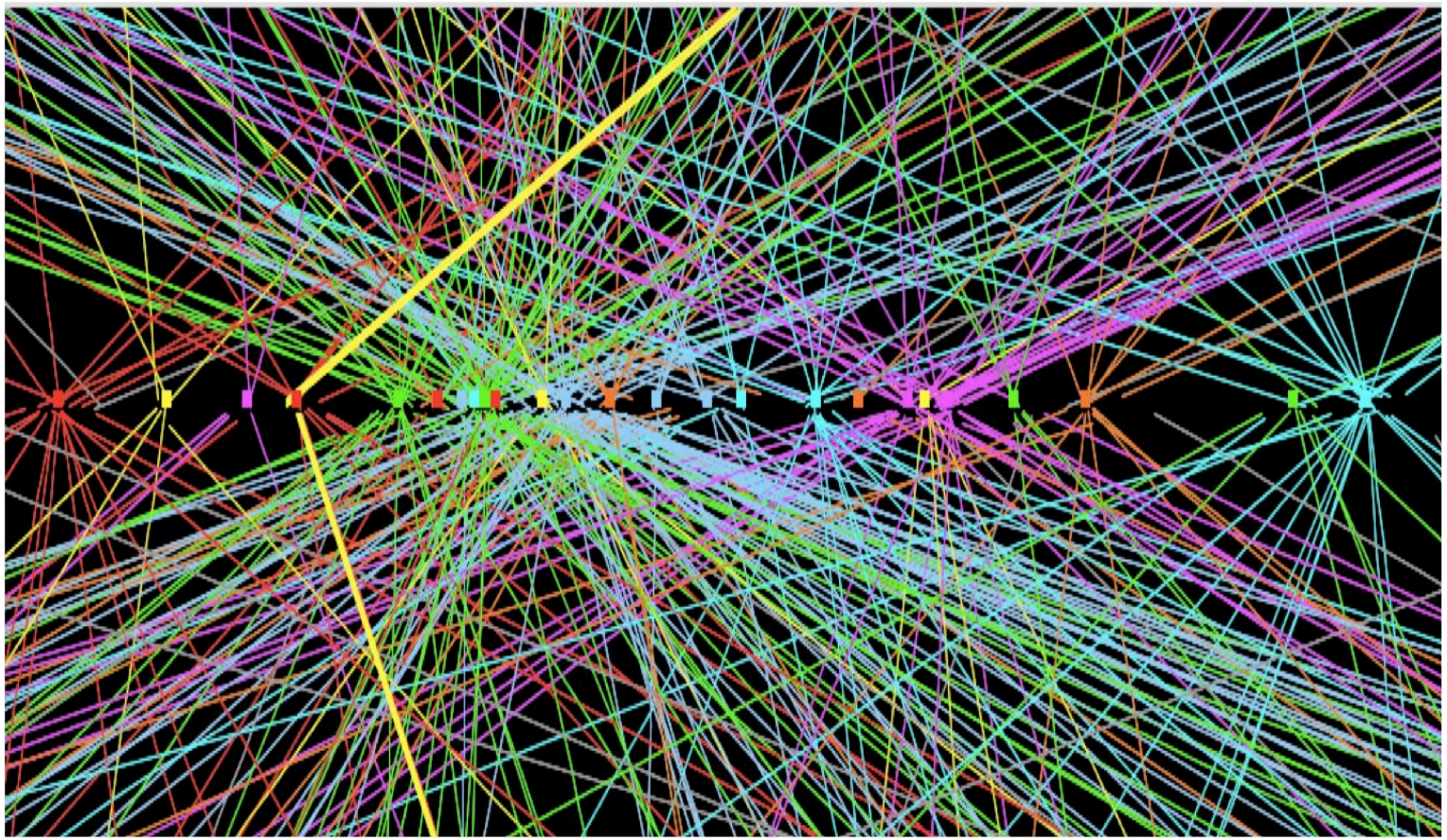
Conversion de l'énergie cinétique en masse.

Création de nouvelles particules, d'une centaine de sortes

La plupart se désintègrent immédiatement
⇨Il n'en reste que de ~6 sortes,
qui vont traverser le détecteur.

Bunch collision

~15 cm



many p

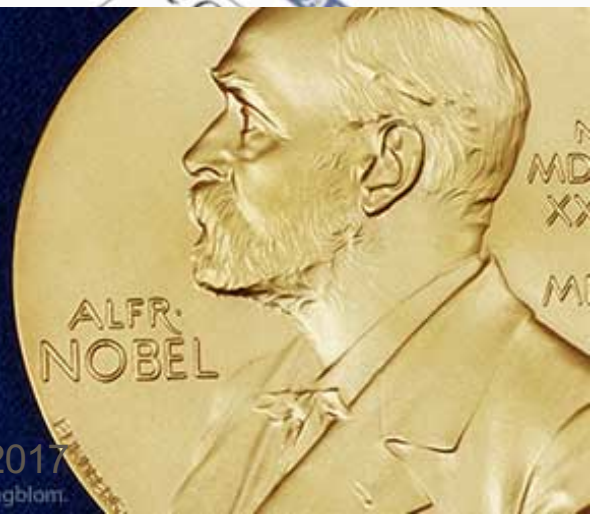
many p

Situation actuelle : 20aine de collision parasites

HL-LHC : facteur 10

2013 NOBEL PRIZE IN PHYSICS

François Englert
Peter W. Higgs

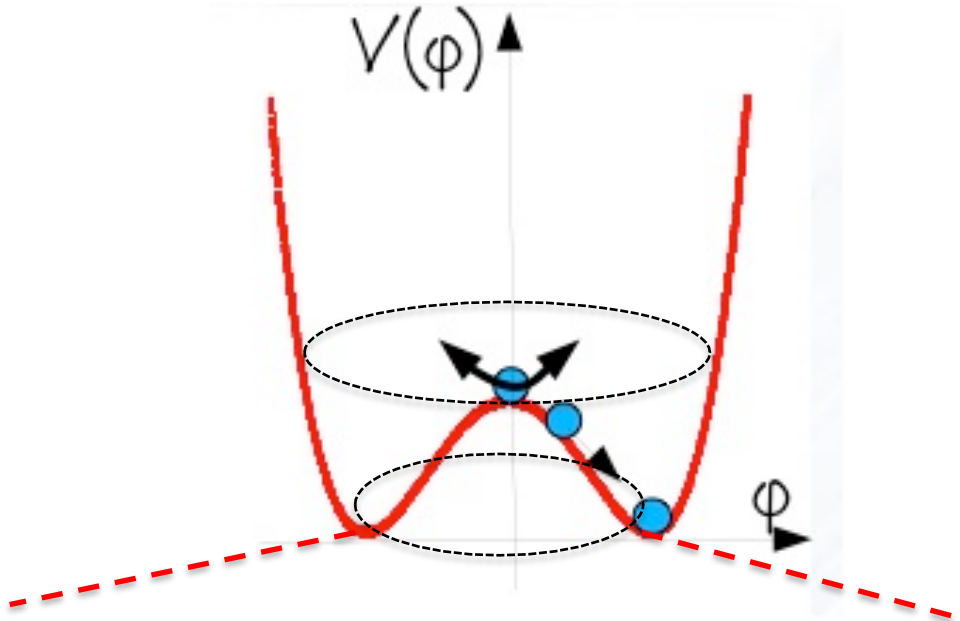


Future of LHC beyond Higgs boson discovery

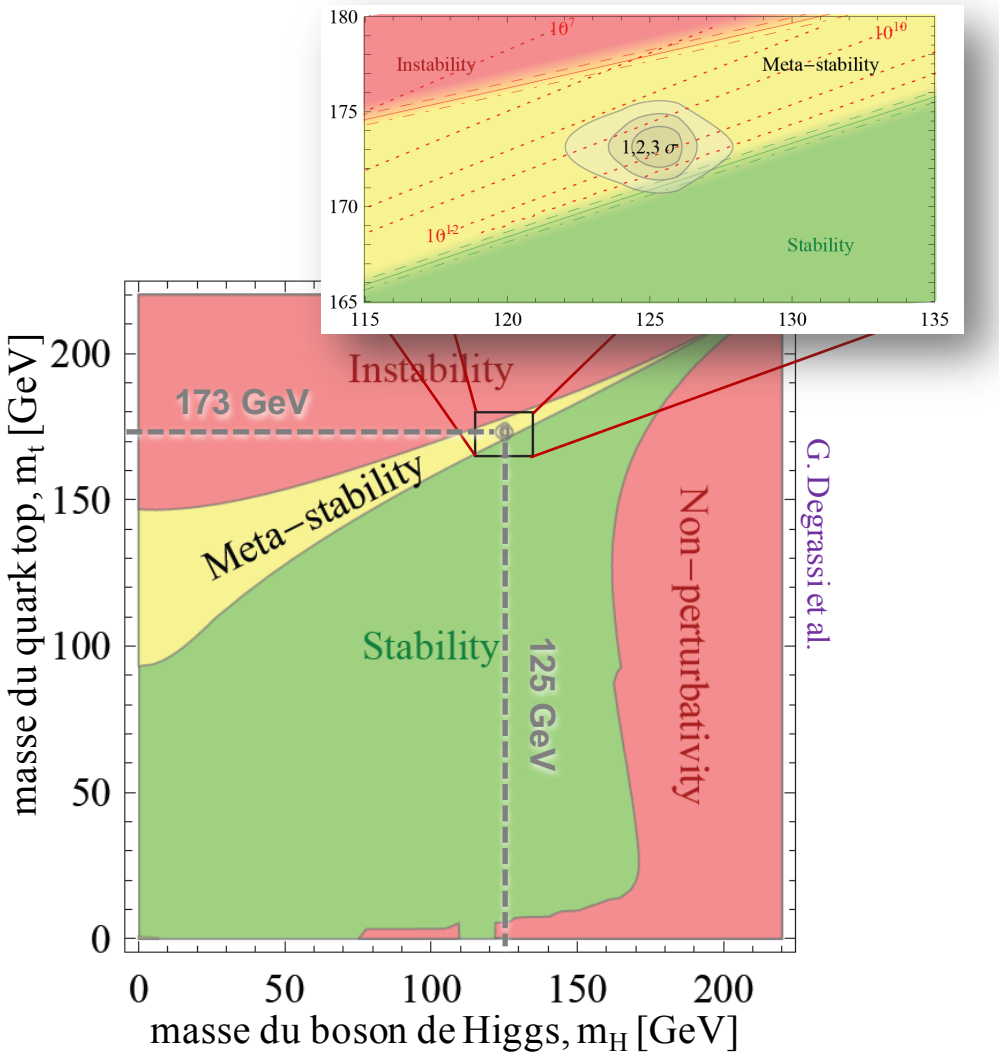
CDS pitching day 9th Nov 2016

L'Univers est-il stable ?

La stabilité du vide dépend des masses du boson de Higgs et du quark top

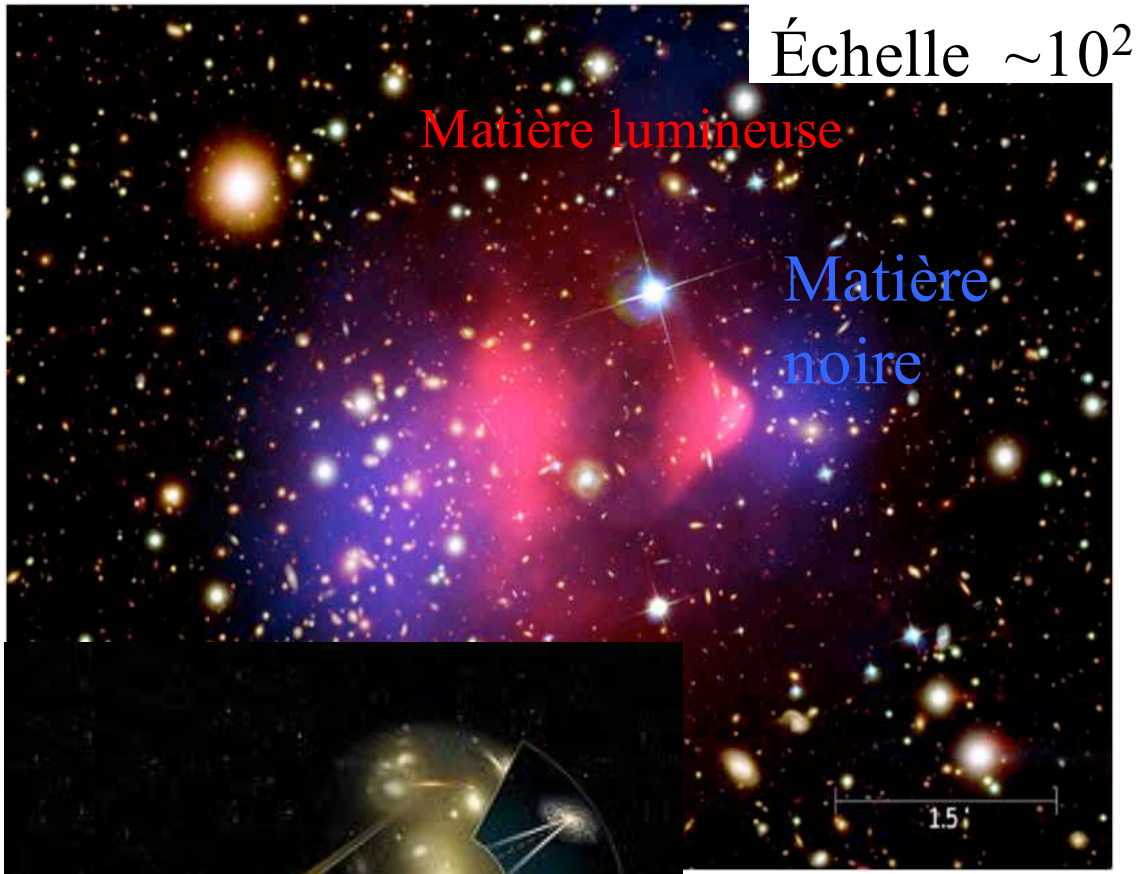


Notre Univers vit au bord du pre



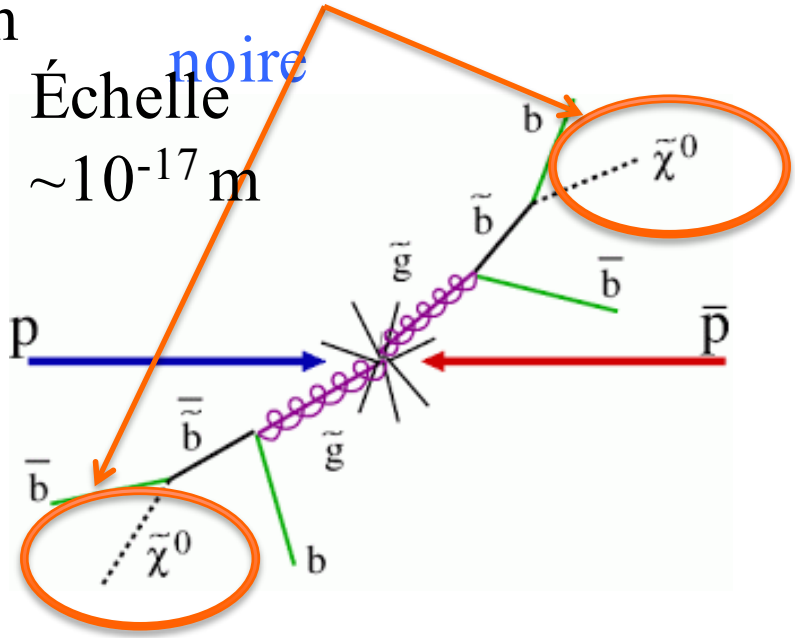
“Physique des deux infinis

Échelle $\sim 10^{22}$ m



Lentille gravitationnelle

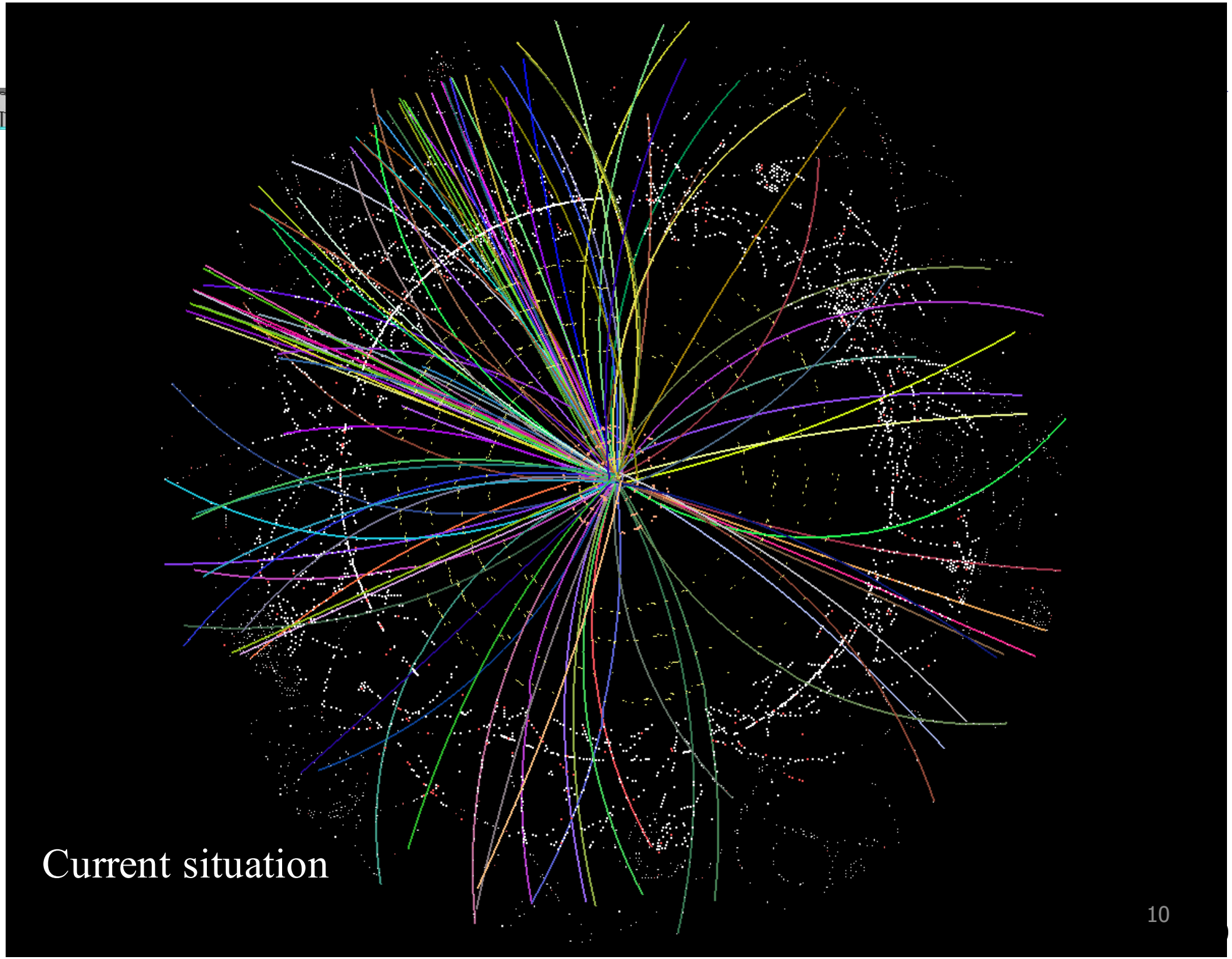
Échelle $\sim 10^{-17}$ m

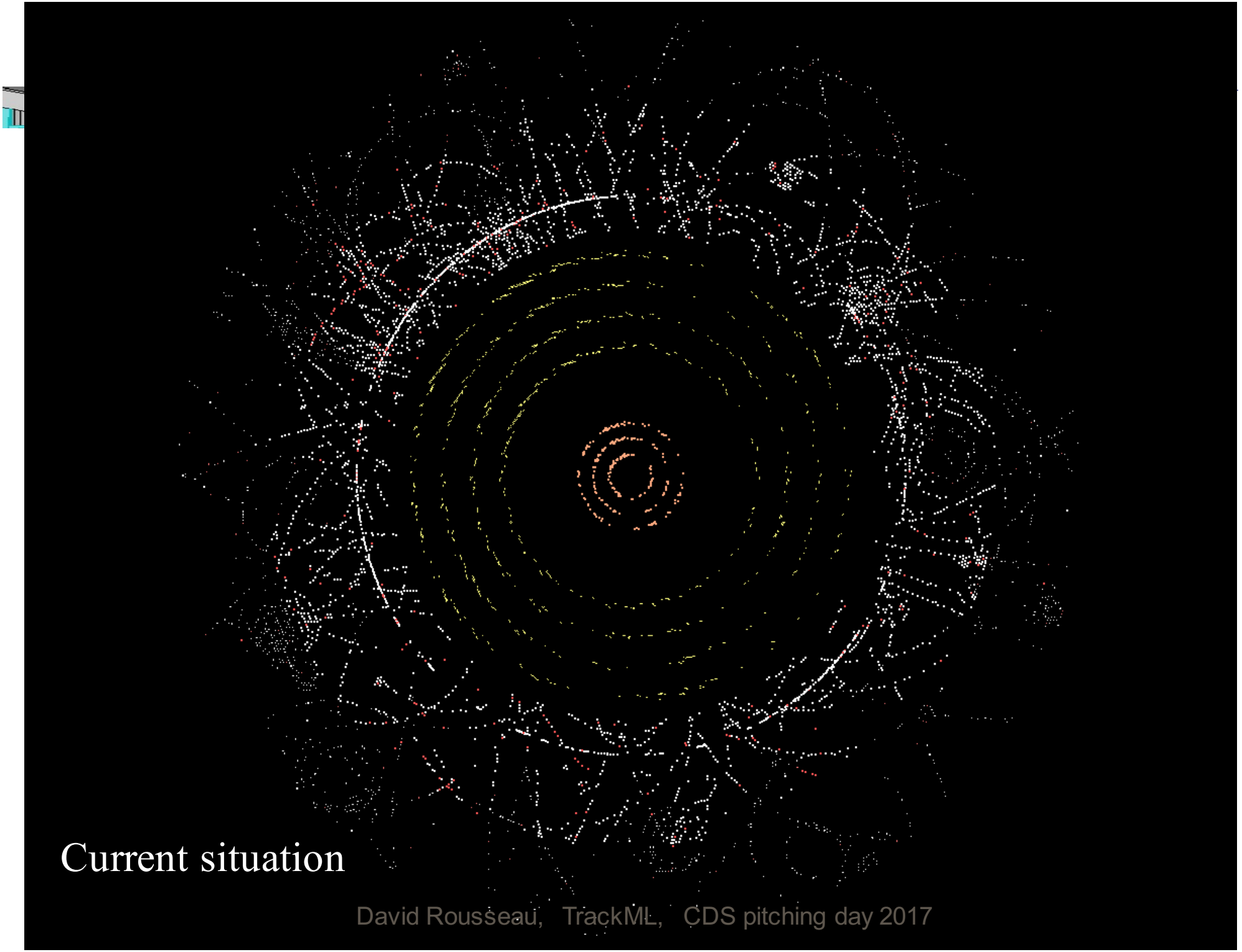


How ?
➔HL-LHC, increase LHC Luminosity by 10 in 2025

Tracking challenge

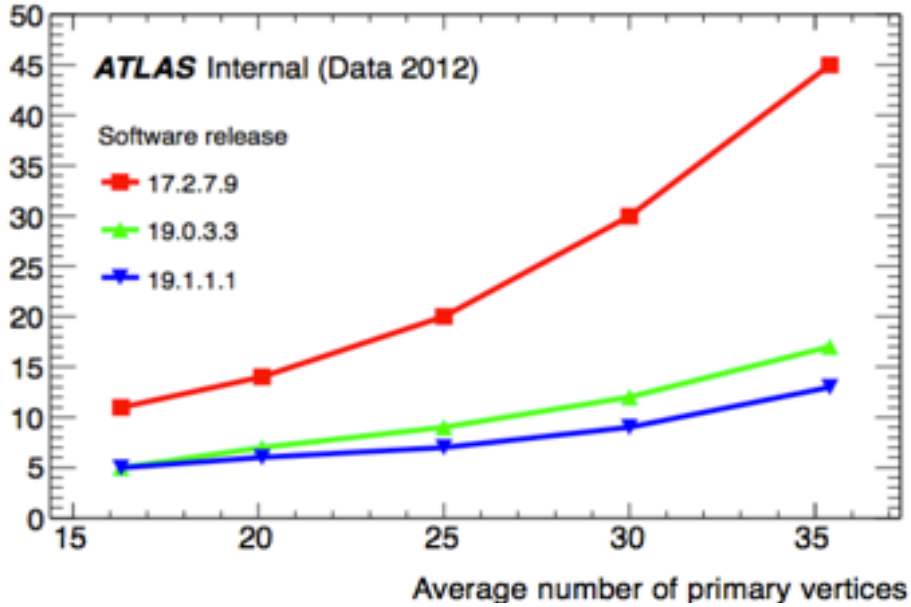
CDS pitching day 9th Nov 2016

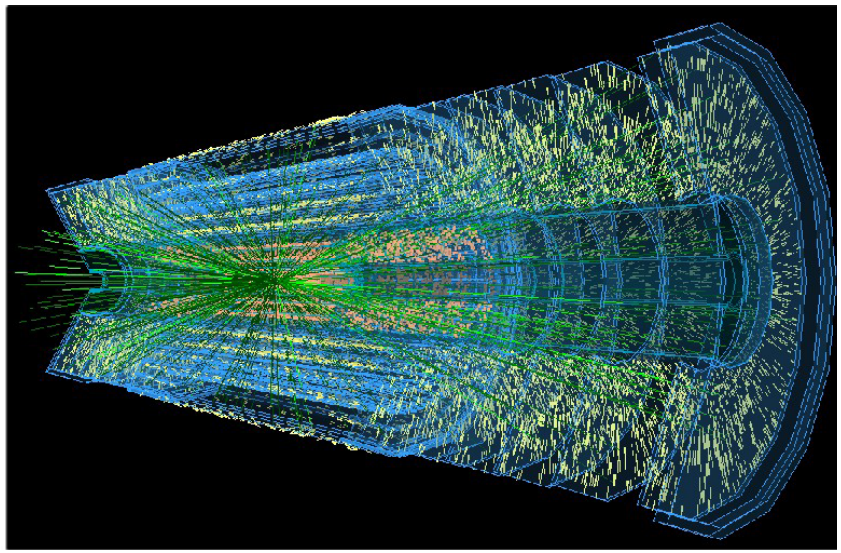

Current situation

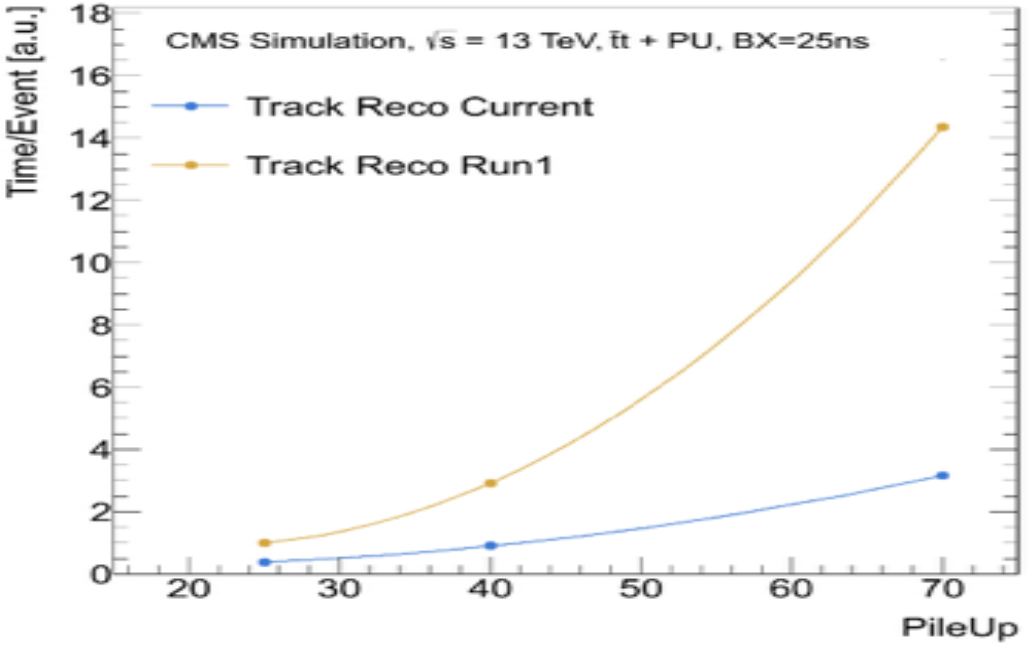

Current situation

Motivation 1

- Tracking (in particular pattern recognition) dominates reconstruction CPU time at LHC
- HighLumi-LHC perspective : increased rate of parasitic collisions
  - Run 1 (2010-2012): <>~20
  - Run 2 (2015-2018): <>~30
  - Phase 2 (2025): <>~150
- CPU time of current software quadratic/exponential extrapolation (difficult to quote any number)
- (but current software give reasonably good results, but too slow)





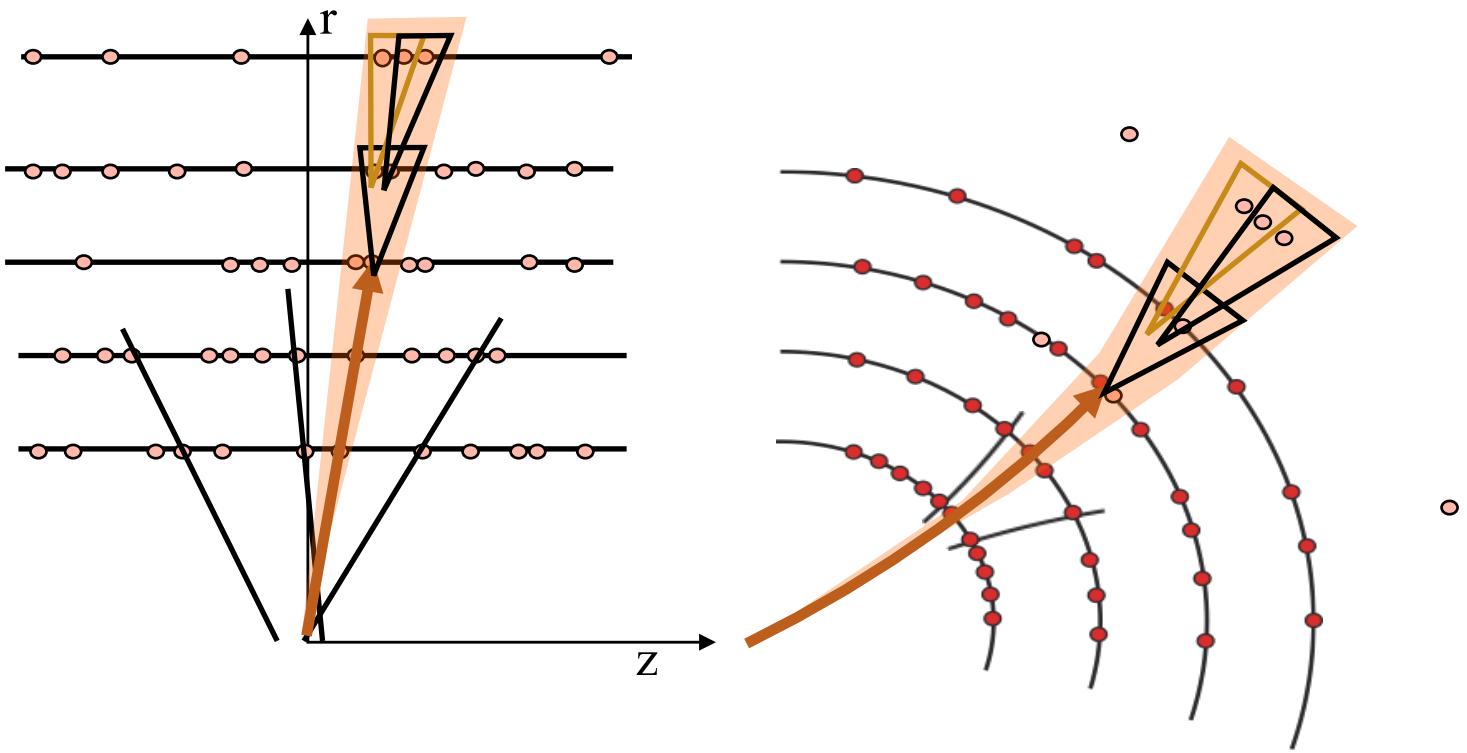


Motivation 2

- LHC experiments future computing budget flat (at best) (LHC experiments use 300.000 CPU cores worldwide)
- Installed CPU power per $==€==CHF expected increase factor <10 in 2025
- Experiments plan on increase of amount of data recorded (by a factor ~10)
- ➔HighLumi reconstruction to be as fast as current reconstruction despite factor 10 in complexity
- ➔requires very significant software CPU improvement, factor ~10
- Large effort within HEP to optimise software and tackle micro and macro parallelism, likely not enough
- >20 years of LHC tracking development. Everything has been tried!
  - Maybe yes, but maybe algorithm slower at low lumi but with a better scaling have been dismissed ?
  - Maybe no, brand new ideas from ML (i.e. Convolutional NN)
- Need to engage a wide community to tackle this problem

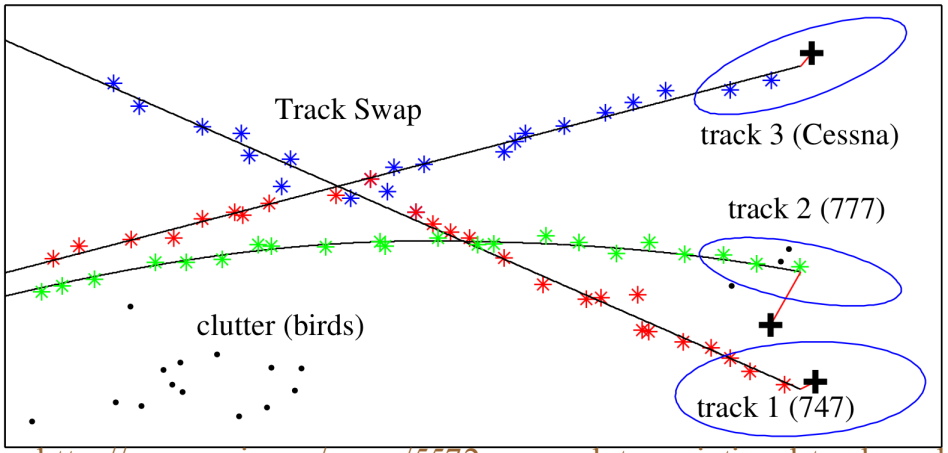
Curent Algorithm

- Pattern : connect 3D points into tracks
- Essentially combinatorial approach
- Tracks are (not perfect) helices pointing (approximately) to the origin
- Challenge : explore completely new approaches
- (not part of the challenge : given the points, estimate the track parameters)

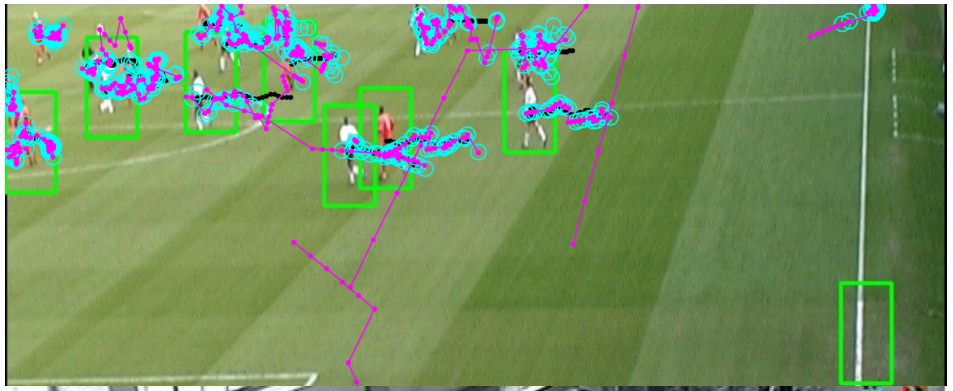


Pattern recognition

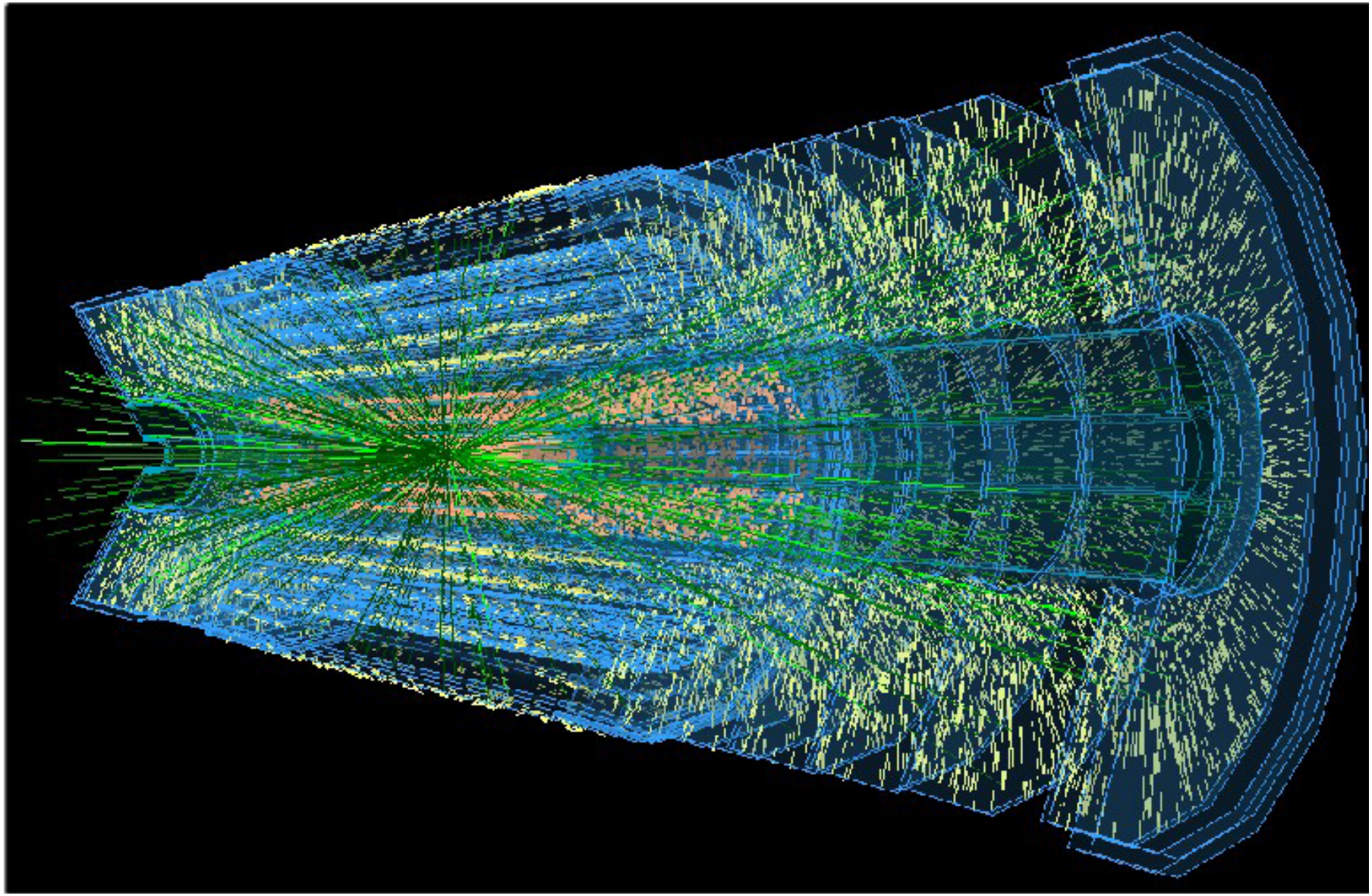
- Pattern recognition, tracking, is a very old, very hot topic in Artificial Intelligence : examples➔



http://papers.nips.cc/paper/5572-a-complete-variational-tracker.pdf



- Note that these are real-time applications, with CPU constraints
- Worry about efficiency, "track swap",…
- But no on-the-shelf algorithm will solve our problem



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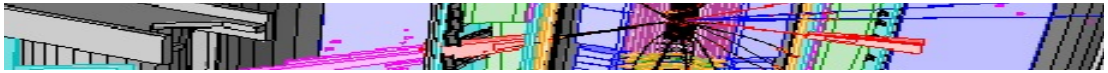
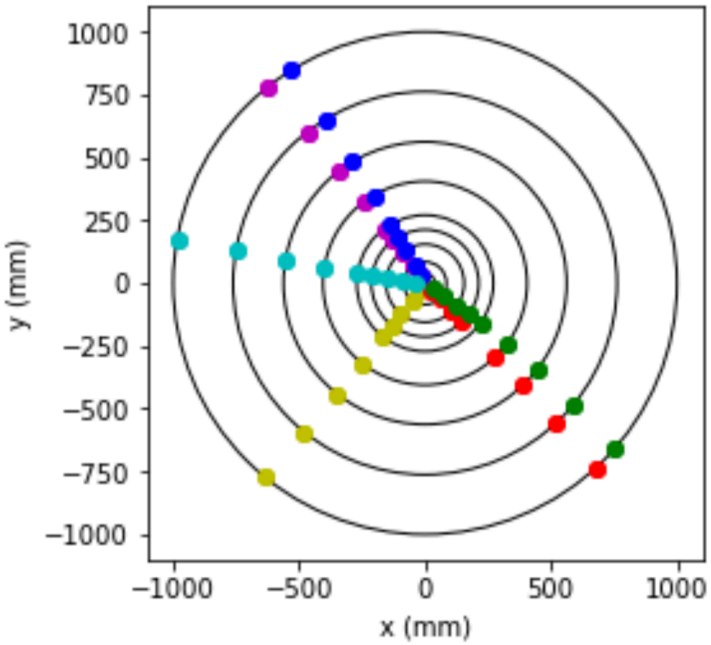
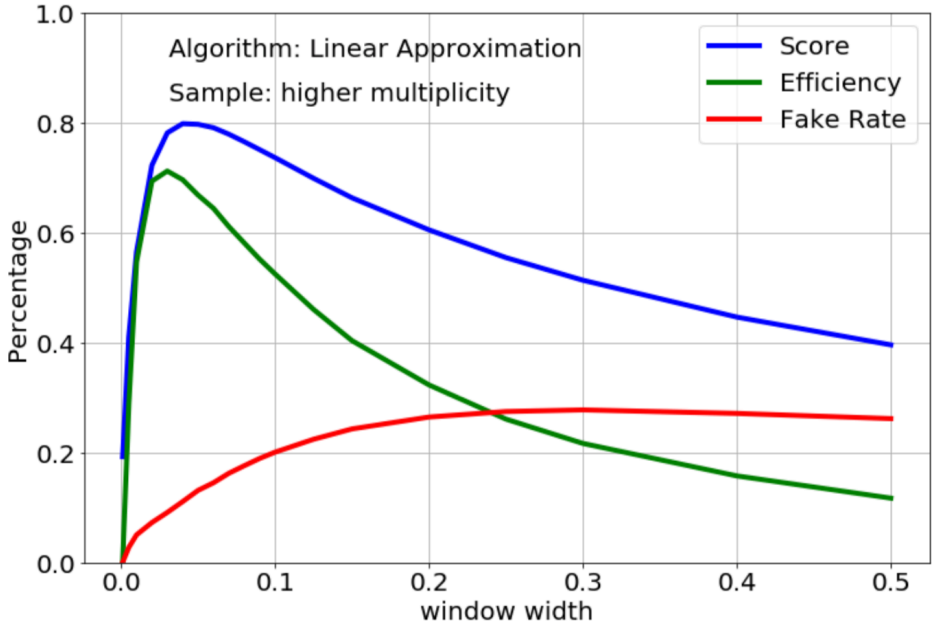
TrackMLRamp



- A simplified tracking challenge setup on RAMP with CDS help (Yetkin Yilmaz Balazs' post-doc 3months, setting up and submission analysis)
- A (non completely trivial) 2D simulation with 10 tracks instead of 3D/10.000 tracks
- Run as a 40 hours hackathon during CTDWIT 6-9th March 2017 LAL-Orsay
- Allowed to validate robustness a scoring variable and show richness of possible algorithms: combinatorial (HEP baseline), conformal mapping, MCTS, LSTM
- Published in proceedings EPJ Web Conf., 150 (2017) 00015





TrackML : current thinking

- We now have a dataset (sorry it took so long)
  - Use ACTS (A Common Tracking Software) to generate fast simulation of a generic Silicon detector at HL-LHC (cylinder and disks)
  - battlefield tested ATLAS software moved to public gitlab@cern
  - ➔simplified simulation but not too simple (otherwise a simple Hough transform would probably work)
  - "cheap" but realistic events which do not "belong" to any collaboration (ATLAS, CMS,…)
- Dataset:
  - 3D points and truth track parameters for n events
  - Typical events with ~200 parasitic collisions (~10.000 tracks/event)
  - Large training sample 1 million events, 100 billion tracks ~1TeraByte
  - Also thinking of allowing participants to generate their dataset
- Participants are given the test sample. They should upload the tracks they have found
  - A track is a list of points belonging to it
  - We don't ask for track parameters, nothing will beat Kalman filter
  - Figure of merit built from efficiency, fake rate, CPU time
- We have decided to run in two phases
  - Phase 1 : focus only on accuracy, no CPU incentive
    - Discussing with Kaggle next week
    - To run in Winter 2018
  - Phase 2 : focus on CPU, preserving accuracy
    - More tricky, require the challenge platform to run the algorithm within controlled environment
    - To run in Summer 2018

What with CDS?

- We're not looking really for new collaboration on preparing the challenge itself but still:
  - 3-months of an engineer (preferably from CDS core) to finalise the challenge operation, especially phase 2
  - …tricky, need to run submitted software in a controlled environment, and to handle many submissions
- Put more emphasis on post challenge analysis and mid/long term collaboration
  - use the CDS channels to advertise the challenge
  - master internship for post-challenge analysis
  - Build in/post-challenge collaboration with CDS scientists on innovative approaches to the tracking problem as revealed by the challenge.
  - possibly collaboration on the visualization (Tobias Isenberg INRIA/Saclay expressed interest, thanks to pitching day 2016)