

Disorder in complex systems

M.L. Manning

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What are the origins of long-range velocity correlations in dense active matter systems?

- 1) for nearly arrested systems, explained by combined effect of persistent motion + elastic response
use notation from this \rightarrow Henkes et al, Nat Comm (2020)
also c.f. Henkes, Fily, Marchetti PRE 2011
Bi, Yang, Marchetti Manning PRX 2016

- 2) for diffusive systems, explained by persistent motion + bulk modulus.

Flemer + Szamel EPL (2021)

Elastic response:

moves along a direction \hat{n} , and orientation angle experiences white noise

Let's investigate self-propelled particles with a simple two-body interaction potential:

$$m \frac{dv_i}{dt} = F_{int} + F_{propulsion} + F_{drag} + F_{positional\ noise}$$

\downarrow \downarrow \downarrow \downarrow

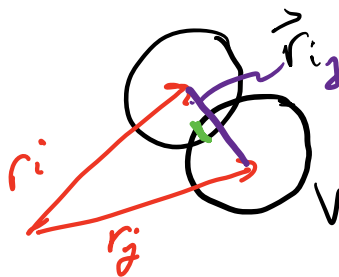
$$-\sum_j \frac{\partial V(r_{ij})}{\partial r_i} \quad F_0 \hat{n}_i \quad -\zeta v_i \quad 0$$

0
"overdamped limit"
inertial effects negligible compared to drag

$$\hookrightarrow \frac{d\mathbf{r}_i}{dt} = \frac{F_0}{\xi} \hat{n}_i - \frac{1}{\xi} \sum_j \nabla_i V(r_{ij})$$

Here we consider 2-body potentials

where $V(r_{ij})$ depends on distance between two particles



e.g.

$$V(r_{ij}) = \begin{cases} \epsilon \left[1 - \frac{r_{ij}}{2\sigma}\right]^\alpha, & r_{ij} < 2\sigma \\ 0 & \text{o.w.} \end{cases}$$



\Rightarrow

$$\dot{\mathbf{r}}_i = v_0 \hat{n}_i - \frac{1}{\xi} \sum_j \nabla_i V(r_{ij})$$


$$\text{and } \hat{n}_i = \cos \phi_i \hat{x} + \sin \phi_i \hat{y}$$

with $\phi_i = \eta_i(t)$, $\langle \eta_i(t) \rangle = 0$

\uparrow angle experiences white noise with persistence time

$$\text{and } \langle \eta_i(t) \eta_j(t') \rangle = \frac{2}{\tau} \delta_{ij} \delta(t-t')$$

low τ SPP trajectory



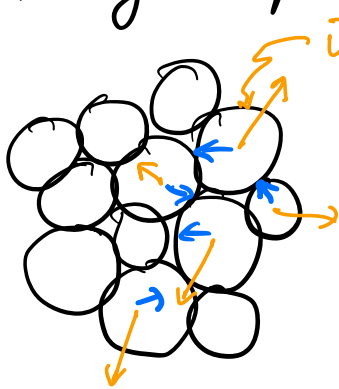
high τ SPP trajectory



Next: start from solid-like perspective:

At high densities, where system would be arrested in the absence of self-propulsion, we can define a Dynamical Matrix describing linear response around a mechanically stable state (local minimum of total potential energy $V_{\text{tot}} = \sum_{\text{all pairs } \langle i, j \rangle} V(r_{ij})$).

→ if you displace packing of particles by a field \vec{u} :
it will result in a set of restoring forces \vec{f} :



$$\vec{f} = \vec{M} \vec{u}$$

for N particles, in 2d, $\vec{u} = \begin{bmatrix} u_{1x} \\ u_{1y} \\ u_{2x} \\ u_{2y} \\ \vdots \end{bmatrix}$, in general is an $Nd \times 1$ vector

$\vec{f} = \begin{bmatrix} f_{1x} \\ f_{1y} \\ \vdots \end{bmatrix}$ is also an $Nd \times 1$ vector.

One can show

$$M_{\alpha\beta} = \frac{\partial^2 V(|\mathbf{r}_i - \mathbf{r}_j|)}{\partial r_{i\alpha} \partial r_{j\beta}} \quad \text{and}$$

$$M_{\alpha\beta} = - \sum_j \frac{\partial^2 V(r_{ij})}{\partial r_{i\alpha} \partial r_{j\beta}}$$

and $\vec{f}_i = \sum_j \vec{M}_{ij} \vec{r}_j$

\downarrow 2-comp. vector in 2D \downarrow 2x2 matrix \downarrow 2-comp vector

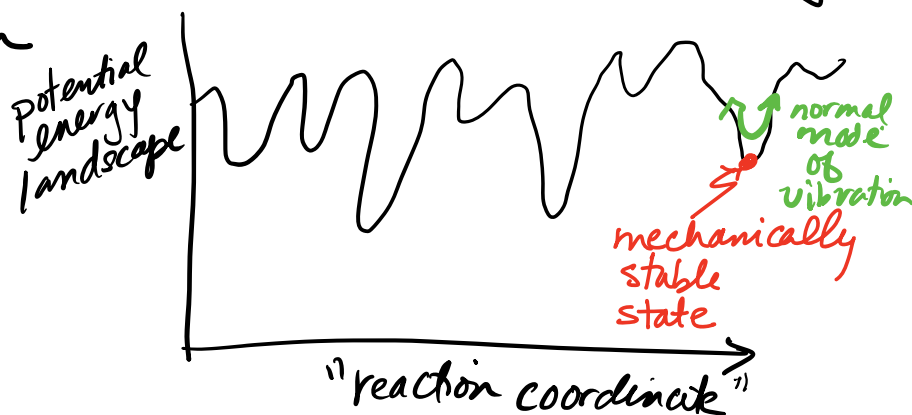
The eigenvalues of this matrix are related to the frequencies of the normal modes of vibration:

$$\omega_v^2 = \lambda_v \leftarrow \text{labels mode index}$$

and the histogram of ϵ_v is the density of vibrational states.

the eigenvectors ϵ_v are the normal modes of vibration. (complete basis set)

They describe the curvatures around a local energy minimum



We can look at dynamics of dense SPP system around such a state:

Let \vec{r}_{oi} be a mechanically stable "inherent state"

Let $\delta \vec{r}_i$ be the displacement from that state:

$$\delta \vec{r}_i = \vec{r}_i - \vec{r}_{oi}$$

Expand $\delta \vec{r}_i$ into the basis of normal modes:

$$\delta \vec{r}_i = \sum_{v=1}^{2N} a_v \epsilon_v^i \quad \text{or} \quad |\delta r\rangle = \sum_v a_v |\epsilon_v^i\rangle$$

\hat{n}_i can also be represented in normal mode basis:

$$|n\rangle = \sum_v n_v |\epsilon_v\rangle \quad \text{or} \quad \hat{n}_i = \sum_{v=1}^{2N} n_v \epsilon_v^i$$

Note that $\textcircled{*}$ can be linearized around \vec{r}_{0i} and written as:

$$\dot{\vec{r}}_i = v_0 \hat{n}_i - \frac{1}{\xi} \sum_j \overset{2 \times 2 \text{ block of dynamical matrix}}{M_{ij}} \cdot \vec{r}_j \quad \textcircled{**}$$

So projecting $\textcircled{**}$ on the normal modes we have

$$\frac{d}{dt} a_v = - \frac{\lambda_v a_v}{\xi} + v_0 \eta_v \quad \textcircled{***}$$

note $\eta_v = \langle n | \xi \rangle = \sum_{i=1}^{2N} \hat{n}_i \cdot \xi_i^v$

very important in rest of this: projection of SPP onto normal modes eigenvector angle

$$= \cos(\theta_v - \phi)$$

polarization angle with $\phi =$ white noise
 $\langle \cos(\phi) \rangle = 0$

So $\langle \eta_v(t) \rangle = 0$

Note $\textcircled{***}$ looks like a single SPP tethered to a spring

Solving it explicitly:

$$(4) \quad a_v(t) = a_v(t=0) e^{-k_v t} + v_0 \int_0^t dt' \frac{\eta_v}{\xi} e^{-k(t-t')}$$

where $k = \frac{\lambda_v}{\xi}$

Now let's average over the noise:

As shown in the appendix,

$$\underbrace{\langle \eta_\nu(t) \eta_{\nu'}(t') \rangle}_{\text{correlation of noise in eigenvalue basis}} = \langle \cos[\phi(t) - \phi(t')] \rangle \delta_{\nu\nu'}$$

$$= e^{-|t|/\tau} \delta_{\nu\nu'}$$

So from (4)
One can show

that as $t \rightarrow \infty$

$$\langle a_\nu^2 \rangle = \frac{\mathcal{Q}}{\lambda_\nu} \int_0^\infty dv \frac{v_0^2}{2} e^{-|v|/\tau} e^{-\lambda_\nu v}$$

$$= \frac{\int_0^\infty v_0^2}{2\lambda_\nu} \int_0^\infty dv e^{-\left(\frac{1}{\tau} + \frac{\lambda_\nu}{\mathcal{Q}}\right)v}$$

$$= \frac{\int_0^\infty v_0^2 \tau}{2\lambda_\nu \left(1 + \frac{\lambda_\nu}{\mathcal{Q}} \tau\right)}$$

average energy per mode:

$$\Rightarrow E_\nu = \left\langle \frac{1}{2} \lambda_\nu a_\nu^2 \right\rangle = \frac{\int_0^\infty v_0^2 \tau}{4 \left(1 + \frac{\lambda_\nu}{\mathcal{Q}} \tau\right)}$$

$$E_\nu \approx \begin{cases} \frac{\int_0^\infty v_0^2 \tau}{4} & \tau \ll \mathcal{Q} \lambda_\nu^{-1} \text{ (equipartition)} \\ \frac{\int_0^\infty v_0^2}{4\lambda_\nu} & \tau \gg \mathcal{Q} \lambda_\nu^{-1} \text{ dominated by soft modes!} \end{cases}$$

~ thermal

Velocity correlation in Fourier space :

$$\hat{G}(\vec{q}) = \langle v(q) \cdot v^*(q) \rangle; v(\vec{q}) = \frac{1}{N} \sum_{j=1}^N e^{i\vec{q} \cdot \vec{r}_j^0} \dot{\vec{r}}_j$$

$$= \sum_{v, v'} \langle \dot{a}_v \dot{a}_{v'} \rangle \xi_v(\vec{q}) \xi_{v'}^*(\vec{q}); \xi_v(\vec{q}) = \frac{1}{N} \sum_{j=1}^N e^{i\vec{q} \cdot \vec{r}_j^0} \xi_j^v$$

from above ~~***~~

$$\langle \dot{a}_v \dot{a}_{v'} \rangle = \frac{1}{\xi^2} \left[\lambda_v^2 \langle a_v^2 \rangle - 2 \lambda_v \langle a_v \eta_v \rangle + \langle \eta_v^2 \rangle \right] \delta_{v, v'}$$

$$\frac{1}{\xi} \int_0^\infty dt' \langle \eta_v(t') \eta_v(t) \rangle e^{-k(t-t')}$$

$$= \frac{\xi v_0^2}{2} \frac{\tau}{1 + \frac{\lambda_v}{\xi} \tau} \quad (\text{similar to above})$$

math
↓

$$\langle \dot{a}_v^2 \rangle = \frac{v_0^2}{2(1 + \frac{\lambda_v}{\xi} \tau)} \Rightarrow \hat{G}(q) = \sum_v \frac{v_0^2}{2(1 + \frac{\lambda_v}{\xi} \tau)} \|\xi_v(q)\|^2$$

and by Parseval's theorem

$$\langle |v|^2 \rangle = \frac{1}{N} \sum_{j=1}^N \langle |\dot{\vec{r}}_j|^2 \rangle = \sum_{\vec{q}} \hat{G}(\vec{q})$$

$$\langle |v|^2 \rangle = \frac{L^2}{(2\pi)^2} \int d^2 q \sum_v \frac{v_0^2}{2(1 + \frac{\lambda_v \tau}{\xi})} \|\xi_v(q)\|^2$$

velocity correlations are dominated by lowest frequency modes for $\tau \gg \xi \lambda_v^{-1}$

There is a continuum elastic formulation, too. But, it has

very similar logic:

$$\langle \hat{n}(\vec{r}, t), \hat{n}(\vec{r}', t') \rangle = a^2 \delta(\vec{r} - \vec{r}') e^{-|t - t'|/\tau}$$

$$\langle F^{\text{act}}(q, \omega), F^{\text{act}}(-q, \omega') \rangle = 2\pi N \xi v_0^2 \frac{2\tau}{1 + (\tau\omega)^2} \delta(\omega + \omega')$$

$$\langle \tilde{v}(q, t), \tilde{v}(q', t) \rangle = 2\pi a^2 v_0^2 \frac{1}{\delta(q + q')} \left[\frac{1}{1 + \left[\frac{(B+\mu)\tau}{\xi} \right]^2 q^2} + \frac{1}{1 + \frac{\mu\tau^2}{\xi} q^2} \right]$$

$$\xi_L = \left(\frac{(B+\mu)\tau}{\xi} \right)^{1/2}$$



longitudinal
length
scale
squared

transverse
length
scale
squared

B and μ come from isotropic continuum linear elasticity

$$\nabla \sigma = f = \zeta \dot{u} = \overset{\substack{\text{bulk modulus} \\ \downarrow}}{B} \nabla (\nabla \cdot u) + \overset{\substack{\text{shear modulus} \\ \downarrow}}{\mu} \nabla u$$

↑ overdamped dynamics

So note that the correlation length in both transverse + longitudinal directions scales as $\xi_L \sim \xi_T \sim \tau^{1/2}$

Section 2: Fluid-like starting point:

Very briefly discuss work by Szamel + Fleener:

What about dense liquids where there is no elasticity or reference state?

same eqn:

$$\zeta \vec{r}_i = -\nabla_i \sum_j V(r_{ij}) + \zeta v_0 \hat{n}_i$$

derive an expression relating velocity polarization + force fields:

$$(6) \quad \vec{v}(\vec{q}, t) = \sum_j \sum_{k \neq j} \vec{F}_{jk} e^{-i\vec{q} \cdot \vec{r}_j} + \gamma v_0 \hat{n}(q, t)$$

$$\text{where } \vec{v}(\vec{q}, t) = \sum_j \dot{\vec{r}}_j e^{-i\vec{q} \cdot \vec{r}_j(t)}$$

$$\hat{n}(q, t) = \sum_j \hat{n}_j e^{-i\vec{q} \cdot \vec{r}_j(t)}$$

Trick: one can show the first term on RHS of (6) can be written so that it looks like the interaction part of the ^{fourier transform} pressure tensor

$$i\vec{q} \cdot \sum_j \sum_{k \neq j} \vec{r}_{jk} \frac{\vec{r}_{jk}}{2r_{jk}} v'(r_{jk}) \left[\frac{e^{i\vec{q} \cdot \vec{r}} - 1}{i\vec{q} \cdot \vec{r}} \right] e^{-i\vec{q} \cdot \vec{r}}$$

$$= i\vec{q} \cdot \Pi_v(\vec{q}, t)$$

Assume a virial expansion of Π in terms of ρ

$$\Pi_v(\vec{r}, t) = \underbrace{P_v}_{\substack{\text{steady state} \\ \text{pressure} \\ \text{math}}} + \frac{\partial P_v}{\partial \rho} (\underbrace{\rho(r, t)}_{\substack{\text{steady} \\ \text{state} \\ \text{avg} \\ \text{density}}} - \rho)$$

$$\langle |\hat{q} \cdot v(q)|^2 \rangle = \frac{N v_0^2}{2} \frac{1}{1 + \frac{\rho^2 \epsilon B_v}{(\epsilon \rho)}} \Rightarrow \xi_L = \sqrt{\frac{\epsilon B_v}{\epsilon \rho}}$$

Appendix note that the two point correlation fn for weights η is:

$$\langle \eta_v(t) \eta_v(t') \rangle = \frac{1}{2} \langle \cos[\phi(t) - \phi(t')] \rangle$$

dot product is just cos difference b/w angles for unit vectors

recall $\dot{\phi} = \eta$ $\langle \eta(t) \eta(t') \rangle = \frac{2}{\tau} \delta(t - t')$

$$\Rightarrow \phi(t) = \int_0^t \eta(t') dt'$$

$$\cos \phi(t) = \frac{1}{2} (e^{i\phi(t)} + e^{-i\phi(t)})$$

(5) $\langle \cos[\phi(t) - \phi(t')] \rangle = \langle \frac{1}{2} (e^{i(\phi(t) - \phi(t'))} + e^{-i(\phi(t) - \phi(t'))}) \rangle$

If θ is Gaussian, use cumulant expansion:

$$\begin{aligned} \langle e^{i\theta} \rangle &= e^{-\frac{\langle \theta^2 \rangle}{2}} \Rightarrow \\ &= \frac{1}{2} \left(e^{-\frac{\langle [\phi(t) - \phi(t')]^2 \rangle}{2}} + e^{-\frac{\langle [\phi(t) - \phi(t')]^2 \rangle}{2}} \right) \end{aligned}$$

$$\langle [\phi(t) - \phi(t')]^2 \rangle = \underbrace{\langle \phi(t)^2 \rangle}_{(1)} - 2 \underbrace{\phi_t \phi_{t'}}_{(2)} + \underbrace{\langle \phi(t')^2 \rangle}_{(3)}$$

(1) $\int_0^t \int_0^{t'} \underbrace{\langle \eta(\tilde{t}) \eta(\tilde{t}') \rangle}_{\substack{2/\tau \delta(\tilde{t} - \tilde{t}') \\ 1}} d\tilde{t} d\tilde{t}' = \frac{2t}{\tau}$

$$\textcircled{2} \phi(t) \phi(t') = \int_0^t \int_0^{t'} \underbrace{\langle \eta(\tilde{t}) \eta(\tilde{t}') \rangle}_{\delta(\tilde{t} - \tilde{t}')} d\tilde{t} d\tilde{t}' =$$

$$= \begin{cases} \frac{2}{\tau} \int_0^t 1 d\tilde{t} = \frac{2t}{\tau} & \text{if } t' > t \\ \frac{2}{\tau} \int_0^{t'} 1 d\tilde{t}' = \frac{2t'}{\tau} & \text{if } t' < t \end{cases}$$

$$= \frac{2}{\tau} \min(t, t')$$

Assume time translation invariance, so
WLOG $t' = 0$

$$\begin{aligned} \text{then } \textcircled{5} &= \frac{1}{2} \left(e^{-\frac{\langle \phi^2(t) \rangle}{2}} \left[e^{\frac{2\langle \phi(t) \phi(t') \rangle}{2}} + e^{\frac{2\langle \phi(t') \phi(t) \rangle}{2}} \right] \right) \\ &= e^{-\frac{\langle \phi^2(t) \rangle}{2}} e^{\frac{2\langle \phi(t) \phi(t') \rangle}{2}} \\ &= e^{t/\tau} e^{-\frac{2\min(t, t')}{\tau}} \\ &= \begin{cases} e^{-t/\tau - 0} & t > 0 \\ e^{-t/\tau + \frac{2t}{\tau}} & t < 0 \end{cases} \\ &= e^{-|t|/\tau} \quad \text{Phew!} \end{aligned}$$