## Superfluid Fraction in an Interacting Spatially Modulated Bose-Einstein Condensate

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## Superfluidity: a hallmark of quantum many-body systems

Some characteristics

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- Non-viscous flow around impurity for $v<v_{c}$

(Desbuquois et al., 2012), (Raman et al., 2001)


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- Two sound modes

(Christodoulou et al., 2021)


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- Quantized angular momentum: vortices



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Our work: $T=0$

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In the case of weakly interacting Bose gas at $T=0$, with separable density, i.e. $\rho(x, y, z)=\rho_{x}(x) \rho_{y}(y) \rho_{z}(z)$, we showed:

## Saturation of Leggett's formula

$$
f_{s}=\frac{1}{\langle\rho\rangle\langle 1 / \rho\rangle}
$$

## Superfluidity and density modulation

The superfluid fraction is reduced due to the density modulation
Break translational invariance along 1
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$\Rightarrow$ Expect reduction of $f_{s}$


## Measurement of superfluid fraction

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## Measurement of superfluid fraction

How to measure this reduction of superfluid fraction?

Superfluid fraction measured for different $V_{0}$, with two different methods:

- Dynamic measurement: excite the cloud and measure its response to density perturbation (oscillation at speed of sound frequency)
- Static measurement: measure density and apply Leggett's formula


## Our experimental platform



## Dynamic measurement of $f_{s}$



- For a given $V_{0}$, we shake the BEC along $x$
- We measure the frequency of the standing wave created by this perturbation $\nu_{x}$
- Speed of sound $c_{x}=2 L_{x} \nu_{x}$
- We do the same but excitation along $y$ and extract $c_{y}$
- We repeat these 2 measurements for another $V_{0}$


$$
\begin{aligned}
& \text { Speed of sound } \\
& \text { measurement of } f_{s} \\
& \qquad f_{s, x}=\frac{c_{x}^{2}}{c_{y}^{2}}=\frac{\nu_{x}^{2}}{\nu_{y}^{2}}
\end{aligned}
$$

## Dynamic measurement of $f_{s}$

## Center of mass oscillations



Oscillations fit by: $\langle x, y\rangle=e^{-\Gamma t}\left[A \cos \left(2 \pi \nu_{x, y} t\right)+B \sin \left(2 \pi \nu_{x, y} t\right)\right]$

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## Dynamic measurement of $f_{s}$

## Center of mass oscillations



$$
V_{0}=0: \nu_{x} \simeq \nu_{y}
$$


$V_{0}>0: \nu_{x}<\nu_{y}$


Solid lines: GP simulations

## Dynamic measurement of $f_{s}$

$$
f_{s, x}=\frac{\nu_{x}^{2}}{\nu_{y}^{2}}
$$



## Static measurement of $f_{s}$

Naive way


Measure $\rho$, fit with a sine wave and deduce

$$
f_{s}=\frac{1}{\langle\rho\rangle\langle 1 / \rho\rangle}=\left(1-\frac{\rho_{1}^{2}}{\rho_{0}^{2}}\right)^{\frac{1}{2}}
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More elaborate way
Higher harmonics take importance for large $V_{0}$ and we expand $\rho$ in Fourier modes.

Ideal world infinite imaging resolution

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\rho(x)=\rho_{0}-\sum_{n>0} \rho_{n} \cos (n q x)
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More elaborate way
Higher harmonics take importance for large $V_{0}$ and we expand $\rho$ in Fourier modes. Finite imaging resolution $\Rightarrow$ spatial filtering of the harmonics

Ideal world infinite imaging resolution

$$
\rho(x)=\rho_{0}-\sum_{n>0} \rho_{n} \cos (n q x)
$$

Real world finite imaging resolution

$$
\begin{gathered}
\rho^{(\text {meas })}(x)=\rho_{0}-\sum_{n>0} \beta_{n} \rho_{n} \cos (n q x) \\
\beta_{1}=0.73 \\
\beta_{2}=0.27 \\
\forall i \geq 3, \beta_{i}=0
\end{gathered}
$$

## Static measurement of $f_{s}$

$\underline{\text { Reconstruction of } \rho(x)}$


Red: first harmonic; green: second harmonic. Solid lines: GP predictions

Static measurement of $f_{s}$

$$
f_{s}=\frac{1}{\langle\rho(x)\rangle\langle 1 / \rho(x)\rangle}
$$

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Solid line: GP prediction

## Summarizing results

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## Thanks!

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## Theory - Saturation of Leggett's formula

- $f_{5, \times}$ calculated by applying the perturbation $-v_{0} \hat{P}_{\times}$to the system

$$
\begin{equation*}
f_{s, x}=1-\lim _{v_{0} \rightarrow 0} \frac{\left\langle\hat{P}_{x}\right\rangle}{N m v_{0}} \tag{1}
\end{equation*}
$$

- equation of continuity:

$$
\begin{equation*}
\frac{\partial \rho(x, t)}{\partial t}+\frac{\partial}{\partial x}\left[\rho(x, t)\left(v(x, t)-v_{0}\right)\right]=0 \tag{2}
\end{equation*}
$$

- stationary solution in the moving frame

$$
\Rightarrow f_{s}=\frac{1}{\langle\rho\rangle\langle 1 / \rho\rangle}
$$

## Theory - Effective mass

Equivalently, one can apply twisted boundary conditions and look at the evolution of energy:

$$
\begin{gather*}
\psi(L)=\psi(0) e^{i \theta}  \tag{3}\\
E(\theta) \simeq E(0)+N f_{s, x} \frac{\hbar^{2} \theta^{2}}{2 m L^{2}} \tag{4}
\end{gather*}
$$

Look for solutions written as Bloch functions:

$$
\begin{align*}
E(k) & \simeq E(0)+N \frac{\hbar^{2} k^{2}}{2 m_{x}^{*}}  \tag{5}\\
& \Rightarrow f_{s, x}=\frac{m}{m_{x}^{*}}
\end{align*}
$$

## Theory - Speed of sound

In the presence of $V(x)$, the velocity of a sound wave propagating along $x$ is:

$$
\begin{equation*}
c_{x}^{2}=\frac{1}{m_{x}^{*} \kappa} \tag{6}
\end{equation*}
$$

with $\kappa=\frac{1}{\rho_{0} \frac{\partial \mu\left(\rho_{0}\right)}{\partial \rho_{0}}}$.
And along $y$ :

$$
\begin{align*}
& c_{y}^{2}=\frac{1}{m \kappa}  \tag{7}\\
& f_{s, x}=\frac{m}{m_{x}^{*}}=\frac{c_{x}^{2}}{c_{y}^{2}}  \tag{8}\\
& f_{s, y}=\frac{m}{m_{y}^{*}}=1 \tag{9}
\end{align*}
$$

## Theory - Limit of small $V_{0}$

We expand the solution of the GPE in powers of $V_{0}$. It yields:

$$
\begin{gather*}
\frac{\rho_{1}}{\rho_{0}}=\frac{2 V_{0}}{2 \mu_{0}+\epsilon_{q}}+\mathcal{O}\left(V_{0}^{3}\right)  \tag{10}\\
f_{s, x}=1-\frac{2 V_{0}^{2}}{\left(2 \mu_{0}+\epsilon_{q}\right)^{2}}+\mathcal{O}\left(V_{0}^{4}\right)  \tag{11}\\
\kappa=\mu_{0}^{-1}\left[1-\frac{2 V_{0}^{2} \epsilon_{q}}{\left(2 \mu_{0}+\epsilon_{q}\right)^{3}}\right]+\mathcal{O}\left(V_{0}^{4}\right) \tag{12}
\end{gather*}
$$

## Experiment - Full graph



