

# Machine Learning for Accelerators

## Automatic Accelerator Tuning

Emmanuel Goutierre<sup>1, 2</sup>

<sup>1</sup>IJCLab

<sup>2</sup>LISN

Thursday October 28, 2021

# Outline

- 1 Automatic Accelerator Tuning Problem
  - Mathematical Formulation
  - Challenges
- 2 Machine Learning meets Accelerator Tuning
  - Surrogate Models to Speedup Accelerator Optimization
  - Reality Gap between Simulator and Accelerator
  - Exploration vs. Exploitation Tradeoff to Discover Internal State

# Outline

- 1 Automatic Accelerator Tuning Problem
  - Mathematical Formulation
  - Challenges
- 2 Machine Learning meets Accelerator Tuning
  - Surrogate Models to Speedup Accelerator Optimization
  - Reality Gap between Simulator and Accelerator
  - Exploration vs. Exploitation Tradeoff to Discover Internal State

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Parameters

### Accelerator Description

- $\mathcal{A}$  : Set of controllable commands of the accelerator
- $\Theta$  : Set of non-controllable commands of the accelerator
- $\mathcal{O}$  : Set of observations of the state of the accelerator

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Parameters

### Accelerator Description

- $\mathcal{A}$  : Set of controllable commands of the accelerator
- $\Theta$  : Set of non-controllable commands of the accelerator
- $\mathcal{O}$  : Set of observations of the state of the accelerator

### $\mathcal{A}$

- Accelerating gradient
- Solenoid strength
- RF phase
- ...

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Parameters

### Accelerator Description

- $\mathcal{A}$  : Set of controllable commands of the accelerator
- $\Theta$  : Set of non-controllable commands of the accelerator
- $\mathcal{O}$  : Set of observations of the state of the accelerator

$\mathcal{A}$

- Accelerating gradient
- Solenoid strength
- RF phase
- ...

$\Theta$

- Elements position
- Accelerating section misalignments
- ...

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Parameters

### Accelerator Description

- $\mathcal{A}$  : Set of controllable commands of the accelerator
- $\Theta$  : Set of non-controllable commands of the accelerator
- $\mathcal{O}$  : Set of observations of the state of the accelerator

$\mathcal{A}$

- Accelerating gradient
- Solenoid strength
- RF phase
- ...

$\Theta$

- Elements position
- Accelerating section misalignments
- ...

$\mathcal{O}$

- BPM
- ICT
- Screen station
- ...

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Optimization Function

What is the objective

- optimize  $(\epsilon_x, \epsilon_y, \Delta E, \sigma_x, \sigma_y, \dots) = f(\theta, A)$

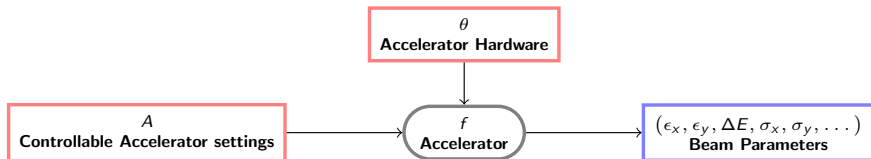


# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Optimization Function

What is the objective

- optimize  $(\epsilon_x, \epsilon_y, \Delta E, \sigma_x, \sigma_y, \dots) = f(\theta, A)$

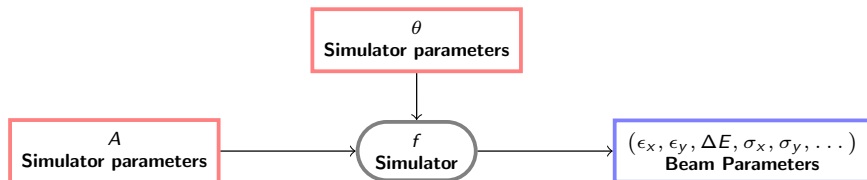


# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Optimization Function

### What is the objective

- optimize  $(\epsilon_x, \epsilon_y, \Delta E, \sigma_x, \sigma_y, \dots) = f(\theta, A)$



# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Optimization Function

### What is the objective

- optimize  $(\epsilon_x, \epsilon_y, \Delta E, \sigma_x, \sigma_y, \dots) = f(\theta, A)$
- Multi objective, parametric, black box optimization

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Problems

### Problems ...

- 1 The function  $f$  to optimize is rarely directly observed in real life

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Problems

### Problems ...

- 1 The function  $f$  to optimize is rarely directly observed in real life
- 2 Simulators computational time can be huge

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Problems

### Problems ...

- 1 The function  $f$  to optimize is rarely directly observed in real life
- 2 Simulators computational time can be huge
- 3 Simulations are not perfectly representing the reality

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Problems

### Problems ...

- 1 The function  $f$  to optimize is rarely directly observed in real life
- 2 Simulators computational time can be huge
- 3 Simulations are not perfectly representing the reality
- 4  $\theta$  is partially unknown

# Automatic Accelerator Tuning Problem

## Mathematical Formulation of the Problem: Problems

### Problems ...

- 1 The function  $f$  to optimize is rarely directly observed in real life
- 2 Simulators computational time can be huge
- 3 Simulations are not perfectly representing the reality
- 4  $\theta$  is partially unknown
- 5  $\theta$  is potentially not fixed on an accelerator



# Outline

- 1 Automatic Accelerator Tuning Problem
  - Mathematical Formulation
  - Challenges
- 2 Machine Learning meets Accelerator Tuning
  - Surrogate Models to Speedup Accelerator Optimization
  - Reality Gap between Simulator and Accelerator
  - Exploration vs. Exploitation Tradeoff to Discover Internal State

# Surrogate Models to Speedup Accelerator Optimization

## Problem

- Simulators computational time can be huge (2)

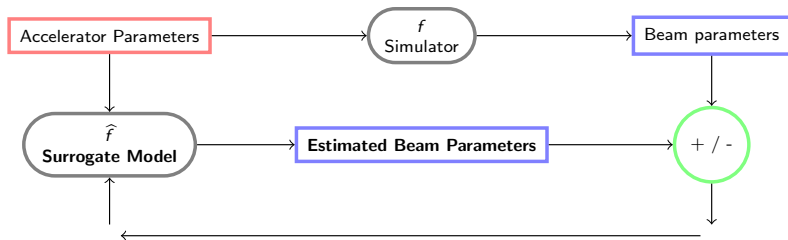
# Surrogate Models to Speedup Accelerator Optimization

## Problem

- Simulators computational time can be huge (2)

## Solution

- Compute surrogate model



# Surrogate Models to Speedup Accelerator Optimization

## Problem

- Simulators computational time can be huge (2)

## Solution

- Compute surrogate model

## Tool

- Supervised Learning and Neural Networks<sup>a</sup>

---

<sup>a</sup>Edelen et al., 2020.

# Reality Gap between Simulator and Accelerator

## Problem

- Simulations are not perfectly representing the reality (3)

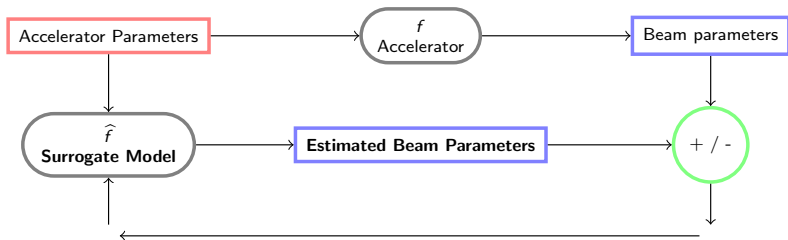
# Reality Gap between Simulator and Accelerator

## Problem

- Simulations are not perfectly representing the reality (3)

## Solution

- Incorporate experimental data



# Reality Gap between Simulator and Accelerator

## Problem

- Simulations are not perfectly representing the reality (3)

## Solution

- Incorporate experimental data
- Learn to discriminate real data from generated data

# Reality Gap between Simulator and Accelerator

## Problem

- Simulations are not perfectly representing the reality (3)

## Solution

- Incorporate experimental data
- Learn to discriminate real data from generated data

## Tool

- Fine Tuning
- Generative Adversarial Networks



# Exploration vs. Exploitation Tradeoff to Discover Internal State

## Problem

- Partially unobserved and changing environment (1, 4, 5)

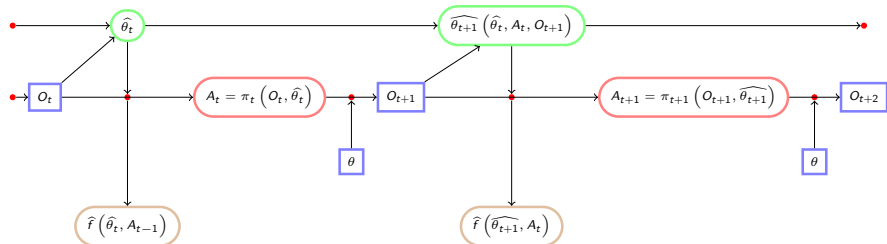
# Exploration vs. Exploitation Tradeoff to Discover Internal State

## Problem

- Partially unobserved and changing environment (1, 4, 5)

## Solution

- Partially Observable Markov Decision Process



# Exploration vs. Exploitation Tradeoff to Discover Internal State

## Problem

- Partially unobserved and changing environment (1, 4, 5)

## Solution

- Partially Observable Markov Decision Process

## Solution

- RL (Reinforcement Learning)

# Questions?